

# MATH2020A Lecture 20 Notes

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Recall the statement of the Divergence Theorem:

**Theorem 1** (Divergence Theorem). *Let  $\vec{F}$  be a  $C^1$  vector field on an open domain  $\Omega \subseteq \mathbb{R}^3$ . Let  $S$  be a piecewise smooth oriented closed (having no boundary) surface enclosing a (solid) region  $D \subseteq \Omega$ . Let  $\hat{\mathbf{n}}$  be the outward-pointing unit normal vector field on  $S$ . Then*

$$\iint_S \vec{F} \cdot \hat{\mathbf{n}} \, d\sigma = \iiint_D \operatorname{div} \vec{F} \, dV = \iiint_D \vec{\nabla} \cdot \vec{F} \, dV. \quad (1)$$

We will prove this result for a special case.

*Proof of the Divergence Theorem.* We will only prove this in the case of a special domain  $D$  which is simultaneously of Type I, II, and III.

Recall that this means that there exist regions  $R_1$ ,  $R_2$ , and  $R_3$  in  $\mathbb{R}^2$  and functions  $f_1$ ,  $f_2$ ,  $g_1$ ,  $g_2$ ,  $h_1$ , and  $h_2$  such that

$$\begin{aligned} D &= \{(x, y, z) \in \mathbb{R}^3 \mid (x, y) \in R_1, \quad f_1(x, y) \leq z \leq f_2(x, y)\} && \text{[Type I]} \\ &= \{(x, y, z) \in \mathbb{R}^3 \mid (x, z) \in R_2, \quad g_1(x, z) \leq y \leq g_2(x, z)\} && \text{[Type II]} \\ &= \{(x, y, z) \in \mathbb{R}^3 \mid (y, z) \in R_3, \quad h_1(y, z) \leq x \leq h_2(y, z)\}. && \text{[Type III]} \end{aligned} \quad (2)$$

Like we did for the proof of Green's Theorem, given

$$\vec{F} = M \hat{\mathbf{i}} + N \hat{\mathbf{j}} + L \hat{\mathbf{k}}, \quad (3)$$

we will prove three equalities that combine together to give the result.

In particular, we want to show that

$$\begin{cases} \iint_S M \hat{\mathbf{i}} \cdot \hat{\mathbf{n}} \, d\sigma &= \iiint_D \frac{\partial M}{\partial x} \, dV, & \text{[by Type III]} \\ \iint_S N \hat{\mathbf{j}} \cdot \hat{\mathbf{n}} \, d\sigma &= \iiint_D \frac{\partial N}{\partial y} \, dV, & \text{[by Type II]} \\ \iint_S L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} \, d\sigma &= \iiint_D \frac{\partial L}{\partial z} \, dV. & \text{[by Type I]} \end{cases} \quad (4)$$

The proofs of all three are similar so we will only show the last one:

$$\iint_S L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} \, d\sigma = \iiint_D \frac{\partial L}{\partial z} \, dV. \quad (5)$$

By Fubini's Theorem, since  $D$  is Type I, the RHS is

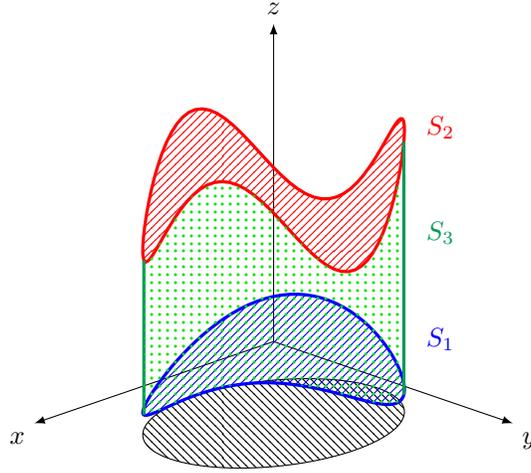
$$\begin{aligned} \text{RHS} &= \iiint_D \frac{\partial L}{\partial z} \, dV \\ &= \iint_{R_1} \left[ \int_{f_1(x, y)}^{f_2(x, y)} \frac{\partial L}{\partial z} \, dz \right] dx \, dy \\ &= \iint_{R_1} \left[ L(x, y, f_2(x, y)) - L(x, y, f_1(x, y)) \right] dx \, dy. \end{aligned} \quad (6)$$

For the LHS, we note that by the definition of a Type I domain, the boundary  $S = \partial D$  can be written as

$$S = S_1 \cup S_2 \cup S_3 \quad (7)$$

where

- $S_1$  is the graph of  $f_1$  over  $R_1$ ,
- $S_2$  is the graph of  $f_2$  over  $R_1$ ,
- $S_3$  is a “vertical” surface between  $S_1$  and  $S_2$ .



**Figure 1:** The boundary of a Type I 3D domain can be decomposed into three parts.

Hence

$$\begin{aligned} \text{LHS} &= \iint_S L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} d\sigma \\ &= \iint_{S_1} L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} d\sigma + \iint_{S_2} L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} d\sigma + \iint_{S_3} L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} d\sigma. \end{aligned} \quad (8)$$

The integral over  $S_3$  vanishes since  $S_3$  is a “vertical” surface, and so the unit normal  $\hat{\mathbf{n}}$  there has no  $\hat{\mathbf{k}}$  component.

For the upper surface  $S_2$ , the outward-pointing unit normal  $\hat{\mathbf{n}}$  points upwards (that is, has non-negative  $\hat{\mathbf{k}}$ -component). Note that we have the natural parameterization

$$(x, y) \mapsto \vec{r}(x, y) = (x, y, f_2(x, y)) \quad (9)$$

where

$$\begin{cases} \vec{r}_x &= \hat{\mathbf{i}} + \frac{\partial f_2}{\partial x} \hat{\mathbf{k}}, \\ \vec{r}_y &= \hat{\mathbf{j}} + \frac{\partial f_2}{\partial y} \hat{\mathbf{k}} \end{cases} \quad (10)$$

and

$$\vec{r}_x \times \vec{r}_y = -\frac{\partial f_2}{\partial x} \hat{\mathbf{i}} - \frac{\partial f_2}{\partial y} \hat{\mathbf{j}} + \hat{\mathbf{k}}. \quad (11)$$

With this, the outward unit normal  $\hat{\mathbf{n}}$  is given by

$$\hat{\mathbf{n}} = \frac{\vec{r}_x \times \vec{r}_y}{\|\vec{r}_x \times \vec{r}_y\|} \implies \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} = \frac{1}{\|\vec{r}_x \times \vec{r}_y\|}. \quad (12)$$

Therefore,

$$\begin{aligned}\iint_{S_2} L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} d\sigma &= \iint_{R_1} L(x, y, f_2(x, y)) \frac{1}{\|\vec{r}_x \times \vec{r}_y\|} \|\vec{r}_x \times \vec{r}_y\| dx dy \\ &= \iint_{R_1} L(x, y, f_2(x, y)) dx dy.\end{aligned}\tag{13}$$

For the lower surface  $S_1$ , we have a similar computation, except that the unit normal points downwards.

Using the natural parameterization

$$(x, y) \mapsto \vec{r}(x, y) = (x, y, f_1(x, y)),\tag{14}$$

we have

$$\hat{\mathbf{n}} = -\frac{\vec{r}_x \times \vec{r}_y}{\|\vec{r}_x \times \vec{r}_y\|} \implies \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} = -\frac{1}{\|\vec{r}_x \times \vec{r}_y\|}.\tag{15}$$

As such,

$$\iint_{S_1} L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} d\sigma = -\iint_{R_1} L(x, y, f_1(x, y)) dx dy.\tag{16}$$

Putting everything together, we see that

$$\begin{aligned}\iint_S L \hat{\mathbf{k}} \cdot \hat{\mathbf{n}} d\sigma &= \iint_{R_1} L(x, y, f_2(x, y)) dx dy - \iint_{R_1} L(x, y, f_1(x, y)) dx dy \\ &= \iint_{R_1} \left[ L(x, y, f_2(x, y)) - L(x, y, f_1(x, y)) \right] dx dy \\ &= \iiint_D \frac{\partial L}{\partial z} dV,\end{aligned}\tag{17}$$

which proves the result.  $\square$

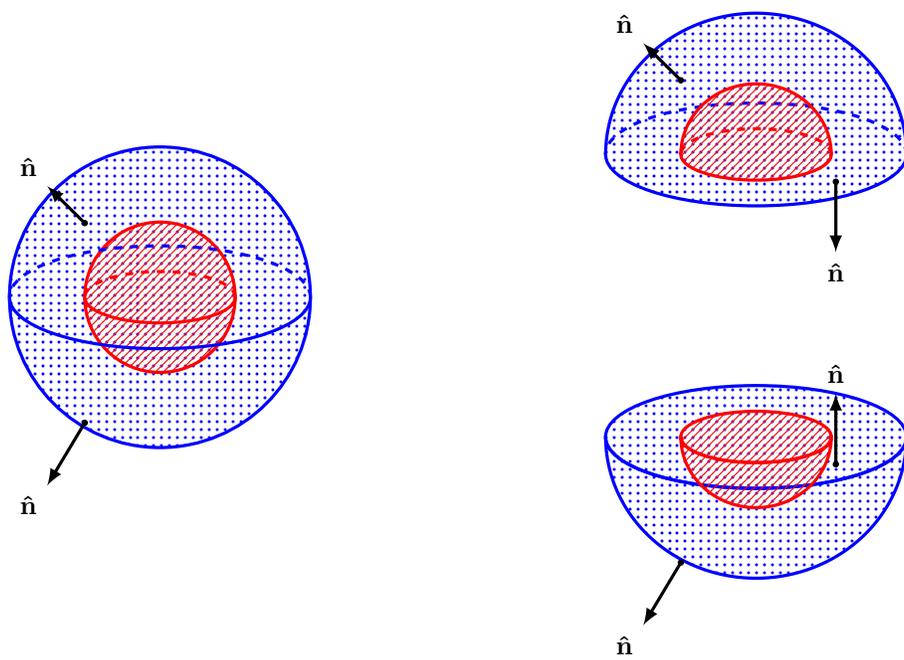
**Remark 2.** Similarly to Green's Theorem, the Divergence Theorem also holds for solid regions with finitely many "holes" inside so long as the surfaces are oriented appropriately.

To prove this general version, we make "cuts" to the solid to "expose" the holes to the boundary analogously to the method used for Green's Theorem. The newly exposed surfaces are double-counted, but with opposite orientations, which cancel out in the end (see figure on next page).

**Remark 3.** The notion of *flux density* from before also applies in this case via the Divergence Theorem.

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(End of Lecture 20 – Nov 20)



**Figure 2:** Cutting a solid in the proof of the general case of the Divergence Theorem.