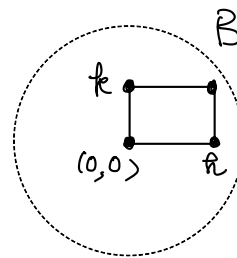


Pf of Clairaut's Thm

We may assume $\vec{a} = (0,0) \in \Omega$,
and we need to show

$$f_{xy}(0,0) = f_{yx}(0,0)$$

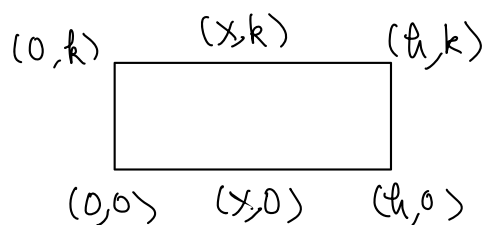


the open ball s.t. f_{xy}, f_{yx} both exist
in B .

Let $h, k > 0$ and $[0,h] \times [0,k] \subset B \subset \Omega$

Define

$$\alpha = f(h,k) - f(h,0) - f(0,k) + f(0,0)$$



Let $g(x) = f(x,k) - f(x,0)$, $0 \leq x \leq h$

Then $\alpha = g(h) - g(0)$

$$g'(x) = f_x(x,k) - f_x(x,0)$$

Mean Value Thm $\Rightarrow \exists \theta_1 \in (0,h)$ s.t.

$$\frac{g(h) - g(0)}{h} = g'(\theta_1)$$

$$\Rightarrow \frac{\alpha}{h} = f_x(\theta_1, k) - f_x(\theta_1, 0)$$

$$\text{i.e. } \alpha = h [f_x(\theta_1, k) - f_x(\theta_1, 0)]$$

Mean Value Thm $\Rightarrow \exists \theta_2 \in (0,k)$ s.t.

$$\frac{f_x(\theta_1, k) - f_x(\theta_1, 0)}{k} = (f_x)_y(\theta_1, \theta_2)$$

$$\Rightarrow \alpha = \lim_{h,k \rightarrow 0} f_{xy}(h_1, k_1)$$

Similarly, $\exists (h_2, k_2) \in (0, h) \times (0, k)$ s.t.

$$\alpha = \lim_{h,k \rightarrow 0} f_{yx}(h_2, k_2) \quad (\text{Ex!})$$

$$\Rightarrow f_{xy}(h_1, k_1) = f_{yx}(h_2, k_2)$$

Letting $h, k \rightarrow 0^+ \Rightarrow h_1, k_1 \rightarrow 0^+, \& \ h_2, k_2 \rightarrow 0^+$

By continuity of f_{xy} & f_{yx} at $\vec{a}=(0,0)$, we have

$$f_{xy}(0,0) = f_{yx}(0,0) \quad \text{**}$$

Def Let $f: \Omega \rightarrow \mathbb{R}$ ($\Omega \subseteq \mathbb{R}^n$, open)

Then • f is called a C^k function if
all partial derivatives of f up to
order k exist and are continuous on Ω

• f is called a C^∞ function if
 f is C^k for all $k \geq 0$.

egs: (1) If f is continuous (0-order partial derivative)
then f is C^0 .

(2) If f is C^2 , then $f, f_x, f_y, f_{xx}, f_{xy} = f_{yx}, f_{yy}$ exist &
are all continuous. (by Clairaut's)

(3) Polynomials, Rational functions, exponential, logarithm, trigonometric functions are C^∞ function on their domains of definition & hence their sum/difference/product/quotient/compositions are C^∞ function on their domains of definition.

explicit eg: $e^{x^2-y} \sin\left(\frac{x}{y}\right)$ is C^∞ on domain of definition $= \mathbb{R}^2 \setminus \{x\text{-axis}\}$ (except $y=0$)

Generalization of Clairaut's Thm

If f is C^k on an open set $\Omega \subseteq \mathbb{R}^n$, then the order of (taking) differentiation does not matter for all partial derivatives up to order k .

eg If $f(x,y,z)$ is C^3 , then

$$\begin{aligned} f_{xz} &= f_{zx}, \quad f_{xyx} = f_{xzy} = f_{zxy} = f_{zyx} \\ &\vdots \\ \text{etc.} &= f_{yzx} = f_{yxz} \end{aligned}$$

$$f_{xxy} = f_{xyx} = f_{yxx} \text{ and etc.}$$

Differentiability

Recall : 1-variable : f is differentiable at a

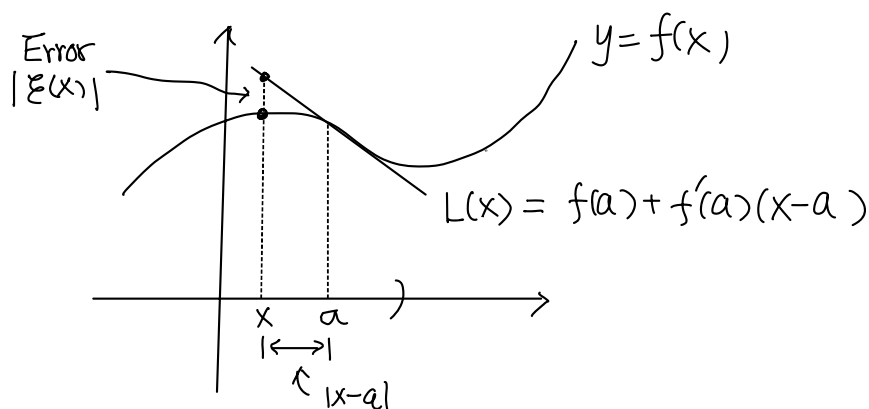
$$\text{if } f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a} \text{ exists}$$

which is equivalent to

Linear Approximation of f at the point a :

$$f(x) \approx f(a) + f'(a)(x-a)$$

$L(x)$ is the "best" linear function ($\deg \leq 1$, poly)
to approximate $f(x)$ near a



What does it mean by the "best"?

Answer :
$$\lim_{x \rightarrow a} \frac{|f(x) - L(x)|}{|x-a|} = 0$$

where $f(x) - L(x)$ is usually referred as the

"error" term $E(x) = f(x) - L(x)$.

$$\left(\begin{array}{c} \lim_{x \rightarrow a} \left| \frac{f(x) - f(a)}{x - a} - f'(a) \right| \\ \parallel \\ \lim_{x \rightarrow a} \frac{|E(x)|}{|x-a|} = 0 \end{array} \right)$$

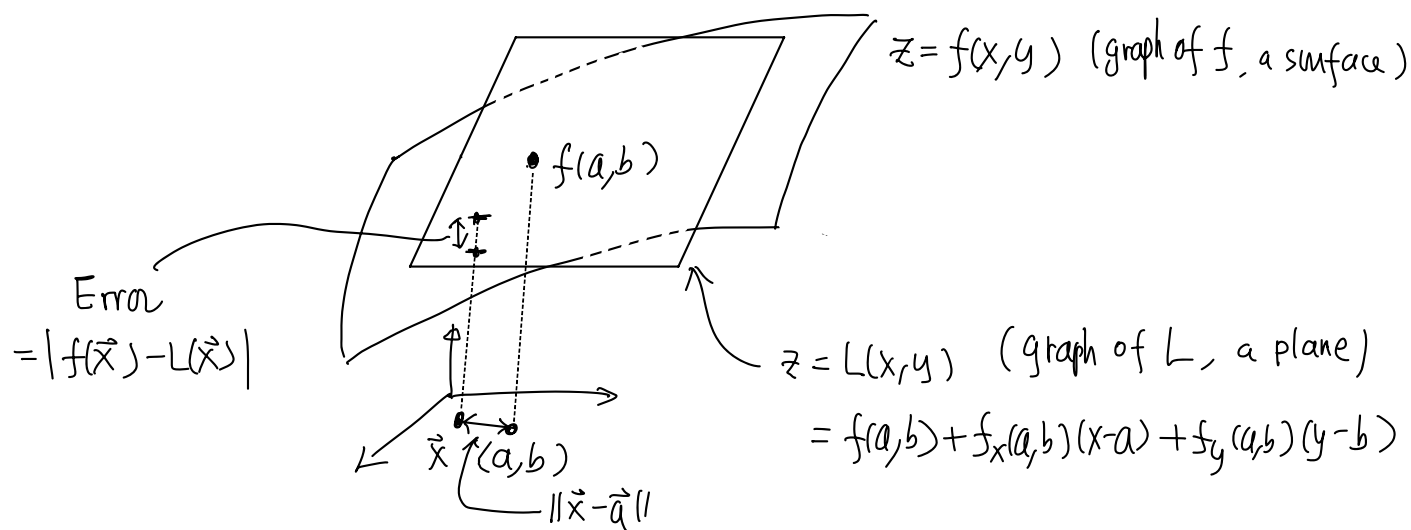
Higher dimension's analog:

linear function (deg ≤ 1 , poly)

$$L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b)$$

and want

$$f(x,y) \approx L(x,y) = f(a,b) + f_x(a,b)(x-a) + f_y(a,b)(y-b).$$



Def: Let $f: \Omega \rightarrow \mathbb{R}$, $\Omega \subseteq \mathbb{R}^n$, open
• $\vec{a} = (a_1, \dots, a_n) \in \Omega$

Then f is said to be differentiable at \vec{a}

if (1) $\frac{\partial f}{\partial x_i}(\vec{a})$ exists for all $i=1, \dots, n$

(2) In the linear approximation for $f(\vec{x})$ at \vec{a}

$$f(\vec{x}) = f(\vec{a}) + \underbrace{\sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{a})(x_i - a_i)}_{L(\vec{x}) \text{ linear approx.}} + \underbrace{\varepsilon(\vec{x})}_{\text{error term}}$$

the error term $\varepsilon(\vec{x})$ satisfies

$$\lim_{\vec{x} \rightarrow \vec{a}} \frac{|\varepsilon(\vec{x})|}{\|\vec{x} - \vec{a}\|} = 0.$$

(A differentiable function is one which can be well approximated by a linear function locally.)

Remark: $L(\vec{x}) = f(\vec{a}) + \sum_{i=1}^n \underbrace{\frac{\partial f}{\partial x_i}(\vec{a})}_{\substack{\uparrow \\ \text{slope of } f \text{ in} \\ x_i\text{-direction at } \vec{a}}} \underbrace{(x_i - a_i)}_{\Delta x_i}$

- $L(\vec{x})$ is a $\deg \leq 1$ polynomial
- $L(\vec{a}) = f(\vec{a})$
- $\frac{\partial L}{\partial x_i}(\vec{a}) = \frac{\partial f}{\partial x_i}(\vec{a})$ (Easy Ex!)
- The graph of $y = L(\vec{x})$ is a n -plane tangent to the graph of $y = f(\vec{x})$ (which is a surface) at the point $\vec{x} = \vec{a}$.

eg 1: $f(x,y) = x^2 y$

(1) Show that f is differentiable at $(1,2)$

(2) Approximate $f(1.1, 1.9)$ using linearization, $f(1,2)$

(3) Find tangent plane of $z = f(x,y)$ at $(1,2,z)$.

Soln: (1) $\frac{\partial f}{\partial x} = 2xy$, $\frac{\partial f}{\partial y} = x^2$
 $\frac{\partial f}{\partial x}(1,2) = 4$, $\frac{\partial f}{\partial y}(1,2) = 1$

\therefore The linearization at $(1,2)$ is

$$\begin{aligned} L(x,y) &= f(1,2) + \frac{\partial f}{\partial x}(1,2)(x-1) + \frac{\partial f}{\partial y}(1,2)(y-2) \\ &= 2 + 4(x-1) + (y-2) \quad (\text{or } = 4x + y - 4) \end{aligned}$$

With error term

$$\begin{aligned} E(x,y) &= f(x,y) - L(x,y) \\ &= x^2y - [2 + 4(x-1) + (y-2)] \end{aligned}$$

$$\begin{aligned} \lim_{(x,y) \rightarrow (1,2)} \frac{|E(x,y)|}{\|(x,y) - (1,2)\|} &= \lim_{(x,y) \rightarrow (1,2)} \frac{|x^2y - 2 - 4(x-1) - (y-2)|}{\sqrt{(x-1)^2 + (y-2)^2}} \\ &= \lim_{(h,k) \rightarrow (0,0)} \frac{|(1+h)^2(k+2) - 2 - 4h - k|}{\sqrt{h^2 + k^2}} \quad \left(\begin{array}{l} \text{letting } h = x-1 \\ k = y-2 \end{array} \right) \\ &= \lim_{(h,k) \rightarrow (0,0)} \frac{|h^2k + 2hk + 2h^2|}{\sqrt{h^2 + k^2}} \quad \left(\text{let } \begin{array}{l} h = r \cos \theta \\ k = r \sin \theta \end{array} \right) \\ &= \lim_{r \rightarrow 0} r |r \cos^3 \theta \sin \theta + 2 \cos \theta \sin \theta + 2 \cos^2 \theta| \\ &= 0 \quad (\text{by Squeeze Thm}) \end{aligned}$$

$\therefore f$ is differentiable at $(1,2)$.

$$(b) \quad ((1.1, 1.9) \approx (1, 2))$$

$$\begin{aligned} f(1.1, 1.9) &\approx L(1.1, 1.9) \\ &= 2 + 4(1.1-1) + (1.9-2) \\ &= 2 + 4 \cdot 0.1 + (-0.1) \\ &= 2.3 \end{aligned}$$

(c) The equation of the tangent plane of $z=f(x,y)$ at the point $(x,y)=(1,2)$ is

$$z = L(x,y) = 2 + 4(x-1) + (y-2)$$

$$\left(\begin{array}{l} \text{i.e.} \quad z = 4x + y - 4 \\ \text{or} \quad 4x + y - z = 4 \end{array} \right) \quad \times \times$$

eg 2 Is $f(x,y) = \sqrt{|xy|}$ differentiable at $(0,0)$?

Soln: $\frac{\partial f}{\partial x}(0,0) = \lim_{h \rightarrow 0} \frac{f(h,0) - f(0,0)}{h} = \lim_{h \rightarrow 0} \frac{0-0}{h} = 0$

$$\frac{\partial f}{\partial y}(0,0) = \dots = 0 \quad (\text{Similarly. Ex!})$$

$$\begin{aligned} \text{Linearization } L(x,y) &= f(0,0) + \frac{\partial f}{\partial x}(0,0)x + \frac{\partial f}{\partial y}(0,0)y \\ &= 0 + 0 \cdot x + 0 \cdot y \\ &\equiv 0 \end{aligned}$$

$$\begin{aligned} \text{Error term } \xi(x,y) &= f(x,y) - L(x,y) = f(x,y) \\ &= \sqrt{|xy|} \end{aligned}$$

$$\begin{aligned} \lim_{(x,y) \rightarrow (0,0)} \frac{|\xi(x,y)|}{\|(x,y)-(0,0)\|} &= \lim_{(x,y) \rightarrow (0,0)} \frac{\sqrt{|xy|}}{\sqrt{x^2+y^2}} \\ &= \lim_{r \rightarrow 0} \frac{r \sqrt{|\cos \theta \sin \theta|}}{r} = \lim_{r \rightarrow 0} \sqrt{|\cos \theta \sin \theta|} \end{aligned}$$

Different directions (ie different θ) give different limits.

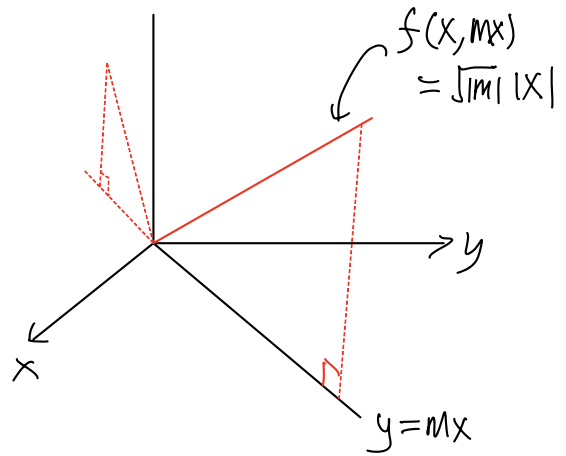
$$\therefore \lim_{(x,y) \rightarrow (0,0)} \frac{|\xi(x,y)|}{\|(x,y)-(0,0)\|} \quad \text{DNE}$$

$\therefore f = \sqrt{|xy|}$ is not differentiable at $(0,0)$.

Remark: In this example,
along the straight line $y=mx$

$$f(x,y) = \sqrt{|xmx|} = \sqrt{|m|} |x|$$

(only "approximated" by
 $L(x,y)$ in the $m=0$ situation.)



(Note: "Differentiability" \Rightarrow we can approximate all (infinitely many) directions by information along x & y direction. (x_1, \dots, x_n) in general)

Thm If $f(\vec{x})$ is differentiable at \vec{a} , then
 $f(\vec{x})$ is continuous at \vec{a} .

Def: $f(\vec{x}) = L(\vec{x}) + \epsilon(\vec{x})$ is differentiable $\Leftrightarrow \lim_{\vec{x} \rightarrow \vec{a}} \frac{|\epsilon(\vec{x})|}{\|\vec{x} - \vec{a}\|} = 0$

$$= f(\vec{a}) + \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{a})(x_i - a_i) + \epsilon(\vec{x})$$

$$\Rightarrow |f(\vec{x}) - f(\vec{a})| \leq \left| \sum_{i=1}^n \frac{\partial f}{\partial x_i}(\vec{a})(x_i - a_i) \right| + |\epsilon(\vec{x})| \quad (\text{Triangle inequality})$$

$$(\text{Cauchy-Schwarz}) \leq \left(\sqrt{\left(\frac{\partial f}{\partial x_i}(\vec{a}) \right)^2} + \frac{|\epsilon(\vec{x})|}{\|\vec{x} - \vec{a}\|} \right) \cdot \|\vec{x} - \vec{a}\|$$

$$\rightarrow 0 \quad \text{as } \vec{x} \rightarrow \vec{a}$$

by Squeeze Thm & Differentiability \nexists

Thm If $f, g: \Omega \rightarrow \mathbb{R}$ ($\Omega \subseteq \mathbb{R}^n$, open)

are differentiable at $\vec{a} \in \Omega$,

then (1) $f(\vec{x}) \pm g(\vec{x})$, $c f(\vec{x})$, $f(\vec{x})g(\vec{x})$ are
differentiable at \vec{a} .

(2) $\frac{f(\vec{x})}{g(\vec{x})}$ is differentiable at \vec{a} if $g(\vec{a}) \neq 0$

(3) (Special case of Chain Rule)

For 1-variable function $h(x)$ differentiable

at $f(\vec{a})$, $h \circ f$ is differentiable at \vec{a} .