

Lecture 6:

Recall:

Definition: (Discrete Fourier Transform) Given $f_0, f_1, \dots, f_{n-1} \in \mathbb{C}$, then the discrete Fourier Transform (DFT) is defined as:

$$\vec{c} = \begin{pmatrix} c_0 \\ c_1 \\ \vdots \\ c_{n-1} \end{pmatrix} \in \mathbb{C}^n \text{ where } c_k = \frac{1}{n} \sum_{j=0}^{n-1} f_j e^{-i\left(\frac{2jk\pi}{n}\right)} \text{ for } k=0, 1, 2, \dots, n-1$$

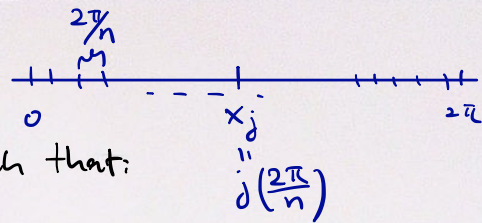
The inverse discrete Fourier Transform recovers the original signal:

$$f_j = \sum_{k=0}^{n-1} c_k e^{i\left(\frac{2jk\pi}{n}\right)} \text{ for } j=0, 1, 2, \dots, n-1$$

Motivation 1: Let $f(x)$ defined on $[0, 2\pi]$

Approximate $f(x)$ by:

$$F_n(x) = \sum_{k=0}^{n-1} C_k e^{ikx}, \quad x \in [0, 2\pi] \text{ such that:}$$



$$F_n(x_j) = f(x_j) \stackrel{\text{def}}{=} f_j, \quad x_j = \frac{2\pi}{n} j \quad (\text{for all } j=0, 1, 2, \dots, n-1)$$

$$(*) \left\{ \begin{array}{l} F_n(x_0) = C_0 + C_1 + C_2 + \dots + C_{n-1} = f_0 \\ F_n(x_1) = C_0 + C_1 e^{ix_1} + C_2 e^{i2x_1} + \dots + C_{n-1} e^{i(n-1)x_1} = f_1 \\ \vdots \\ F_n(x_{n-1}) = C_0 + C_1 e^{ix_{n-1}} + C_2 e^{i2x_{n-1}} + \dots + C_{n-1} e^{i(n-1)x_{n-1}} = f_{n-1} \end{array} \right.$$

Remark: Computational cost for DFT is:

$$\begin{array}{l} n^2 \text{ multiplication} \\ + \\ n(n-1) \text{ addition} \end{array} = \mathcal{O}(n^2)$$

$$A_\omega = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & \omega & \omega^2 & \omega^3 \\ 1 & \omega^2 & \omega^4 & \omega^5 \\ 1 & \omega^3 & \omega^6 & \omega^7 \end{pmatrix}$$
$$\omega = e^{i\frac{2\pi}{4}}$$

Example: Consider $f(t) = 5 + 2\cos(t - \frac{\pi}{2}) + 3\cos(2t)$.

f is 2π -periodic. Divide $[0, 2\pi]$ by 4 partitions. Find the DFT of f (discretized by 4 points).

$$f_0 = f(0) = 8; \quad f_1 = f\left(\frac{2\pi}{4}\right) = 4; \quad f_2 = f\left(\frac{4\pi}{4}\right) = 8; \quad f_3 = f\left(\frac{6\pi}{4}\right) = 0$$

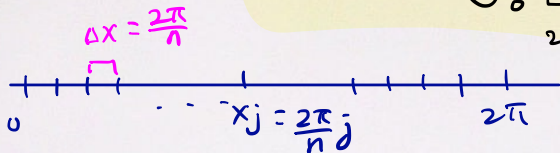
$$\therefore \text{DFT: } C_k = \frac{1}{4} \sum_{j=0}^3 f_j e^{-i\left(\frac{2jk\pi}{4}\right)} \quad \text{for } k=0, 1, 2, 3 \quad \text{or}$$

$$\begin{pmatrix} C_0 \\ C_1 \\ C_2 \\ C_3 \end{pmatrix} = \frac{1}{4} A_\omega \begin{pmatrix} f_0 \\ f_1 \\ f_2 \\ f_3 \end{pmatrix} = \frac{1}{4} \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & -i & -1 & i \\ 1 & -1 & 1 & -1 \\ 1 & i & -1 & -i \end{pmatrix} \begin{pmatrix} 8 \\ 4 \\ 8 \\ 0 \end{pmatrix} = \begin{pmatrix} 5 \\ -i \\ 3 \\ i \end{pmatrix}$$
$$\omega = e^{i\frac{2\pi}{4}}$$

Motivation 2: Fourier Transform $\leftrightarrow$ Fourier Series extended to related $(-\infty, \infty)$

Fourier coefficients: $C_k = \frac{1}{2\pi} \int_0^{2\pi} \underbrace{f(x)}_{2\pi\text{-periodic}} e^{-ikx} dx$

Divide:



We can approximate the integration:

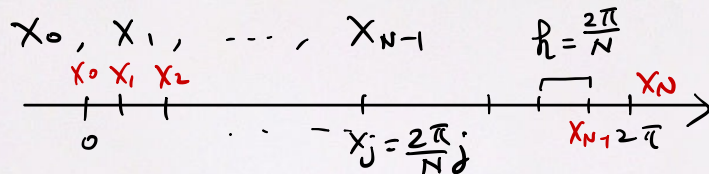
$$\begin{aligned} C_k &\approx \frac{1}{2\pi} \sum_{j=0}^{n-1} f(x_j) e^{-ikx_j} \Delta x = \frac{1}{2\pi} \sum_{j=0}^{n-1} f_j e^{-i \frac{2\pi}{n} j k} \left(\frac{2\pi}{n} \right) \\ &= \frac{1}{n} \sum_{j=0}^{n-1} f_j e^{-i \frac{2jk\pi}{n}} \quad \text{for } k=0, 1, 2, \dots, n-1 \\ &= \text{DFT} \end{aligned}$$

DFT = approximation of (complex) Fourier coefficient.

DFT and numerical diff eqt

Consider: $\frac{d^2 u}{dx^2} = f$ for $x \in [0, 2\pi]$ with periodic boundary condition $u(0) = u(2\pi)$

Suppose f is measured only at N discrete points:



Let $\vec{f} = \begin{pmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f(x_{N-1}) \end{pmatrix} \stackrel{\text{def}}{=} \begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_{N-1} \end{pmatrix} \in \mathbb{R}^N$ and $\vec{u} = \begin{pmatrix} u(x_0) \\ u(x_1) \\ \vdots \\ u(x_{N-1}) \end{pmatrix} \stackrel{\text{def}}{=} \begin{pmatrix} u_0 \\ u_1 \\ \vdots \\ u_{N-1} \end{pmatrix} \in \mathbb{R}^N$

(unknown)

By Taylor's expansion,

$$u(x_j+h) \approx u(x_j) + h u'(x_j) + \frac{h^2}{2} u''(x_j) \quad \text{--- (1)}$$

$$u(x_j-h) \approx u(x_j) - h u'(x_j) + \frac{h^2}{2} u''(x_j) \quad \text{--- (2)}$$

$$(1) + (2) : u''(x_j) \approx \frac{u(\overset{x_{j-1}}{x_j-h}) - 2u(x_j) + u(\overset{x_{j+1}}{x_j+h})}{h^2}$$

$$\therefore u''(x_j) \approx \frac{u_{j-1} - 2u_j + u_{j+1}}{h^2} \quad (\text{Central difference approximation})$$

Thus: $\begin{pmatrix} u''(x_0) \\ u''(x_1) \\ \vdots \\ u''(x_{N-1}) \end{pmatrix} \approx \tilde{D} \vec{u}$ where $\tilde{D} = \frac{1}{h^2} \begin{pmatrix} -2 & 1 & & & \\ 1 & -2 & & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & -2 & 1 \\ & & & 1 & -2 \end{pmatrix}$

for $j=0, 1, 2, \dots, N-1$

$u_0, u_1, \dots, u_{N-1}$

$\boxed{1}$ $\boxed{1}$

(Use the fact that $u_0 = u_N, u_{-1} = u_{N-1}$)

$\therefore \frac{d^2 u}{dx^2} = f$ can be discretized as $\boxed{\tilde{D} \vec{u} = \vec{f}}$ (Linear System)
Numerical differential eqt

Remark: $\tilde{D}$ is B/G matrix!!

Goal: Design numerical spectral method to solve $\tilde{D} \vec{u} = \vec{f}$.

Need to: Determine eigenvalues / eigenvectors of $\tilde{D}$

In continuous case, e^{ikx} is an eigenfunction of $\frac{d^2}{dx^2}$, that is periodic.

In discrete case, define: $\vec{e^{ikx}} \stackrel{\text{def}}{=} \begin{pmatrix} e^{ikx_0} \\ e^{ikx_1} \\ \vdots \\ e^{ikx_{N-1}} \end{pmatrix}$ (Capture the values of e^{ikx} at N discrete points)

Claim: $\overrightarrow{e^{ikx}}$ is an eigenvector of $\tilde{D}$ ($k=0,1,2,\dots,N-1$)

More precisely,

$$\tilde{D} \overrightarrow{e^{ikx}} = \underbrace{\left(-\frac{4 \sin^2 \frac{kh}{2}}{h^2} \right)}_{-\lambda_k^2} \overrightarrow{e^{ikx}}$$

where: $\lambda_k^2 = \left(\frac{4 \sin^2 \frac{kh}{2}}{h^2} \right).$

or $\lambda_k = \left(\frac{2 \sin \frac{kh}{2}}{h} \right)$

Proof: For each j , $(\tilde{D} \overrightarrow{e^{ikx}})_j = \frac{e^{ikx_{j-1}} - 2e^{ikx_j} + e^{ikx_{j+1}}}{h^2}$

$$= e^{ikx_j} \left(\frac{e^{-ikh} - 2 + e^{ikh}}{h^2} \right)$$

$$= e^{ikx_j} \left(\frac{\cos kh - \cancel{isinh} - 2 + \cos kh + \cancel{isinh}}{h^2} \right)$$

$$= e^{ikx_j} \left(\frac{2\cos kh - 2}{h^2} \right) = \underbrace{\left(-\frac{4 \sin^2 \frac{kh}{2}}{h^2} \right)}_{-\lambda_k^2} e^{ikx_j}$$

Let $-\lambda_k^2 = \left(-\frac{4 \sin^2 \frac{kh}{2}}{h^2} \right)$. Then: $\tilde{D} \overrightarrow{e^{ikx}} = -\lambda_k^2 \overrightarrow{e^{ikx}}$