

Lecture 14: Recall:

Splitting choice 3: Successive overrelaxation method (SOR)

Consider the iterative scheme =

$$(\text{Suppose } A = L + D + U) \\ L \vec{x}^{k+1} + D \vec{y}^{k+1} + U \vec{x}^k = \vec{b} \quad (*)$$

$$\vec{x}^{k+1} = \vec{x}^k + \omega (\vec{y}^{k+1} - \vec{x}^k) \quad (**)$$

$$\Leftrightarrow \vec{y}^{k+1} = \frac{1}{\omega} (IR \vec{x}^{k+1} + (\omega-1)\vec{x}^k)$$

Putting (\*\*) into (\*):

$$(L + \frac{1}{\omega} D) \vec{x}^{k+1} + \frac{1}{\omega} (\omega U + (\omega-1)D) \vec{x}^k = \vec{b}$$

$$\text{or } \underbrace{(L + \frac{1}{\omega} D)}_N \vec{x}^{k+1} = \underbrace{\left( \frac{1}{\omega} D - (D+U) \right)}_P \vec{x}^k + \vec{b}$$

Remark: SOR is equivalent to:

$$A = N - P = \underbrace{\left( L + \frac{1}{\omega} D \right)}_{N} - \underbrace{\left( \frac{1}{\omega} D - (D + U) \right)}_{P}$$

Or equivalently,  $A = (a_{ij})$

$$\left\{ \begin{array}{l} a_{11} y_1^{k+1} + a_{12} x_2^k + \dots + a_{1n} x_n^k = b_1 \text{ for } x_1^{k+1} = x_1^k + \omega(y_1^{k+1} - x_1^k) \\ a_{21} x_1^{k+1} + a_{22} y_2^{k+1} + a_{23} x_3^k + \dots + a_{2n} x_n^k = b_2 \text{ for } x_2^{k+1} = x_2^k + \omega(y_2^{k+1} - x_2^k) \\ \vdots \\ a_{n1} x_1^{k+1} + a_{n2} x_2^{k+1} + \dots + a_{nn} y_n^{k+1} = b_n \text{ for } x_n^{k+1} = x_n^k + \omega(y_n^{k+1} - x_n^k) \end{array} \right.$$

- SOR = Gauss-Seidel if  $\omega = 1$ .

## Condition for convergence

Theorem: The necessary condition (not sufficient) for SOR to converge is  $0 < \omega < 2$ .

Theorem: If  $A$  is strictly diagonally dominant (SDD), then SOR converges if  $0 < \omega \leq 1$ .

Proof: We need to show  $\rho(M_{SOR}) < 1$  if  $0 < \omega \leq 1$ .

We'll show it by contradiction.

Suppose  $\exists$  eigenvalue  $\lambda$  such that  $|\lambda| \geq 1$ . Then:

$$\det(\lambda I - M_{SOR}) = 0$$

$$\therefore \det(\lambda I - (D + \omega L)^{-1}((1-\omega)D - \omega U)) = 0$$

$$\Rightarrow \det\left(\lambda(D + \omega L)^{-1}\left((D + \omega L) - \frac{1}{\lambda}((1-\omega)D - \omega U)\right)\right) = 0$$

$$\Rightarrow \det(C) = 0 \quad (\because \lambda \neq 0, (D + \omega L) \text{ is invertible})$$

$$\text{Note: } \omega(1 - \frac{1}{|\lambda|}) \leq (1 - \frac{1}{|\lambda|}) \Rightarrow \left(1 - \frac{1}{|\lambda|}(1-\omega)\right) \geq \omega$$

Now,

$$|C_{ii}| = \left| 1 - \frac{1}{\lambda} (1-\omega) \right| |a_{ii}| \geq \left[ 1 - \frac{1}{|\lambda|} (1-\omega) \right] |a_{ii}|$$

$$\geq \omega |a_{ii}| > \omega \sum_{j=1}^n |a_{ij}| \geq \underbrace{\omega \sum_{j=1}^{i-1} |a_{ij}|}_{\text{"}} + \underbrace{\frac{\omega}{|\lambda|} \sum_{j=i+1}^n |a_{ij}|}_{\text{"}}$$

$$|C_{ii}| > \sum_{\substack{j=1 \\ j \neq i}}^n |C_{ij}| \quad \text{for all } i$$

$\therefore C$  is SDD  $\Rightarrow C$  is non-singular!!

$$\Rightarrow \det(C) \neq 0$$

Contradiction.

$$\boxed{\begin{aligned} & \left( (D + \omega L) - \frac{1}{\lambda} \left( \underset{\text{"}}{(1-\omega)D} - \omega U \right) \right) \\ & C \end{aligned}}$$

## Optimal parameter $\omega_{\text{opt}}$ for SOR method

lower  $\downarrow$  diagonal  $\swarrow$  upper

Definition: Consider the system  $A\vec{x} = \vec{b}$ . Let  $A = L + D + U$ .

If the eigenvalues of  $\alpha D^{-1}L + \frac{1}{\alpha} D^{-1}U$  ( $\alpha \neq 0$ ) are independent of  $\alpha$ . Then, the matrix  $A$  is said to be consistently ordered.

## Example of consistently ordered matrices

1. Tridiagonal matrix :

$$\begin{pmatrix} \lambda_1 & * & & & 0 \\ * & \lambda_2 & * & & \\ & * & \ddots & & \\ & & & \ddots & * \\ 0 & & & * & \lambda_N \end{pmatrix}$$

2. Block tridiagonal matrix :

$$\begin{pmatrix} D_1 & T_{12} & & & 0 \\ T_{21} & D_2 & T_{23} & & \\ & & \ddots & & \\ & & & \ddots & \\ 0 & & & & D_p \end{pmatrix}$$

where  $D_i = \text{diagonal matrix}$

Theorem: [ D. Young] Assume:

1.  $0 < \omega < 2$
2.  $M_J = N_J^{-1} P_J$  has only real eigenvalues
3.  $\beta \stackrel{\text{def}}{=} \rho(M_J) < 1$
4.  $A$  is consistently ordered.

Then:  $\rho(M_{SOR}) < 1$

Also, the optimal parameter  $\omega_{opt}$  for fastest convergence

$$\omega_{opt} = \frac{2}{1 + \sqrt{1 - \beta^2}} \quad \text{and}$$

$$\rho(M_{SOR}, \omega_{opt}) = \omega_{opt} - 1$$

$$\text{Example: } A\vec{x} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$$

$$\text{Then: } \alpha D^{-1}L + \frac{1}{\alpha} D^{-1}U = \begin{pmatrix} 0 & -\frac{1}{10}\alpha \\ -\frac{\alpha}{10} & 0 \end{pmatrix}$$

$$\therefore \text{Char. poly} = \lambda^2 - \left(-\frac{1}{10\alpha}\right)\left(\frac{-\alpha}{10}\right) = 0 \Rightarrow \lambda^2 - \frac{1}{100} = 0$$

(independent of  $\alpha$ )

$\therefore A$  is consistently ordered.

Also,  $M_J$  has only real eigenvalues and  $\lambda_1 = \frac{1}{10}, \lambda_2 = -\frac{1}{10}$ .

$\therefore$  SOR converges if  $0 < \omega < 2$ .

$$\because \rho(M_J) < 1$$

$$\therefore \text{Optimal } \omega_{\text{opt}} = \frac{2}{1 + \sqrt{1 - \rho(M_J)^2}} = \frac{2}{1 + \sqrt{1 - \left(\frac{1}{10}\right)^2}} = 1.0025126$$

$$\rho(M_{\text{SOR}}, \omega_{\text{opt}}) = \omega_{\text{opt}} - 1 = 0.0025126.$$