Dynamic Programming: Piggyback, Dependency, and Space

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Principle of Dynamic Programming

- Remember the output of every subproblem to avoid re-computation.
- Resolve subproblems according to an appropriate order.

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Problem 2 (Regular List 6)

In the lecture, we derived for the rod cutting problem:

$$opt(n) = \max_{i=1}^{n} (P[i] + opt(n-i)).$$

Define bestSub(n) = k if the above maximization is obtained at i = k.



How to compute bestSub(1), bestSub(2), ..., bestSub(n) in $O(n^2)$ time?

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First, compute opt(1), opt(2), ..., opt(n) in $O(n^2)$ time, as discussed in the lecture.

For each $t \in [1, n]$, compute bestSub(t) as follows:

- Identify the $k \in [1, k]$ maximizing P[k] + opt(t k).
 - This takes O(t) time.
- Set bestSub(t) = k.

Doing so for all $t \in [1, n]$ takes $O(n^2)$ time.

The idea of computing bestSub(t) for all $t \in [1, n]$ is called the **piggyback technique**.

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Problem 2 (cont.)

In the lecture, we derived for the rod cutting problem:

$$opt(n) = \max_{i=1}^{n} (P[i] + opt(n-i)).$$

Define bestSub(n) = k if the above maximization is obtained at i = k.

Suppose that we have already computed bestSub(1), bestSub(2), ..., bestSub(n). How do we output an optimal cutting method — namely, a sequence of lengths achieving the maximum revenue — in O(n) time?

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- 1. $\ell \leftarrow n$
- 2. while $\ell > 0$ do
- 3. output "length $bestSub(\ell)$ "

4.
$$\ell \leftarrow \ell - bestSub(\ell)$$

Example					
length <i>i</i>		1	2	3	4
price P[i]	1	5	8	9
opt(i)		1	5	8	10
bestSub()	i)	1	2	3	2
Output: length 2 length 2					

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Problem 3 (Regular List 6)

Let A be an array of n integers. Define function f(a, b) — where $a \in [1, n]$ and $b \in [1, n]$ — as follows:

$$f(a,b) = \begin{cases} 0 & \text{if } a \ge b \\ (\sum_{c=a}^{b} A[c]) + \min_{c=a+1}^{b-1} \{f(a,c) + f(c,b)\} & \text{otherwise} \end{cases}$$

Design an algorithm to calculate f(1, n) in $O(n^3)$ time.

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List all the subproblems.



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f(a, b) = 0 when $a \ge b$.



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Solution

$$f(a,b) = \left(\sum_{c=a}^{b} A[c]\right) + \min_{c=a+1}^{b-1} \{f(a,c) + f(c,b)\} \text{ when } a < b.$$

Find out the dependency relationships.



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$$f(a, b) = (\sum_{c=a}^{b} A[c]) + \min_{c=a+1}^{b-1} \{f(a, c) + f(c, b)\}$$
 when $a < b$.

Let us start with the gray cells — they correspond to f(a, b) where a = b - 1. These cells depend on no other cells.



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Let us continue with the green cells — they correspond to f(a, b) where a = b - 2. Every such cell depends on two gray cells, which have already been computed.



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Let us continue with the red cells — they correspond to f(a, b) where a = b - 3. Every such cell depends on two gray cells and two green cells, all of which have been computed.



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The order can be summarized as follows.

- All cells f(a, b) with b a = 1, each computed in O(1) time.
- All cells f(a, b) with b a = 2, each computed in O(2) time.

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• All cells f(a, b) with b - a = k, each computed in O(k) time.

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• All cells f(a, b) with b - a = n - 1, each computed in O(n - 1) time. There are $O(n^2)$ values to calculate. Total time complexity $= O(n^3)$.

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Problem 4 (Space Consumption)

In Lecture Notes 8, our algorithm for computing f(n, m) used O(nm) space. Next, we will reduce the space complexity to O(n + m).

Recall the dependency graph:



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We can calculate the values in the row-major order, i.e., row 0 to row 3 and left to right in each row. We used O(mn) space because we stored all the values. Observe, however, that only two rows need to be stored at any moment .



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Same idea for the column-major order.



So the space complexity is $O(\min\{m, n\})$, in addition to the O(n + m) space needed to store x and y.

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Think: Can this trick be used to reduce the space in Problem 2?



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