

Question 1.
Solution.

$$\begin{bmatrix} 1 & 4 & 1 & 1 & 1 \\ -1 & -3 & -2 & 1 & 1 \\ 2 & 0 & 6 & 1 & 1 \\ 0 & 2 & -1 & 2 & 1 \\ 0 & 2 & -1 & 2 & 1 \end{bmatrix} \quad (1)$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 & 2 \\ 0 & -8 & 4 & -1 & -1 \\ 0 & 2 & -1 & 2 & 1 \\ 0 & 2 & -1 & 2 & 1 \end{bmatrix} \quad \begin{array}{l} \text{Row2} + \text{Row1} \\ \text{Row3} - 2\text{Row1} \end{array} \quad (2)$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 & 2 \\ 0 & 0 & -4 & 15 & 15 \\ 0 & 0 & 1 & -2 & -3 \\ 0 & 0 & 1 & -2 & -3 \end{bmatrix} \quad \begin{array}{l} \text{Row3} + 8\text{Row2} \\ \text{Row4} - 2\text{Row2} \\ \text{Row5} - 2\text{Row2} \end{array} \quad (3)$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 & 2 \\ 0 & 0 & -4 & 15 & 15 \\ 0 & 0 & 0 & 7 & 3 \\ 0 & 0 & 0 & 7 & 3 \end{bmatrix} \quad \begin{array}{l} 4\text{Row4} + \text{Row3} \\ 4\text{Row5} + \text{Row3} \end{array} \quad (4)$$

$$\rightarrow \begin{bmatrix} 1 & 4 & 1 & 1 & 1 \\ 0 & 1 & -1 & 2 & 2 \\ 0 & 0 & -4 & 15 & 15 \\ 0 & 0 & 0 & 7 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{Row5} - \text{Row4} \quad (5)$$

Hence, the rank of the matrix is 4.

Question 2.

Solution.

(a) Augmented matrix

$$\begin{aligned} \begin{bmatrix} 2 & 4 & -2 & 0 \\ 3 & 5 & 0 & 1 \end{bmatrix} &\Rightarrow \begin{bmatrix} 6 & 12 & -6 & 0 \\ 6 & 10 & 0 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 6 & 12 & -6 & 0 \\ 0 & -2 & 6 & 2 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 2 & -1 & 0 \\ 0 & 1 & -3 & -1 \end{bmatrix} \\ &\Rightarrow \begin{bmatrix} 1 & 0 & 5 & 2 \\ 0 & 1 & -3 & -1 \end{bmatrix} \end{aligned}$$

This indicates equations:

$$\begin{aligned} x_1 + 5x_3 &= 2 \\ x_2 - 3x_3 &= -1 \end{aligned}$$

Hence all the solutions $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ constitute the set:

$$\left\{ \begin{bmatrix} 2 - 5t \\ -1 + 3t \\ t \end{bmatrix} \mid t \in \mathbb{R} \right\}$$

(b) Augmented matrix

$$\begin{bmatrix} 1 & 1 & 1 & 6 \\ 2 & 1 & 4 & 9 \\ 3 & -1 & a & b \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & -1 & 2 & -3 \\ 0 & -4 & a-3 & b-18 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & -1 & 2 & -3 \\ 0 & 0 & a-11 & b-6 \end{bmatrix}$$

Hence, for the system to have a unique solution, it must hold that $a \neq 11$ (the value of b can be anything).

(c) For the system to have no solutions, it must hold that $a = 11$ and $b \neq 6$.

Question 3.

Solution.

(a) It is easy to show that $\det(\mathbf{A}) = \det(\mathbf{B}) = 36$. Therefore, $\det(\mathbf{A}^{-1}\mathbf{B}^T) = \frac{1}{\det(\mathbf{A})} \cdot \det(\mathbf{B}) = 1$.

(b)

$$x_1 = \frac{\begin{vmatrix} 9 & -1 & 0 \\ 5 & 1 & 1 \\ 8 & 1 & -1 \end{vmatrix}}{\begin{vmatrix} 1 & -1 & 0 \\ -1 & 1 & 1 \\ 0 & 1 & -1 \end{vmatrix}} = \frac{-31}{-1} = 31$$

$$x_2 = \frac{\begin{vmatrix} 1 & 9 & 0 \\ -1 & 5 & 1 \\ 0 & 8 & -1 \end{vmatrix}}{\begin{vmatrix} 1 & -1 & 0 \\ -1 & 1 & 1 \\ 0 & 1 & -1 \end{vmatrix}} = \frac{-22}{-1} = 22$$

$$x_3 = \frac{\begin{vmatrix} 1 & -1 & 9 \\ -1 & 1 & 5 \\ 0 & 1 & 8 \end{vmatrix}}{\begin{vmatrix} 1 & -1 & 0 \\ -1 & 1 & 1 \\ 0 & 1 & -1 \end{vmatrix}} = \frac{-14}{-1} = 14$$

Question 4.

Solution.

1. Compute A^{-1} : The augmented matrix is expressed as

$$\begin{aligned} & \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 & 0 & 0 & 1 & 0 \\ 1 & 3 & 3 & 1 & 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{row2}' = \text{row2} - \text{row1}; \\ \rightarrow & \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & -1 & 1 & 0 & 0 \\ 1 & 2 & 1 & 0 & 0 & 0 & 1 & 0 \\ 1 & 3 & 3 & 1 & 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{row3}' = \text{row3} - \text{row1}; \text{row3}' = \text{row3} - 2\text{row2} \\ \rightarrow & \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & -2 & 1 & 0 \\ 1 & 3 & 3 & 1 & 0 & 0 & 0 & 1 \end{bmatrix} \quad \text{row4}' = \text{row4} - \text{row1} - 3\text{row2} - 3\text{row3} \\ \rightarrow & \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 3 & -3 & 1 \end{bmatrix} \\ \Rightarrow & A^{-1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ -1 & 3 & -3 & 1 \end{bmatrix} \end{aligned}$$

2. Compute $(\frac{1}{2}A)^{-1}$:

$$\left(\frac{1}{2}A\right)^{-1} = 2A^{-1} = \begin{bmatrix} 2 & 0 & 0 & 0 \\ -2 & 2 & 0 & 0 \\ 2 & -4 & 2 & 0 \\ -2 & 6 & -6 & 2 \end{bmatrix}.$$

Question 5.

Solution. Consider the characteristic equation of \mathbf{A} :

$$\begin{aligned} |\mathbf{A} - \lambda \mathbf{I}| &= 0 \\ \begin{vmatrix} a - \lambda & b \\ c & d - \lambda \end{vmatrix} &= 0 \\ (a - \lambda)(d - \lambda) - bc &= 0 \\ \lambda^2 - (a + d)\lambda + ad - bc &= 0. \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= \frac{(a + d) + \sqrt{\Delta}}{2} \\ \lambda_2 &= \frac{(a + d) - \sqrt{\Delta}}{2} \end{aligned}$$

where $\Delta = (a + d)^2 - 4(ad - bc)$. It thus follows that $\lambda_1 + \lambda_2 = a + d$.

Question 6.

Solution. It is clear that \mathbf{A} has eigenvalues $\lambda_1 = 1$ and $\lambda_2 = 0$. We aim to find three eigenvectors that are linearly independent.

Towards this purpose, let us first obtain the eigenspace of λ_1 , i.e., the set of $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ satisfying

$$\begin{bmatrix} 0 & 0 & -1 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0.$$

This set can be represented as

$$\left\{ \begin{bmatrix} t \\ 0 \\ 0 \end{bmatrix} \mid t \in \mathbb{R} \right\}$$

Pick an arbitrary non-zero vector from the set, e.g., $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

Next, let us obtain the eigenspace of λ_2 , i.e., the set of $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ satisfying

$$\begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0.$$

This set can be represented as

$$\left\{ \begin{bmatrix} v \\ u \\ v \end{bmatrix} \mid u, v \in \mathbb{R} \right\}$$

Pick two non-zero vectors that are linearly independent, e.g., $\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ and $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.

With the above, we can decide \mathbf{P} and \mathbf{B} as:

$$\mathbf{P} = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
$$\mathbf{B} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Question 7.

Solution.

(a) Since \mathbf{A} is skew-symmetric, we have

$$\begin{aligned}a &= d = 0 \\c &= -b\end{aligned}$$

Since \mathbf{A} is orthogonal, we have

$$\mathbf{A}^T = \mathbf{A}^{-1}$$

Consider

$$\begin{aligned}\mathbf{I} &= \mathbf{A}\mathbf{A}^{-1} = \mathbf{A}\mathbf{A}^T \Rightarrow \\ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} &= \begin{bmatrix} 0 & b \\ -b & 0 \end{bmatrix} \begin{bmatrix} 0 & -b \\ b & 0 \end{bmatrix} = \begin{bmatrix} b^2 & 0 \\ 0 & b^2 \end{bmatrix} \Rightarrow \\ b &= \pm 1\end{aligned}$$

Therefore,

$$\mathbf{A} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}, \quad \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

(b) If \mathbf{B} is skew-symmetric, then

$$e = 0$$

This implies

$$\det(\mathbf{B}) = 0$$

which means that \mathbf{B}^{-1} does not exist. Therefore, \mathbf{B} is not orthogonal.