

# CMSC 5743



## Efficient Computing of Deep Neural Networks

### Implementation 06: TVM

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These slides contain/adapt materials developed by

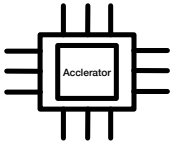
Chen, Tianqi, et al. "TVM: An automated end-to-end optimizing compiler for deep learning." 13th USENIX Symposium on Operating Systems Design and Implementation (OSDI 18). 2018.



# Beginning of Story

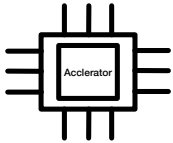


# Beginning of Story



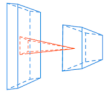


# Beginning of Story





# Beginning of Story



02 p(cat)  
015 p(dog)



```
// Pseudo-code for convolution program for the VIA accelerator
// Virtual Thread 0
0x00: LOAD(PARAM[ 0-71]) // LDMT00
0x01: LOAD(ACTIV[ 0-24]) // LDMT00
0x02: LOAD(LDBUF[ 0-31]) // LDMT00
0x03: PUSH(LD->EX) // EXMT00
0x04: POP(LD->EX) // EXMT00
0x05: EXE (ACTIV[ 0-24],PARAM[ 0-71],LDBUF[ 0-31],STBUF[ 0-7]) // EXGT00
0x06: PUSH(EX->LD) // EXMT00
0x07: PUSH(EX->ST) // EXMT00
0x08: POP (EX->ST) // STMT00
0x09: STOR(STBUF[ 0-7]) // STMT00
0x0A: PUSH(ST->EX) // STMT00
// Virtual Thread 1
0x0B: LOAD(ACTIV[25-50]) // LDMT01
0x0C: LOAD(LDBUF[32-63]) // LDMT01
0x0D: PUSH(LD->EX) // LDMT01
0x0E: POP (LD->EX) // EXMT01
0x0F: EXE (ACTIV[25-50],PARAM[ 0-71],LDBUF[32-63],STBUF[32-39]) // EXGT01
0x10: PUSH(EX->LD) // EXMT01
0x11: PUSH(EX->ST) // EXMT01
0x12: POP (EX->ST) // STMT01
0x13: STOR(STBUF[32-39]) // STMT01
0x14: PUSH(ST->EX) // STMT01
// Virtual Thread 2
0x15: POP (EX->LD) // LDMT02
0x16: LOAD(PARAM[ 0-71]) // LDMT02
0x17: LOAD(ACTIV[ 0-24]) // LDMT02
0x18: LOAD(LDBUF[ 0-31]) // LDMT02
0x19: PUSH(LD->EX) // LDMT02
0x1A: POP (LD->EX) // EXMT02
0x1B: POP (ST->EX) // EXMT02
0x1C: EXE (ACTIV[ 0-24],PARAM[ 0-71],LDBUF[ 0-31],STBUF[ 0-7]) // EXGT02
0x1D: PUSH(EX->ST) // EXMT02
0x1E: POP (EX->ST) // STMT02
0x1F: STOR(STBUF[ 0-7]) // STMT02
// Virtual Thread 3
0x20: POP (EX->LD) // LDMT03
0x21: LOAD(ACTIV[25-50]) // LDMT03
0x22: LOAD(LDBUF[32-63]) // LDMT03
0x23: PUSH(LD->EX) // LDMT03
0x24: POP (LD->EX) // EXMT03
0x25: POP (ST->EX) // EXMT03
0x26: EXE (ACTIV[25-50],PARAM[ 0-71],LDBUF[32-63],STBUF[32-39]) // EXGT03
0x27: PUSH(EX->ST) // EXMT03
0x28: POP (EX->ST) // STMT03
0x29: STOR(STBUF[32-39]) // STMT03
```

(a) Blocked convolution program with multiple thread contexts

```
// Convolution access pattern dictated by micro-coded program.
// Each register index is derived as a 2-D affine function.
// e.g.  $idx_{xy} = a_x y + b_x + c_x r$ , where  $c_x$  is specified by
// micro op B fields.
for y in [B.1]
  for x in [B.2]
     $rf[idx_{xy}] += GEV(act[idx_{xy}], par[idx_{xy}])$ 
     $rf[idx_{xy}] += GEV(act[idx_{xy}+1], par[idx_{xy}+1])$ 
  -
   $rf[idx_{xy}] += GEV(act[idx_{xy}], par[idx_{xy}])$ 
```

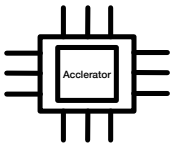


(b) Convolution micro-coded program

```
// Max-pool, batch normalization and activation function
// Access pattern dictated by micro-coded program.
// Each register index is derived as a 2D affine function.
// e.g.  $idx_{xy} = a_{xy} y + b_{xy} + c_{xy} r$ , where  $c_{xy}$  is specified by
// micro op B fields.
for x in [B.1]
  for y in [B.2]
    // max pooling
     $rf[idx_{xy}] = \text{MAX}(rf[idx_{xy}], rf[idx_{xy}+1])$ 
     $rf[idx_{xy}] = \text{MAX}(rf[idx_{xy}], rf[idx_{xy}+2])$ 
    // batch norm
     $rf[idx_{xy}] = \text{MUL}(rf[idx_{xy}], rf[idx_{xy}+3])$ 
     $rf[idx_{xy}+3] = \text{ADD}(rf[idx_{xy}+3], rf[idx_{xy}+4])$ 
     $rf[idx_{xy}+3] = \text{MUL}(rf[idx_{xy}+3], rf[idx_{xy}+5])$ 
     $rf[idx_{xy}+3] = \text{ADD}(rf[idx_{xy}+3], rf[idx_{xy}+6])$ 
  -
  // activation
   $rf[idx_{xy}+7] = \text{RELU}(rf[idx_{xy}+7], rf[idx_{xy}+8])$ 
   $rf[idx_{xy}+7] = \text{RELU}(rf[idx_{xy}+7], rf[idx_{xy}+9])$ 
```



(c) Max pool, batch norm and activation micro-coded program





# Goal: Deploy Deep Learning Everywhere

Frameworks





# Goal: Deploy Deep Learning Everywhere



Explosion of models and frameworks





# Goal: Deploy Deep Learning Everywhere



Explosion of models and frameworks

Explosion of hardware backends



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Explosion of models and frameworks

Explosion of hardware backends





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Explosion of models and frameworks

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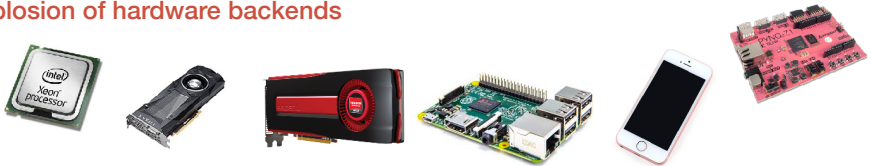


# Goal: Deploy Deep Learning Everywhere



Explosion of models and frameworks

Explosion of hardware backends



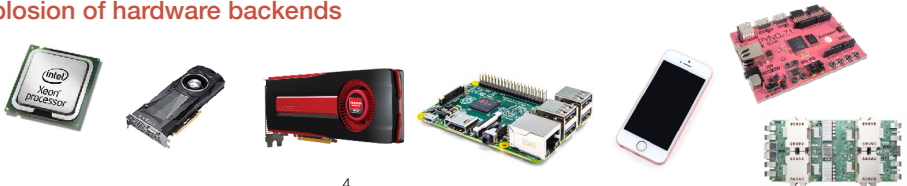


# Goal: Deploy Deep Learning Everywhere



Explosion of models and frameworks

Explosion of hardware backends





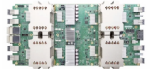
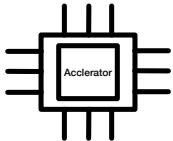


# Goal: Deploy Deep Learning Everywhere



Explosion of models and frameworks

Explosion of hardware backends





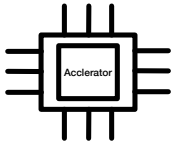
# Goal: Deploy Deep Learning Everywhere



Explosion of models and frameworks

Huge gap between model/frameworks and hardware backends

Explosion of hardware backends





# Existing Approach

Frameworks



Hardware

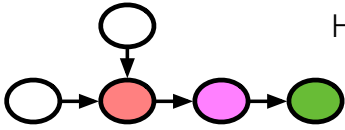


NVIDIA





# Existing Approach

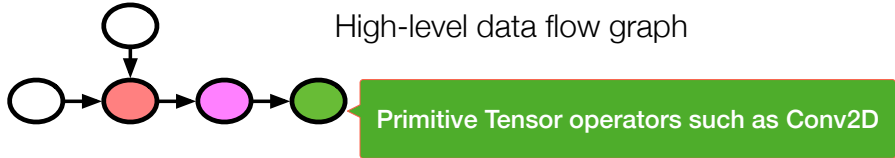


High-level data flow graph





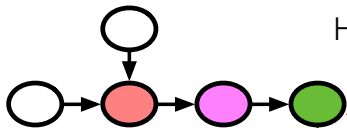
# Existing Approach





# Existing Approach

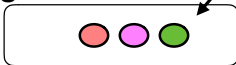
Frameworks



High-level data flow graph

Primitive Tensor operators such as Conv2D

eg. cuDNN



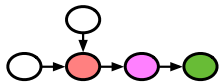
Offload to heavily optimized  
DNN operator library

Hardware



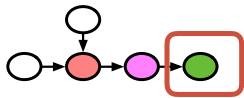


# Existing Approach: Engineer Optimized Tensor Operators





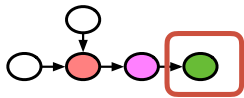
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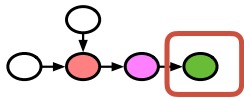


## Matmul: Operator Specification

```
C = tvn.compute((m, n),  
    lambda y, x: tvn.sum(A[k, y] * B[k, x], axis=k))
```



# Existing Approach: Engineer Optimized Tensor Operators



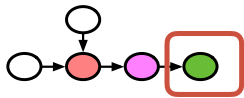
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# Existing Approach: Engineer Optimized Tensor Operators



## Matmul: Operator Specification

```
C = tvm.compute((m, n),  
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```

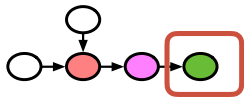


## Vanilla Code

```
for y in range(1024):  
    for x in range(1024):  
        C[y][x] = 0  
        for k in range(1024):  
            C[y][x] += A[k][y] * B[k][x]
```



# Existing Approach: Engineer Optimized Tensor Operators



## Matmul: Operator Specification

```
C = tvm.compute((m, n),  
                lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

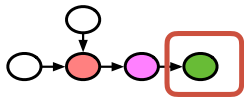


## Loop Tiling for Locality

```
for yo in range(128):  
    for xo in range(128):  
        C[yo*8:yo*8+8][xo*8:xo*8+8] = 0  
        for ko in range(128):  
            for yi in range(8):  
                for xi in range(8):  
                    for ki in range(8):  
                        C[yo*8+yi][xo*8+xi] +=  
                            A[ko*8+ki][yo*8+yi] * B[ko*8+ki][xo*8+xi]
```



# Existing Approach: Engineer Optimized Tensor Operators



## Matmul: Operator Specification

```
C = tvn.compute((m, n),  
    lambda y, x: tvn.sum(A[k, y] * B[k, x], axis=k))
```



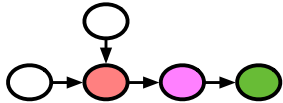
## Map to Accelerators

```
inp_buffer AL[8][8], BL[8][8]  
acc_buffer CL[8][8]  
for yo in range(128):  
    for xo in range(128):  
        vdl.a.fill_zero(CL)  
        for ko in range(128):  
            vdl.a.dma_copy2d(AL, A[ko*8:ko*8+8][yo*8:yo*8+8])  
            vdl.a.dma_copy2d(BL, B[ko*8:ko*8+8][xo*8:xo*8+8])  
            vdl.a.fused_gemm8x8_add(CL, AL, BL)  
            vdl.a.dma_copy2d(C[yo*8:yo*8+8,xo*8:xo*8+8], CL)
```

## Human exploration of optimized code



# Limitations of Existing Approach

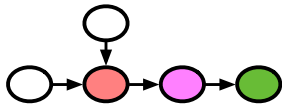


cuDNN





# Limitations of Existing Approach

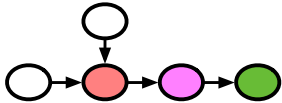


cuDNN

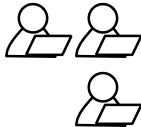




# Limitations of Existing Approach



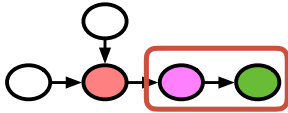
cuDNN



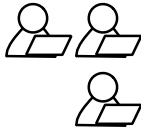




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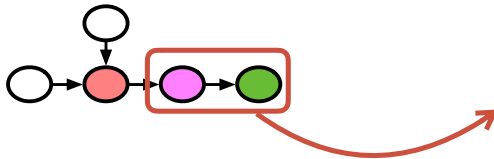


cuDNN

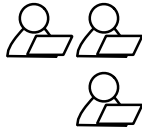




# Limitations of Existing Approach

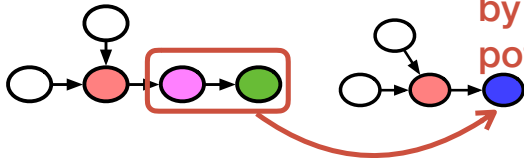


cuDNN





# Limitations of Existing Approach



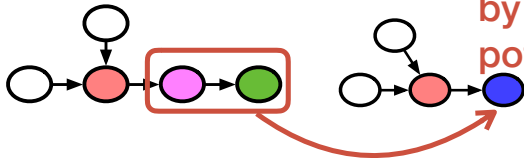
New operator introduced  
by operator fusion optimization  
potentially benefit: 1.5x speedup

cuDNN



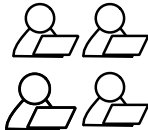


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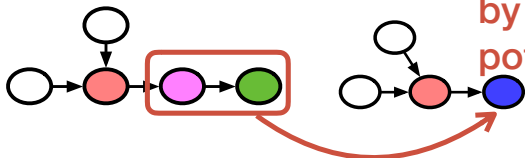
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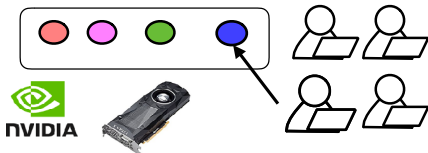


# Limitations of Existing Approach



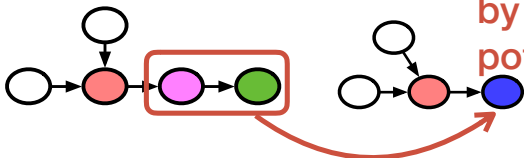
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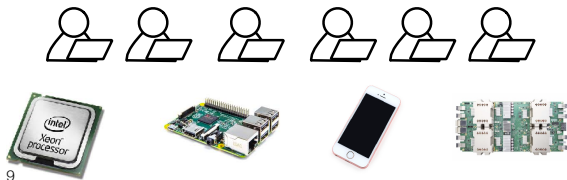
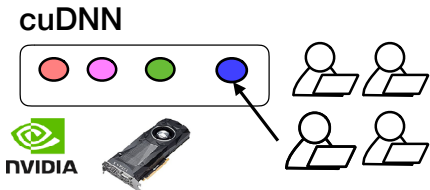


# Limitations of Existing Approach



New operator introduced  
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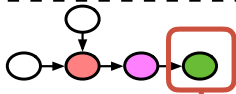
Engineering intensive



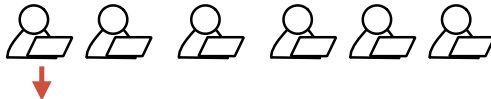


# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations



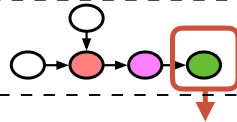
Hardware





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware

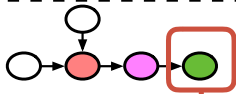






# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

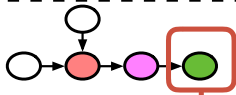
Hardware





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

Machine Learning based Program Optimizer

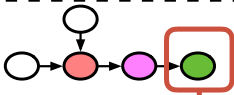
Hardware





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

Machine Learning based Program Optimizer

directly generate optimized program  
for new operator workloads and hardware

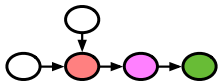
Hardware





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

Machine Learning based Program Optimizer

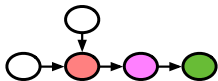
Hardware





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

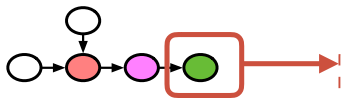
Machine Learning based Program Optimizer

Hardware





# Hardware-aware Search Space



## Tensor Expression Language (Specification)

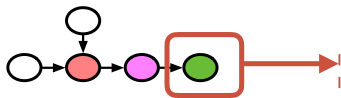
```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Hardware





# Hardware-aware Search Space



## Tensor Expression Language (Specification)

```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Define search space of hardware aware mappings from expression to hardware program

Based on Halide's compute/schedule separation

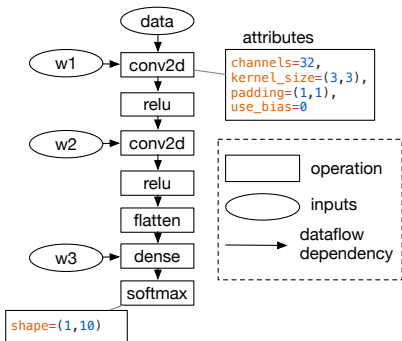
Hardware



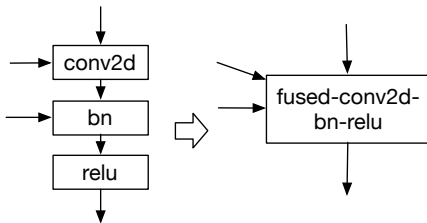


# Computational Graph as IR

Represent High level  
Deep Learning Computations



Effective Equivalent Transformations  
to Optimize the Graph



Approach taken by: TensorFlow XLA, Intel NGraph, Nvidia TensorRT





# The Remaining Gap

Frameworks



CNTK

Computational Graph Optimization

need to build and optimize operators for each hardware,  
variant of layout, precision, threading pattern ...

Hardware





# Tensor Level Optimizations

Frameworks



CNTK

Computational Graph Optimization

Tensor Expression Language

```
C = t.compute((m, n),  
             lambda i, j: t.sum(A[i, k] * B[j, k], axis=k))
```

Hardware





# Tensor Index Expression

Compute  $C = \text{dot}(A, B.T)$

```
import tvn
```

```
m, n, h = tvn.var('m'), tvn.var('n'), tvn.var('h')
```

```
A = tvn.placeholder((m, h), name='A')
```

```
B = tvn.placeholder((n, h), name='B')
```

Inputs

```
k = tvn.reduce_axis((0, h), name='k')
```

```
C = tvn.compute((m, n), lambda i, j: tvn.sum(A[i, k] * B[j, k], axis=k))
```

Shape of C

Computation Rule



# Tensor Expressions are Expressive

## Affine Transformation

```
out = tvm.compute((n, m), lambda i, j: tvm.sum(data[i, k] * w[j, k], k))
out = tvm.compute((n, m), lambda i, j: out[i, j] + bias[i])
```

## Convolution

```
out = tvm.compute((c, h, w),
    lambda i, x, y: tvm.sum(data[kc,x+kx,y+ky] * w[i,kx,ky], [kx,ky,kc]))
```

## ReLU

```
out = tvm.compute(shape, lambda *i: tvm.max(0, out(*i)))
```



# Emerging Tools Using Tensor Expression Language

Halide: Image processing language

Loopy: python based kernel generator

TACO: sparse tensor code generator

Tensor Comprehension



# Schedule: Tensor Expression to Code

Tensor Expression Language

```
C = t.compute((m, n),  
             lambda i, j: t.sum(A[i, k] * B[j, k], axis=k))
```

Key Idea:  
Separation of Compute  
and Schedule  
**introduced by Halide**

Schedule Optimizations

Hardware





# Example Schedule Transformation

```
C = tvm.compute((n,), lambda i: A[i] + B[i])  
s = tvm.create_schedule(C.op)
```

---

```
for (int i = 0; i < n; ++i) {  
    C[i] = A[i] + B[i];  
}
```



# Example Schedule Transformation

```
C = tvm.compute((n,), lambda i: A[i] + B[i])  
s = tvm.create_schedule(C.op)  
xo, xi = s[C].split(s[C].axis[0], factor=32)
```

---

```
for (int xo = 0; xo < ceil(n / 32); ++xo) {  
  for (int xi = 0; xi < 32; ++xi) {  
    int i = xo * 32 + xi;  
    if (i < n) {  
      C[i] = A[i] + B[i];  
    }  
  }  
}
```





# Example Schedule Transformation

```
C = tvm.compute((n,), lambda i: A[i] + B[i])
s = tvm.create_schedule(C.op)
xo, xi = s[C].split(s[C].axis[0], factor=32)
s[C].recorder(xi, xo)
```

---

```
for (int xi = 0; xi < 32; ++xi) {
  for (int xo = 0; xo < ceil(n / 32); ++xo) {
    int i = xo * 32 + xi;
    if (i < n) {
      C[i] = A[i] + B[i];
    }
  }
}
```



# Example Schedule Transformation

```
C = tvm.compute((n,), lambda i: A[i] + B[i])
s = tvm.create_schedule(C.op)
xo, xi = s[C].split(s[C].axis[0], factor=32)
s[C].recorder(xi, xo)
s[C].bind(xo, tvm.thread_axis("blockIdx.x"))
s[C].bind(xi, tvm.thread_axis("threadIdx.x"))
```

---

```
int i = threadIdx.x * 32 + blockIdx.x;
if (i < n) {
    C[i] = A[i] + B[i];
}
```



# Key Challenge: Good Space of Schedule

Should contain any knobs that produces a logically equivalent program that runs well on backend models

Must contain the common manual optimization patterns

Need to actively evolve to incorporate new techniques

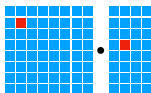


# Hardware-aware Search Space

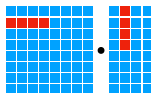
## CPU



### Compute Primitives



scalar



vector

### Memory Subsystem



implicitly managed

Loop Transformations

Cache Locality

Vectorization

Reuse primitives from prior work:  
Halide, Loopy



# Challenge to Support Diverse Hardware Backends

## CPU



## GPU



## TPU-like specialized Accelerators



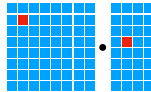


# Hardware-aware Search Space

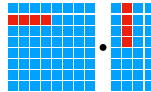
## GPUs



### Compute Primitives



*scalar*



*vector*

### Memory Subsystem



*mixed*

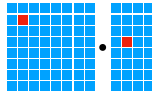


# Hardware-aware Search Space

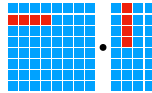
## GPUs



### Compute Primitives

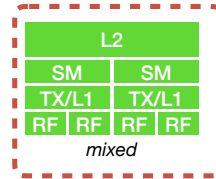


*scalar*



*vector*

### Memory Subsystem



Shared memory among  
compute cores

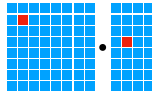


# Hardware-aware Search Space

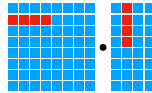
GPUs



Compute Primitives

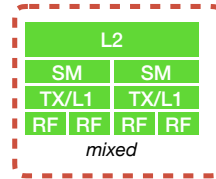


*scalar*



*vector*

Memory Subsystem



Shared memory among  
compute cores

Use of Shared  
Memory

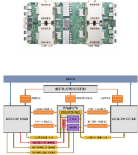
Thread  
Cooperation



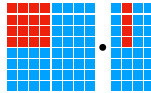


# Hardware-aware Search Space

## TPU-like Specialized Accelerators



## Compute Primitives



*tensor*

## Memory Subsystem

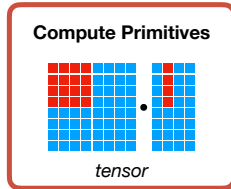
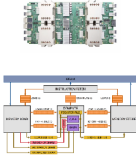


*explicitly managed*

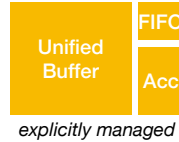


# Hardware-aware Search Space

## TPU-like Specialized Accelerators



## Memory Subsystem





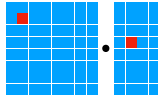
# Tensorization Challenge

**Compute  
primitives**



# Tensorization Challenge

Compute  
primitives

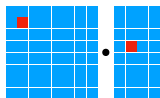


*scalar*

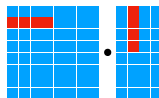


# Tensorization Challenge

Compute  
primitives



*scalar*

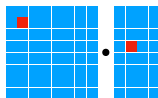


*vector*

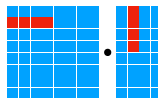


# Tensorization Challenge

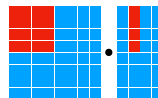
Compute  
primitives



*scalar*



*vector*

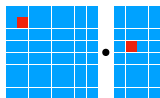


*tensor*

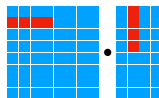


# Tensorization Challenge

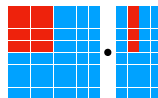
Compute primitives



scalar



vector



tensor

Hardware designer:  
declare tensor instruction interface  
with Tensor Expression

```
w, x = t.placeholder((8, 8)), t.placeholder((8, 8))
k = t.reduce_axis((0, 8))
y = t.compute((8, 8), lambda i, j:
    t.sum(w[i, k] * x[j, k], axis=k))
```

← declare behavior

```
def gemm_intrin_lower(inputs, outputs):
    ww_ptr = inputs[0].access_ptr("r")
    xx_ptr = inputs[1].access_ptr("r")
    zz_ptr = outputs[0].access_ptr("w")
    compute = t.hardware_intrin("gemm8x8", ww_ptr, xx_ptr, zz_ptr)
    reset = t.hardware_intrin("fill_zero", zz_ptr)
    update = t.hardware_intrin("fuse_gemm8x8_add", ww_ptr, xx_ptr, zz_ptr)
    return compute, reset, update
```

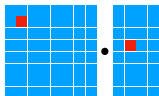
← lowering rule to generate hardware intrinsics to carry out the computation

```
gemm8x8 = t.decl_tensor_intrin(y.op, gemm_intrin_lower)
```

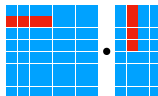


# Tensorization Challenge

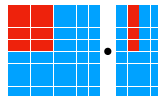
Compute primitives



scalar



vector



tensor

Hardware designer:  
declare tensor instruction interface  
with Tensor Expression

```
w, x = t.placeholder((8, 8)), t.placeholder((8, 8))
k = t.reduce_axis((0, 8))
y = t.compute((8, 8), lambda i, j:
    t.sum(w[i, k] * x[j, k], axis=k))
```

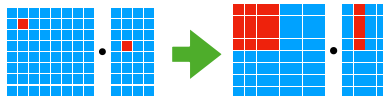
declare behavior

```
def gemm_intrin_lower(inputs, outputs):
    ww_ptr = inputs[0].access_ptr("r")
    xx_ptr = inputs[1].access_ptr("r")
    zz_ptr = outputs[0].access_ptr("w")
    compute = t.hardware_intrin("gemm8x8", ww_ptr, xx_ptr, zz_ptr)
    reset = t.hardware_intrin("fill_zero", zz_ptr)
    update = t.hardware_intrin("fuse_gemm8x8_add", ww_ptr, xx_ptr, zz_ptr)
    return compute, reset, update
```

lowering rule to generate  
hardware intrinsics to carry  
out the computation

```
gemm8x8 = t.decl_tensor_intrin(y.op, gemm_intrin_lower)
```

Tensorize:  
transform program  
to use tensor instructions



scalar

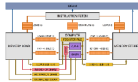
tensor



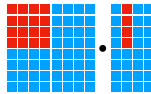


# Hardware-aware Search Space

## TPU-like Specialized Accelerators



## Compute Primitives



*tensor*

## Memory Subsystem

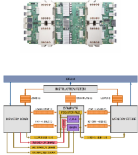


*explicitly managed*

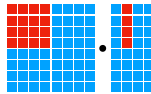


# Hardware-aware Search Space

## TPU-like Specialized Accelerators



## Compute Primitives



*tensor*

## Memory Subsystem

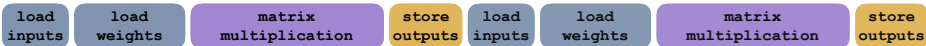


*explicitly managed*



# Software Support for Latency Hiding

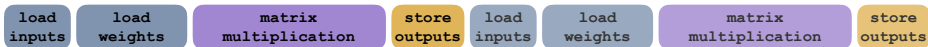
Single Module  
No Task-Pipelining



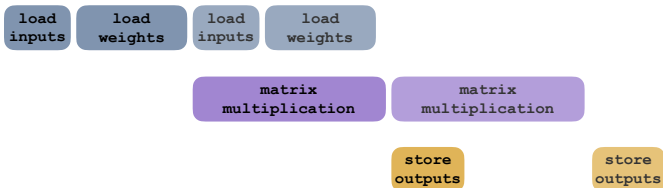


# Software Support for Latency Hiding

Single Module  
No Task-Pipelining



Multiple-Module  
Task-Level Pipelining



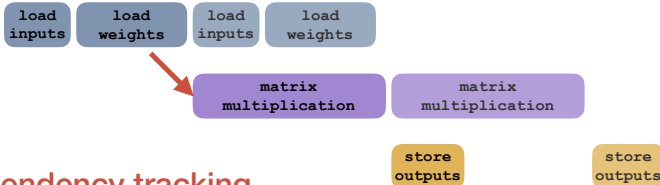


# Software Support for Latency Hiding

Single Module  
No Task-Pipelining



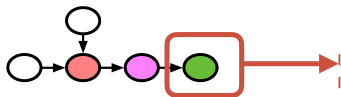
Multiple-Module  
Task-Level Pipelining



**Explicit dependency tracking  
managed by software to hide memory latency**



# Hardware-aware Search Space



## Tensor Expression Language

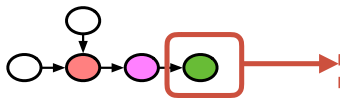
```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Hardware





# Hardware-aware Search Space



## Tensor Expression Language

```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Primitives in prior work:  
Halide, Loopy

Loop  
Transformations

Thread  
Bindings

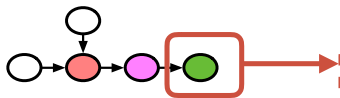
Cache  
Locality

Hardware





# Hardware-aware Search Space



## Tensor Expression Language

```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Primitives in prior work:  
Halide, Loopy

Loop Transformations

Thread Bindings

Cache Locality

New primitives for GPUs,  
and enable TPU-like  
Accelerators

Thread Cooperation

Tensorization

Latency Hiding

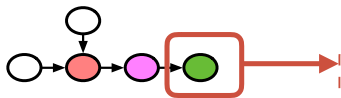
Hardware







# Hardware-aware Search Space



## Tensor Expression Language

```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Loop Transformations

Thread Bindings

Cache Locality

Thread Cooperation

Tensorization

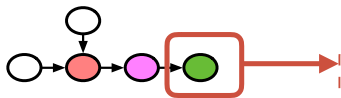
Latency Hiding

Hardware





# Hardware-aware Search Space



## Tensor Expression Language

```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Loop Transformations

Thread Bindings

Cache Locality

Thread Cooperation

Tensorization

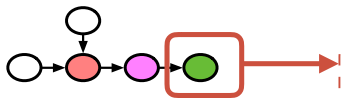
Latency Hiding

Hardware





# Hardware-aware Search Space



## Tensor Expression Language

```
C = tvm.compute((m, n),  
    lambda y, x: tvm.sum(A[k, y] * B[k, x], axis=k))
```

Billions  
of possible  
optimization  
choices

Loop  
Transformations

Thread  
Bindings

Cache  
Locality

Thread  
Cooperation

Tensorization

Latency  
Hiding

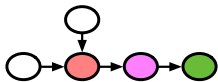
Hardware





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

Machine Learning based Program Optimizer

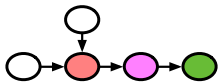
Hardware





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

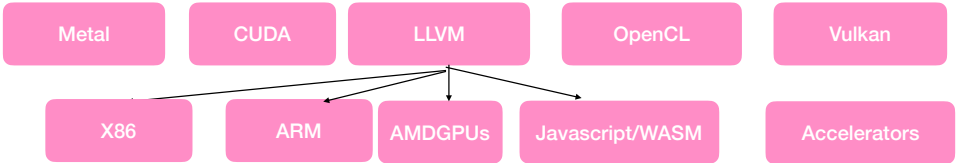
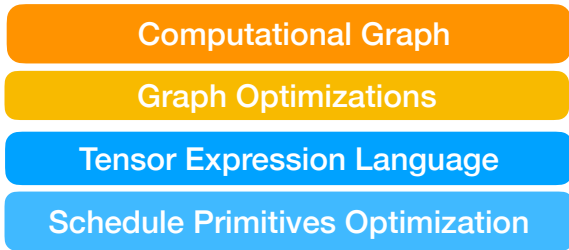
Machine Learning based Program Optimizer

Hardware





# Global View of TVM Stack



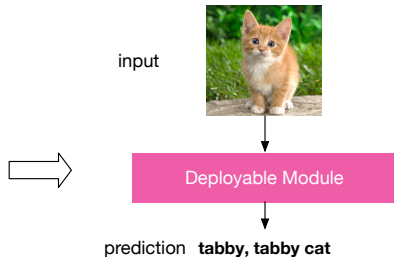


# High Level Compilation Frontend

```
import tvm
import nnvm.frontend
import nnvm.compiler
```

```
graph, params =
nnvm.frontend.from_keras(keras_resnet50)
graph, lib, params =
nnvm.compiler.build(graph, target)
```

```
module = runtime.create(graph, lib, tvm.gpu(0))
module.set_input(**params)
module.run(data=data_array)
output = tvm.nd.empty(out_shape, ctx=tvm.gpu(0))
module.get_output(0, output)
```



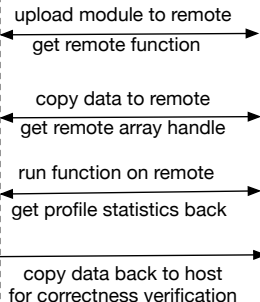
On languages and platforms you choose





# Program Your Phone with Python from Your Laptop

RPC Server on  
Embedded Device



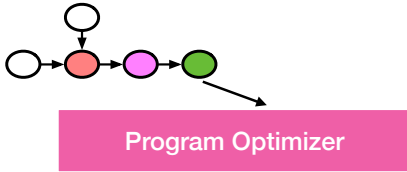
Compiler Stack

```
lib = t.build(s, [A, B],  
            'llvm -target=armv7l-none-linux-gnueabihf',  
            name='myfunc')  
remote = t.rpc.connect(host, port)  
lib.save('myfunc.o')  
remote.upload('myfunc.o')  
f = remote.load_module('myfunc.o')  
ctx = remote.cpu(0)  
a = t.nd.array(np.random.uniform(size=1024), ctx)  
b = t.nd.array(np.zeros(1024), ctx)  
remote_timer = f.time_evaluator('myfunc', ctx, number=10)  
time_cost = remote_timer(a, b)  
  
np.testing.assert_equal(b.asnumpy(), expected)
```



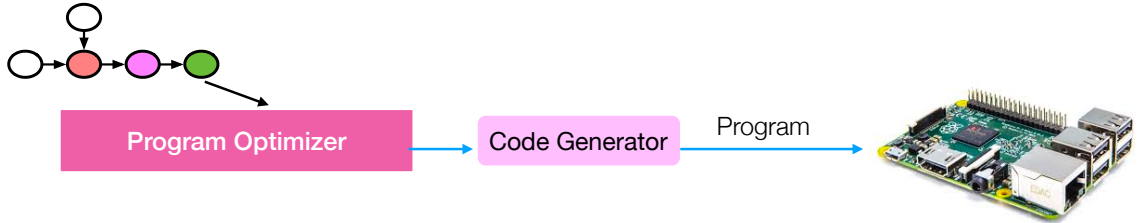


# Learning-based Program Optimizer



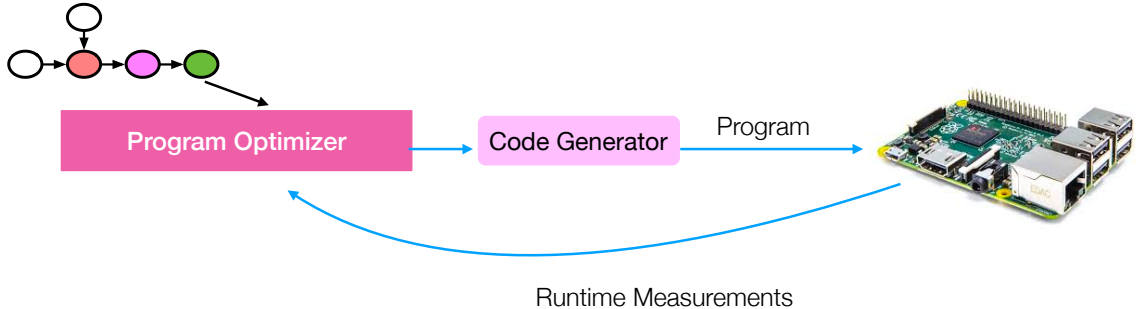


# Learning-based Program Optimizer



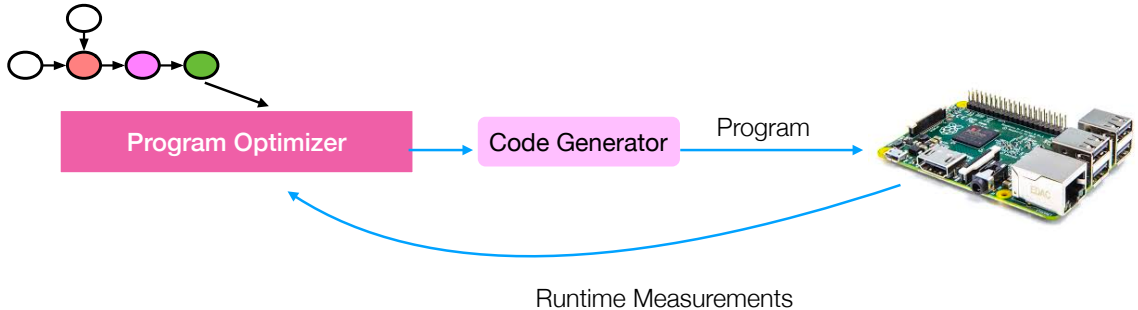


# Learning-based Program Optimizer





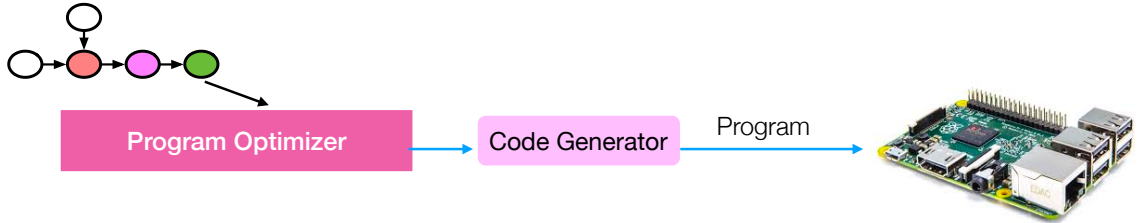
# Learning-based Program Optimizer



High experiment cost,  
each trial costs ~1second

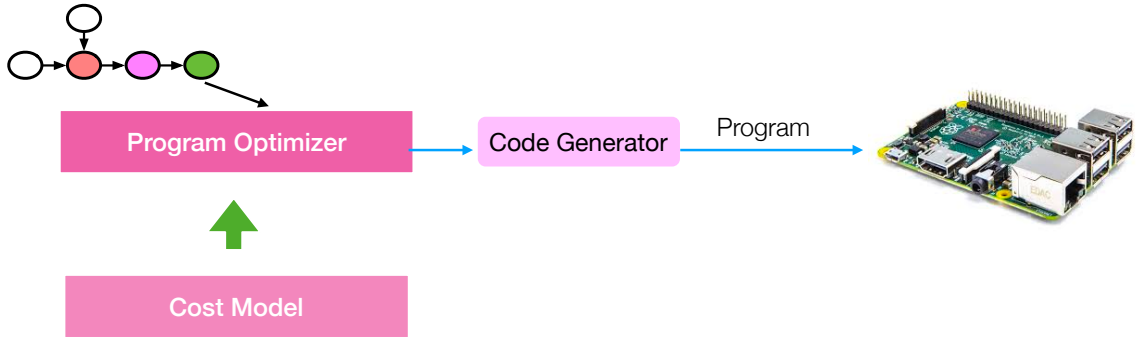


# Learning-based Program Optimizer



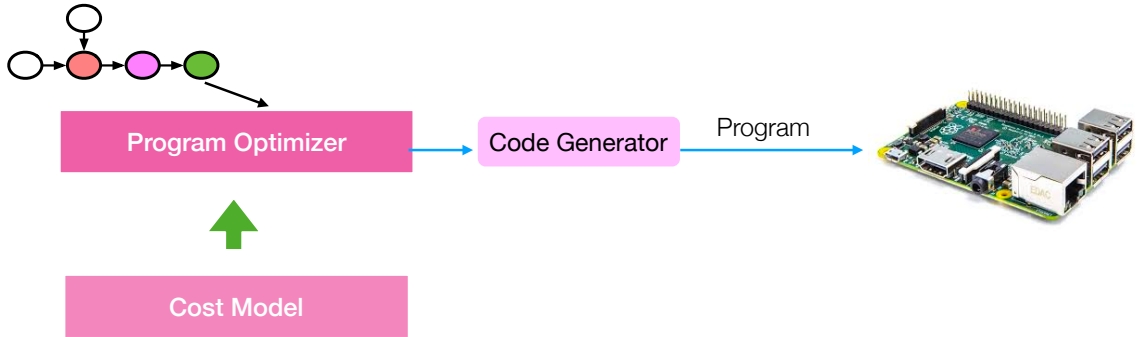


# Learning-based Program Optimizer





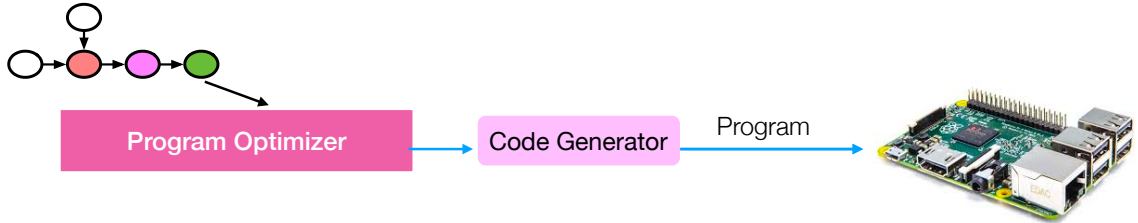
# Learning-based Program Optimizer



**Need reliable cost model per hardware**



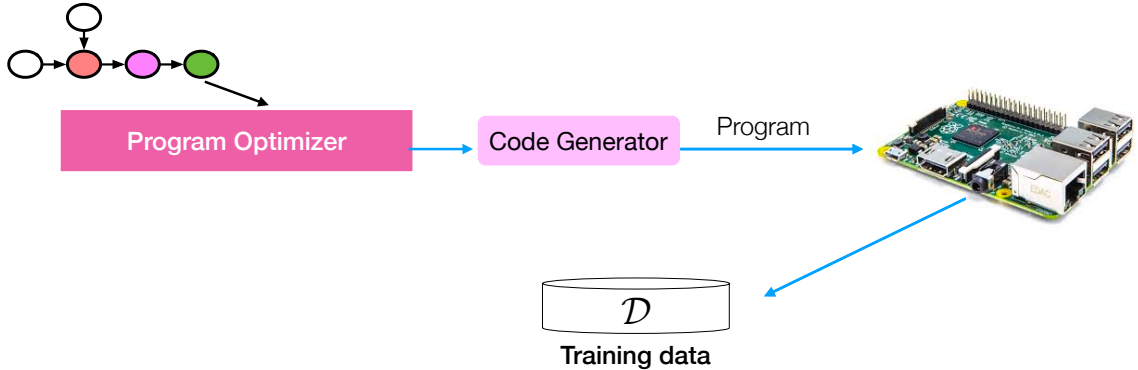
# Learning-based Program Optimizer





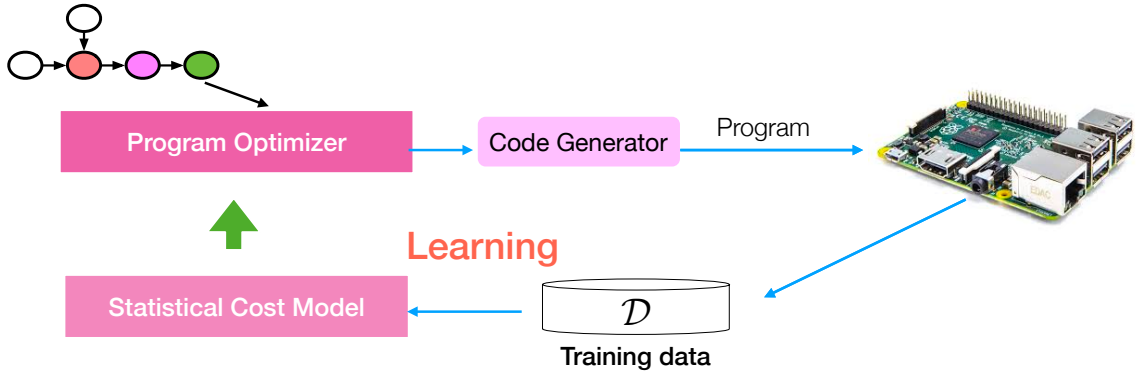


# Learning-based Program Optimizer



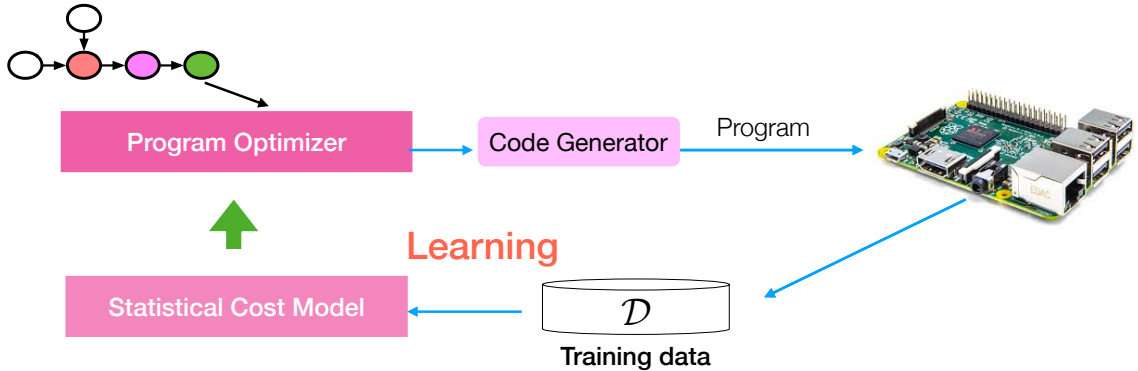


# Learning-based Program Optimizer





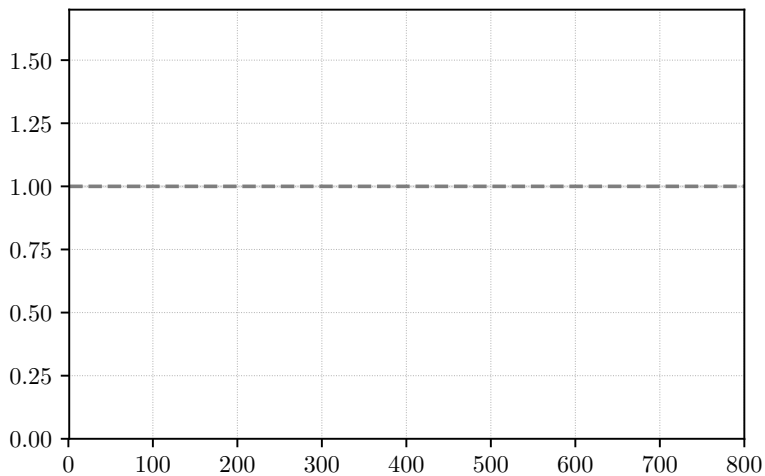
# Learning-based Program Optimizer



Adapt to hardware type by learning  
Make prediction in 1ms level

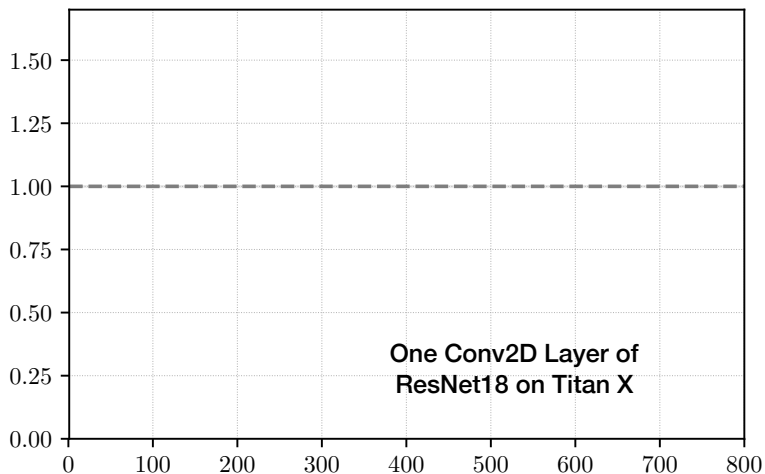


# Effectiveness of ML based Model



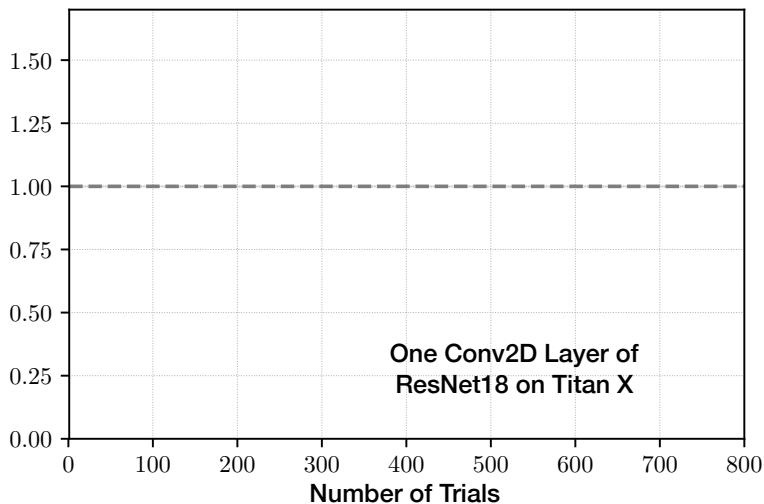


# Effectiveness of ML based Model



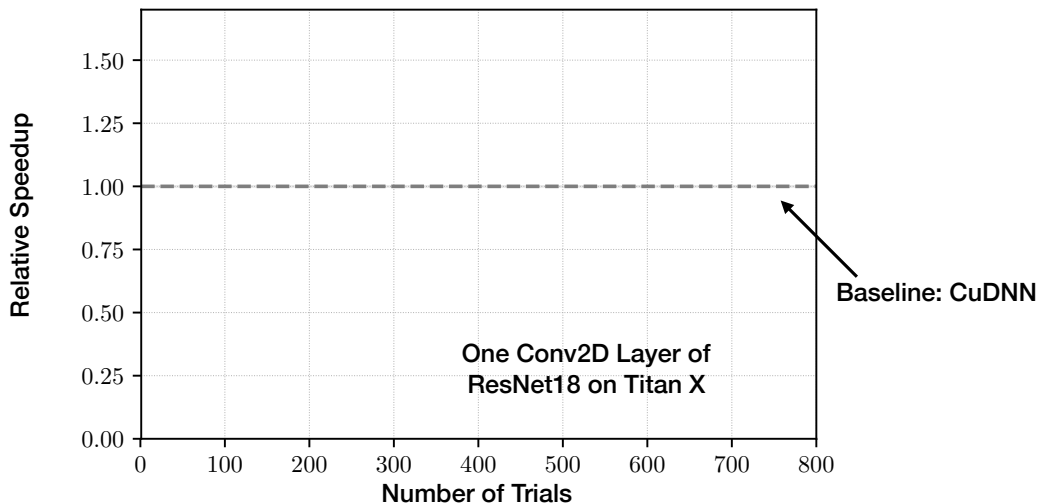


# Effectiveness of ML based Model



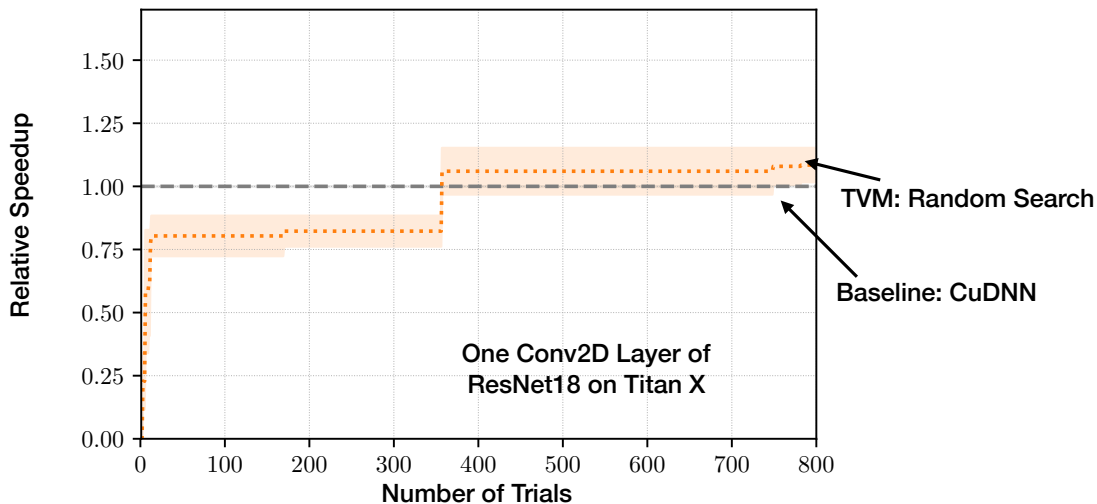


# Effectiveness of ML based Model





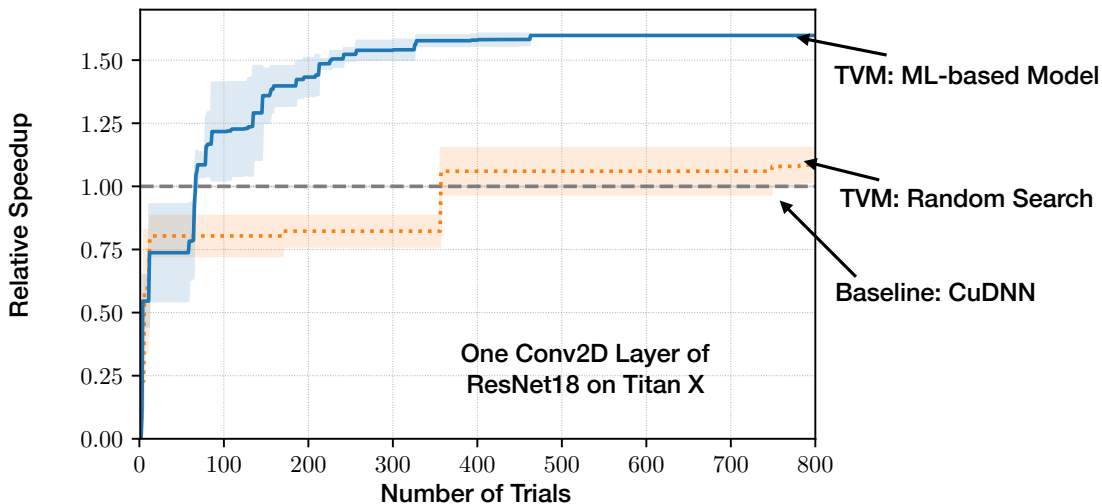
# Effectiveness of ML based Model







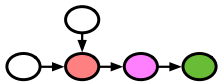
# Effectiveness of ML based Model





# Learning-based Learning System

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

Machine Learning based Program Optimizer

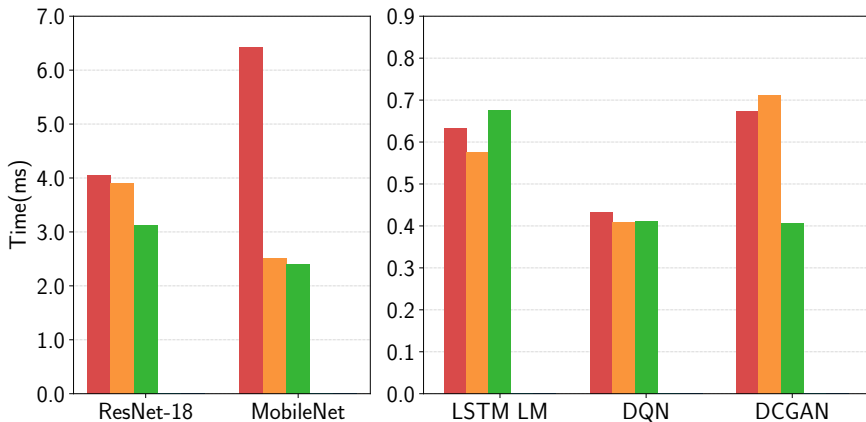
Hardware





# End to End Inference Performance (Nvidia Titan X)

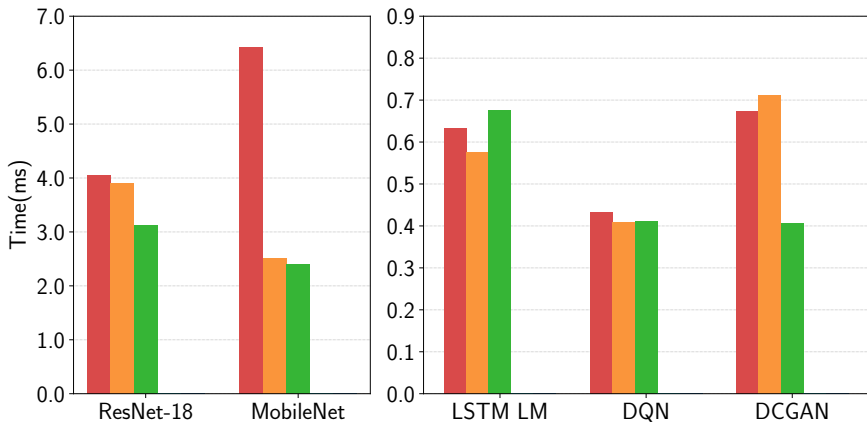
Tensorflow Apache MXNet  
Tensorflow-XLA





# End to End Inference Performance (Nvidia Titan X)

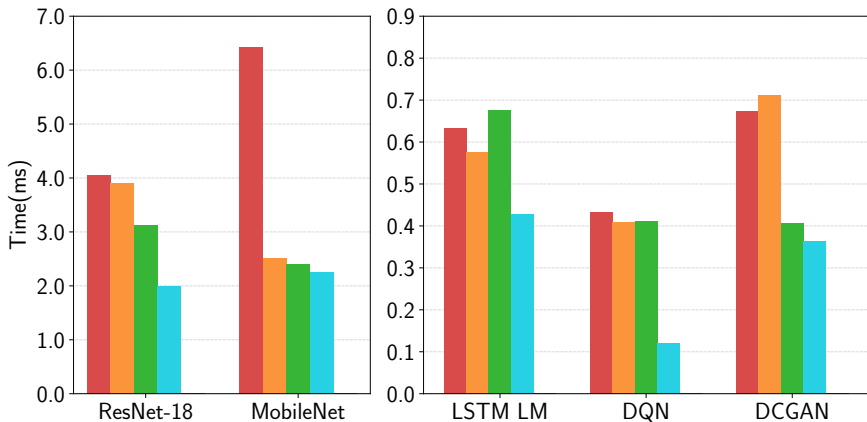
Backed by cuDNN





# End to End Inference Performance (Nvidia Titan X)

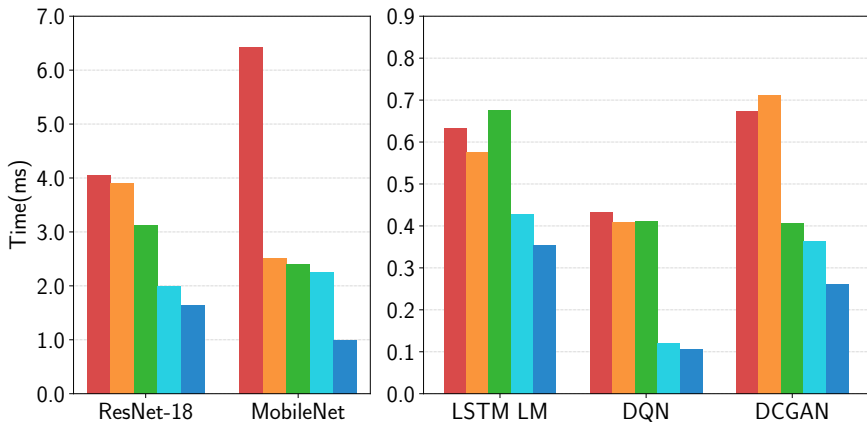
Tensorflow   Apache MXNet   TVM: without graph optimizations  
Tensorflow-XLA





# End to End Inference Performance (Nvidia Titan X)

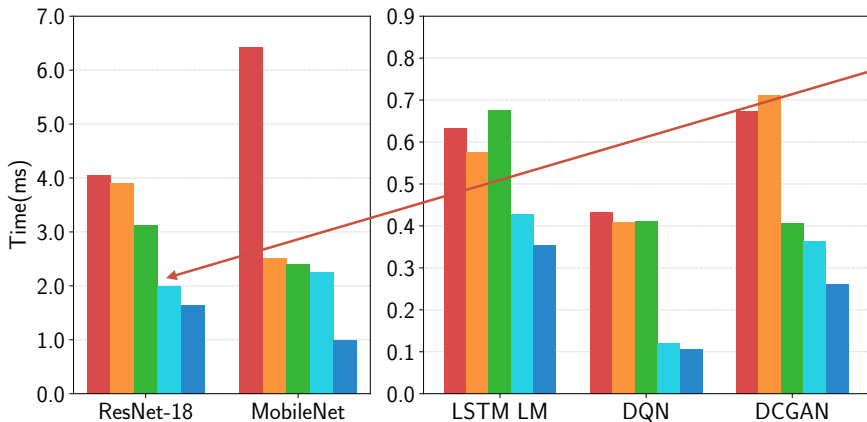
Tensorflow   Apache MXNet   TVM: without graph optimizations  
Tensorflow-XLA   TVM: all optimizations





# End to End Inference Performance (Nvidia Titan X)

Tensorflow   Apache MXNet   TVM: without graph optimizations  
Tensorflow-XLA   TVM: all optimizations

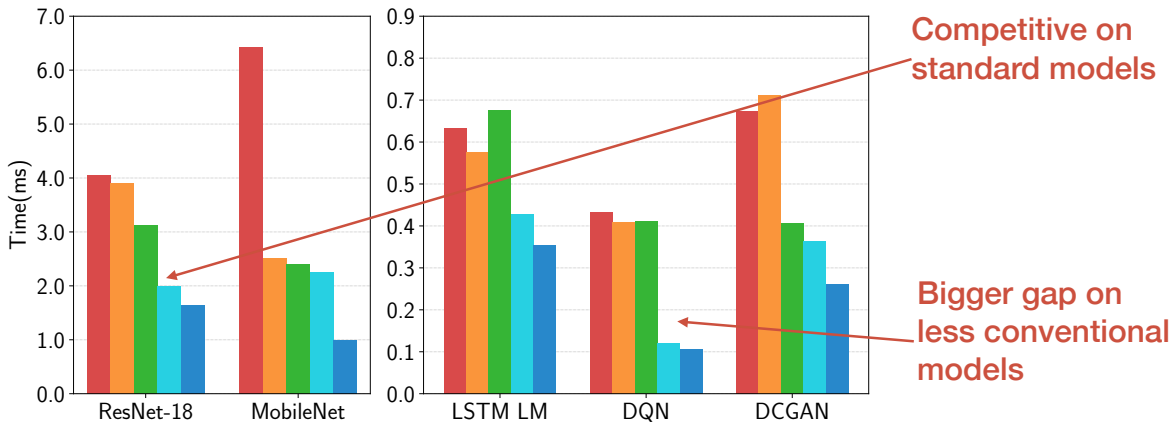


Competitive on standard models



# End to End Inference Performance (Nvidia Titan X)

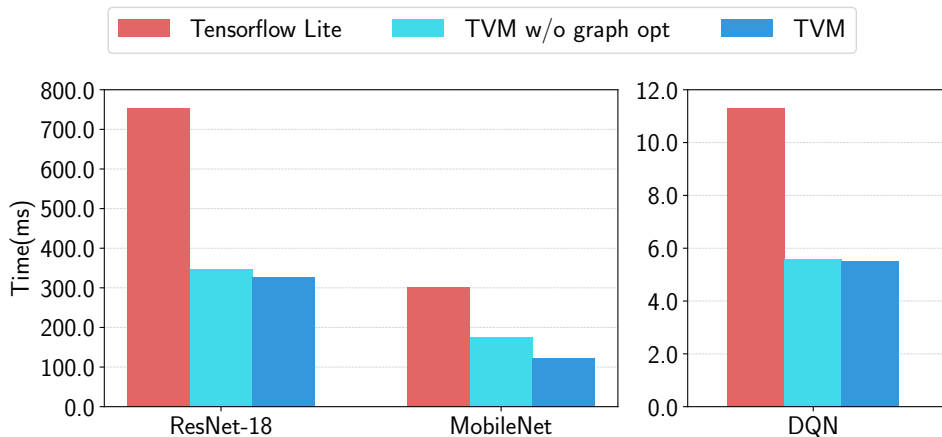
Tensorflow   Apache MXNet   TVM: without graph optimizations  
Tensorflow-XLA   TVM: all optimizations







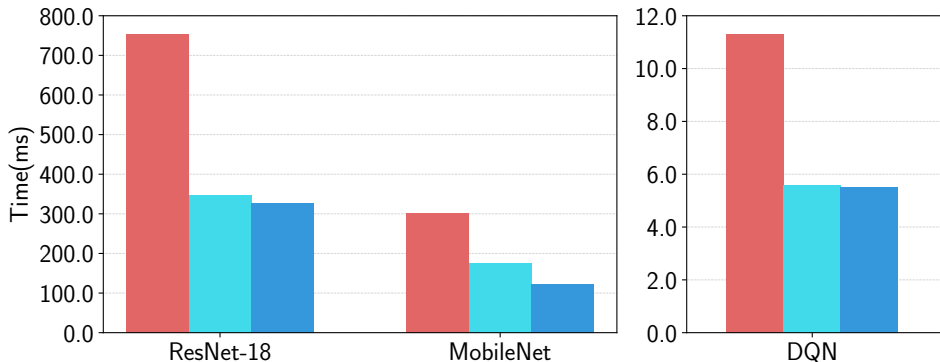
# End to End Performance(ARM Cortex-A53)





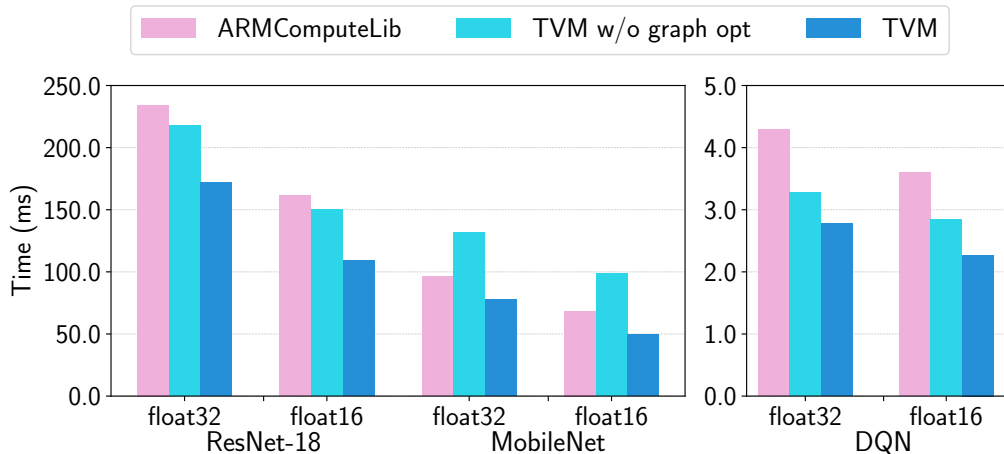
# End to End Performance(ARM Cortex-A53)

Specially optimized for  
Embedded system(ARM)





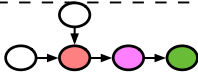
# End to End Performance(ARM GPU)





# Supporting New Specialized Accelerators

Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

Machine Learning based Program Optimizer

LLVM

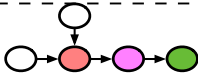
CUDA





# Supporting New Specialized Accelerators

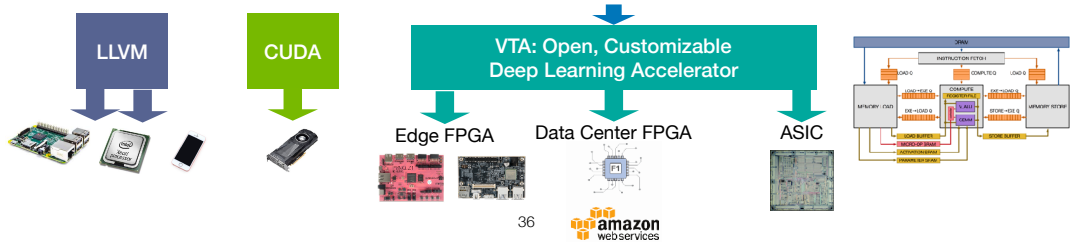
Frameworks



High-level data flow graph and optimizations

Hardware aware Search Space of Optimized Tensor Programs

Machine Learning based Program Optimizer





# TVM/MTA: Full Stack Open Source System



High-level Optimizations

Tensor Program Search Space

ML-based Optimizer





# TVM/VTA: Full Stack Open Source System



High-level Optimizations

Tensor Program Search Space

ML-based Optimizer

VTA MicroArchitecture





# TVM/VTA: Full Stack Open Source System



High-level Optimizations

Tensor Program Search Space

ML-based Optimizer

VTA Hardware/Software Interface (ISA)

VTA MicroArchitecture







# TVM/VTA: Full Stack Open Source System



High-level Optimizations

Tensor Program Search Space

ML-based Optimizer

VTA Runtime & JIT Compiler

VTA Hardware/Software Interface (ISA)

VTA MicroArchitecture





# TVM/VTA: Full Stack Open Source System



High-level Optimizations

Tensor Program Search Space

ML-based Optimizer

VTA Runtime & JIT Compiler

VTA Hardware/Software Interface (ISA)

VTA MicroArchitecture

VTA Simulator





# TVM/VTA: Full Stack Open Source System



High-level Optimizations

Tensor Program Search Space

ML-based Optimizer

VTA Runtime & JIT Compiler

VTA Hardware/Software Interface (ISA)

VTA MicroArchitecture

VTA Simulator



- JIT compile accelerator micro code
- Support heterogenous devices, 10x better than CPU on the same board.
- Move hardware complexity to software



# TVM/VTA: Full Stack Open Source System

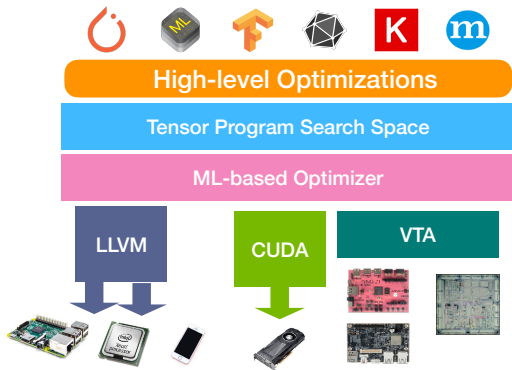


- JIT compile accelerator micro code
- Support heterogenous devices, 10x better than CPU on the same board.
- Move hardware complexity to software

**compiler, driver,  
hardware design  
full stack open source**



# TVM: Learning-based Learning System



Check it out!



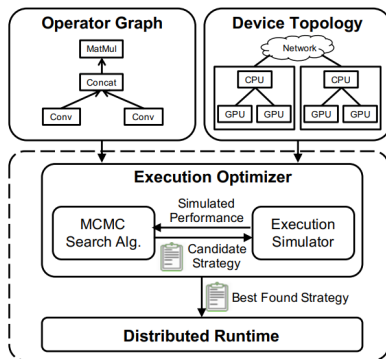


# SOTA Solutions



- “The optimizer uses a MCMC search algorithm to explore the space of possible parallelization strategies and iteratively proposes candidate strategies that are evaluated by a execution simulator.”

1

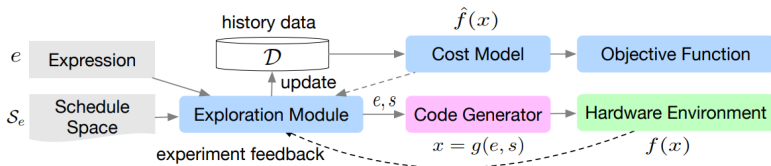


<sup>1</sup>Zhihao Jia, Matei Zaharia, and Alex Aiken (2019). “Beyond Data and Model Parallelism for Deep Neural Networks”. In: *Proceedings of Machine Learning and Systems 2019, MLSys 2019, Stanford, CA, USA, March 31 - April 2, 2019*. Ed. by Ameet Talwalkar, Virginia Smith, and Matei Zaharia. mlsys.org. URL: <https://proceedings.mlsys.org/book/265.pdf>.



- “We learn domain-specific statistical cost models to guide the search of tensor operator implementations over billions of possible program variants. We further accelerate the search using effective model transfer across workloads.”

2



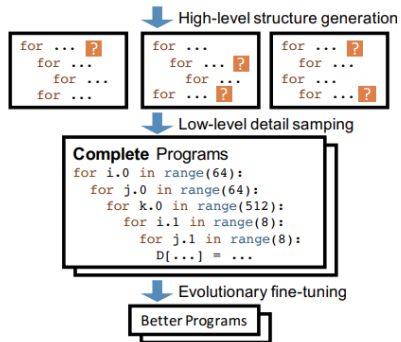
<sup>2</sup>Tianqi Chen et al. (2018). “Learning to Optimize Tensor Programs”. In: *Advances in Neural Information Processing Systems 31: Annual Conference on Neural Information Processing Systems 2018, NeurIPS 2018, 3-8 December 2018, Montréal, Canada*. Ed. by Samy Bengio et al., pp. 3393–3404. URL: <http://papers.nips.cc/paper/7599-learning-to-optimize-tensor-programs>.





- “We present Anso, a tensor program generation framework for deep learning applications. Compared with existing search strategies, Anso explores much more optimization combinations by sampling programs from a hierarchical representation of the search space.”

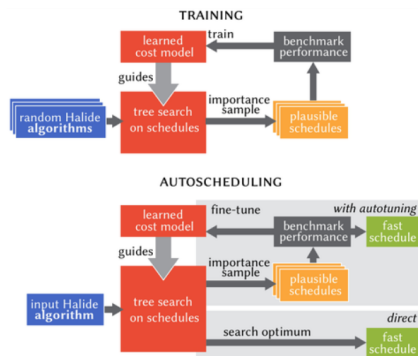
3



<sup>3</sup>Lianmin Zheng et al. (2020). “Anso : Generating High-Performance Tensor Programs for Deep Learning”. In: *CoRR* abs/2006.06762. arXiv: 2006.06762. URL: <https://arxiv.org/abs/2006.06762>.

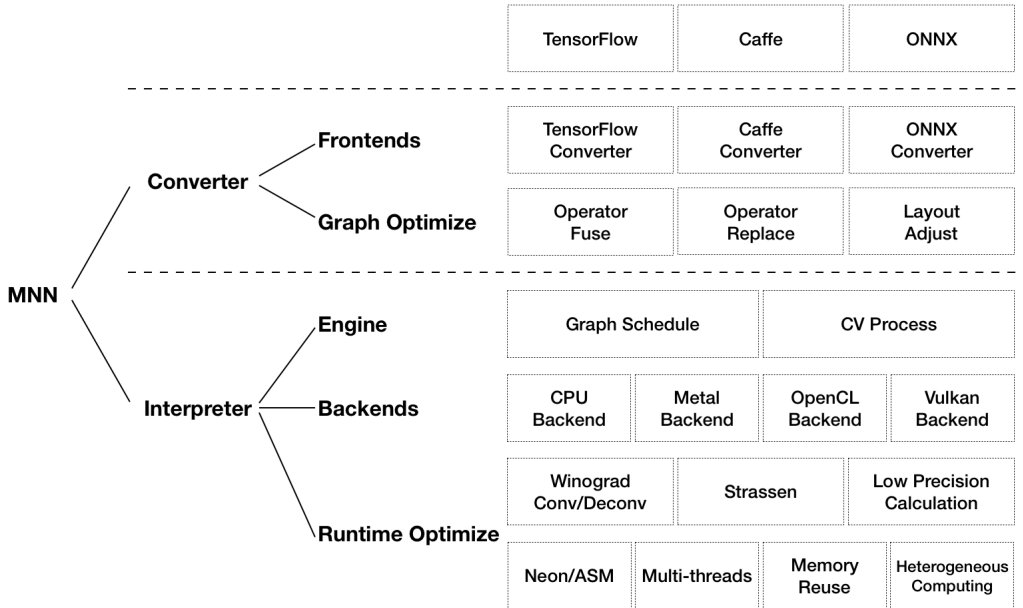


- “We generate schedules for Halide programs using tree search over the space of schedules guided by a learned cost model and optional autotuning. The cost model is trained by benchmarking thousands of randomly-generated Halide programs and schedules. The resulting code significantly outperforms prior work and human experts.”

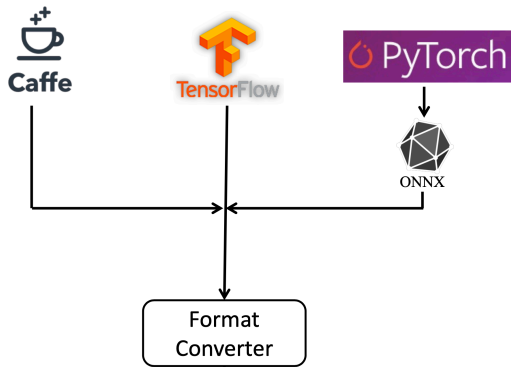




MNN



<sup>5</sup>Xiaotang Jiang et al. (2020). "MNN: A Universal and Efficient Inference Engine". In:



- Caffe Deep Learning Framework
- TensorFlow Deep Learning Framework
- Pytorch Deep Learning Framework



# PyTorch

- PyTorch is a **python** package that provides two high-level features:
  - Tensor computation (like numpy) with strong GPU acceleration
  - Deep Neural Networks built on a tape-based autograd system
- Model Deployment:
  - For high-performance inference deployment for trained models, export to **ONNX** format and optimize and deploy with **NVIDIA TensorRT** or **MNN** inference accelerator



```
1 import torch.nn as nn
2 import torch.nn.functional as F
3
4
5 class Net(nn.Module):
6
7     def __init__(self):
8         super(Net, self).__init__()
9         # 1 input image channel, 6 output channels, 3x3 square convolution
10        # kernel
11        self.conv1 = nn.Conv2d(1, 6, 3)
12        self.conv2 = nn.Conv2d(6, 16, 3)
13        # an affine operation: y = Wx + b
14        self.fc1 = nn.Linear(16 * 6 * 6, 120) # 6*6 from image dimension
15        self.fc2 = nn.Linear(120, 84)
16        self.fc3 = nn.Linear(84, 10)
17
18    def forward(self, x):
19        # Max pooling over a (2, 2) window
20        x = F.max_pool2d(F.relu(self.conv1(x)), (2, 2))
21        # If the size is a square you can only specify a single number
22        x = F.max_pool2d(F.relu(self.conv2(x)), 2)
23        x = x.view(-1, self.num_flat_features(x))
24        x = F.relu(self.fc1(x))
25        x = F.relu(self.fc2(x))
26        x = self.fc3(x)
27        return x
28
29    def num_flat_features(self, x):
30        size = x.size()[1:] # all dimensions except the batch dimension
31        num_features = 1
32        for s in size:
33            num_features *= s
34        return num_features
35
36
```



## TensorFlow

- TensorFlow is an open source software library for numerical computation using data flow graphs
- Model Deployment
  - For high-performance inference deployment for trained models, using **TensorFlow-MNN** integration to optimize models within TensorFlow and deploy with **MNN** inference accelerator





```
1 import tensorflow as tf
2 from tensorflow.keras import Model, layers
3 import numpy as np
4
5 # Create TF Model.
6 class NeuralNet(Model):
7     # Set layers.
8     def __init__(self):
9         super(NeuralNet, self).__init__()
10        # First fully-connected hidden layer.
11        self.fc1 = layers.Dense(n_hidden_1, activation=tf.nn.relu)
12        # First fully-connected hidden layer.
13        self.fc2 = layers.Dense(n_hidden_2, activation=tf.nn.relu)
14        # Second fully-connected hidden layer.
15        self.out = layers.Dense(num_classes)
16
17    # Set forward pass.
18    def call(self, x, is_training=False):
19        x = self.fc1(x)
20        x = self.fc2(x)
21        x = self.out(x)
22        if not is_training:
23            # tf cross entropy expect logits without softmax, so only
24            # apply softmax when not training.
25            x = tf.nn.softmax(x)
26        return x
```



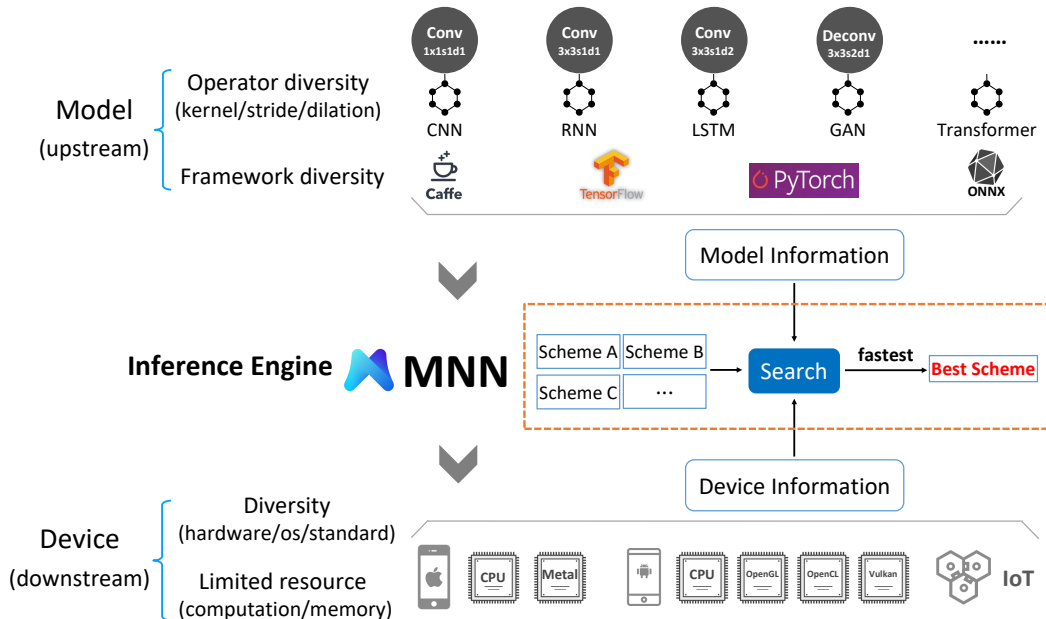
# Caffe

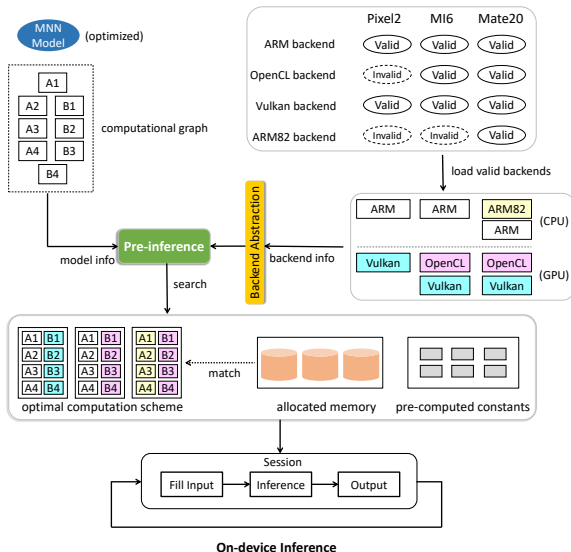
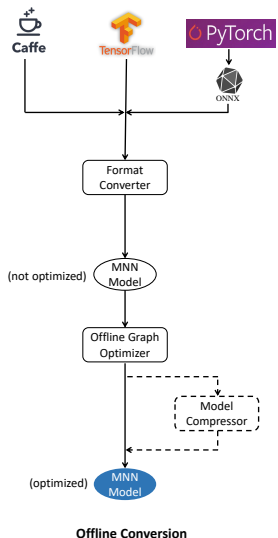
- Caffe is a deep learning framework made with **expression**, **speed**, and **modularity** in mind:
  - **Expressive architecture** encourages application and innovation
  - **Extensible code** fosters active development.
  - **Speed** makes Caffe perfect for research experiments and industry deployment
- Model Deployment:
  - For high-performance inference deployment for trained models, using **Caffe-MNN** integration to optimize models within Caffe and **MNN** inference accelerator



```
1  caffe_root = '../'
2  import sys
3  sys.path.insert(0, caffe_root + 'python')
4  import caffe
5  # run scripts from caffe root
6  import os
7  os.chdir(caffe_root)
8  # Download data
9  !data/mnist/get_mnist.sh
10 # Prepare data
11 !examples/mnist/create_mnist.sh
12 # back to examples
13 os.chdir('examples')
14
15 from caffe import layers as L, params as P
16
17 def lenet(Lmdb, batch_size):
18     # our version of LeNet: a series of linear and simple nonlinear transformations
19     n = caffe.NetSpec()
20
21     n.data, n.label = L.Data(batch_size=batch_size, backend=P.Data.LMDB, source=lmdb,
22                             transform_param=dict(scale=1./255), ntop=2)
23
24     n.conv1 = L.Convolution(n.data, kernel_size=5, num_output=20, weight_filler=dict(type='xavier'))
25     n.pool1 = L.Pooling(n.conv1, kernel_size=2, stride=2, pool=P.Pooling.MAX)
26     n.conv2 = L.Convolution(n.pool1, kernel_size=5, num_output=50, weight_filler=dict(type='xavier'))
27     n.pool2 = L.Pooling(n.conv2, kernel_size=2, stride=2, pool=P.Pooling.MAX)
28     n.fc1 = L.InnerProduct(n.pool2, num_output=500, weight_filler=dict(type='xavier'))
29     n.relu1 = L.ReLU(n.fc1, in_place=True)
30     n.score = L.InnerProduct(n.relu1, num_output=10, weight_filler=dict(type='xavier'))
31     n.loss = L.SoftmaxWithLoss(n.score, n.label)
32
33     return n.to_proto()
34
35 with open('mnist/lenet_auto_train.prototxt', 'w') as f:
36     f.write(str(lenet('mnist/mnist_train_lmdb', 64)))
37
38 with open('mnist/lenet_auto_test.prototxt', 'w') as f:
39     f.write(str(lenet('mnist/mnist_test_lmdb', 100)))
```

# Overview of the proposed Mobile Neural Network







- Training in fp32 and inference in fp16 is expected to get same accuracy as in fp32 most of the time
- Add batch normalization to activation
- If it is integer RGB input (0 - 255), normalize it to be float (0 - 1)

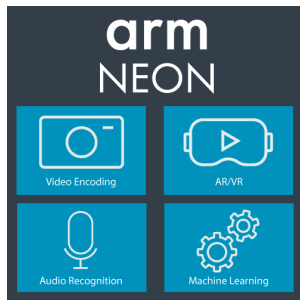


- Advantages of FP16:
  - FP16 improves speed (TFLOPS) and performance
  - FP16 reduces memory usage of a neural network
  - FP16 data transfers are faster than FP32
- Disadvantages of FP16:
  - They must be converted to or from 32-bit floats before they are operated on

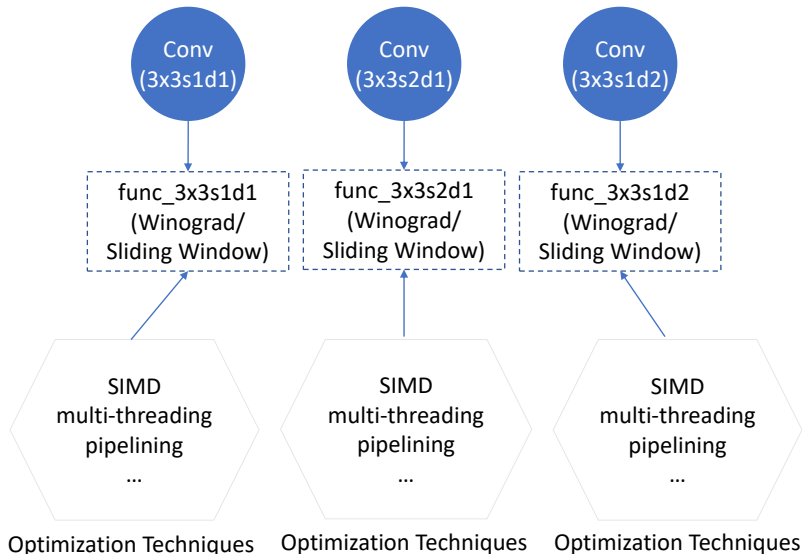


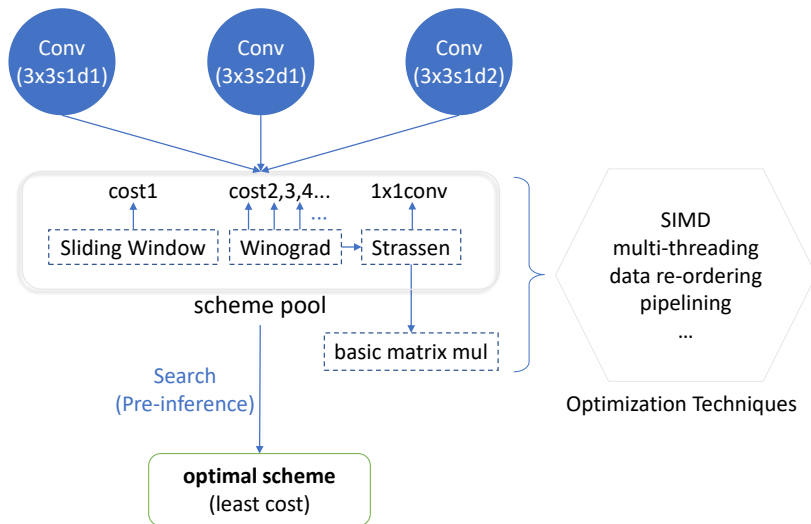
- As a programmer, there are several ways you can use **Neon** technology:
  - Neon intrinsics
  - Neon-enabled libraries
  - Auto-vectorization by your compiler
  - Hand-coded Neon assembler

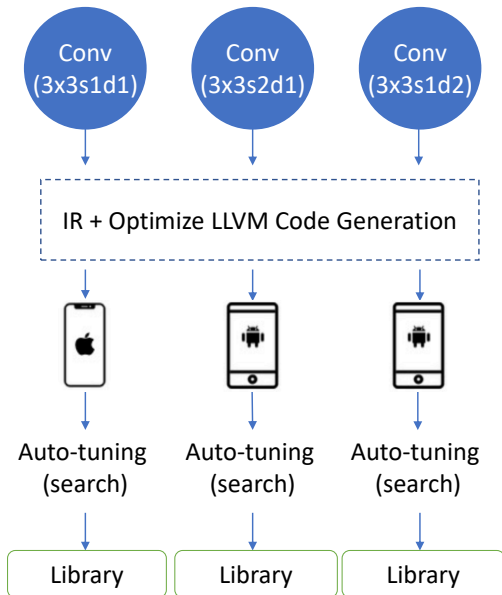




- Support for both integer and floating point operations ensures the adaptability of a broad range of applications, from codecs to High Performance Computing to 3D graphics.
- Tight coupling to the Arm processor provides a single instruction stream and a unified view of memory, presenting a single development platform target with a simpler tool flow



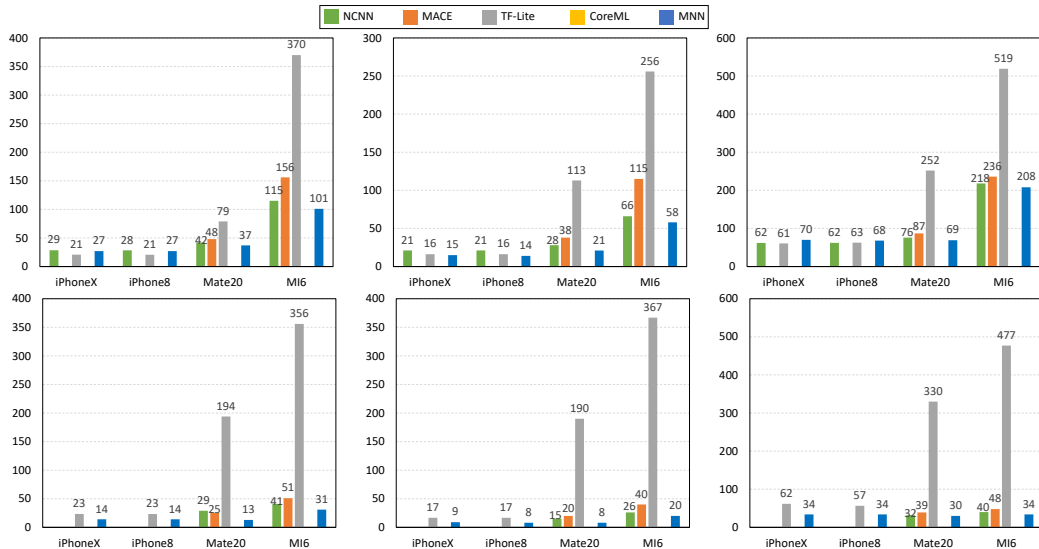




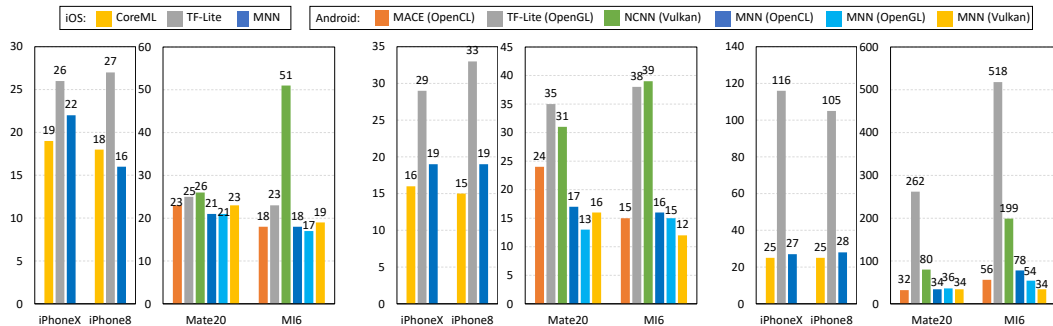


- Generally, MNN outperforms other inference engines under almost all settings by about 20% – 40%, regardless of the smartphones, backends, and networks
- For CPU, on average, 4-thread inference with MNN is about 30% faster than others on iOS platforms, and about 34% faster on Android platforms
- For Metal GPU backend on iPhones, MNN is much faster than TF-Lite, a little slower than CoreML but still comparable

# Performance on different smartphones and networks



# Performance on different smartphones and networks





- **alibaba2020mnn**
- Christian Szegedy et al. (2015). "Going deeper with convolutions". In: *CVPR*