

Incorporating Cut Redistribution with Mask Assignment to Enable 1D Gridded Design

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Outline

- Background
- Problem Formulation
- ILP
- Graph Model and Algorithm
- Post-processing
- Results and Conclusions

Lithography Technologies

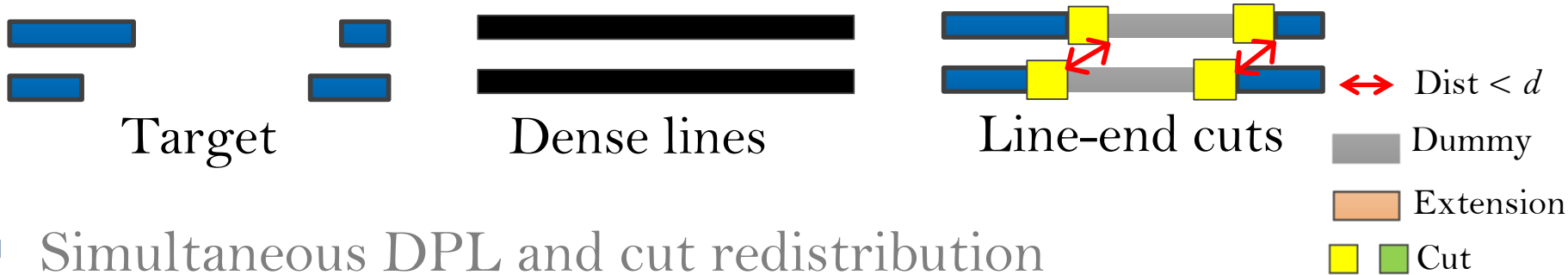
- DPL (double patterning lithography)
 - One layout is decomposed into two masks
 - Litho-etch process is repeated twice
 - Resolution can be improved
 - Like 2-coloring



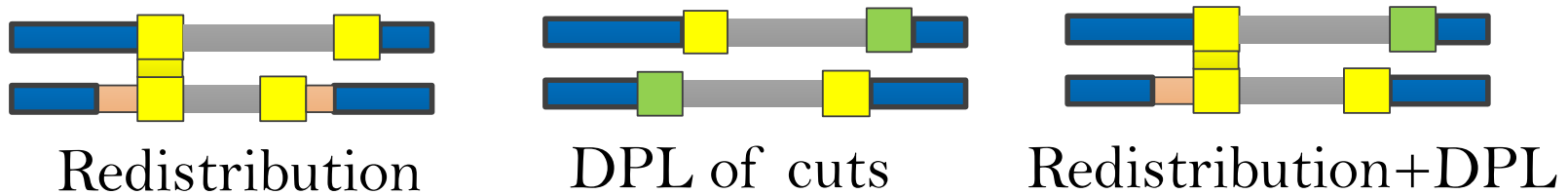
- EBL (e-beam lithography)
 - Directly creates features by electron beams w/o mask
 - Excellent resolution

Fabrication of 1D Layout

- Line-end cuts



- Simultaneous DPL and cut redistribution



- Native conflict: Even redistribution plus DPL decomposition cannot solve the conflict. **Requires EBL.**



Resolving Conflicts between Cuts

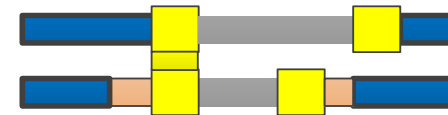
- Three ways to resolve a conflict

- DPL (coloring)



- Redistribute (move the location)

cost of wire extension



- Manufacture one cut by EBL

cost of EBL



Outline

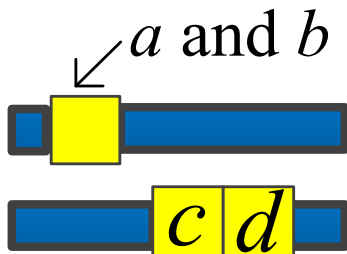
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Problem Definition

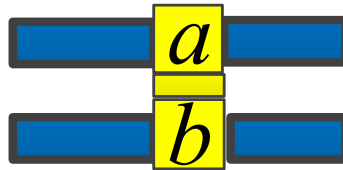
- Given a layout of n wires and $2n$ cuts, decide the fabrication method (using EBL or not), the mask and the location of each cut, such that
 - All design rules are satisfied.
 - $wire_extension \leq \text{limit}$ for each wire
 - $\min. \sum wire_extension + \partial \cdot EBL_cut\#$

Design Rules

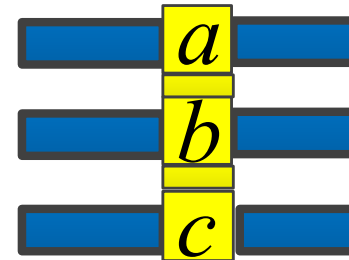
- Wires can be extended but not shortened.
- No conflict between two cuts if they are merged.



Merging on the same track (overlap or abut)



Adjacent tracks (aligned)



Non-adjacent tracks (a, b, c aligned)

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ILP

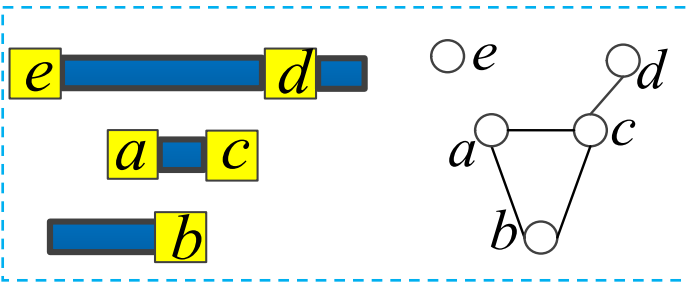
- Existing ILP [DAC'14] solves problem for EBL plus redistribution but no DPL considerations.
- Our contributions:
 - Analyze the potential problems in [DAC'14].
 - Show how to fix the problems.
 - Consider DPL besides EBL and redistribution.

[DAC'14] Ding et al. "Throughput optimization for SADP and e-beam based manufacturing of 1D layout", In Proc. DAC, 2014

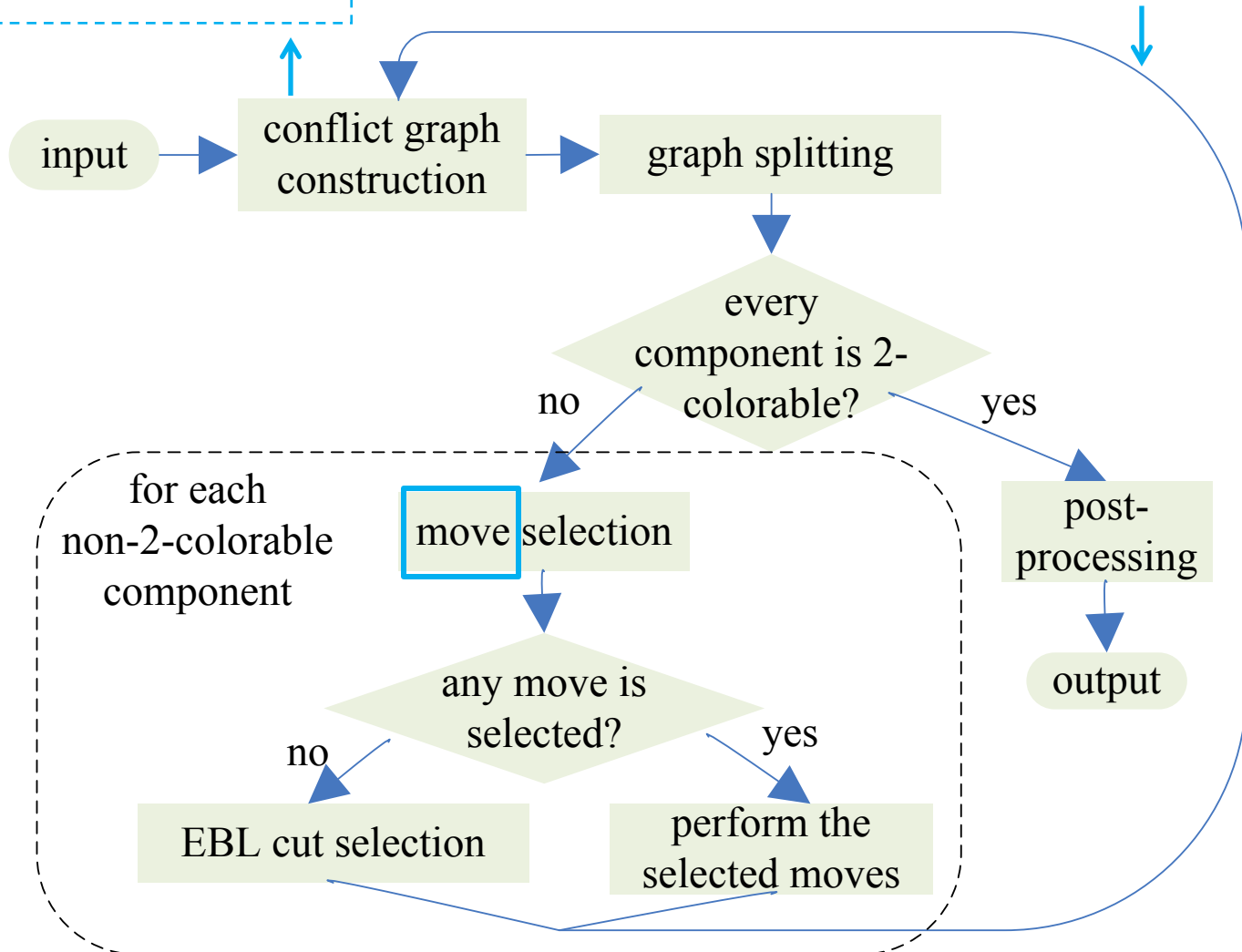
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Flow

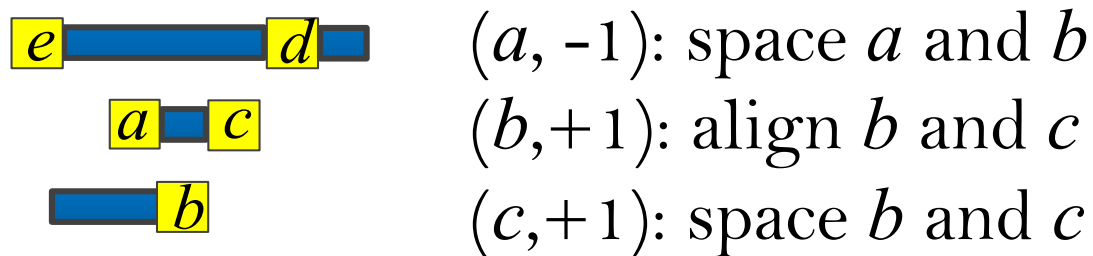


conflict graph will change with cut shifting



What is a “Move”?

- A move $(c_i, \pm d_i)$
 - Cut c_i
 - Right/Left: \pm
 - Discrete moving distance d_i
 - Cost = Wire extension resulted



Move Selection

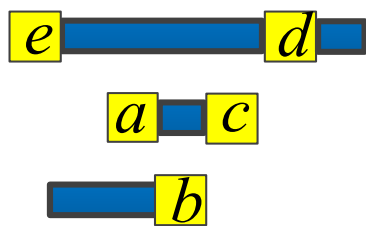
- Select moves to change locations of cuts such that no odd cycle is created in conflict graph
 - No odd cycle \equiv 2-colorable



- Select moves based on an integrated graph model
 - Obtained by integrating G_1 , G_2 and G_3

Graph Model 1

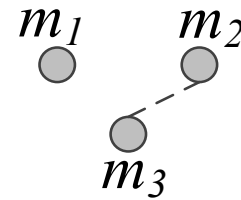
- G_I : constraint graph for move operations:



$(a, -1) : m_1$

$(b, +1) : m_2$

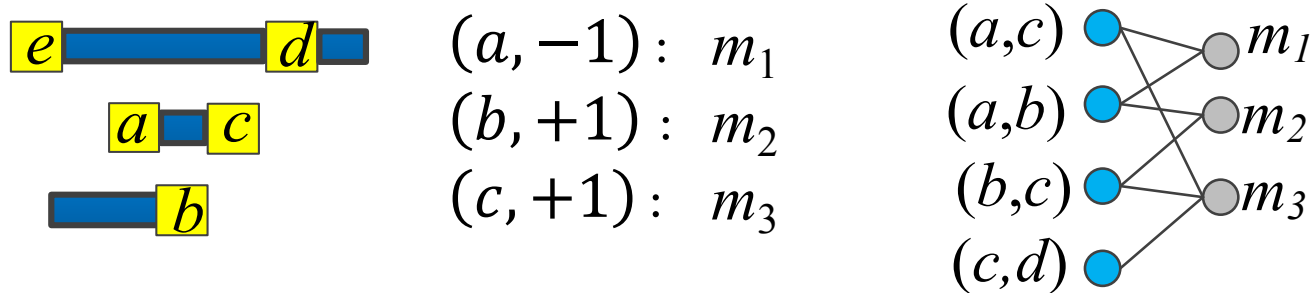
$(c, +1) : m_3$



- Two moves are incompatible (have an edge) if
 - Exceed limit on wire extension, or
 - Both shift a cut in different directions, or
 - Applying both cannot resolve the targeted conflicts

Graph Model 2

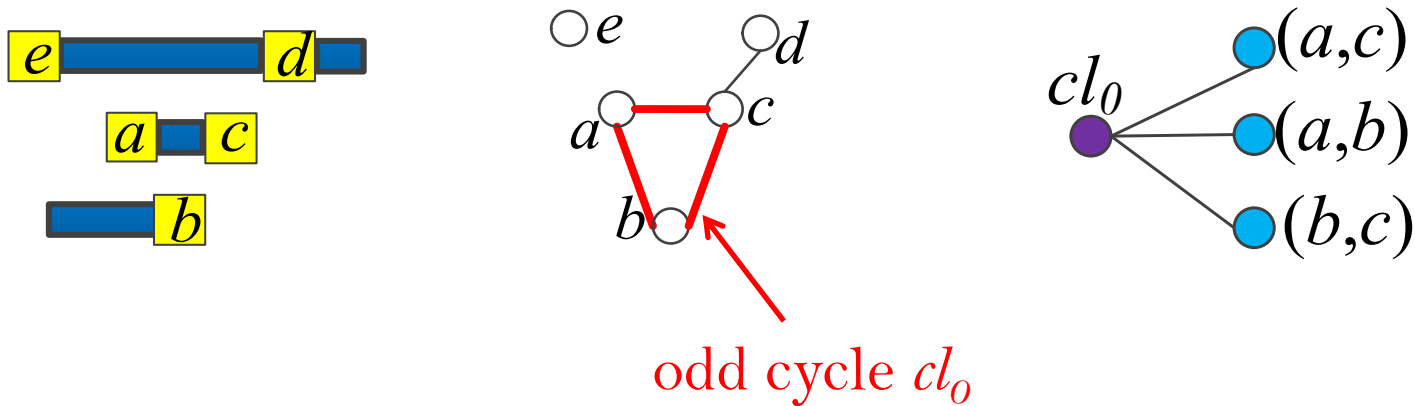
- G_2 is a bipartite graph between conflicts and moves:



e.g. Moving a to the left 1 step (m_1) can resolve the conflict between (a,c) and m_1 . Thus there is an edge between (a,c) and m_1 .

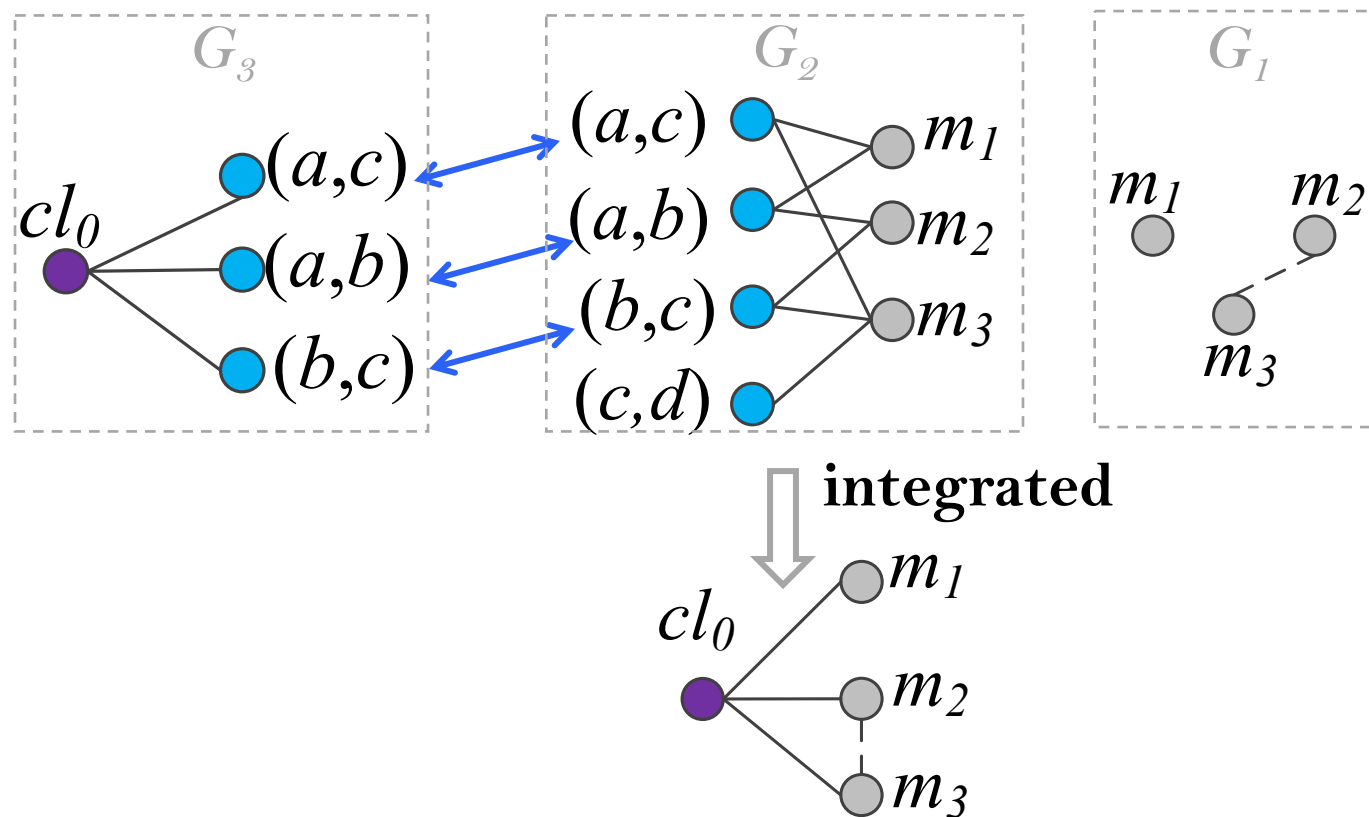
Graph Model 3

- G_3 : bipartite graph between conflicts and odd cycles



- The edge between cl_0 and (a,c) means that resolving conflict (a,c) can break odd cycle cl_0 .
- All odd cycles should be broken.
- Number of odd cycles can be exponential.
 - Only consider odd cycles in a cycle basis - a set of cycles that can be combined to form every cycle in a graph.

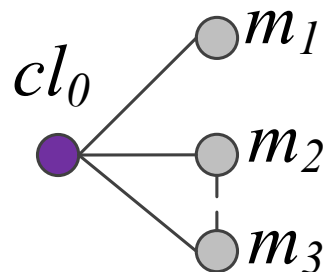
Integrated Graph Model



- Constraints between moves (dash lines) are copied.
- cl_0 — (a,c) in G_3 and (a,c) — m_1 in G_2 gives cl_0 — m_1 in the final graph meaning that move m_1 can break cycle cl_0 .

Move Selection by Constrained Set Cover

- Select moves to break all the identified odd cycles
- Constrained set cover problem:
- Select a set of min-cost moves to break all cycles under some constraints.

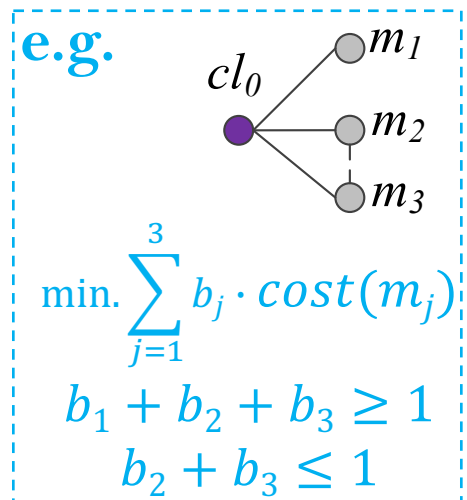


Solving Constrained Set Cover

- Use ILP to solve the constrained set cover problem:
 - Constant a_{ij} indicates if an edge exists btw. cycle i and move m_j
 - Variable b_j indicates if move m_j is selected

$$\begin{aligned} \min. \quad & \sum_{j=1}^{\#move} b_j \cdot cost(m_j), \\ \text{s.t.} \quad & \sum_{j=1}^{\#move} a_{ij} \cdot b_j \geq 1, \quad \forall \text{cycle}, \end{aligned}$$

$$b_i + b_j \leq 1, \quad \forall \text{move } m_i \text{ incompatible with } m_j$$



- Much smaller and simpler than the ILP solving the original problem directly.

EBL Cut Selection

Flow (Review)

do

Select some moves.

Perform selected moves.

Rebuild conflict graph.

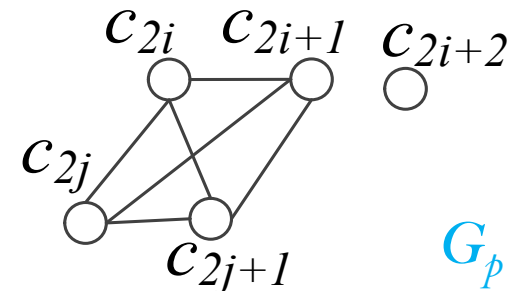
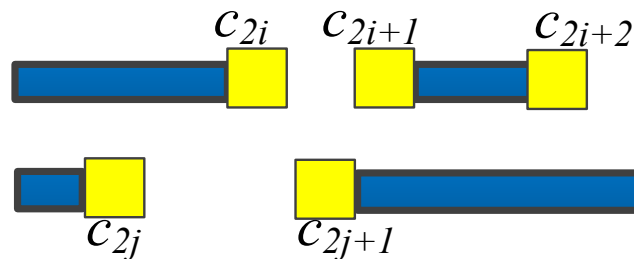
until all cuts 2-colorable **or** no moves are available.

Select some cuts as EBL cuts.

- When a cut is an EBL cut, its corresponding node is deleted from the conflict graph.
- **Problem:** Delete a minimum number of nodes from the conflict graph such that at least one node will be deleted from each cycle in a cycle basis.
- **Solution:** Use a similar ILP without incompatible constraints

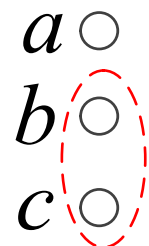
Accelerating by Potential Conflict Graph

- Conflict graph G of cuts:
Conflicts between cuts can change dynamically if cuts can move.
- Potential conflict graph G_p .
An edge between two nodes iff there is a potential conflict between the two cuts with cut redistribution
- G_p is stable and can be safely split into sub-layouts to reduce problem size



Handling Vertically Aligned Cuts

- #cut=2: a and b never conflict
 - As we can merge them if $\text{color}(a)=\text{color}(b)$
- #cut=3: no conflict if $\text{color}(b) = \text{color}(a)$ or $\text{color}(c)$
 - Conflict edge $a-c$: unnecessary
- # vertically aligned cuts = $n \leq H+1$:
 (H is the largest difference between two conflicting track labels.)
- **Lemma:** No conflict iff $\exists i$ for $2 \leq i \leq n$ s.t. $c_1 \dots c_{i-1}$ are colored the same and $c_i \dots c_n$ are colored the same.
- Grouping nodes instead of adding many edges in conflict graph

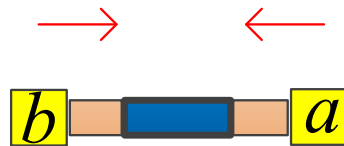


DPL+EBL

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Post-processing methods

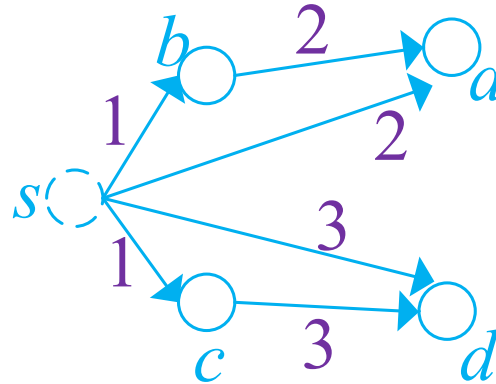
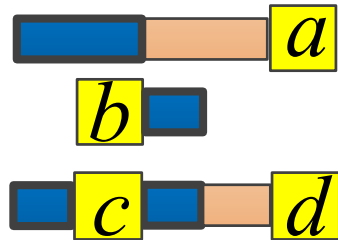
- Objective: To minimize wire extensions.
- Globally: Longest-path algorithm:
 - Compact the cuts at right ends of wires to the left
 - Compact the cuts at left ends of wires to the right



- Locally: Greedily shift cuts towards their original locations

Longest Path algorithm

- For those right end cuts, construct a left compaction graph:



- Edge cost:
 - s to node: Leftmost x of the movable range of the cut.
 - Between nodes: Required distance between the 2 nodes.
- Edge direction:
 - b to a iff $x_a > x_b$
- Distance of the longest path from s to i :
 - Leftmost x to place i

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Comparison with ILP

Dataset	Optimal ILP			Ours		
	EBL#	Extension	Time(s)	EBL#	Extension	Time(s)
50	0	26	18.0	0	26	0.1
100	0	46	180.4	0	46	0.2
150	0	78	6446.9	0	79	0.4
200	-	-	>36000	0	104	0.5
250	-	-	>36000	0	129	0.6
300	-	-	>36000	0	164	0.7
1000	-	-	>36000	0	583	2.2
2000	-	-	>36000	0	1230	4.5
4000	-	-	>36000	1	2500	9.4
8000	-	-	>36000	1	5178	18.8

Caused by native conflict



- ILP is too slow.
- Our EBL# has achieved lower bound for all datasets.
- Our quality is very close to ILP if ILP has solutions.

Comparison with

Optimal Coloring + Optimal Redistribution

Dataset	Opt. color + redistribute		Ours	
Track#	Cost	Time (s)	Cost	Time (s)
50	4029	0.7	26	0.1
100	9050	1.2	46	0.2
150	14091	2.4	79	0.4
200	17109	2.8	104	0.5
250	19135	3.4	129	0.6
300	23174	4.7	164	0.7
1000	69670	35.6	583	2.2
2000	132380	91.4	1230	4.5
4000	280764	245.3	3500	9.4
8000	573740	2784.9	6178	18.8
Ratio	95.0	84.8	1	1

- Our algorithm optimizes coloring and redistribution simultaneously
- $Cost = \sum wire_extension + \partial \cdot EBL_cut\# \quad \partial=100$

Conclusion

- Co-optimization of cut redistribution and mask assignment for 1D gridded design.
- Novel graph-theoretic method that makes use of integrated graph model + longest path-based refinement
- 1D design is the future of 10nm technology node and beyond and more research can be done.