Online Learning and Feature Optimization in Lithography Hotspot Detection

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Outline

Introduction

Feature Optimization

Learning Model

Experimental Results and Conclusion

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Moore's Law to Extreme Scaling





Lithographic Mechanism

- light diffraction when through photomask
- May cause performance degradation, or even yield loss
- What you see \neq what you get





Lithography Hotspot Detection



- ▶ RET: OPC, SRAF, MPL
- Still hotspot: low fidelity patterns
- Simulations: extremely CPU intensive



Layout Verification Hierarchy



(Relative) CPU runtime at each level

Sampling:

scan and rule check each region

Hotspot Detection:

verify the sampled regions and report potential hotspots

Lithography Simulation:

final verification on the reported hotspots



Pattern Matching based Hotspot Detection



Pattern Matching based Hotspot Detection



Pattern Matching based Hotspot Detection



Fast and accurate

- [Yu+,ICCAD'14] [Nosato+,JM3'14] [Su+,TCAD'15]
- Fuzzy pattern matching [Wen+,TCAD'14]
- Hard to detect non-seen pattern

Machine Learning based Hotspot Detection



Machine Learning based Hotspot Detection



Machine Learning based Hotspot Detection



- Predict new patterns
- Decision-tree, ANN, SVM, Boosting ...
- [Drmanac+,DAC'09] [Ding+,TCAD'12] [Yu+,JM3'15] [Matsunawa+,SPIE'15]
 [Yu+,TCAD'15]
- Hard to balance accuracy and false-alarm

Rethinking Performance Metrics

- Accuracy: The rate of correctly predicted hotspots among the set of actual hotspots.
- **False Alarm**: The number of incorrectly predicted non-hotspots.
- **Detection Runtime**: CPU runtime of hotspot detection.

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Overall Detection and Simulation Time (ODST)

Includes: (1) Detection runtime; (2) Lithography simulation time for hotspots in testing.

*Transfer false alarm into equivelent lithography simulation time.

Rethinking Hotspot Detection Framework



- Conventional framework: supervised learning.
- Two stages: training and testing.
- Testing hotspot (HS) is verified by litho simulator.

Rethinking Hotspot Detection Framework



Conventional framework: supervised learning.

- Two stages: training and testing.
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Proposed New Framework:

- Feature optimization.
- Online model learning.

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Conventional Feature Extraction



- Hard to be adaptive to different layout designs
- Too many parameters to tune
- Sometimes very complex and may cause over fitting

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Rethinking CCAS



- Concentric Circle Area Sampling (CCAS) [Matsunawa+,JM3'16].
- Capture the affects of light diffraction.
- Simple rule to select circles from dense samples.

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Question:

Can we find **correlation** between circles and hotspots, and select circles samrtly?

Rethinking CCAS

Measure correlation between circle and the hotspot.

Mutual Information

$$I(C_i; Y) = \sum_{c_i \in C} \sum_{y \in Y} p(c_i, y) \log \frac{p(c_i, y)}{p(c_i)p(y)}$$

- c_i: one encoded decimal number in circle C
- $p(c_i)$: probability of c_i
- y: each classification label
- p(y): probability of y



Decimal number encoding

Smart CCAS Circle Selection

Higer Mutual Information

More correlation between circle and label variable.

- Mutual information curve can be drawn based on training data
- We donot want to sample circles too dense



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Smart CCAS Circle Selection

Mathematical Formulation

$\max \mathbf{v}^\mathsf{T} \mathbf{w}$

s.t.
$$v_i = I(C_i; Y), \quad \forall v_i \in \mathbf{v},$$

 $||w_i||_0 = n_c, \quad \forall i, w_i \in \{0, 1\},$
 $|i - j| \ge d, \quad \forall i \ne j, w_i = w_j = 1$



Smart CCAS Circle Selection

Mathematical Formulationmax $\mathbf{v}^{\mathsf{T}}\mathbf{w}$ s.t. $v_i = I(C_i; Y), \quad \forall v_i \in \mathbf{v},$ $||w_i||_0 = n_c, \quad \forall i, w_i \in \{0, 1\},$ $|i - j| \ge d, \quad \forall i \ne j, w_i = w_j = 1$



Optimally Solved by Dynamic Programming

$$D[i,j] = \max\{v[i] + D[i-d,j-1], D[i-1,j]\}\}$$

Performance of Feature Optimization

Smart Circle Selection v.s. Conventional CCAS.



(a) The impact on accuracy; (b) The impact on false alarm.

Review of the Feature Optimization Framework

- Firstly, we densely sample the circles from the training data.
- Secondly, we optimally select circles by DP algorithm.
- Thirdly, we use the obtained circle index to extract features.



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Motivation of Online Hotspot Detection

- In (a), all testing hotspots and non-hotspots can be correctly detected.
- But in (b), all testing non-hotspots become false alarms.



Algorithm Flow of Smboost

Smooth Boosting [Servedio, JMLR'03]

Require:
$$\{(x_1, y_1), ..., (x_m, y_m)\}, \gamma, \theta = \frac{\gamma}{2+\gamma}, T.$$

1: for $i \leftarrow 1$ to n do
2: $M_1(i) \leftarrow 1;$
3: $N_0(i) \leftarrow 0;$
4: end for
5: for $t \leftarrow 1$ to T do
6: Run weak classifier to get h_t such that
 $\frac{1}{2} \sum_{j=1}^n M_t(j) |h_t(x_j) - y_j| \le \frac{1}{2} - \gamma;$
7: for $j \leftarrow 1$ to n do
8: $N_t(j) \leftarrow N_{t-1}(j) + y_j h_t(x_j) - \theta;$
9: end for
10: for $j \leftarrow 1$ to n do
11: $M_{t+1}(j) \leftarrow \min\{1.0, (1-\gamma)^{\frac{N_t(j)}{2}}\};$
12: end for
13: end for
14: return $f \leftarrow \text{sign}(\frac{1}{T} \sum_{t=1}^T h_t);$

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Algorithm Flow of Online Smboost

Extend conventional smboost to the online scenario.

Online Smooth Boosting

Require: Streaming instance (x, y), batch smboost classifier.

- 1: $M_1 \leftarrow 1, N_0 \leftarrow 0;$
- 2: for $t \leftarrow 1$ to T do
- 3: online update $h_t(x, y)$;

4:
$$N_t \leftarrow N_{t-1} + yh_t(x) - \theta$$

- 5: $M_{t+1} \leftarrow \min\{1.0, (1-\gamma)^{\frac{N_t}{2}}\};$
- 6: end for
- 7: return $f \leftarrow \operatorname{sign}(\frac{1}{T}\sum_{t=1}^{T}h_t);$

Online Weak Classifier

- Use Naive Bayes (NB) as weak classifier [Chen+,ICML'12].
- ▶ NB is a lossless [Oza, ICSMC'05] online weak classifier.
- Modify NB to work better with our proposed feature.



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Comparison with [Matsunawa+,SPIE'15]

- Verified in ICCAD-2012 contest benchmark
- 4x speed-up due to the simple feature.
- Increase detection accuracy from 95.13% to 97.95%.

	[Matsunawa+,SPIE'15]			batch		
	FA#	CPU(s)	Accuracy	FA#	CPU(s)	Accuracy
Case1	0	7	100.00%	0	7	100.00%
Case2	0	351	98.60%	0	53	99.40%
Case3	0	297	97.20%	3	66	97.51%
Case4	1	170	87.01%	0	49	97.74%
Case5	0	69	92.86%	0	27	95.12%
avg.	0.2	178.8	95.13%	0.6	40.4	97.95%
ratio	-	4.43	0.97	-	1.0	1.0%

Comparisons with [Wen+,TCAD'14] [Yu+,TCAD'15]

- ODST = Overall Detection and Simulation Time
- Increase detection accuracy by at least 3.47% on average.
- Improve the performance of ODST by at least 58.80% on average.

	[Wen+,TCAD'14]		[Yu+,TCAD'15]		batch		
	ODST(s)	Accuracy	ODST(s)	Accuracy	ODST(s)	Accuracy	
Case1	17151	100.00%	14968	94.69%	7890	100.00%	
Case2	40867	99.80%	118574	98.20%	5572	99.40%	
Case3	95277	93.80%	139278	91.88%	20660	97.51%	
Case4	11302	91.00%	36996	85.94%	33526	97.74%	
Case5	2039	87.80%	12070	92.86%	1005	95.12%	
avg.	33327.2	94.48%	64377.2	92.71%	13730.6	97.95%	
ratio	2.43	0.96	4.69	0.95	1.0	1.0	

Batch Learning v.s. Online Learning

- Further improve the detection accuracy from 97.95% to 98.45%.
- ► Further reduce ODST by 26.1%.

	batch				online			
	FA#	CPU(s)	ODST(s)	Acccuracy	FA#	CPU(s)	ODST(s)	Accuracy
Case1	788	10	7890	100.00%	704	13	7050	100.00%
Case2	544	132	5572	99.40%	308	152	3251	99.40%
Case3	2052	140	20660	97.51%	1819	180	18379	97.57%
Case4	3341	116	33526	97.74%	2096	158	21148	97.74%
Case5	94	76	1005	95.12%	82	78	910	97.56%
avg.	1363.8	94.8	13730.6	97.95%	1008.8	116.4	10147.6	98.45%
ratio	-	-	1.35	0.99	-	-	1.0	1.0

Runtime Breakdown for ICCAD Benchmark

- Online updating is only a small portion of the whole detection flow.
- False alarms of Case 2 and Case 5 are dramatically reduced.



Conclusion



A New Hotspot Detection Framework

- New performance metric: runtime & performance trade-off
- Feature optimization based on mutual information
- Online learning

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A New Hotspot Detection Framework

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Future work

- Further improve the accuracy
- Hardware or parallel speedup of hotspot detector

Thank You

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