

Dynamic Programming: Matrix-Chain Multiplication

Yufei Tao's Teaching Team

Department of Computer Science and Engineering
Chinese University of Hong Kong

Matrix-Chain Multiplication

You are given an algorithm \mathcal{A} that, given an $a \times b$ matrix \mathbf{A} and a $b \times c$ matrix \mathbf{B} , can calculate \mathbf{AB} in $O(abc)$ time. You need to use \mathcal{A} to calculate the product of $\mathbf{A}_1\mathbf{A}_2\dots\mathbf{A}_n$ where \mathbf{A}_i is an $a_i \times b_i$ matrix for $i \in [1, n]$. This implies that $b_{i-1} = a_i$ for $i \in [2, n]$, and the final result is an $a_1 \times b_n$ matrix.

A trivial strategy is to apply \mathcal{A} to evaluate the product from left to right. However, we may be able to reduce the cost by following a different multiplication order.

Example

Consider $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3$ where \mathbf{A}_1 and \mathbf{A}_2 are $m \times m$ matrices, but \mathbf{A}_3 is $m \times 1$.

There are two multiplication orders:

- $(\mathbf{A}_1\mathbf{A}_2)\mathbf{A}_3$.

The cost of computing $\mathbf{B} = \mathbf{A}_1\mathbf{A}_2$ is $O(m \cdot m \cdot m) = O(m^3)$ and \mathbf{B} is an $m \times m$ matrix. The cost of $\mathbf{B}\mathbf{A}_3$ is $O(m \cdot m \cdot 1) = O(m^2)$. The total cost is $O(m^3)$.

- $\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3)$.

The cost of computing $\mathbf{B} = \mathbf{A}_2\mathbf{A}_3$ is $O(m \cdot m \cdot 1) = O(m^2)$ and \mathbf{B} is an $m \times 1$ matrix. The cost of $\mathbf{A}_1\mathbf{B}$ is $O(m \cdot m \cdot 1) = O(m^2)$. The total cost is $O(m^2)$.

Parenthesizing $\mathbf{A}_1\mathbf{A}_2\dots\mathbf{A}_n$ at \mathbf{A}_k for some $k \in [1, n - 1]$ converts the expression to $(\mathbf{A}_1\dots\mathbf{A}_k)(\mathbf{A}_{k+1}\dots\mathbf{A}_n)$, after which you can parenthesize each of $\mathbf{A}_1\dots\mathbf{A}_i$ and $\mathbf{A}_{i+1}\dots\mathbf{A}_n$ recursively.

A **fully parenthesized product** is

- either a single matrix or
- the product of two fully parenthesized products.

For example, if $n = 4$, then $(\mathbf{A}_1\mathbf{A}_2)(\mathbf{A}_3\mathbf{A}_4)$ and $((\mathbf{A}_1\mathbf{A}_2)\mathbf{A}_3)\mathbf{A}_4$ are fully parenthesized, but $\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4)$ is not.

A fully parenthesized product determines a multiplication order that, in turn, determines the computation cost.

Goal: Design an algorithm to find in $O(n^3)$ time a fully parenthesized product with the smallest cost.

Recursive Structure

By parenthesizing at \mathbf{A}_k , we obtain

$$\underbrace{(\mathbf{A}_1 \dots \mathbf{A}_k)}_{\mathbf{B}_1} \underbrace{(\mathbf{A}_{k+1} \dots \mathbf{A}_n)}_{\mathbf{B}_2},$$

where \mathbf{B}_1 is an $a_1 \times b_k$ matrix and \mathbf{B}_2 is an $a_{k+1} \times b_n$ matrix.

The total cost is

$$\text{cost of computing } \mathbf{B}_1 + \text{cost of computing } \mathbf{B}_2 + O(a_1 b_k b_n).$$

We define $cost(i, j)$, where $1 \leq i \leq j \leq n$, to be the smallest achievable cost for calculating $\mathbf{A}_i \dots \mathbf{A}_j$. Our objective is to calculate $cost(1, n)$.

If we parenthesize $\mathbf{A}_i \dots \mathbf{A}_j$ at \mathbf{A}_k , we obtain

$$\underbrace{(\mathbf{A}_i \dots \mathbf{A}_k)}_{cost(i, k)} \underbrace{(\mathbf{A}_{k+1} \dots \mathbf{A}_j)}_{cost(k+1, j)}.$$

The total cost is

$$cost(i, k) + cost(k + 1, j) + O(a_i b_k b_j).$$

To attain $cost(i, j)$, we should try all possible parenthesizations of $\mathbf{A}_i \dots \mathbf{A}_j$. This implies:

$$cost(i, j) = \begin{cases} O(1) & \text{if } i = j \\ \min_{k=i}^{j-1} (cost(i, k) + cost(k+1, j) + O(a_i b_k b_j)) & \text{if } i < j \end{cases}$$

By dyn. programming, we can compute $cost(1, n)$ in $O(n^3)$ time.

Consider $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4$ where \mathbf{A}_1 and \mathbf{A}_2 are $m \times m$ matrices, \mathbf{A}_3 is $m \times 1$, and \mathbf{A}_4 is $1 \times m$.

$i \backslash j$	1	2	3	4
1				— $cost(1,4)$
2	0			
3	0	0		
4	0	0	0	

After solving all subproblems, we obtain:

$i \backslash j$	1	2	3	4
1	$O(1)$	$O(m^3)$	$O(m^2)$	$O(m^2)$
2	0	$O(1)$	$O(m^2)$	$O(m^2)$
3	0	0	$O(1)$	$O(m^2)$
4	0	0	0	$O(1)$

Next, we apply the “piggyback technique” to generate an optimal parenthesization.

Define $bestSub(i, j) =$

- nil, if $i = j$;
- k , if the best parenthesization for $\mathbf{A}_i\mathbf{A}_{i+1}\dots\mathbf{A}_j$ is $(\mathbf{A}_i\dots\mathbf{A}_k)(\mathbf{A}_{k+1}\dots\mathbf{A}_j)$.

$i \backslash j$	1	2	3	4
1	$O(1)$	$O(m^3)$	$O(m^2)$	$O(m^2)$
2	0	$O(1)$	$O(m^2)$	$O(m^2)$
3	0	0	$O(1)$	$O(m^2)$
4	0	0	0	$O(1)$

After $cost(i, j)$ is ready for all i, j , we can compute all $bestSub(i, j)$ in $O(n^3)$ time.

$i \backslash j$	1	2	3	4
1	$O(1)$	$O(m^3)$	$O(m^2)$	$O(m^2)$
2	0	$O(1)$	$O(m^2)$	$O(m^2)$
3	0	0	$O(1)$	$O(m^2)$
4	0	0	0	$O(1)$

$\mathbf{A}_1: m \times m$

$\mathbf{A}_2: m \times m$

$\mathbf{A}_3: m \times 1$

$\mathbf{A}_4: 1 \times m$

Example:

$bestSub(1, 4) = 3$, i.e., the best way to calculate $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4$ is $(\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3)\mathbf{A}_4$.

Similarly, $bestSub(1, 3) = 1$, i.e., the best way to calculate $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3$ is $\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3)$.

Therefore, an optimal fully parenthesized product of $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4$ is $(\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3))\mathbf{A}_4$.