

# Lecture one

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## 1 What is a Partial differential equation (PDE)?

**Definition 1.** A **PDE** is an identity that relates more than one the independent variables (say  $x, y, z, t \dots$ ), dependent variable  $u(x, y, z, \dots)$ , and partial derivatives of  $u$ .

- More than one independent variable  $x, y, t \dots$ , Ordinary differential equation has only one independent variable  $x$ .
- The dependent variable  $u$  is an unknown function of these variables  $x, y, \dots$ .
- The partial derivatives of  $u$  is often denoted by  $u_x := \frac{\partial u}{\partial x}$ ,  $u_y := \frac{\partial u}{\partial y}$ ,  $u_{xx} := \frac{\partial^2 u}{\partial x^2}$ ,  $u_{xy} := \frac{\partial^2 u}{\partial x \partial y}$  and so on.

For example:  $u_x + u_y = 0$  (transport),  $u_{tt} - u_{xx} = 0$  (wave equation),  $u_t = u_{xx}$  (diffusion equation) and  $u_{xx} + u_{yy} + u_{zz} = 0$  (Laplace's equation).

Let us see the physical interpretation of the above equations.

**Example 2.** Simple Transport.

*Proof.* Consider a water flowing at a constant speed  $c$  cm/s along a horizontal pipe of fixed cross section in the positive  $x$  direction. A pollutant with density  $u(x, t)$  g/cm is suspended in the water. The amount of pollutant in the interval  $[0, x]$  at time  $t$  is  $M = \int_0^x u(x', t) dx'$ . At the later time  $t + h$ , the same amount of pollutant have moved to the right by  $c \cdot h$  cm. Hence

$$M = \int_0^x u(x', t) dx' = \int_{ch}^{x+ch} u(x', t+h) dx'.$$

Differentiating with respect to  $x$ , we get

$$u(x, t) = u(x + ch, t + h).$$

Differentiating with respect to  $h$  and putting  $h = 0$ , we get

$$0 = cu_x(x, t) + u_t(x, t).$$

□

**Example 3.** Vibrating string.

*Proof.* A elastic homogeneous string with length  $l$  undergoes relatively small transverse vibrations in a plane. Denote  $u(x, t)$  to be the hight of the string at time  $t$  and position  $x$ . Let  $T$  (constant) be the magnitude of tension and  $\rho$  (constant) be the density (mass per unit length) of string. At very small section of string

$$-T \sin \theta(x, t) + T \sin \theta(x + \Delta x, t) = F.$$

On the other hand, by Newton's law we have

$$F = ma = \rho(\Delta x)u_{tt}.$$

So we have

$$\rho(\Delta x)u_{tt} = -T \sin \theta(x, t) + T \sin \theta(x + \Delta x, t).$$

Dividing both side by  $\rho(\Delta x)$ ,

$$\begin{aligned} u_{tt} &= \frac{T}{\rho} \lim_{\Delta x \rightarrow 0} \frac{-\sin \theta(x, t) + \sin \theta(x + \Delta x, t)}{\Delta x} \\ &= \frac{T}{\rho} \frac{\partial}{\partial x} \sin \theta(x, t). \end{aligned}$$

Observing that  $u_x = \tan \theta(x, t) \approx \sin \theta(x, t)$ , we get

$$u_{tt} = c^2 u_{xx},$$

where  $c = \sqrt{\frac{T}{\rho}}$ .

This is the **wave** equation. □

**Example 4.** Diffusion.

*Proof.* Let us imagine a motionless liquid filling a straight pipe and a chemical substance which is diffusing through the liquid. Let  $u(x, t)$  g/cm be the density of the substance. The mass of it from  $[0, x]$  is

$$M = \int_0^x u(x', t) dx'. \tag{1}$$

The chemical substance moves from regions of higher concentration to regions of lower concentration. By Fick's law of diffusion, the rate of motion is proportional to the concentration gradient.

$$\frac{dM}{dt} = \text{flowin} - \text{flowout} = k(u_x(x, t) - u_x(0, t)), \tag{2}$$

where  $k$  is a proportionally constant. So (1) and (2) give the identity

$$\int_0^x u_t(x', t) dx' = k(u_x(x, t) - u_x(0, t)).$$

Differentiating with respect to  $x$ , we get

$$u_t = ku_{xx}.$$

This is the **diffusion** equation.  $\square$

**Example 5.** Heat Flow and the Laplace equation.

*Proof.* Let  $u(x, y, z, t)$  be the temperature and  $H(t)$  be the amount of heat contained in the region  $D$ . Then

$$H(t) = \iiint_D c\rho u dx dy dz,$$

where  $c$  is the “specific heat” of the material and  $\rho$  is its density (mass per unit volume). The change of the heat energy in  $D$  is

$$\frac{dH}{dt} = \iiint_D c\rho u_t dx dy dz \quad (3)$$

On the other hand, Fourier’s law says the heat flows from hot to cold regions proportionately to the temperature gradient. But the heat cannot be lost from  $D$  except by leaving it through the boundary. This is the law of conservation of energy. Therefore, the change of heat energy in  $D$  also equals the heat flux across the boundary,

$$\frac{dH}{dt} = \iint_{\partial D} k(\nabla u \cdot \nu) dS,$$

where  $k$  is a heat conductivity and  $\nu$  is the out normal vector of  $\partial D$ .

Denote  $\Delta u := u_{xx} + u_{yy} + u_{zz}$ .

By divergence theorem,

$$\iint_{\partial D} k(\nabla u \cdot \nu) dS = \iiint_D k\Delta u dx dy dz. \quad (4)$$

Thus (3) and (4) give us the **heat** equation

$$u_t = \frac{k}{c\rho} \Delta u.$$

This is the same as the diffusion equation!

In a situation where the physical state does not change with time. Then  $u_t = 0$ , the heat equation reduce to the Laplace equation

$$\Delta u = 0.$$

For example, the temperature of this room eventually reaches a steady state which satisfies the laplace equation.  $\square$

**Definition 6.** The **order** of an equation is the highest derivative that appears.

For example:  $u_x + u_t = 0$  is a first order PDE.  $u_{tt} - u_{xx} = 0$  is a second order PDE.  $u_{xxx} + u_t + uu_x = 0$  is a third order PDE.

The most general PDE in two independent variables of first order can be written as

$$F(x, y, u(x, y), u_x(x, y), u_y(x, y)) = F(x, y, u, u_x, u_y) = 0.$$

A **solution** of a PDE is a function  $u(x, y, \dots)$  that satisfies the equation identically, at least in some region of the  $x, y, \dots$  variables.

A **operator**  $\mathcal{L}$  means: if  $v$  is a function  $\mathcal{L}v$  is a new function. For instance  $\mathcal{L} = \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$  is the operator that takes  $v$  into  $v_x + v_y$ .

**Definition 7.** Linearity: for any functions  $u$  and  $v$  and any constant  $c$  if  $\mathcal{L}$  satisfy

$$\mathcal{L}(u + v) = \mathcal{L}u + \mathcal{L}v,$$

and

$$\mathcal{L}(cu) = c\mathcal{L}(u).$$

We call  $\mathcal{L}$  is a linear operator.

The equation

$$\mathcal{L}u = 0 \tag{5}$$

is a linear PDE if  $\mathcal{L}$  is a linear operator.

**Example 8.**  $u_{xxx} + u_t + uu_x = 0$  is not linear equation. Because the operator  $\mathcal{L}u = \frac{\partial^3 u}{\partial x^3} + \frac{\partial}{\partial t}u + u\frac{\partial}{\partial x}u$  is not a linear operator.

$$\begin{aligned} \mathcal{L}(u + v) &= \frac{\partial^3(u + v)}{\partial x^3} + \frac{\partial}{\partial t}(u + v) + (u + v)\frac{\partial}{\partial x}(u + v), \\ \mathcal{L}u + \mathcal{L}v &= \frac{\partial^3 u}{\partial x^3} + \frac{\partial u}{\partial t} + u\frac{\partial u}{\partial x} + \frac{\partial^3 v}{\partial x^3} + \frac{\partial v}{\partial t} + v\frac{\partial v}{\partial x}, \\ \mathcal{L}(u + v) &\neq \mathcal{L}u + \mathcal{L}v. \end{aligned}$$

The equation (5) is called **homogeneous** linear equation. The equation

$$\mathcal{L}u = g,$$

where  $g \neq 0$  is a given function of the independent variables, is called an **inhomogeneous** linear equation.

The advantage of linearity for the equation  $\mathcal{L}u = 0$  is that

- if  $u, v$  are both solutions, so is  $au + bv$  for any  $a$  and  $b$  constants. This is sometimes called the Superposition principle.
- If you add a homogeneous solution to an inhomogeneous solution you get an inhomogeneous solution.