

## Nonsingular matrices & basis

Recall: A square matrix  $A \in M_{n \times n}$  is called nonsingular if  $N(A) = \{0\}$ .

Example:  $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  is nonsingular

•  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$  is singular.

Theorem:  $A$  is nonsingular if and only if the columns of  $A$  are a basis of  $\mathbb{R}^n$ .

(i.e., if  $A = [\vec{u}_1 | \dots | \vec{u}_n]$ ,  $\vec{u}_1, \dots, \vec{u}_n$  are a basis).

Proof: Show A nonsingular  $\Rightarrow \vec{u}_1, \dots, \vec{u}_n$  is a basis

Need to show 1)  $\langle \vec{u}_1, \dots, \vec{u}_n \rangle = \mathbb{R}^n$ .

2)  $\vec{u}_1, \dots, \vec{u}_n$  are linearly independent.

Let's start with 2):

Suppose  $a_1\vec{u}_1 + \dots + a_n\vec{u}_n = 0_n$ .

We have  $a_1\vec{u}_1 + \dots + a_n\vec{u}_n = A \cdot \vec{x}$

where  $\vec{x} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}$ .

So  $\vec{x} \in N(A) \Rightarrow \vec{x} = 0_n$  by assumption

$$\Rightarrow a_1 = a_2 = \dots = a_n = 0. \checkmark$$

Now let's show 1).

We need to show that for all  $\vec{v} \in \mathbb{R}^n$ ,

$$\exists a_1, \dots, a_n \text{ s.t. } a_1 \vec{u}_1 + \dots + a_n \vec{u}_n = \vec{v}.$$

$$\Leftrightarrow \exists \vec{x} \in \mathbb{R}^n \text{ s.t. } A \vec{x} = \vec{v}. (\vec{x} = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix}).$$

$$A \xrightarrow{\text{RREF}} B \quad \text{so } \mathcal{N}(A) = N(B).$$

It follows that  $B$  has no zero rows.

$$\Rightarrow B \vec{y} = \vec{v} \quad \text{always has a solution}$$
  
$$\vec{y}$$

$$\Rightarrow A \vec{x} = \vec{v} \quad \text{always has a solution } \vec{x}. \checkmark$$

We conclude that if  $A$  is nonsingular,  
then  $\vec{u}_1, \dots, \vec{u}_n$  are a basis of  $\mathbb{R}^n$ .

We leave the converse ( $\vec{u}_1, \dots, \vec{u}_n$  are basis  
 $\Rightarrow A$  nonsingular)

as an exercise.

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Consequence: let  $\vec{u}_1, \dots, \vec{u}_n \in \mathbb{R}^n$ . To check if

$\vec{u}_1, \dots, \vec{u}_n$  is a basis, let

$$A = [\vec{u}_1 | \dots | \vec{u}_n].$$

Perform row reduction  $A \xrightarrow{\text{RREF}} B$ .

Check that  $B$  has no zero rows  $\equiv I_n$ .

Example: Verify that  $\vec{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\vec{u}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ ,  $\vec{u}_3 = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}$

is a basis of  $\mathbb{R}^3$ .

Proof: let  $A = [\vec{u}_1 | \vec{u}_2 | \vec{u}_3] = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$  <sup>RREF</sup>  $\rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   
~~\* no zero rows ✓~~



Theorem: Suppose  $A \in M_{n \times n}$  is non-singular.

Let  $\vec{u}_1, \dots, \vec{u}_n$  be a basis of  $\mathbb{R}^n$

(not necessarily having any relation to A).

Then  $A\vec{u}_1, \dots, A\vec{u}_n$  is also a

basis of  $\mathbb{R}^n$ .

Proof: Consider  $B = [A\vec{u}_1 | \dots | A\vec{u}_n]$ .

$A\vec{u}_1, \dots, A\vec{u}_n$  is a basis if and only if

$$\mathcal{N}(B) = \{0_n\}$$

Let  $C = [\vec{u}_1 | \dots | \vec{u}_n]$ . Since  $\vec{u}_1, \dots, \vec{u}_n$  is a basis,  
 $\mathcal{N}(C) = \{0_n\}$ .

But,  $B = A \cdot C$ .

Since  $A$  &  $C$  are nonsingular, so is  $B$ .

It follows that  $A\vec{u}_1, \dots, A\vec{u}_n$  is also a  
basis of  $\mathbb{R}^n$ .

Now suppose  $A \in M_{m \times n}$   $m < n$ .

$$A = \begin{bmatrix} \vdots \\ \tilde{u}_1 \\ \vdots \\ \tilde{u}_n \end{bmatrix}^n \cdots \begin{bmatrix} \vdots \\ \tilde{u}_1 \\ \vdots \\ \tilde{u}_n \end{bmatrix}^m.$$

As we have seen previously, the columns  $\tilde{u}_1, \dots, \tilde{u}_n$  of  $A$  are never a basis of  $\mathbb{R}^m$ .

Suppose instead  $A \in M_{m \times n}$   $m > n$ .

$$A = \begin{bmatrix} \vdots \\ \tilde{u}_1 \\ \vdots \\ \tilde{u}_n \end{bmatrix}^n \cdots \begin{bmatrix} \vdots \\ \tilde{u}_1 \\ \vdots \\ \tilde{u}_n \end{bmatrix}^m$$

Then  $\tilde{u}_1, \dots, \tilde{u}_n$  is never a basis of  $\mathbb{R}^m$ .

because.  $\langle \vec{u}_1, \dots, \vec{u}_n \rangle \neq \mathbb{R}^m$ .

Indeed, the equation  $A\vec{x} = \vec{b}$  does not always have a solution, because after row reduction  $A \xrightarrow{\text{REF}} \tilde{A}$ ,  $\tilde{B}$  will have zero rows.

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On the other hand, if  $\vec{u}_1, \dots, \vec{u}_n$  are linearly independent, then they are (by definition) a basis of the column space  $\langle A \rangle \subset \mathbb{R}^m$ .