

Pf of Thm 10: It is clear that we only need to show

the cases of $K=0, +1, -1$. And we may assume

$$M = \mathbb{R}^n, S^n \text{ or } H^n.$$

Case 1 : $K=0 \text{ or } -1$.

Since $K \leq 0$, Cartan-Hadamard \Rightarrow

$$\left\{ \begin{array}{l} \exp_x^M : T_x M \rightarrow M \\ \exp_y^N : T_y N \rightarrow N \end{array} \right. \quad \text{are diffeomorphisms.}$$

Let $\phi : T_x M \rightarrow T_y N$ be the unique isometry between
the inner product spaces $T_x M$ & $T_y N$ s.t.

$$\bar{\Phi}(e_i) = \varepsilon_i \quad \forall i=1, \dots, n.$$

Define $\varphi: M \rightarrow N$ by

$$T_x M \xrightarrow{\bar{\Phi}} T_y N$$

$$\varphi = \exp_y^N \circ \bar{\Phi} \circ (\exp_x^M)^{-1}$$

$$\begin{array}{ccc} \exp_x^M \downarrow & & \downarrow \exp_y^N \\ M & \longrightarrow & N \end{array}$$

Clearly φ is a diffeomorphism. We need to show

that φ is an isometry.

i.e. $\forall z \in M$ and $x \in T_z M$, we have

$$|d\varphi(x)|_N = |x|_M$$

By Cartan-Hadamard,

$$\exists \quad T \in T_x M \quad \text{and} \quad w \in T_T(T_x M) \cong T_x M \quad \text{s.t.}$$

$$z = \exp_x^M(T) \quad \text{and} \quad x = (\operatorname{dexp}_x^M)_T(w),$$

By the identification $T_T(T_x M) \cong T_x M$, we can define a 1-parameter family of geodesics

$$\gamma_u(t) = \exp_x^M [t(T + uw)].$$

Let $U(t)$ = transversal vector field of γ_u along γ_0 .
Then (from the fact (B) in the proof of Cartan-

Hadamard), $\mathcal{U}(t)$ is a Jacobi field s.t.

$$\begin{cases} \mathcal{U}(0) = 0 \\ \mathcal{U}'(0) = w \end{cases}$$

and further $\mathcal{U}(1) = (\underset{T}{d\exp_x^M})(w) = x$.

In N , we define correspondingly

$$\gamma_u^N(t) = \exp_y^N [t(\Phi(T) + u\Phi(w))]$$

& $\mathcal{U}^N(t) = \text{transversal vector field of } \{\gamma_u^N\}$
along γ_0^N .

Then \mathcal{U}^N is a Jacobi field along $\gamma_0^N \subset N$

S.t.

$$\begin{cases} U^N(0) = 0 \\ (U^N)'(0) = \Phi(w) \end{cases} .$$

Note that

$$\begin{aligned} \varphi(\gamma_u(t)) &= \exp_y^N \circ \underline{\Phi} \circ (\exp_x^M)^{-1} (\exp_x^M[t(T+uw)]) \\ &= \exp_y^N \circ \underline{\Phi} (t(T+uw)) \\ &= \exp_y^N [t(\Phi(T)+u\underline{\Phi}(w))] \\ &= \gamma_u^N(t) . \end{aligned}$$

$$\Rightarrow d\varphi(U(t)) = U^N(t) \quad (\text{by differentiation})$$

$$\Rightarrow U^N(1) = d\varphi(U(1)) = d\varphi(X) .$$

Therefore, what we need to show is

$$|\mathcal{U}^N(1)| = |\mathcal{U}(1)|.$$

To see this, we use parallel orthonormal frames

$\{e_1(t), \dots, e_n(t)\}$ & $\{\varepsilon_1(t), \dots, \varepsilon_n(t)\}$ along γ_0 and γ_0^N respectively s.t.

$$\begin{cases} e_i(0) = e_i & \forall i=1, \dots, n \\ \varepsilon_i(0) = \varepsilon_i \end{cases}$$

Then

$$\begin{cases} \mathcal{U}(t) = \sum_i f_i(t) e_i(t) & \text{for some functions} \\ \mathcal{U}^N(t) = \sum_i g_i(t) \varepsilon_i(t) & f_i(t) \& g_i(t) \end{cases}$$

Let $V_0(t) = \frac{\gamma'_0(t)}{|\gamma'_0(t)|}$, then

$$R_{\gamma'_0(t) U(t)} \gamma'_0(t) = |\gamma'_0(t)|^2 R_{V_0(t) U(t)} V_0(t)$$

$$(\text{Lemma 12}) = |\gamma'_0(t)|^2 K \left[U(t) - \langle U(t), V_0(t) \rangle V_0(t) \right]$$

$$\text{Since } \langle \gamma'_0(t), r'_0(t) \rangle = \langle \gamma'_0(0), \gamma'_0(0) \rangle = |T|^2$$

$$\langle \gamma'_0(t), e_i(t) \rangle = \langle T, e_i \rangle,$$

we have

$$U''(t) + R_{\gamma'_0(t) U(t)} \gamma'_0(t) = 0$$

$$\Leftrightarrow \sum f_i'' e_i + |r_0'|^2 \kappa \left[\sum f_i e_i - \frac{\langle \sum f_i e_i, r_0' \rangle r_0'}{|r_0'|^2} \right] = 0$$

$$\Leftrightarrow \sum (f_i'' + |\tau|^2 \kappa f_i) e_i - \kappa \sum f_i \langle e_i, r_0' \rangle r_0' = 0$$

$$\Leftrightarrow \sum (f_i'' + |\tau|^2 \kappa f_i) e_i - \kappa \sum f_i \langle e_i, \tau \rangle \sum \langle e_j, r_0' \rangle e_j = 0$$

$$\Leftrightarrow \sum_i (f_i'' + |\tau|^2 \kappa f_i) e_i - \kappa \sum_{i,j} f_i \langle e_i, \tau \rangle \langle e_j, \tau \rangle e_j = 0$$

$$\Leftrightarrow \sum_i \left[f_i'' + |\tau|^2 \kappa f_i - \kappa \sum_j f_j \langle e_j, \tau \rangle \langle e_i, \tau \rangle \right] e_i = 0$$

$$\Leftrightarrow f_i'' + \sum_j f_j \kappa [|\tau|^2 \delta_{ij} - \langle \tau, e_i \rangle \langle \tau, e_j \rangle] = 0, \quad \forall i=1 \dots n.$$

Furthermore $\nabla(0) = 0$ & $\nabla'(0) = w \Rightarrow$

$$\begin{cases} f_i(0) = 0 \\ f'_i(0) = \langle w, e_i \rangle \end{cases}$$

$$\therefore \begin{cases} f''_i + \sum_j f_j K [|\tau|^2 \delta_{ij} - \langle \tau, e_i \rangle \langle \tau, e_j \rangle] = 0, \\ f_i(0) = 0 \\ f'_i(0) = \langle w, e_i \rangle \end{cases}$$

Similarly, we have

$$\begin{cases} g''_i + \sum_j g_j K [|\underline{\Phi}(\tau)|^2 \delta_{ij} - \langle \underline{\Phi}(\tau), \varepsilon_i \rangle \langle \underline{\Phi}(\tau), \varepsilon_j \rangle] = 0, \\ g_i(0) = 0 \\ g'_i(0) = \langle \underline{\Phi}(w), \varepsilon_i \rangle \end{cases}$$

Using the fact Φ is an isometry (between inner product spaces $T_x M \times T_y N$) we have

$$\left\{ \begin{array}{l} |\Phi(T)|^2 = |T|^2 \\ \langle \Phi(T), e_i \rangle = \langle \Phi(T), \Phi(e_i) \rangle = \langle T, e_i \rangle \\ \langle \Phi(w), e_i \rangle = \langle w, e_i \rangle. \end{array} \right.$$

$\therefore \{f_i\}$ & $\{g_i\}$ satisfy the same IVP of an ODE system.

$$\Rightarrow f_i \equiv g_i, \forall t, \forall i=1, \dots, n.$$

Therefore $|U^N(1)|^2 = \sum_i g_i(1)^2 = \sum_i f_i(1)^2 = |U(1)|^2$

This completes the proof of the case that $k=0 \text{ or } 1$,

Case of $K=+1$

We may assume $M = S^n$.

If $\bar{x} = -x$ (the antipodal point of x), then

$(\exp_x^M)^{-1}: S^n \setminus \{\bar{x}\} \rightarrow T_x S^n$ is well-defined.

Therefore, we can define similarly the map

$$\varphi = \exp_y^N \circ \Phi \circ (\exp_x^M)^{-1}: S^n \setminus \{\bar{x}\} \rightarrow N.$$

Similar argument shows that φ is a local isometry
(not necessary global yet.)

Observe that $\forall z \in S^n \setminus \{x, \bar{x}\}$, we still have

$$\begin{array}{ccc}
 \overline{T_z S^n} & \xrightarrow{d\varphi} & T_{\varphi(z)} N \\
 (\exp_z^M)^{-1} \uparrow & \cong & \downarrow \exp_{\varphi(z)}^N \\
 S^n \setminus \{\bar{x}, \bar{z}\} & \xrightarrow{\varphi} & N
 \end{array}$$

as φ is a local isometry.

Note that $d\varphi|_{T_z S^n} : T_z S^n \rightarrow T_{\varphi(z)} N$ is an inner product space isometry, same argument above implies that

$$\varphi: S^n \setminus \{\bar{z}\} \rightarrow N$$

defined by $\varphi = \exp_{\varphi(z)}^N \circ d\varphi|_{T_z S^n} \circ (\exp_z^{S^n})^{-1}$

is a local isometry. By the above commutative diagram, $\forall p \in S^n \setminus \{\bar{x}, \bar{z}\}$

$$\varphi(p) = (\exp_{\varphi(z)}^N) \circ d\varphi \circ (\exp_z^{S^n})^{-1}(p)$$

$$= (\exp_{\varphi(z)}^N) \circ d\varphi|_{T_z S^n} \circ (\exp_z^{S^n})^{-1}(p)$$

$$= \varphi(p)$$

Therefore, we can extend φ to define on S^n by setting

$$\varphi(\bar{x}) = \psi(\bar{x}).$$

Then by construction $\varphi: S^n \rightarrow N$ is a local isometry.

Hence Lemma 8 \Rightarrow φ is a covering map. Since

N is simply-connected, φ has to be an isometry.

It is clear from the construction, $d\varphi(e_i) = \varepsilon_i$, $\forall i=1,\dots,n$.

So we've proved the existence part of Thm 10.

Finally, the uniqueness follows from:

Lemma 13: Let $\varphi_i: M \rightarrow N$, $i=1,2$ be 2 local isometries

between complete Riem. mfds M & N s.t. for some

$x \in M$, $\varphi_1(x) = \varphi_2(x)$ (in N) and

$$d\varphi_1|_{T_x M} = d\varphi_2|_{T_x M}.$$

Then $\varphi_1 = \varphi_2$.

Pf: Let $S = \{z \in M : \varphi_1(z) = \varphi_2(z) \text{ & } d\varphi_1|_{T_z M} = d\varphi_2|_{T_z M}\}$.

- By assumption, $x \in S$. $\therefore S \neq \emptyset$.
- It is clearly that S is closed by continuity.
- If $z \in S$, take $\delta > 0$ s.t.

$\exp_z^M : B(\delta) \rightarrow M$ is a diffeo. injection,

(where $B(\delta) = \{x \in T_z M : |x| < \delta\}$).

Recall that we have commutative diagram

$$\begin{array}{ccc} T_z M & \xrightarrow{d\varphi} & T_{\varphi(z)} N \\ \exp_z^M \downarrow & & \downarrow \exp_{\varphi(z)}^N \\ M & \xrightarrow{\varphi} & N \end{array}$$

A local isometry φ .

Applying this to φ_1 & φ_2 , we have

$$\exp_z^M(B(\delta)) \subset S. \quad (\text{Ex!})$$

$\Rightarrow S$ is open.

Therefore, by connectedness of $M \Rightarrow S = M$ ~~✓~~

This complete the proof of Thm 10. ~~✓~~

Crlt 4: Let M = complete simply-connected Riem. mfd of
 $\dim = n$.

Then M is a space form

$\Leftrightarrow \forall x, y \in M$ and

\forall orthonormal bases $\{e_i\}$ of $T_x M$ &
 $\{\varepsilon_i\}$ of $T_y M$,

\exists isometry $\varphi: M \rightarrow M$ s.t. $\varphi(x) = y$ and
 $d\varphi(e_i) = \varepsilon_i \quad \forall i$.

(Pf : Immediately from Thm 10)

Note : Ca 14 proves that simply-connected space form
is homogeneous. In fact, we have more

Ca 15 : Simply-connected space forms are two-points
homogeneous.

Def : M is called two-points homogeneous if

$\forall p_1, p_2, q_1, q_2 \in M$ with $d(p_1, p_2) = d(q_1, q_2)$,

\exists an isometry $\varphi: M \rightarrow M$ s.t.

$$\varphi(p_1) = q_1 \quad \& \quad \varphi(p_2) = q_2 .$$

Pf of Cor 15 :

Let p_1, p_2, q_1, q_2 be points in a simply-connected space form M s.t. $d(p_1, p_2) = d(q_1, q_2) = \alpha$.

Let $\xi, \tilde{\xi} : [0, \alpha] \rightarrow M$ be normalized geodesics s.t.

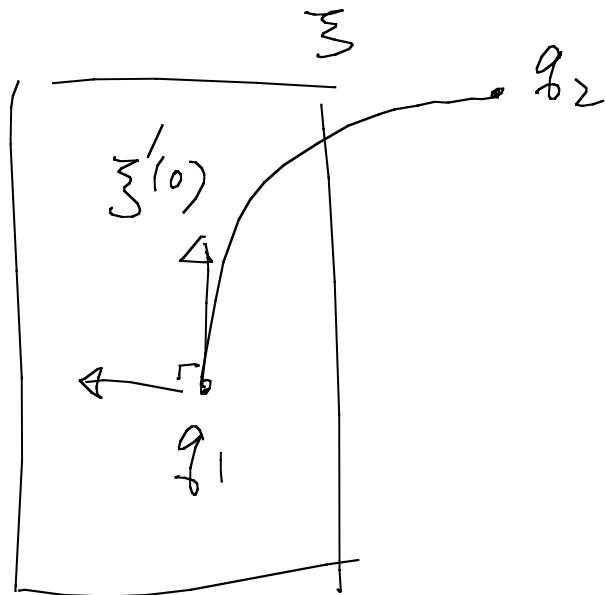
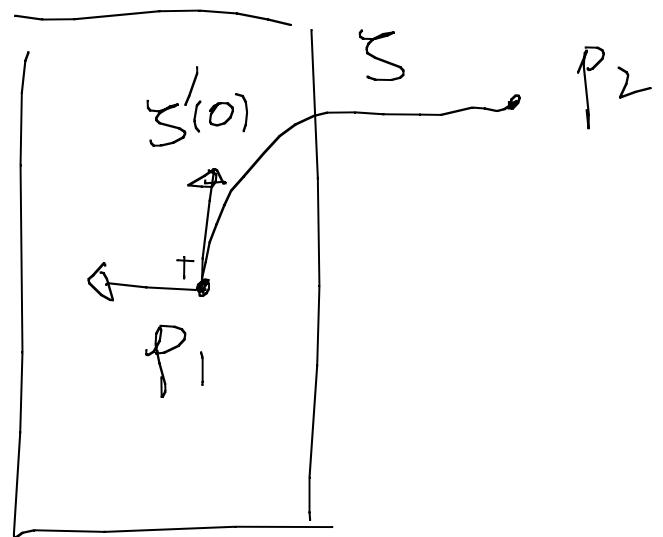
$$\xi(0) = p_1, \quad \xi(\alpha) = p_2$$

$$\tilde{\xi}(0) = q_1, \quad \tilde{\xi}(\alpha) = q_2$$

Choose orthonormal bases

$\{e_i\}$ on $T_{p_1}M$ s.t. $e_1 = \xi'(0)$ &

$\{e_i\}$ on $T_{q_1}M$ s.t. $e_1 = \tilde{\xi}'(0)$



Then Thm 10(a)(or 14) $\Rightarrow \exists$ isometry $\varphi: M \rightarrow M$

$$\text{s.t. } \varphi(p_1) = q_1 \quad \& \quad d\varphi(e_i) = \xi'_i$$

$\Rightarrow \varphi \circ \xi$ & ξ are geodesics with same initial data, hence $\varphi \circ \xi = \xi$.

$$\Rightarrow \varphi(p_2) = q_2 . \quad \#$$

Ch 7 The 1st & 2nd variation formula

Let • $M = \text{complete Riem. mfd}$

- $\gamma(t, u) : [a, b] \times [-\varepsilon, \varepsilon] \rightarrow M$ a C^∞ map,
- $\{\gamma_u(t)\}$ corresponding 1-parameter family of curves
with base curve γ_0 equal to a given curve
 $\gamma(t)$ parametrized by arc-length, i.e. $|\gamma'(t)| = 1$.
- \mathcal{U} = transversal vector field of $\{\gamma_u\}$
- T = tangent vector field along $\{\gamma_u\}$.

Then the length of $\gamma_u(t)$ is

$$L(u) = \int_a^b |\gamma'_u(t)| dt = \int_a^b |T| dt$$

$$\therefore \frac{dL}{du}(u) = \int_a^b \frac{d}{du} |T| dt$$

$$= \int_a^b \sqrt{\langle T, T \rangle} dt$$

$$= \int_a^b \frac{\langle T, D_u T \rangle}{|T|} dt$$

$$= \int_a^b \frac{1}{|T|} \langle T, D_T U \rangle dt \quad \text{since } [T, U] = 0$$

Putting $u=0$,

$$\frac{dL}{du}(0) = \int_a^b \langle \gamma'(t), D_{\gamma'(t)} U \rangle dt$$

$$= \int_a^b \left[\frac{d}{dt} \langle \gamma'(t), U \rangle - \langle D_{\gamma'(t)} \gamma'(t), U \rangle \right] dt$$

where $U(t) = U(t, 0)$ is the transversal vector field along γ .

$$\Rightarrow \boxed{\frac{dL}{du}(0) = \left. \langle \gamma'(t), U(t) \rangle \right|_a^b - \int_a^b \langle D_{\gamma'(t)} \gamma'(t), U(t) \rangle dt}$$

which is the 1st variation formula for arc-length.

Lemma 1 : A curve $\gamma: [a, b] \rightarrow M$ is a geodesic if and only if it is a critical point of the arc-length functional with

respect to normal variations $\{\gamma_u\}$ (i.e. $\forall u$,

$$\gamma_u(a) = \gamma(a) \quad \& \quad \gamma_u(b) = \gamma(b).$$
)

Pf: For normal variations, $U(a) = U(b) = 0$

$$\therefore \frac{dL}{du}(0) = - \int_a^b \langle D_{\gamma'} \gamma', U \rangle dt$$

$\forall U$ with $U(a) = U(b) = 0$.

$$\therefore 0 = \frac{dL}{du}(0) \Leftrightarrow D_{\gamma'} \gamma' = 0 \quad (\text{Ex!})$$

~~X~~

Lemma 2: Let $\circ N$ = closed submanifold of M

- $x \notin N$
- $y \in N$ s.t.

$$d(x, y) = d(x, N) \stackrel{\text{def}}{=} \inf \{d(x, y) : y \in N\}$$

$\gamma: [a, b] \rightarrow M$ shortest geodesic joining x to y .

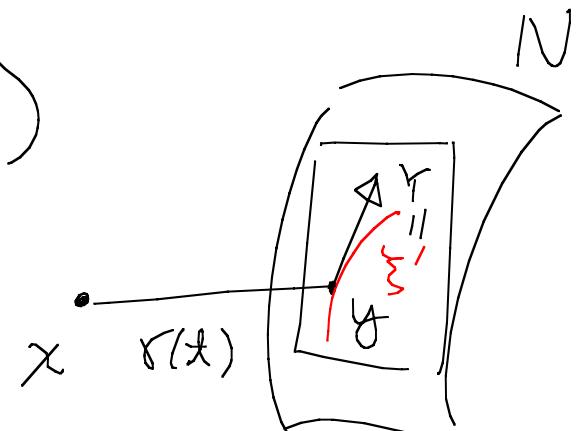
Then γ is normal to N (ie. $\gamma'(b) \perp T_y N$).

Pf: Let $Y \in T_y N$. We need to show that $\langle \gamma'(b), Y \rangle = 0$.

For this, take a C^∞ curve $\xi: [-\varepsilon, \varepsilon] \rightarrow N$ s.t.

$$\xi'(0) = Y \quad (\xi(0) = y)$$

Let $\{\gamma_u\}$ be a 1-parameter family of curves given by



$\gamma(t, u) = [a, b] \times [-\varepsilon, \varepsilon] \rightarrow M$ with

$$\begin{cases} \gamma_0(t) = \gamma(t), & \forall t \in [a, b] \\ \gamma_u(a) = x, & \forall u \\ \gamma_u(b) = \xi(u). \end{cases}$$

By assumption

$$L(0) = d(x, y) \leq d(x, \xi(u)) \leq L(u), \quad \forall u \in [-\varepsilon, \varepsilon]$$

$$\Rightarrow \frac{dL}{du}(0) = 0.$$

1st variation formula \Rightarrow

$$\begin{aligned} 0 &= \langle \gamma'(t), \tau \rangle \Big|_a^b - \int_a^b \cancel{\langle D_{\gamma} \gamma', \tau \rangle} dt \\ &= \langle \gamma'(b), \tau \rangle - \langle \gamma'(a), \tau \rangle \quad (\text{since } \gamma \text{ is a geodesic}) \end{aligned}$$

Note that

$$U(a) = 0 \quad *$$

$$U(b) = \left. \frac{\partial}{\partial u} \right|_{u=0} \gamma_u(b) = \left. \frac{d}{du} \right|_{u=0} \gamma(u) = \gamma'(0) = Y.$$

- - - $\langle \gamma'(b), Y \rangle = 0$ ~~*~~

Now suppose that $\gamma: [a, b] \rightarrow M$ is a normalized geodesic.

We would like to calculate $\frac{d^2 L}{du^2}(0)$ for the family $\{\gamma_u\}$.

We've proved that

$$\frac{dL}{du}(u) = \int_a^b \frac{1}{|\dot{\gamma}|} \langle T, D_T U \rangle dt$$

$$\begin{aligned}
\Rightarrow \frac{d^2L}{du^2}(u) &= \int_a^b \frac{d}{du} \left[\frac{1}{|T|} \langle T, D_T U \rangle \right] dt \\
&= \int_a^b \left\{ -\frac{1}{|T|^3} \langle T, D_T U \rangle^2 + \frac{1}{|T|} U \langle T, D_T U \rangle \right\} dt \\
&= \int_a^b \left\{ -\frac{1}{|T|^3} \langle T, D_T U \rangle^2 + \frac{1}{|T|} \langle D_U T, D_T U \rangle + \frac{1}{|T|} \langle T, D_U D_T U \rangle \right\} dt \\
&= \int_a^b \left\{ -\frac{1}{|T|^3} \langle T, D_T U \rangle^2 + \frac{1}{|T|} |D_T U|^2 + \frac{1}{|T|} \langle T, D_T D_U U + R_{TU} U \rangle \right\} dt \\
&\quad \text{(since } \langle U, T \rangle = 0 \text{)}
\end{aligned}$$

$$= \int_a^b \left\{ -\frac{1}{|T|^3} [T \langle T, U \rangle - \langle D_T T, U \rangle]^2 + \frac{1}{|T|} |D_T U|^2 + \frac{1}{|T|} \langle T, D_T D_U U \rangle - \frac{1}{|T|} \langle R_{U T} U, T \rangle \right\} dt$$

Note that at $u=0$, $D_T T = D_r \gamma' = 0$
 $|T| = |\gamma'| = 1$.

$$\Rightarrow \frac{d^2 L}{du^2}(0) = \int_a^b \left\{ - \left[\frac{d}{dt} \langle \gamma', U \rangle \right]^2 + |U'|^2 + \langle \gamma', D_r D_U U \rangle - \langle R_{U \gamma'} U, \gamma' \rangle \right\} dt$$

where $U' = D_r U$.

$$\Rightarrow \frac{d^2 L}{du^2}(0) = \int_a^b \left\{ - \left[\frac{d}{dt} \langle \gamma', U \rangle \right]^2 + \frac{d}{dt} \langle \gamma', D_U U \rangle + |U'|^2 - \langle R_{U \gamma'} U, \gamma' \rangle \right\} dt$$

$$\frac{d^2L}{du^2}(0) = \langle \gamma', D_u U \rangle \Big|_a^b + \int_a^b \left\{ (|U'|^2 - \left[\frac{d}{dt} \langle \gamma', U \rangle \right]^2) - \langle R_{U\gamma}, U, \gamma' \rangle \right\} dt$$

which is the 2nd variation formula.

Let $U^\perp = U - \langle U, \gamma' \rangle \gamma'$ the normal component of U ,
 then the 2nd variation formula can be written as

$$\frac{d^2L}{du^2}(0) = \langle \gamma', D_u U \rangle \Big|_a^b + \int_a^b \left\{ |D_\gamma U^\perp|^2 - \langle R_{U^\perp \gamma}, U^\perp, \gamma' \rangle \right\} dt$$

(Ex!)

Note : If $\{\gamma_u\}$ is normal in the sense that

$$\gamma_u(a) = \gamma(a), \quad \gamma_u(b) = \gamma(b),$$

then $\langle \gamma', D_v U \rangle(a) = \langle \gamma', D_v U \rangle(b) = 0$.

- If $\{\gamma_u\}$ is a 1-parameter of (smooth) closed curves,

then $\langle \gamma', D_v U \rangle \Big|_a^b = 0$

- The interior term $\int_a^b \left[|D_{\gamma} U^\perp|^2 - \langle R_{U^\perp}, U', \gamma' \rangle \right] dt$

$$= \int_a^b \left[|D_{\gamma'} U^\perp|^2 - \langle R_{\gamma' U^\perp} \gamma', U^\perp \rangle \right] dt$$

is related to the Jacobi Operator on U^\perp (provided a right bdy condition)
(Ex!)