

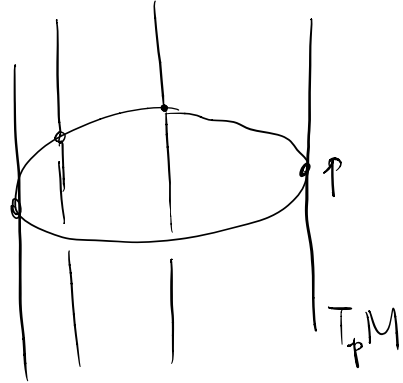
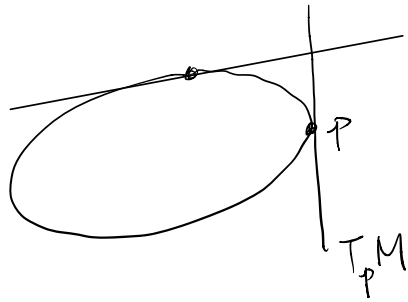
- Notes:
- In def 1, a tangent vector is represented by a curve γ . We usually write $\gamma'(0)$ for the tangent vector $[\gamma]$ for simplicity. (independent of chart!)
 - In def 2, the "same" tangent vector will be represented in a chart (U, ϕ) by a vector $u \in \mathbb{R}^n$.
 - Def 1 \Leftrightarrow Def 2 by taking $u = (\phi \circ \gamma)'(0)$.

Notation: The set of tangent vectors to M at p is denoted by $T_p M$ (Tangent space to M at $p \in M$)

Note: If a chart (U, ϕ) is given, then we have an "isomorphism"

$$\begin{array}{ccc} \theta_{U, \phi, p} : \mathbb{R}^n & \longrightarrow & T_p M \\ \downarrow & & \downarrow \\ u & \longmapsto & [(U, \phi, u)] \end{array}$$

Def: The disjoint union TM of $T_p M$, $\forall p \in M$, is called the tangent bundle of M .



Thm: Let M be an n -dim'd C^k manifold ($k > 1$).

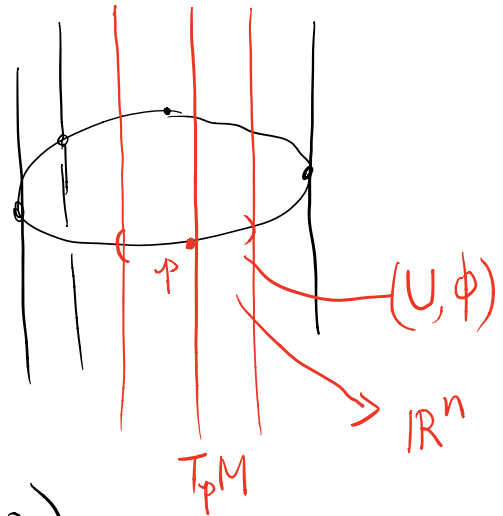
Then TM can be equipped with a $2n$ -dim'd
 C^{k-1} abstract manifold structure.

Pf: (Sketch)

For each chart (U, ϕ) of M ,

define a "chart"

$$\left(\bigsqcup_{p \in U} T_p M, \bar{\Phi} \right) \text{ for } TM$$



by

$$\bar{\Phi}(\xi_p) = \left(\phi(p), \theta_{U, \phi, p}^{-1}(\xi_p) \right) \in \mathbb{R}^n \times \mathbb{R}^n$$

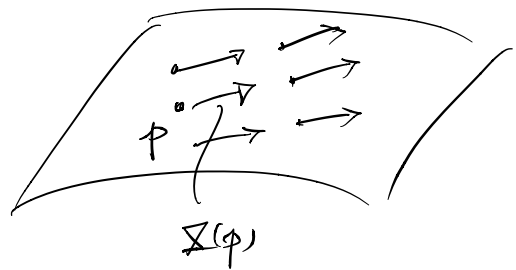
$$\forall \xi_p \in T_p M, p \in U.$$

then one can see all these " $\coprod_{p \in U} T_p M$ " give a topology on TM such that Φ are homeomorphisms. And one can check that TM is Hausdorff and $\left\{ \left(\coprod_{p \in U} T_p M, \Phi \right) \right\}_{(U, \phi)}$ forms a C^{k-1} atlas of TM . (We've differentiated once in the equi. relation for tangent vectors.) ~~✗~~

Def: A (smooth) vector field \mathcal{X} on a manifold M is a smooth section of the tangent bundle TM of M , i.e.

$\mathcal{X} : M \rightarrow TM$ is a smooth map such that $\mathcal{X}(p) \in T_p M$.

• The set of (smooth) vector fields on M is denoted by $\Gamma(TM)$.

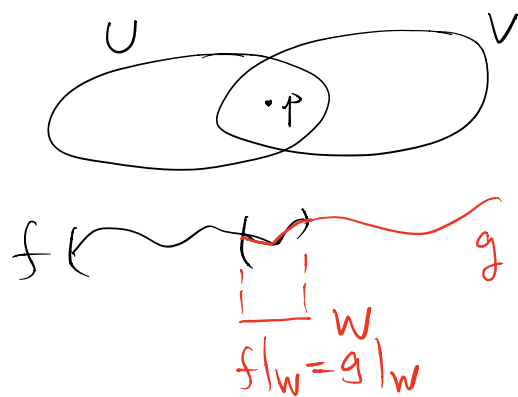


1.5 Tangent vectors as derivations

Let M be a smooth manifold, $p \in M$, consider C^∞ functions defined in a nbd. of p . Then we can define an equivalence relation:

$$f: U \rightarrow \mathbb{R} \sim g: V \rightarrow \mathbb{R} \quad (p \in U \cap V)$$

$$\Leftrightarrow \exists \text{ nbd } W \subset U \cap V \text{ of } p \text{ s.t. } f|_W = g|_W$$



Def: The equivalence classes for this relation are the germs of C^∞ functions at p . The space of germs of C^∞ functions at p is denoted by $\mathcal{L}_p^\infty(M)$.

Similarly, we can define $\mathcal{L}_p^0(M)$, $\mathcal{L}_p^k(M)$ & $\mathcal{L}_p^\omega(M)$ germs of constants, C^k , and (real) analytic functions

respectively at p .

Remarks : • Space of functions has linear structure
(and a product structure)

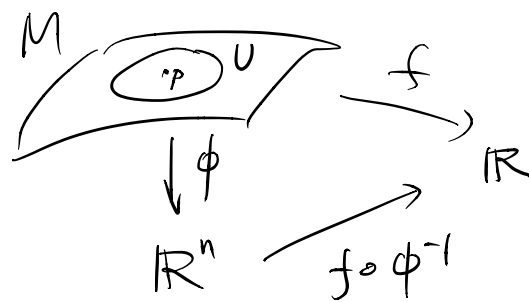
\Rightarrow corresponding space of germs is a
vector space (with a product structure)

• If M is a C^k manifold ($0 \leq k \leq \infty$)

then $\mathcal{E}_p^k(M) \cong \mathcal{E}_0^k(\mathbb{R}^n)$ (vector space
isomorphism)

Pf: (Sketch)

germ of $f \leftrightarrow$ germ of $f \circ \phi^{-1}$
for a chart (U, ϕ)



Def: A derivation on $\mathcal{E}_p^k(M)$ is a linear map

$\delta: \mathcal{E}_p^k(M) \rightarrow \mathbb{R}$ such that $\forall f, g \in \mathcal{E}_p^k(M)$

$$\delta(fg) = f(p) \delta(g) + g(p) \delta(f).$$

where $fg =$ product of the germs $f \approx g$

(Ex: How to define fg ?)

Notation: We denote the set of derivations on $\mathcal{E}_p^k(M)$ by $\mathcal{D}_p^k(M)$, or $\mathcal{D}_p(M)$ if k is clear.

Thm: Any derivation of $\mathcal{E}_0^\infty(\mathbb{R}^n)$ can be written

as

$$\delta(f) = \sum_{j=1}^n \delta(x^j) \frac{\partial f}{\partial x^j}(0)$$

germ \nearrow is a function representing the germ f .

Hence $\dim(\mathcal{D}_0^\infty(\mathbb{R}^n)) = n$

(where $x^j =$ germ of the coordinate function

$$x^j: \mathbb{R}^n \rightarrow \mathbb{R}$$
$$\left(\begin{matrix} x^1 \\ \vdots \\ x^n \end{matrix} \right) \mapsto x^j$$

Pf: \forall germ $f \in \mathcal{E}_0^\infty(\mathbb{R})$, f is represented by a C^∞ function, denoted by f again, in a nbd. of 0.

Then $f(x) - f(0) = \int_0^1 \frac{d}{dt} f(tx) dt$

$$\begin{aligned}
&= \int_0^1 \sum_{j=1}^n \frac{\partial f}{\partial x^j}(tx) x^j dt \\
&= \sum_{j=1}^n x^j h_j(x)
\end{aligned}$$

where $h_j(x) = \int_0^1 \frac{\partial f}{\partial x^j}(tx) dt \in C^\infty$.

Then $\delta(f) = \delta(f - f(0))$ since $\delta(\text{const.}) = 0$
 (Ex!)

$$\begin{aligned}
&= \delta\left(\sum_{j=1}^n x^j h_j(x)\right) \\
&= \sum_{j=1}^n \cancel{x^j(0)} \delta(h_j) + h_j(0) \delta(x^j) \\
&= \sum_{j=1}^n \delta(x^j) \frac{\partial f}{\partial x^j}(0) \quad \text{X}
\end{aligned}$$

Lemma $\forall \xi \in T_p M$, $L_\xi(f) \stackrel{\text{def}}{=} (D_p f)(\xi)$, $\forall f \in C_p^\infty(M)$.

Then $L_\xi \in \mathcal{D}_p(M)$.

(Pf: Ex!) (Where $D_p f$ is the differential of a representation of f defined similarly as in Diff. Geom using def 1 of vecta.)

Thm : $T_p M \rightarrow \mathcal{D}_p(M)$ is an isomorphism
 (between vector spaces)

$$\begin{array}{ccc} \zeta & \mapsto & L_\zeta \end{array}$$

Pf : • $\zeta \mapsto L_\zeta$ is clear linear.

• $\ker(\zeta \mapsto L_\zeta) = 0$

Pf : Let (U, ϕ) be a chart for M around p
 with $\phi(p) = 0 \in \mathbb{R}^n$. Then ζ can
 be represented by $\zeta = (U, \phi, u)$
 with $u \in T_0 \mathbb{R}^n \cong \mathbb{R}^n$.

$\Rightarrow \forall C^\infty$ function f in a nbd around p

$$L_\zeta f = D_0(f \circ \phi^{-1})(u) \quad (\text{Fix!})$$

$$= \sum_{j=1}^n u^j \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(0)$$

(where $u = (u^1, \dots, u^n)$)

If $\zeta \in \ker(\zeta \mapsto L_\zeta)$, then $\forall f$

$$0 = \sum_{j=1}^n u^j \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(0)$$

$$\Rightarrow u^j = 0, \forall j \Rightarrow \zeta = 0 \quad \times$$

• Finally $\text{Im}(\xi \mapsto L_\xi) = \mathcal{D}_p(M)$.

Pf: $\forall \delta \in \mathcal{D}_p(M) \cong \mathcal{D}_0(\mathbb{R}^n)$, by previous Thm

$$\Rightarrow \delta(f) = \sum_{j=1}^n \delta(x^j) \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(0)$$

$$\therefore \delta = L_\xi \text{ for } \xi = \left[(U, \phi, \begin{pmatrix} \delta(x^1) \\ \vdots \\ \delta(x^n) \end{pmatrix}) \right] \in T_p M$$

*

Remark: In particular, we have $\dim T_p M = n$ with basis corresponds to $\left\{ \frac{\partial}{\partial x^j} \Big|_0 \right\}$ in local coordinates

$$\left(\text{where } \frac{\partial}{\partial x^j} \Big|_0 \in \mathcal{D}_0(\mathbb{R}^n) \text{ s.t. } \begin{pmatrix} \delta(x^1) \\ \vdots \\ \delta(x^n) \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \begin{matrix} \text{jth} \\ \leftarrow \text{place} \end{matrix} \right)$$

Convention: If (U, ϕ) is a chart around p , and (x^1, \dots, x^n) are the corresponding coordinate functions

$$x^j: U \xrightarrow{\phi} \mathbb{R}^n \xrightarrow{\pi_j} \mathbb{R}$$

We denote $\left(\frac{\partial}{\partial x^j} \right)_p (f) \stackrel{\text{def}}{=} \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(\phi(0))$

In this notation $L_\xi = \sum_{j=1}^n u^j \left(\frac{\partial}{\partial x^j} \right)_p$ for $\xi = [(U, \phi, u)] \in T_p M$.

Hence $\left(\frac{\partial}{\partial x^j}\right)_p$ can be regarded as a vector in $T_p M$;

$\Rightarrow \frac{\partial}{\partial x^j}$ is a vector field on $U \subset M$.

If $\mathbb{X}^1, \dots, \mathbb{X}^n$ are smooth functions, then

$$\mathbb{X} = \sum_{j=1}^n \mathbb{X}^j \frac{\partial}{\partial x^j} \quad \text{is a vector field on } U$$

corresponds to

$L_{\mathbb{X}} : C^\infty(U) \rightarrow C^\infty(U)$ defined by

$$(L_{\mathbb{X}} f)(p) = \sum_{j=1}^n \mathbb{X}^j(p) \left(\frac{\partial f}{\partial x^j}\right)_p.$$

Thm: The map $\mathbb{X} \mapsto L_{\mathbb{X}}$ is an isomorphism between the vector spaces $\Gamma(TM)$ and $\mathcal{D}(M)$, where

$\mathcal{D}(M)$ = set of derivations δ on M defined

by (i) $\delta : C^\infty(M) \rightarrow C^\infty(M)$ linear;

(ii) $\delta(fg) = f\delta(g) + g\delta(f)$.

(Pf = Omitted.)

(Caution: Analog statement for complex manifold is not true, since we need to use cut-off functions to reduce it to coordinate systems.)

Note: If $\delta_1, \delta_2 \in \mathcal{D}(M)$, then $\delta_1 \circ \delta_2 \notin \mathcal{D}(M)$

Lemma: If $\delta_1, \delta_2 \in \mathcal{D}(M)$, then

$$\delta_1 \circ \delta_2 - \delta_2 \circ \delta_1 \in \mathcal{D}(M).$$

(Pf: Ex!)

Def: Let X, Y be vector fields on M . Then $[X, Y]$, the bracket of X & Y , is the vector field corresponding to the derivation $L_X \circ L_Y - L_Y \circ L_X$,

i.e.
$$L_{[X, Y]} = L_X \circ L_Y - L_Y \circ L_X.$$

Local formula for $[X, Y]$:

If $X = \sum_{i=1}^n X^i \frac{\partial}{\partial x^i}$, $Y = \sum_{j=1}^n Y^j \frac{\partial}{\partial x^j}$ in some local

coordinates, then

$$L_X f = \sum_i X^i \frac{\partial f}{\partial x^i}$$

$$\Rightarrow L_Y L_X f = \sum_{i,j} Y^j X^i \frac{\partial^2 f}{\partial x^j \partial x^i} + X^j \frac{\partial X^i}{\partial x^j} \frac{\partial f}{\partial x^i}$$

Similar formula for $L_X L_Y$.

$$\Rightarrow (L_X L_Y - L_Y L_X) f = \sum_i \sum_j (X^j \frac{\partial X^i}{\partial x^j} - Y^j \frac{\partial X^i}{\partial x^j}) \frac{\partial f}{\partial x^i}$$

$$\Rightarrow \boxed{\begin{aligned} [\mathcal{X}, \mathcal{Y}] &= \sum_i \mathcal{Z}^i \frac{\partial}{\partial x^i} \\ \text{where } \mathcal{Z}^i &= \sum_j \left(\mathcal{X}^j \frac{\partial \mathcal{Y}^i}{\partial x^j} - \mathcal{Y}^j \frac{\partial \mathcal{X}^i}{\partial x^j} \right) \end{aligned}}$$

Lemma (Jacobi Identity) For vector fields $\mathcal{X}, \mathcal{Y}, \mathcal{Z}$,

$$[\mathcal{X}, [\mathcal{Y}, \mathcal{Z}]] + [\mathcal{Y}, [\mathcal{Z}, \mathcal{X}]] + [\mathcal{Z}, [\mathcal{X}, \mathcal{Y}]] = 0$$

(Pf: Trivial)

1.6 Vector Bundles and Tensors

Def: Let E & B be 2 smooth manifolds and

$\pi: E \rightarrow B$ be a smooth map.

(π, E, B) is a vector bundle of rank n ,

if • π is surjective.

• \exists open covering $(U_i)_{i \in \Lambda}$ of B , and

diffeomorphisms $h_i: \pi^{-1}(U_i) \rightarrow U_i \times \mathbb{R}^n$

such that $\forall x \in U_i, h_i(\pi^{-1}(x)) = \{x\} \times \mathbb{R}^n$

(hence $\pi^{-1}(x)$ can be regarded as a vector space.)

• and such that $\forall i, j \in \Lambda$, the diffeomorphism

$$h_i \circ h_j^{-1} : (U_i \cap U_j) \times \mathbb{R}^n \rightarrow (U_i \cap U_j) \times \mathbb{R}^n$$

are of the form

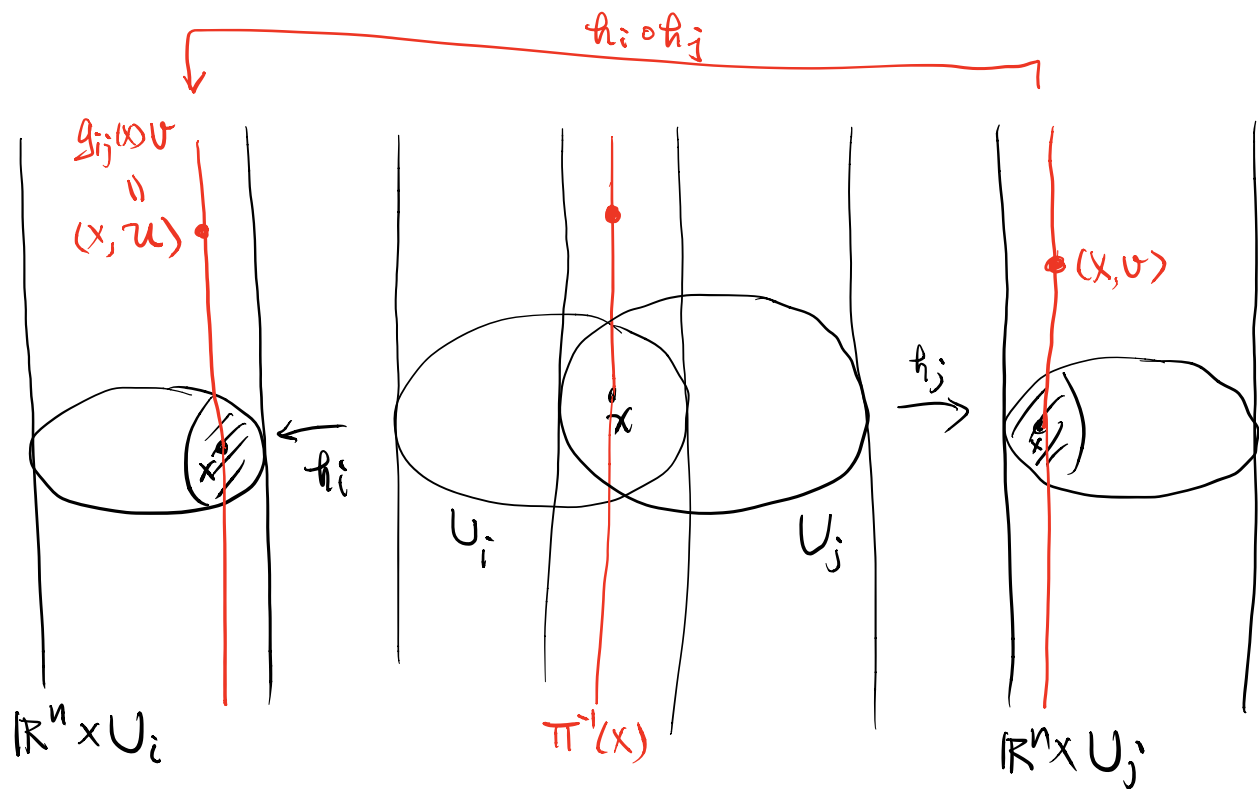
$$h_i \circ h_j^{-1}(x, v) = (x, g_{ij}(x)v)$$

where $g_{ij} : U_i \cap U_j \rightarrow GL(n, \mathbb{R})$.

Terminology: $E =$ total space, $B =$ base

$\mathbb{R}^n \simeq \pi^{-1}(x) =$ fibre

$h_i =$ local trivialization



eg: (Trivial Bundle): $\pi: M \times \mathbb{R}^n \rightarrow M$
 $(x, \vec{v}) \mapsto x$

eg: Tangent bundle of M : $TM = \coprod_{p \in M} T_p M$
 (exercise!)

Def: (a) A vector bundle of rank n , $\pi: E \rightarrow B$, is trivial if \exists is diffeomorphism

$$h: E \rightarrow B \times \mathbb{R}^n$$

s.t. $h|_{\pi^{-1}(x)} \rightarrow \{x\} \times \mathbb{R}^n$ is a vector space isomorphism.

(b) A (global) section of the bundle is a smooth map $s: B \rightarrow E$ such that

$$\pi \circ s = \text{id}$$

$$\begin{array}{c} E \\ \pi \downarrow \uparrow s \\ B \end{array}$$

eg: vector field $X \in \Gamma(M)$ ($= \Gamma(TM)$) is a section of the tangent bundle TM .

Tensor product

Def: Let E, F be 2 finite dimensional vector space,
then $E \otimes F$, the tensor product of E & F ,
is defined as the vector space, unique up to
isomorphism, such that \forall vector space G ,

$$L(E \otimes F, G) \stackrel{\text{isom}}{\cong} L_2(E \times F, G)$$

$\left(\begin{array}{l} \text{linear transformations} \\ \text{from } E \otimes F \text{ to } G \end{array} \right) \quad \left(\begin{array}{l} \text{bilinear maps from} \\ E \times F \text{ to } G \end{array} \right)$

Remark: \exists a bilinear map $\otimes: E \times F \rightarrow E \otimes F$
such that if $\{e_i\}$ = basis of E and
 $\{f_j\}$ = basis of F ,

then $\{e_i \otimes f_j\}_{i,j}$ is a basis of $E \otimes F$.

Hence for $u = \sum_i a^i e_i \in E$ and $v = \sum_j b^j f_j \in F$,

$$\text{then } u \otimes v = \sum_{i,j} a^i b^j e_i \otimes f_j.$$

Facts: (1) If $E^* = \text{dual of } E = L(E, \mathbb{R})$
 $F^* = \text{dual of } F$

then $E^* \otimes F^* \cong L_2(E \times F, \mathbb{R})$
 $\cong L(E \otimes F, \mathbb{R}) = (E \otimes F)^*$
 (by $\alpha \otimes \beta \longmapsto \alpha \otimes \beta(u \otimes v) = \alpha(u) \beta(v)$)

(2) If $\alpha \in L(E, E')$ & $\beta \in L(F, F')$
 (E, E', F, F' are finite dim'd vector spaces)
 then one can define

$$\alpha \otimes \beta \in L(E \otimes F, E' \otimes F')$$

by $(\alpha \otimes \beta)(u \otimes v) \stackrel{\text{def}}{=} \alpha(u) \otimes \beta(v)$.

(3) Given a vector bundle E (with fibers $E_x, x \in M$),
 one can define the vector bundle $E^*, \otimes^p E$
 (with fibers E_x^* and $\otimes^p E_x$ respectively)

(4) Given 2 vector bundles E, F (with fibers E_x, F_x)
 with the same base manifold M , we can define
 the vector bundle $E \otimes F$ over M with fiber
 $E_x \otimes F_x$.

eg: Starting from TM , we can define the cotangent bundle

T^*M of M , and the (p, q) -tensor bundle

$$\left(\otimes^p TM \right) \otimes \left(\otimes^q T^*M \right) \text{ of } M.$$

Def: A (p, q) -tensor (field), or more precisely

p times contravariant & q times covariant

tensor, on M is a smooth section of the bundle $\left(\otimes^p TM \right) \otimes \left(\otimes^q T^*M \right)$.

Note: For $f: M \rightarrow \mathbb{R}$ smooth, we can define

$$df \in \Gamma(T^*M) \text{ by } df(X) = L_X f \\ = Xf, \quad \forall X \in \Gamma(TM)$$

Then $\{dx^i\}_{i=1}^n$ is a dual (local) basis to

$$\left\{ \frac{\partial}{\partial x^i} \right\}_{i=1}^n \text{ since } dx^j \left(\frac{\partial}{\partial x^i} \right) = \frac{\partial x^j}{\partial x^i} = \delta_i^j$$

at each point in a coordinate system with coordinate functions (x^1, \dots, x^n) .

Therefore

$$\left\{ \frac{\partial}{\partial x^{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{j_p}} \otimes dx^{i_1} \otimes \dots \otimes dx^{i_q} \right\}$$

forms a local basis for $\left(\otimes^p TM \right) \otimes \left(\otimes^q T^*M \right)$

\Rightarrow in coordinates, a (p, q) -tensor (field) can be written as

$$T = T_{\substack{\hat{j}_1 \dots \hat{j}_p \\ \hat{i}_1 \dots \hat{i}_q}} \frac{\partial}{\partial x^{\hat{j}_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{\hat{j}_p}} \otimes dx^{\hat{i}_1} \otimes \dots \otimes dx^{\hat{i}_q}$$