

THE CHINESE UNIVERSITY OF HONG KONG
DEPARTMENT OF MATHEMATICS
MATH3070 (Second Term, 2016–2017)
Introduction to Topology
Pre-Notes 01 Metric

We choose to start the study of topology from a natural extension of absolute value or modulus between two numbers, that is, a distance measurement on a set. This provides an easy intuition of the study.

The concept of metric space is trivially motivated by the easiest example, the Euclidean space. Namely, the metric space (\mathbb{R}^n, d) with

$$d(x, y) = \|x - y\| = \left[\sum_{k=1}^n (x_k - y_k)^2 \right]^{1/2},$$

where $x = (x_1, \dots, x_n)$ and $y = (y_1, \dots, y_n)$. This is usually referred to as the *standard metric* on \mathbb{R}^n .

There are other metrics on \mathbb{R}^n , customarily called ℓ_p -metric, for $p \geq 1$, where

$$d_p(x, y) = \|x - y\|_p = \left[\sum_{k=1}^n (x_k - y_k)^p \right]^{1/p}.$$

In this sense, the standard metric is actually the ℓ_2 -metric. There is also the ℓ_∞ -metric given by

$$d_\infty(x, y) = \max \{|x_k - y_k| : k = 1, \dots, n\}.$$

Why can we say that ℓ_p and ℓ_∞ are also *valid* ways to measure distance? **What** are the essential properties?

Let X be a nonempty set. A *metric* on X is a function $d: X \times X \rightarrow [0, \infty)$, that is, $d(x, y) \geq 0$, satisfying the followings

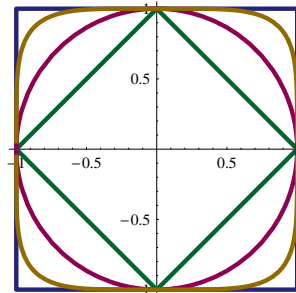
- $d(x, y) = 0$ if and only if $x = y$;
- $d(x, y) = d(y, x)$ for all $x, y \in X$;
- $d(x, y) + d(y, z) \geq d(x, z)$ for all $x, y, z \in X$.

The pair (X, d) is called a *metric space*.

The first criterion emphasizes that a zero distance is exactly equivalent to being the same point. The second symmetry criterion is natural. The third criterion is usually referred to as the *triangle inequality*. It turns out in most examples, the triangle inequality is the crucial one.

Try to verify the properties of metric in the cases of ℓ_p and ℓ_∞ . Note that the triangle inequality is satisfied by the ℓ_p -metric on \mathbb{R}^n for all $p \geq 1$ and $p = \infty$. There is something wrong when $0 < p < 1$.

Let us understand the ℓ_p -metric for different values of p by considering the pictures of the sets of radius 1, i.e., $\{x \in \mathbb{R}^n : d_p(x, 0) = 1\}$. The pictures of other radii are similar and they are convex when $p \geq 1$.



The pictures for $p = 1$ (green), $p = 2$ (purple), $p = 5$ (brown), and $p = \infty$ (blue).

Try to consider both analytically and geometrically why $0 < p < 1$ will not give a metric.

The *discrete metric* on any nonempty set X is defined by

$$d(x, y) = \begin{cases} 0 & \text{if } x = y, \\ 1 & \text{if } x \neq y. \end{cases}$$

That this defines a metric can be readily proved by verifying the criteria case by case. The discrete metric is kind of an uninteresting metric because any two distinct points will have a fixed distance afar. However, it often serves as an example to check certain property of a space.

Similarly, we can understand the discrete metric by **doing** the following exercise about sets of a certain radius. This is often a good way to understand a metric.

Let (X, d) be the discrete metric space and $x_0 \in X$. Determine the sets $\{x \in X : d(x, x_0) < r\}$ for different values of $r > 0$.

Metric can be defined on space of functions, although later you may find that it is sometimes not so successful. Similar to the situation of \mathbb{R}^n , there are several metrics on a function space. For simplicity, let $X = \mathcal{C}([a, b], \mathbb{R})$ be the set of all continuous real valued functions defined on an interval $[a, b]$. We have metrics d_p for $p \geq 1$ and $p = \infty$, namely, for $f, g \in X$,

$$d_p(f, g) = \left[\int_a^b |f(t) - g(t)|^p dt \right]^{1/p},$$

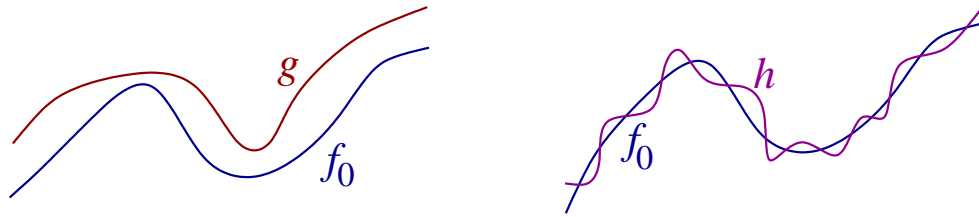
$$d_\infty(f, g) = \sup \{ |f(t) - g(t)| : t \in [a, b] \}.$$

The proof for that these are metrics is similar to the Euclidean cases. In fact, d_∞ is a metric on $\mathcal{B}([a, b], \mathbb{R})$, the set of bounded functions on $[a, b]$. However, there is difficulty extending d_p to a larger set of functions, even the functions are integrable.

A suitable choice of metric may have the effect of good comparison. Let X be the set of all continuously differentiable (C^1) functions on an interval $[a, b]$ and

$$d(f, g) = \sup \{ |f(t) - g(t)| : t \in [a, b] \} + \sup \{ |f'(t) - g'(t)| : t \in [a, b] \}.$$

With this choice of metric, for the functions illustrated below, $d(f, g) < d(f, h)$ because the contribution of derivatives $|f'(t) - h'(t)|$ is large.



To finish, we will give two examples. Both examples are related to error-correcting applications. You are encouraged to understand them by the two standard tasks: verify the metric conditions and think of the typical situation of $d(x, x_0) < r$.

Let $X = \{0, 1\}^n$, i.e., it contains points of n -coordinates of 0 and 1; $d(x, y)$ is the number of different coordinates between x and y .

Let X be the set of finite sequences of alphabets. For example, “homomorphic”, “homeomorphic”, “holomorphic”, “homotopic”, “homologous” are elements of X . Suppose there are three valid operations, inserting an alphabet, deleting an alphabet, and replacing an alphabet by another. For two elements $x, y \in X$, define $d_3(x, y)$ by the minimum number of operations required to transform x to y .

We may also consider replacing an alphabet equivalent to deleting then inserting. In this case, we only accept two types of operations and let $d_2(x, y)$ be the minimum number of such operations.