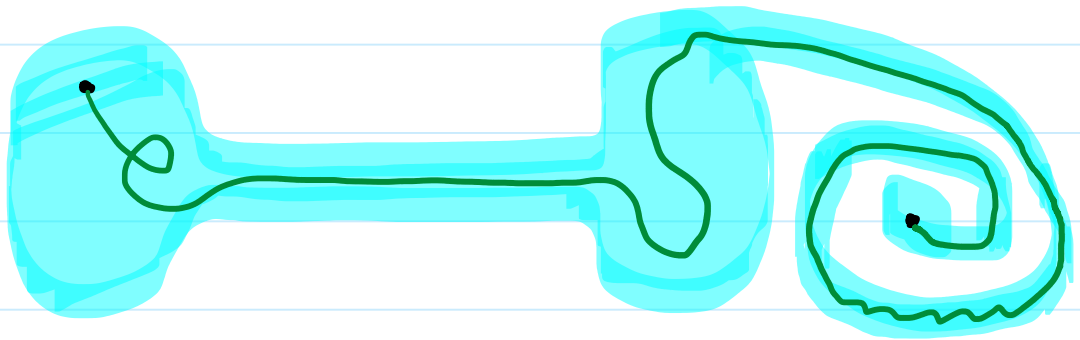
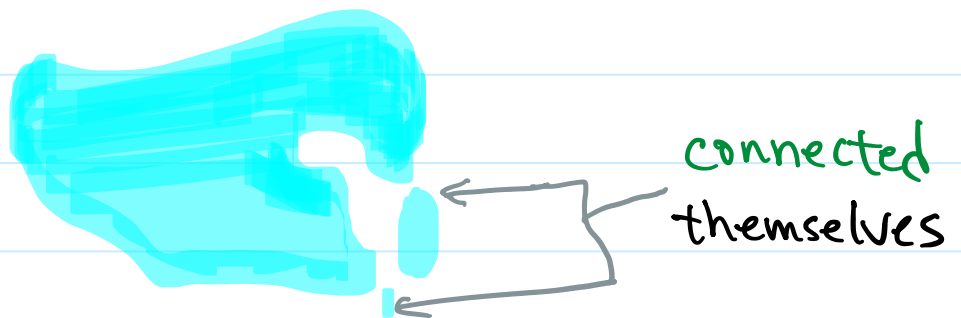


Three other connectedness

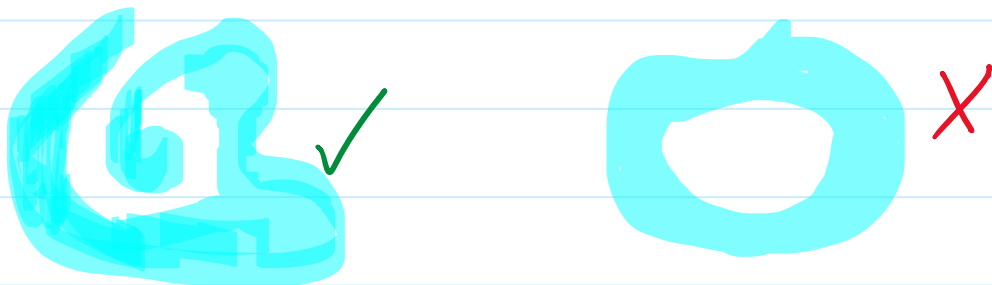
Path connected — stronger, more visual



Local connected — 本土意識



Simply connected — different from above



Definition. A space X is path connected if \forall pair $x, y \in X$, \exists continuous mapping $\gamma: [0, 1] \longrightarrow X$, $\gamma(0) = x$, $\gamma(1) = y$

Theorem. A path connected space is connected.

Proof. By contradiction, assume

$$\exists \emptyset \neq U \subsetneq X, U, X \setminus U \in \mathcal{J}$$

Then pick $x \in U$ and $y \in X \setminus U$ and

⋮

Then we can find a **nontivial** both open and closed subset in $[0, 1]$.

Contradiction

Exercise. Careful argument of above.

Definition. Let \sim be an equivalence relation on X that $x \sim y$ if \exists continuous $\gamma: [0, 1] \rightarrow X, \gamma(0) = x, \gamma(1) = y$.

For $x_0 \in X$, the equivalence class $[x_0]$ is the **path component** of x_0 .

Obviously, X is path connected $\iff X$ has exactly one path component.

Question. While path connected is connected,
Is path component = connected component?

Example. Again, $X = \bigcup G$ formed by
 $\sin \frac{1}{x}, x > 0$

一石二鳥

path component \neq connected component
connected \Rightarrow path connected

Theorem. Let $\emptyset \neq G \subset \mathbb{R}^n$ be an open set.
If G is connected then it is path connected.

Proof. Fix a point $x_0 \in G$ and consider
its path component P in G .

First, P is open.

Wish. $\forall x \in P, \exists$ ball $B, x \in B \subset P$

This is easy

Since G is open, \exists ball B , $x \in B \subset G$
 Only need to show $B \subset P$

Arbitrary $y \in B \Rightarrow y \in P$

B is a ball and $x, y \in B$,
 \exists straight line from x to y

Also, \exists continuous path from x_0 to x ,
 $\therefore \exists$ continuous path from x_0 to y
 and so $y \in P$.

By similar argument (exercise), $x \setminus P \in \emptyset$.

Thus, by connectedness of G ,

$$P = \emptyset \text{ or } P = G$$

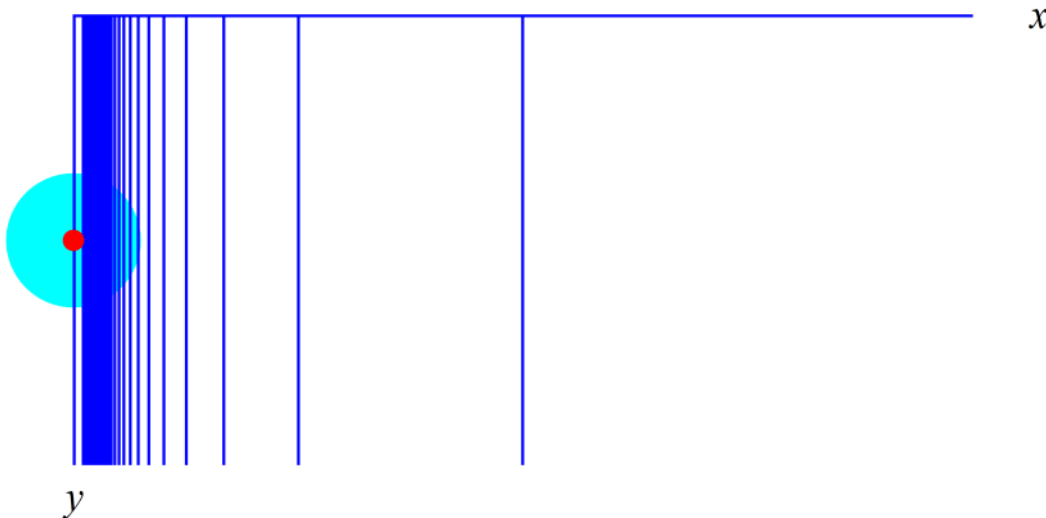
But $x_0 \in P$, $\therefore P = G$ is path connected

Exercise. Show that every pair $x, y \in G$ can be joined by a finite sequence of straight lines parallel to the coordinate axes.

Definition. A space X is **locally connected** if $\forall x \in X \exists$ a local base \mathcal{U}_x at x consisting of connected neighborhoods.

Clearly, locally connected $\not\Rightarrow$ connected
Just $(-\infty, 0) \cup (0, \infty)$ is an example.

Example. Let $F = X \cup Y \cup V \subset \mathbb{R}^2$ where
 $X = \{(x, 0) : 0 \leq x \in \mathbb{R}\} \subset x\text{-axis}$
 $Y = \{(0, y) : y \leq 0\} \subset y\text{-axis}$
 $V = \bigcup_{n=1}^{\infty} \left\{ \left(\frac{1}{n}, y\right) : y \leq 0 \right\}$



F is **clearly** path connected, and
so it is connected

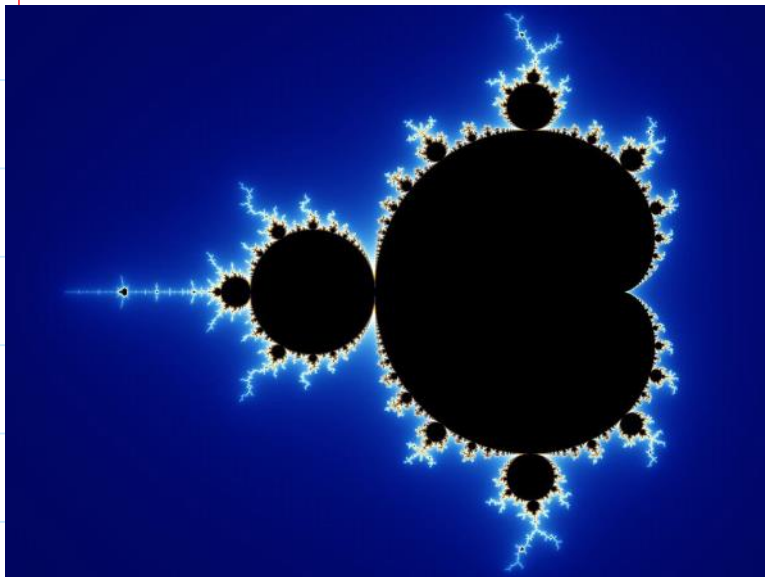
On the other hand, at any $(0, y)$, $y \neq 0$,
take $0 < \varepsilon = \frac{|y|}{2}$ and $U = (-\varepsilon, \varepsilon) \times (-\varepsilon, \varepsilon)$.

Then $U \cap F$ is a nbhd of $(0, y)$ in F

But, every sub-nbhd of $(0, y)$ in it
is disconnected.

Thus, F is **not** locally connected.

Example. This is called Mandelbrot Set $M \subset \mathbb{C}$.



$\zeta \in M$ if the
complex sequence
 $\zeta, \zeta^2 + \zeta,$
 $(\zeta^2 + \zeta)^2 + \zeta, \dots$
is bounded.

- It is connected (in fact, simply connected)
- Still, don't know if it is locally connected

Yoccoz, Fields Medal 1994

Proposition. Let X be locally connected.
Then each connected component is
both open and closed.

Not always true

known before

Infinitely many
components cluster
to one component
not open

A is connected

\Downarrow

\bar{A} is also.

Component is maximal

Proof. Let $G \subset X$ be a connected component
and $x \in G$ be arbitrary.

Take any nbhd of x , e.g., $x \in X \in J$

By local connectedness,

\exists connected U , $x \in \overset{\circ}{U} \subset U$

Since U is connected and G is maximal,
we have $U \subset G$. $\therefore x \in \overset{\circ}{U} \subset G$.

Hence, G must be open.

Example. Given \mathbb{R} and S^1 , both standard.

How do we know $\mathbb{R} \neq S^1$?

Reason. \mathbb{R} is non-compact, S^1 is compact.

That is, we used

Continuous image of compact space is compact

Example. What about $[0,1] \neq S^1$?

Argument. $[0,1] \setminus \{\frac{1}{2}\}$ is disconnected but
 $S^1 \setminus \{pt\}$ is connected.

↓ why?

$[0,1] \neq S^1$

We need something as below:

Continuous image of connected space is connected

AND

If $f: X \rightarrow Y$ is a homeomorphism, $f(x_0) = y_0$,
 then $f|_{X \setminus \{x_0\}}: X \setminus \{x_0\} \rightarrow Y \setminus \{y_0\}$ is
 a homeomorphism

Exercise

Exercise. Use similar technique to show
 that $S^2 \neq S^1 \times S^1$, both standard.

What's Underneath. For topological spaces

* Define $k(X) = \begin{cases} +1 & \text{if } X \text{ is compact} \\ -1 & \text{if } X \text{ is noncompact} \end{cases}$

$$k(X) \neq k(Y) \Rightarrow X \not\cong Y$$

* Define $c(X) = \text{number of connected components}$

$$c(X) \neq c(Y) \Rightarrow X \not\cong Y$$

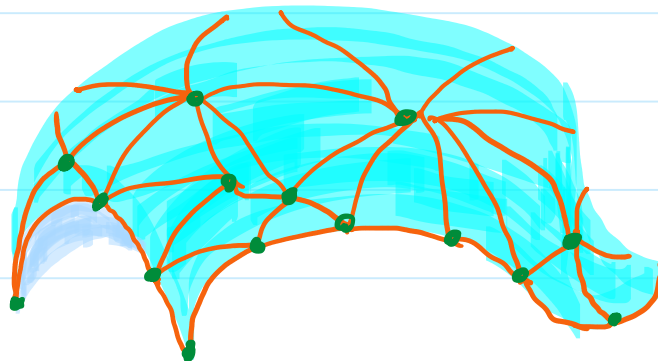
Further, define

$$s(X) = \sup \{ c(X \setminus \{x\}) : x \in X \}$$

$$\text{e.g., } s(S^1) = 1, s([0,1]) = 2$$

$$s(X) \neq s(Y) \Rightarrow X \not\cong Y$$

Example. Let Σ be a surface by intuition



For any triangulation — some adjacent conditions

$$\chi(X) = V - E + F$$

↑ Euler Characteristic

Note: independent of triangulation

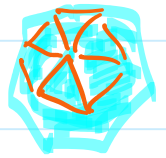
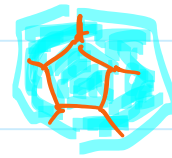
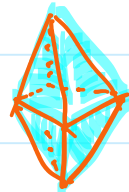
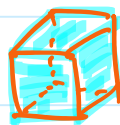
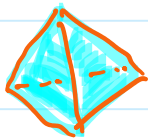
For higher dimensional object,

$$\chi(X) = (-1)^n b_n + \dots + (-1)^2 b_2 + (-1) b_1 + b_0$$

$$\chi(X) \neq \chi(Y) \Rightarrow X \not\stackrel{\text{homeo}}{=} Y$$

Remarks.

- $\chi(\mathbb{R}^n) = \chi(D^n) = 1$, $D^n = \{x \in \mathbb{R}^n : |x| \leq 1\}$
- $\chi(S^n) = (-1)^n + 1$



Tetrahedron Cube Octahedron Dodeca... Icosa...

$$4 - 6 + 4$$

$$6 - 12 + 8$$

$$8 - 12 + 6$$

$$12 - 30 + 20$$

$$20 - 30 + 12$$

$$\bullet \chi(S^1 \times S^1) = 0 \quad \chi(S^1 \times \dots \times S^1) = 0$$

$$\bullet \chi(\mathbb{R}P^2) = 0 = \chi(\text{Klein})$$

Theorem. $\chi(X \times Y) = \chi(X) \cdot \chi(Y)$

↑ Calculation is possible