

1. According to Lemma ( $\gamma$ ) and Theorem (C):

- (a) Each row-operation matrix is non-singular and invertible.
- (b) The product of any (finitely many) row-operation matrices is non-singular and invertible.
- (c) Every non-singular (and invertible) matrix is a product of row-operation matrices.

This allows us to establish a ‘dictionary’ between row-equivalence for general matrices and non-singularity.

## 2. Lemma ( $\mu$ ).

Let  $A, B$  be  $(m \times n)$ -matrices. Suppose  $A$  is row-equivalent to  $B$ .

Then there exists some non-singular and invertible  $(m \times m)$ -square matrix  $H$  such that  $B = HA$ .

### Proof of Lemma ( $\mu$ ).

Let  $A, B$  be  $(m \times n)$ -matrices. Suppose  $A$  is row-equivalent to  $B$ .

Then there is a sequence of row operations joining  $A$  to  $B$ :

$$A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} C_2 \xrightarrow{\rho_3} \cdots \cdots \cdots \xrightarrow{\rho_{N-1}} C_N = B$$

in which the  $\rho_j$ 's are the various row operations involved in this sequence.

For each  $k$ , denote by  $H_k$  the row operation matrix corresponding to  $\rho_k$ .

Then

$$C_2 = H_1 C_1 = H_1 A, C_3 = H_2 C_2, \cdots, C_{N-1} = H_{N-2} C_{N-2}, B = C_N = H_{N-1} C_{N-1}.$$

Therefore  $B = HA$ , in which  $H = H_{N-1} H_{N-2} \cdots H_2 H_1$ .

Then by Lemma ( $\gamma$ ) and Theorem (C), the matrix  $H$  is non-singular and invertible.

## 2. Lemma ( $\mu$ ).

Let  $A, B$  be  $(m \times n)$ -matrices. Suppose  $A$  is row-equivalent to  $B$ .

$A \rightarrow \dots \rightarrow B$   
 There is some sequence of row operations joining  $A$  to  $B$ .

Then there exists some non-singular and invertible  $(m \times m)$ -square matrix  $H$  such that  $B = HA$ .

$B$  is the resultant of multiplication from the left to  $A$  by some appropriate non-singular and invertible square matrix.

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 $C_k \xrightarrow{\rho_k} C_{k+1}$   
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Therefore  $B = HA$ , in which  $H = H_{N-1} H_{N-2} \dots H_2 H_1$ .

$H$  can be obtained from this sequence of row operations:  
 $I_m \xrightarrow{\rho_1} H_1 \xrightarrow{\rho_2} H_2 H_1 \rightarrow \dots \rightarrow H_{N-1} \dots H_1 = H$ .

Then by Lemma ( $\gamma$ ) and Theorem (C), the matrix  $H$  is non-singular and invertible.

### 3. Lemma ( $\nu$ ).

Let  $A, B$  be  $(m \times n)$ -matrices. Suppose there exists some non-singular and invertible  $(m \times m)$ -square matrix  $H$  such that  $B = HA$ .

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#### Proof of Lemma ( $\nu$ ).

Let  $A, B$  be  $(m \times n)$ -matrices. Suppose there exists some non-singular and invertible  $(m \times m)$ -square matrix  $H$  such that  $B = HA$ .

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Define  $C_1 = A, C_2 = H_1C_1, C_3 = H_2C_2, \dots, C_{N-1} = H_{N-2}C_{N-2}, C_N = H_{N-1}C_{N-1}$ .

Then, by definition,

$$B = HA = H_{N-1}H_{N-2} \cdots H_2H_1C_1 = H_{N-1}H_{N-2} \cdots H_2C_2 = \cdots = H_{N-1}C_{N-1} = C_N.$$

Denote the row operations corresponding to the respective row-operation matrices  $H_1, H_2, \dots, H_{N-1}$  by  $\rho_1, \rho_2, \dots, \rho_N$ . Then, by definition, we have the sequence

$$A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} C_2 \xrightarrow{\rho_3} \cdots \cdots \cdots \xrightarrow{\rho_{N-1}} C_N = B.$$

It follows that  $A$  is row-equivalent to  $B$ .

$B = HA$  for some non-singular square matrix  $H$

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There is some sequence of row operations joining  $A$  to  $B$ .

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It follows that  $A$  is row-equivalent to  $B$ .

4. We combine Lemma ( $\mu$ ) and Lemma ( $\nu$ ) into Theorem (F) below.

**Theorem (F).** (Re-formulation of row-equivalence in terms of multiplication by non-singular and invertible matrices.)

*Let  $A, B$  be  $(m \times n)$ -matrices.*

*The statements below are logically equivalent:*

(a)  *$A$  is row-equivalent to  $B$ .*

(b) *There exists some non-singular and invertible  $(m \times m)$ -square matrix  $H$  such that  $B = HA$ .*

**Remark.**

Such a re-formulation of row equivalence is useful in theoretical discussions because it brings in the equality symbol '='.

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The statements below are logically equivalent:

(a)  $A$  is row-equivalent to  $B$ .

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**Remark.**

Such a re-formulation of row equivalence is useful in theoretical discussions because it brings in the equality symbol '='.

This will help save a lot of time and make the arguments concise:

It is usually easier to manipulate a chain of equalities for matrices than to manipulate a chain of sequences of row operations.

## 5. Illustrations.

$$(a) \text{ Let } A = \begin{bmatrix} 1 & 2 & 2 & 4 \\ 1 & 3 & 3 & 5 \\ 2 & 6 & 5 & 6 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & -3 \\ 0 & 0 & 1 & 4 \end{bmatrix}.$$

It happens that

$$A = C_1 \xrightarrow{-1R_1+R_2} C_2 \xrightarrow{-2R_1+R_3} C_3 \xrightarrow{-2R_2+R_3} C_4 \xrightarrow{-1R_3} C_5 \xrightarrow{-2R_2+R_1} C_6 \xrightarrow{-1R_3+R_2} C_7 = B$$

Then

$$B = HA,$$

in which  $H$  is the  $(3 \times 3)$ -square matrix given by the product

$$H = H_6 H_5 H_4 H_3 H_2 H_1,$$

and for each  $k = 1, 2, 3, 4, 5, 6$ , the matrix  $H_k$  is the row operation matrix corresponding to the row operation  $\rho_k$  joining  $C_k$  to  $C_{k+1}$ .



$H$  is obtained as a resultant of the application of the sequence of row operations  $\rho_1, \rho_2, \rho_3, \rho_4, \rho_5$ , on  $I_3$ :

$$\begin{aligned}
 I_3 &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{-1R_1+R_2} H_1 = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{-2R_1+R_3} H_2H_1 = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix} \\
 \xrightarrow{-2R_2+R_3} H_3H_2H_1 &= \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix} \xrightarrow{-1R_3} H_4H_3H_2H_1 = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 0 \\ 0 & 2 & -1 \end{bmatrix} \\
 \xrightarrow{-2R_2+R_1} H_5H_4H_3H_2H_1 &= \begin{bmatrix} 3 & -2 & 0 \\ -1 & 1 & 0 \\ 0 & 2 & -1 \end{bmatrix} \\
 \xrightarrow{-1R_3+R_2} H &= H_6H_5H_4H_3H_2H_1 = \begin{bmatrix} 3 & -2 & 0 \\ -1 & -1 & 1 \\ 0 & 2 & -1 \end{bmatrix}
 \end{aligned}$$

$$(b) \text{ Let } A = \begin{bmatrix} 0 & 1 & -2 & 1 \\ -1 & -2 & 3 & -4 \\ 2 & 7 & -12 & 11 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 1 & 2 \\ 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

It happens that

$$A = C_1 \xrightarrow{R_1 \leftrightarrow R_2} C_2 \xrightarrow{-1R_1} C_3 \xrightarrow{-2R_1 + R_3} C_4 \xrightarrow{-3R_2 + R_3} C_5 \xrightarrow{-2R_2 + R_1} C_6 = B$$

Then

$$B = HA,$$

in which  $H$  is the  $(3 \times 3)$ -square matrix given by the product

$$H = H_5 H_4 H_3 H_2 H_1,$$

and for each  $k = 1, 2, 3, 4, 5$ , the matrix  $H_k$  is the row operation matrix corresponding to the row operation  $\rho_k$  joining  $C_k$  to  $C_{k+1}$ .

$H$  is obtained as a resultant of the application of the sequence of row operations  $\rho_1, \rho_2, \rho_3, \rho_4, \rho_5$  on  $I_3$ :

$$\begin{aligned}
 I_3 &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_2} H_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{-1R_1} H_2 H_1 = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\
 \xrightarrow{-2R_1 + R_3} H_3 H_2 H_1 &= \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 2 & 1 \end{bmatrix} \xrightarrow{-3R_2 + R_3} H_4 H_3 H_2 H_1 = \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ -3 & 2 & 1 \end{bmatrix} \\
 \xrightarrow{-2R_2 + R_1} H &= H_5 H_4 H_3 H_2 H_1 = \begin{bmatrix} -2 & -1 & 0 \\ 1 & 0 & 0 \\ -3 & 2 & 1 \end{bmatrix}
 \end{aligned}$$

$$(c) \text{ Let } A = \begin{bmatrix} 0 & 1 & 1 & 2 & 2 & 2 \\ 1 & 2 & 3 & 2 & 3 & 4 \\ -2 & -1 & -3 & 3 & 1 & 3 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & 1 & 0 & 1 & 10 \\ 0 & 1 & 1 & 0 & 0 & -8 \\ 0 & 0 & 0 & 1 & 1 & 5 \end{bmatrix}.$$

It happens that

$$A = C_1 \xrightarrow{R_1 \leftrightarrow R_2} C_2 \xrightarrow{2R_1 + R_3} C_3 \xrightarrow{-3R_2 + R_3} C_4 \xrightarrow{-2R_2 + R_1} C_5 \xrightarrow{2R_3 + R_1} C_6 \xrightarrow{-2R_3 + R_2} C_7 = B$$

Then

$$B = HA,$$

in which  $H$  is the  $(3 \times 3)$ -square matrix given by the product

$$H = H_6 H_5 H_4 H_3 H_2 H_1$$

and for each  $k = 1, 2, 3, 4, 5, 6$ , the matrix  $H_k$  is the row operation matrix corresponding to the row operation  $\rho_k$  joining  $C_k$  to  $C_{k+1}$ .

$H$  is obtained as a resultant of the application of the sequence of row operations  $\rho_1, \rho_2, \rho_3, \rho_4, \rho_5$ , on  $I_3$ :

$$\begin{aligned}
 I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} &\xrightarrow{R_1 \leftrightarrow R_2} H_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \xrightarrow{2R_1 + R_3} H_2 H_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 2 & 1 \end{bmatrix} \\
 \xrightarrow{-3R_2 + R_3} H_3 H_2 H_1 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ -3 & 2 & 1 \end{bmatrix} &\xrightarrow{-2R_2 + R_1} H_4 H_3 H_2 H_1 = \begin{bmatrix} -2 & 1 & 0 \\ 1 & 0 & 0 \\ -3 & 2 & 1 \end{bmatrix} \\
 \xrightarrow{2R_3 + R_1} H_5 H_4 H_3 H_2 H_1 = \begin{bmatrix} -8 & 5 & 2 \\ 1 & 0 & 0 \\ -3 & 2 & 1 \end{bmatrix} \\
 \xrightarrow{-2R_3 + R_2} H = H_6 H_5 H_4 H_3 H_2 H_1 = \begin{bmatrix} -8 & 5 & 2 \\ 7 & -4 & -2 \\ -3 & 2 & 1 \end{bmatrix}
 \end{aligned}$$

$$(d) \text{ Let } A = \begin{bmatrix} 1 & 2 & 7 & 1 & -1 \\ 1 & 1 & 3 & 1 & 0 \\ 3 & 2 & 5 & -1 & 9 \\ 1 & -1 & -5 & 2 & 0 \end{bmatrix}, B = \begin{bmatrix} 1 & 0 & -1 & 0 & 3 \\ 0 & 1 & 4 & 0 & -1 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

It happens that

$$\begin{aligned} A &= C_1 \xrightarrow{-1R_1+R_2} C_2 \xrightarrow{-3R_1+R_3} C_3 \xrightarrow{-1R_1+R_4} C_4 \xrightarrow{-1R_2} C_5 \\ &\xrightarrow{4R_2+R_3} C_6 \xrightarrow{3R_2+R_4} C_7 \xrightarrow{R_3 \leftrightarrow R_4} C_8 \xrightarrow{4R_3+R_4} C_8 \xrightarrow{-2R_2+R_1} C_9 \xrightarrow{-1R_3+R_1} C_{10} = B \end{aligned}$$

Then

$$B = HA,$$

in which  $H$  is the  $(4 \times 4)$ -square matrix given by the product

$$H = H_{10}H_9 \cdots H_3H_2H_1,$$

and for each  $k = 1, 2, 3, \dots, 9, 10$ , the matrix  $H_k$  is the row operation matrix corresponding to the row operation  $\rho_k$  joining  $C_k$  to  $C_{k+1}$ .

$H$  is obtained as a resultant of the application of the sequence of row operations  $\rho_1, \rho_2, \rho_3, \dots, \rho_9$  on  $I_4$ :

$$\begin{aligned}
I_4 &= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-1R_1+R_2} H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-3R_1+R_3} H_2H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -3 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \\
&\xrightarrow{-1R_1+R_4} H_3H_2H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 \\ -3 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{-1R_2} H_4H_3H_2H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ -3 & 0 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} \\
&\xrightarrow{4R_2+R_3} H_5H_4H_3H_2H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 1 & -4 & 1 & 0 \\ -1 & 0 & 0 & 1 \end{bmatrix} \xrightarrow{3R_2+R_4} H_6H_5H_4H_3H_2H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 1 & -4 & 1 & 0 \\ 2 & -3 & 0 & 1 \end{bmatrix} \\
&\xrightarrow{R_3 \leftrightarrow R_4} H_7H_6H_5H_4H_3H_2H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 2 & -3 & 0 & 1 \\ 1 & -4 & 1 & 0 \end{bmatrix} \xrightarrow{4R_3+R_4} H_8H_7H_6H_5H_4H_3H_2H_1 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 2 & -3 & 0 & 1 \\ 9 & -16 & 1 & 4 \end{bmatrix} \\
&\xrightarrow{-2R_2+R_1} H_9H_8H_7H_6H_5H_4H_3H_2H_1 = \begin{bmatrix} -1 & 2 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 2 & -3 & 0 & 1 \\ 9 & -16 & 1 & 4 \end{bmatrix} \xrightarrow{-1R_3+R_1} H = H_{10}H_9 \cdots H_3H_2H_1 = \begin{bmatrix} -3 & 5 & 0 & -1 \\ 1 & -1 & 0 & 0 \\ 2 & -3 & 0 & 1 \\ 9 & -16 & 1 & 4 \end{bmatrix}
\end{aligned}$$