1. How to re-formulate the notion of non-singularity in terms of row operations and reduced row-echelon forms?

Suppose A is an $(n \times n)$ -square matrix.

Recall that according to the definition for the notion of *non-singularity*:

• A is non-singular if and only if the trivial solution is the only solution for the homogeneous system $\mathcal{LS}(A, \mathbf{0})$.

Now suppose A' is the reduced row-echelon form which is row-equivalent to A, and recall that:

- The respective solution sets of $\mathcal{LS}(A, \mathbf{0})$ and $\mathcal{LS}(A', \mathbf{0})$ are the same as each other;
- Because A' is a reduced row-echelon form, A' is non-singular if and only if $A' = I_n$.

So we will have the mutually exclusive scenarios (\dagger) , (\dagger') below, dependent on whether A' is the identity matrix or not:—

(†) Suppose $A' = I_n$.

Then the trivial solution is the only solution for the homogeneous system $\mathcal{LS}(A, \mathbf{0})$. Therefore A is non-singular.

(†') Suppose $A' \neq I_n$.

Then A' is singular.

Therefore there is a non-trivial solution for the homogeneous system $\mathcal{LS}(A', \mathbf{0})$, which is also a non-trivial solution for the homogeneous system $\mathcal{LS}(A, \mathbf{0})$. Hence A is singular. Summarizing the discussion above, we have obtained a re-formulation for the notion of non-singularity in terms of reduced row-echelon forms.

2. Lemma (4).

Let A be a square matrix.

A is non-singular if and only if the reduced row-echelon form which is row-equivalent to A is given by the identity matrix.

Remark.

In the light of the Lemma (3), we may state Lemma (4) in this way:

Let A be a square matrix.

The following statements are logically equivalent:

(a) A is non-singular.

(b) A is row equivalent to I_n .

Summarizing the discussion above, we have obtained a re-formulation for the notion of non-singularity in terms of reduced row-echelon forms.

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In the light of the Lemma (3), we may state Lemma (4) in this way:

Let A be a square matrix.
The following statements are logically equivalent:
(a) A is non-singular.
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This provides a useful method for determining any given square matrix is non-singular or singular. Suppose A & an (hxn)-matrix. Apply row operations to A to find the reduced row-echelon form A'which is row equivalent to A. . If A=In, then conclude A is non-singular. . If A+In, then conclude A is singular. 3. Example (\star), as illustrations for Lemma (4).

(a) Let
$$A = \begin{bmatrix} 1 & 2 & 1 & 2 & 1 \\ -2 & -3 & 0 & -5 & -1 \\ 1 & 1 & 0 & 2 & 1 \\ -2 & -3 & -1 & -3 & -2 \\ -1 & -3 & -1 & -3 & 1 \end{bmatrix}$$
.

We find the reduced row-echelon form A' which is row-equivalent to A, say, through Gaussian elimination:

$$(\alpha): \quad A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} \cdots \xrightarrow{\rho_{17}} C_{18} \xrightarrow{\rho_{18}} C_{19} = A'$$

in which the ρ_k 's are given by:

It happens that $A' = I_5$. Then we may conclude that A is non-singular.

(b) Let
$$A = \begin{bmatrix} 1 & 1 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & 1 \end{bmatrix}$$
.

We find the reduced row-echelon form A' which is row-equivalent to A, say, through Gaussian elimination:

$$(\alpha): \quad A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} \cdots \xrightarrow{\rho_{11}} C_{12} \xrightarrow{\rho_{12}} C_{13} = A'$$

in which the ρ_k 's are given by:

It happens that $A' = I_4$. Then we may conclude that A is non-singular.

(c) Let
$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 0 & -1 & 0 \\ 3 & 4 & 4 & 3 \\ 2 & 2 & 1 & 1 \end{bmatrix}$$
.

We find the reduced row-echelon form A' which is row-equivalent to A, say, through Gaussian elimination:

$$(\alpha): \quad A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} \cdots \xrightarrow{\rho_8} C_9 \xrightarrow{\rho_9} C_{10} = A'$$

in which the ρ_k 's are given by:

$$\frac{k \quad \rho_k \quad |k \quad \rho_k \quad |k \quad \rho_k \quad |k \quad \rho_k}{1 \quad -1R_1 + R_2 \quad |4 \quad R_2 \leftrightarrow R_3 \quad |7 \quad 1R_3 + R_4} \\ 2 \quad -3R_1 + R_3 \quad |5 \quad 1R_2 + R_3 \quad |8 \quad -1R_2 + R_1 \\ 3 \quad |-2R_1 + R_4 \quad |6 \quad -1R_3 \quad |9 \quad |-1R_3 + R_2 \end{cases}$$

It happens that $A' = \begin{bmatrix} 1 \quad 0 \quad 0 \quad 1 \\ 0 \quad 1 \quad 0 \quad -1 \\ 0 \quad 0 \quad 1 \quad 1 \\ 0 \quad 0 \quad 0 \quad 0 \end{bmatrix}$. Then we may conclude that A is singular.

Remark. In fact, C_8 is a row-echelon form with an entire row of zeros. We can stop there and conclude that A is singular. (Why?)

4. How to re-formulate the notion of non-singularity in terms of matrix multiplication?

Let A be an $(n \times n)$ -square matrix, and A' be the reduced row-echelon form which is row-equivalent to A. We make some observations with the help of the 'dictionary' between row operations and row-operation matrices:

(a) For such matrices A, A', we have some sequence of row operations joining A to A':

$$A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} \cdots \xrightarrow{\rho_{p-2}} C_{p-1} \xrightarrow{\rho_{p-1}} C_p = A'.$$

According to the 'dictionary' between row operations and row-operation matrices, for each j, there is some (unique) $(n \times n)$ -square matrix H_j , namely, the row operation matrix for ρ_j , such that $C_{j+1} = H_j C_j$.

Then

$$A' = C_p = H_{p-1}C_{p-1} = H_{p-1}H_{p-2}C_{p-2} = \dots = H_{p-1}\dots H_2H_1A.$$

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$$H_1 C_1 = C_2, H_2 C_2 = C_3, \dots, H_{p-2} C_{p-2} = C_{p-1}, H_{p-1} C_{p-1} = C_p$$

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(b) Now further suppose A is non-singular.

Then, by Lemma (4), $A' = I_n$.

Therefore there exist some $(n \times n)$ -square matrix H, namely,

$$H = H_{p-1} \cdots H_2 H_1,$$

such that $HA = I_n$.

We summarize the discovery in the above discussion in the form of Lemma (5).

5. Lemma (5). (Converse of Lemma (2).)

Let A be an $(n \times n)$ -square matrix.

Suppose A is non-singular.

Then there exists some $(n \times n)$ -square matrix H such that $HA = I_n$.

Remark. Why do we call Lemma (5) a 'converse of Lemma (2)'?

It is because Lemma (2) reads as:

Let A be an $(n \times n)$ -square matrix. Suppose there exists some $(n \times n)$ -square matrix H such that $HA = I_n$. Then A is non-singular.

Combining Lemma (1), Lemma (2), Lemma (4) and Lemma (5), we obtain Theorem (A).

6. Theorem (A). (Re-formulation of non-singularity in terms of row operations, reduced row-echelon forms and matrix multiplication.)

Let A be an $(n \times n)$ -square matrix.

The statements below are logically equivalent:

(a) A is non-singular.

- (b) For any vector \mathbf{v} in \mathbb{R}^n , if $A\mathbf{v} = \mathbf{0}$ then $\mathbf{v} = \mathbf{0}$.
- (c) The trivial solution is the only solution of the homogeneous system $\mathcal{LS}(A, \mathbf{0})$.
- (d) A is row-equivalent to I_n .
- (e) There exists some $(n \times n)$ -square matrix H such that $HA = I_n$.

7. Towards the notion of invertibility.

Now indeed suppose A is a non-singular $(n \times n)$ -square matrix, which, according to Theorem (A), will satisfy $HA = I_n$ for some appropriate $(n \times n)$ -square matrix H.

(a) Question.

How to write down such a matrix H explicitly?

Answer.

According to our discussion leading up to Lemma (5), such a matrix H can be obtained as the product

$$H = H_{p-1} \cdots H_2 H_1$$

in which each H_j is the row operation matrix corresponding to the row operation ρ_j in some sequence of row operations joining A to I_n :

$$(\alpha): \quad A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} \cdots \xrightarrow{\rho_{p-2}} C_{p-1} \xrightarrow{\rho_{p-1}} C_p = I_n.$$

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Now indeed suppose A is a non-singular $(n \times n)$ -square matrix, which, according to Theorem (A), will satisfy $HA = I_n$ for some appropriate $(n \times n)$ -square matrix H.

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$$(\alpha): A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} \cdots \xrightarrow{\rho_{p-2}} C_{p-1} \xrightarrow{\rho_{p-1}} C_p = I_n.$$

$$\begin{pmatrix} C_2 = H_1 C_1 \\ C_3 = H_2 C_2 \\ C_4 = H_3 C_3 \\ \vdots \\ C_{p-1} = H_{p-2} C_{p-2} \\ C_p = H_{p-1} C_{p-1} \end{pmatrix} \xrightarrow{I_h} = C_p = H_{p-1} H_{p-2} \cdots H_2 H_1 A_1 C_1$$

(b) Further question.

But can we obtain H without multiplying so many matrices together?

Answer to further question.

Yes. How?

Write $H = H_{p-1} \cdots H_2 H_1 I_n$ (as a sleight of hand), and think of how to interpret this product in terms of row operations, according to the 'dictionary' between row operations and row operation matrices.

 H_1 is the resultant of the application of the row operation ρ_1 on I_n .

 H_2H_1 is the resultant of the application of the row operation ρ_2 on H_1 .

 $H_3H_2H_1$ is the resultant of the application of the row operation ρ_3 on H_2H_1 . So forth and so on.

 ${\cal H}$ is therefore the resultant of the sequence of row operations

$$(\beta): I_n \xrightarrow{\rho_1} H_1 \xrightarrow{\rho_2} H_2 H_1 \xrightarrow{\rho_3} \cdots \xrightarrow{\rho_{p-2}} H_{p-2} \cdots H_2 H_1 \xrightarrow{\rho_{p-1}} H_{p-1} \cdots H_2 H_1 = H.$$

(b) Further question.

But can we obtain H without multiplying so many matrices together?

Answer to further question.

Yes. How?

Write $H = H_{p-1} \cdots H_2 H_1 I_n$ (as a sleight of hand), and think of how to interpret this product in terms of row operations, according to the 'dictionary' between row operations and row operation matrices.

 H_1 is the resultant of the application of the row operation ρ_1 on I_n . H_2H_1 is the resultant of the application of the row operation ρ_2 on H_1 . H_1 , H_2 , H_2 , H_1 , H_1 , H_2 , H_2 , H_3 , H_3 , H_4 , H_1 , H_3 , H_2 , H_1 , H_1 , H_1 , H_2 , H_3 ,

H is therefore the resultant of the sequence of row operations

$$(\beta): I_n \xrightarrow{}_{\rho_1} H_1 \xrightarrow{}_{\rho_2} H_2 H_1 \xrightarrow{}_{\rho_3} \cdots \cdots \xrightarrow{}_{\rho_{p-2}} H_{p-2} \cdots H_2 H_1 \xrightarrow{}_{\rho_{p-1}} H_{p-1} \cdots H_2 H_1 = H.$$
So there is no need to perform matrix multiplication in obtaining the product $H_{p-1} H_{p-2} \cdots H_2 H_1$.

(c) **Bonus.**

Again look at the sequence

$$(\beta): \quad I_n \xrightarrow{\rho_1} H_1 \xrightarrow{\rho_2} H_2 H_1 \xrightarrow{\rho_3} \cdots \cdots \xrightarrow{\rho_{p-2}} H_{p-2} \cdots H_2 H_1 \xrightarrow{\rho_{p-1}} H_{p-1} \cdots H_2 H_1 = H.$$

This tells us immediately that:

- I_n is row-equivalent to the $(n \times n)$ -square matrix H, and hence
- the $(n \times n)$ -square matrix H is also row-equivalent to I_n .

Then, by Theorem (A), the statements below all hold immediately and simultaneously for this matrix H:

- *H* is non-singular.
- For any vector \mathbf{u} in \mathbb{R}^n , if $H\mathbf{u} = \mathbf{0}$ then $\mathbf{u} = \mathbf{0}$.
- The trivial solution is the only solution of the homogeneous system $\mathcal{LS}(H, \mathbf{0})$.
- There exists some $(n \times n)$ -square matrix G such that $GH = I_n$.

So now we know that $HA = I_n$, and some matrix G satisfies $GH = I_n$.

(c) Bonus. [Focus on H alone ; forget about A for the moment.]

Again look at the sequence

$$(\beta): \quad I_n \xrightarrow{\rho_1} H_1 \xrightarrow{\rho_2} H_2 H_1 \xrightarrow{\rho_3} \cdots \xrightarrow{\rho_{p-2}} H_{p-2} \cdots H_2 H_1 \xrightarrow{\rho_{p-1}} H_{p-1} \cdots H_2 H_1 = H.$$

This tells us immediately that:

- I_n is row-equivalent to the $(n \times n)$ -square matrix H, and hence
- the $(n \times n)$ -square matrix H is also row-equivalent to I_n .

With $\overline{P_j}$ being the reverse row operation of P_j for each j, we have the sequence $H = H_p H_{p-1} \cdots H_2 H_1 \xrightarrow{\rightarrow} H_2 \cdots H_2 H_1 \xrightarrow{\rightarrow} H_1 H_1 \xrightarrow{$

- H is non-singular.
- For any vector \mathbf{u} in \mathbb{R}^n , if $H\mathbf{u} = \mathbf{0}$ then $\mathbf{u} = \mathbf{0}$.
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So now we know that $HA = I_n$, and some matrix G satisfies $GH = I_n$.

(d) Question.

What is the matrix G?

Answer.

The matrix G can be nothing but A itself.

Justification:

For such matrices A, G, H, we have $G = GI_n = G(HA) = (GH)A = I_nA = A$.

Extra bonus. Therefore, for the same matrices A, H, it happens not only the equality $HA = I_n$ holds, but also the equality $AH = I_n$ holds.

We have obtained something unexpected discovery from the 'practical problem' of computing the matrix H which satisfies $HA = I_n$ for the non-singular matrix A. We formulate this discovery as Lemma (6).

8. Lemma (6).

Let A be an $(n \times n)$ -square matrix.

Suppose A non-singular.

Then there exists some $(n \times n)$ -square matrix H such that H is non-singular, $HA = I_n$ and $AH = I_n$.

(d) Question.

What is the matrix G?

Answer.

The matrix G can be nothing but A itself.

Justification: Reminder. Known by now: HA=In and GH=In.]

For such matrices A, G, H, we have $G = GI_n = G(HA) = (GH)A = I_nA = A$.

Extra bonus. Therefore, for the same matrices A, H, it happens not only the equality $HA = I_n$ holds, but also the equality $AH = I_n$ holds.

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Let A be an $(n \times n)$ -square matrix.

Suppose A non-singular.

Then there exists some $(n \times n)$ -square matrix H such that H is non-singular, $HA = I_n$ and $AH = I_n$. **Remark.** The converse of Lemma (6) is the statement (\sharp) :

(\ddagger) Let A be an $(n \times n)$ -square matrix.

Suppose there exists some $(n \times n)$ -square matrix H such that H is non-singular, $HA = I_n$ and $AH = I_n$.

Then A non-singular.

The statement (\sharp) is certainly true, by virtue of Theorem (A).

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But how about statement (b) below?
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(b) Let A be an $(n \times n)$ -square matrix.

Suppose there exists some $(n \times n)$ -square matrix H such that $AH = I_n$.

Then A non-singular.

We are not so sure at this point, as we are assuming 'less' in Statement (b) then in Statement (\sharp) .

It will transpire that Statement (\flat) is true as well, after more work is done.

9. Example (**), as an illustration for Lemma (6).

Recall Example (*). Let
$$A = \begin{bmatrix} 1 & 2 & 1 & 2 & 1 \\ -2 & -3 & 0 & -5 & -1 \\ 1 & 1 & 0 & 2 & 1 \\ -2 & -3 & -1 & -3 & -2 \\ -1 & -3 & -1 & -3 & 1 \end{bmatrix}$$

We have the sequence of row operations

$$(\alpha): \quad A = C_1 \xrightarrow{\rho_1} C_2 \xrightarrow{\rho_2} \cdots \xrightarrow{\rho_{17}} C_{18} \xrightarrow{\rho_{18}} C_{19} = A',$$

in which the row operations ρ_k and the corresponding row-operation matrices H_k are given by:

k	$ ho_k$	H_k	$\mid k$	$ ho_k$	H_k	$\mid k$	$ ho_k$	H_k
				$1R_1 + R_5$				
				$1R_3 + R_4$				
3	$2R_1 + R_4$	$I_5 + 2E_{4,1}^{5,5}$	9	$-2R_3 + R_5$	$I_5 - 2E_{5,3}^{5,5}$	15	$1R_4 + R_3$	$I_5 + E_{3,4}^{5,5}$
	$1R_1 + R_5$	○,-		$-2R_2 + R_1$	-,-			-,-
5	$1R_2 + R_3$	$I_5 + E_{3,2}^{5,5}$	11	$3R_3 + R_1$	$I_5 + 3E_{1,3}^{5,5}$	17	$1R_5 + R_2$	$I_5 + E_{2,5}^{5,5}$
6	$-1R_2 + R_4$	$ I_5 - E_{4,2}^{5,5} $	12	$-2R_3 + R_2$	$ I_5 - 2E_{2,3}^{5,5} $	18	$ -1R_5+R_3 $	$I_5 - E_{3,5}^{5,5}$

It happens that

$$I_5 = A' = C_{19} = H_{18}C_{18} = H_{18}\cdots H_2H_1A.$$

The matrix

$$H = H_{18}C_{18} = H_{18}\cdots H_2H_1$$

is the resultant of the application of the row operations $\rho_1, \rho_2, \cdots, \rho_{18}$ on I_5 , and is explicitly given by

$$H = \begin{bmatrix} -3 & 3 & 6 & -1 & -2 \\ 0 & -2 & -5 & -1 & 1 \\ 1 & 2 & 4 & 1 & -1 \\ 1 & 0 & 1 & 1 & 0 \\ 1 & -1 & -2 & 0 & 1 \end{bmatrix}.$$

It so happens that H is non-singular, $HA = I_5$ and $AH = I_5$.