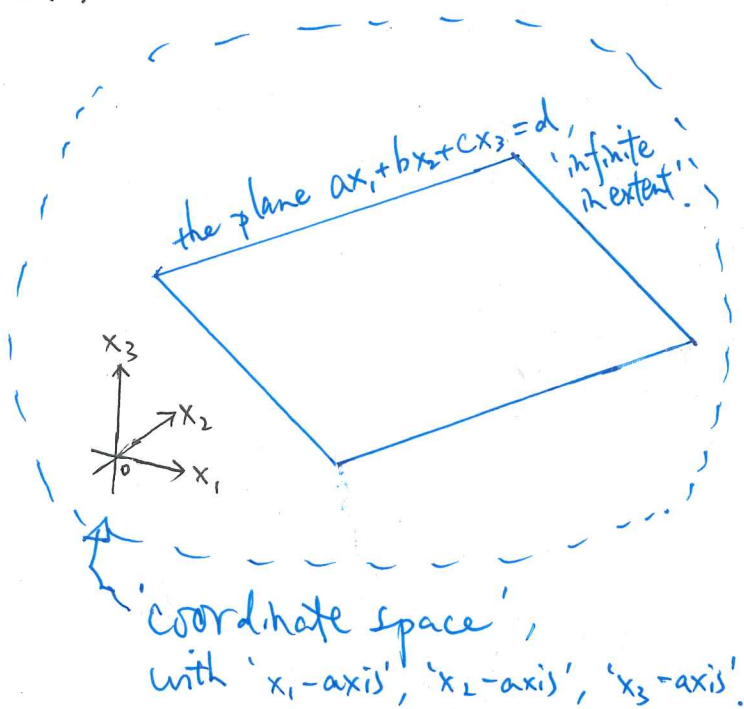


Geometry of a general system of one or two or three linear equations with three unknowns

Suppose a, b, c are real numbers, not all zero.
Suppose d is a real number.

Denote by (U_1) the system
 $ax_1 + bx_2 + cx_3 = d$.

The solution set P_1 of the system (U_1) corresponds to the 'plane with equation $ax_1 + bx_2 + cx_3 = d$ in the coordinate space'. The solutions of (U_1) are those and only those points in this plane in the coordinate space.



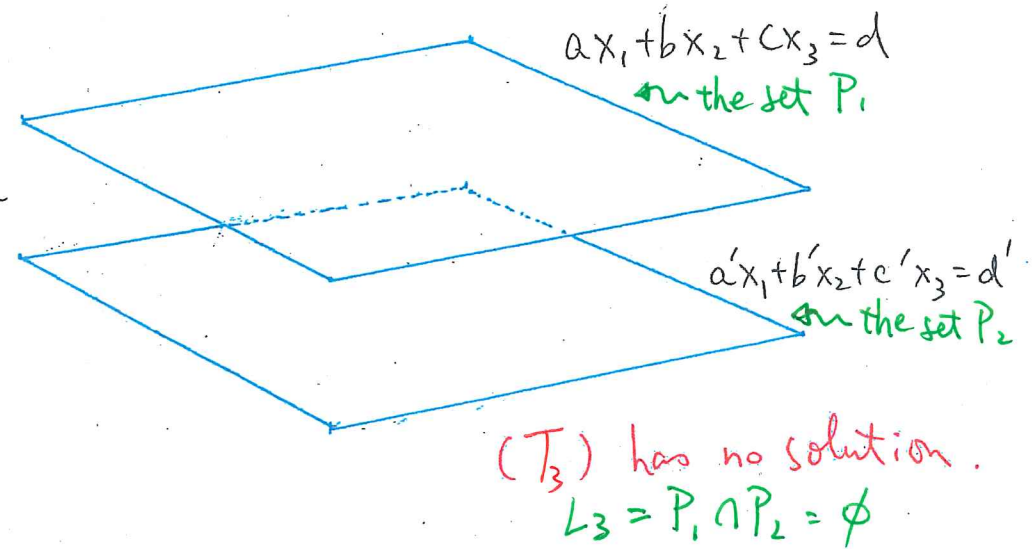
Now further suppose a', b', c' are real numbers, not all zero.
Suppose d' is a real number.

Denote by (U_2) the system
 $a'x_1 + b'x_2 + c'x_3 = d'$
and denote by P_2 the solution set of the system (U_2) .

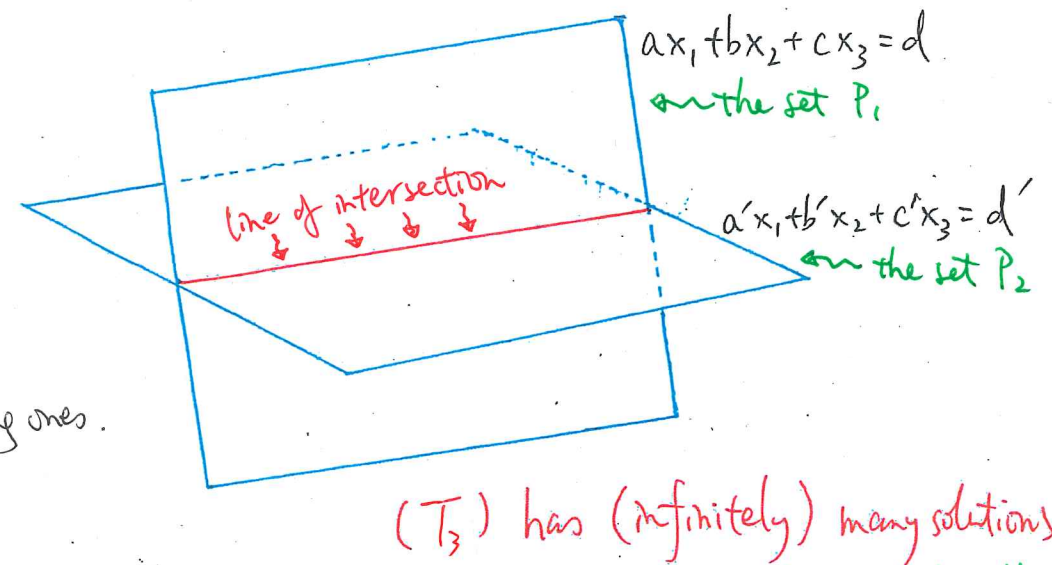
Denote by (T_3) the system
 $\begin{cases} ax_1 + bx_2 + cx_3 = d \\ a'x_1 + b'x_2 + c'x_3 = d' \end{cases}$
and denote by L_3 the solution set of the system (T_3) .

We have $L_3 = P_1 \cap P_2$. There are three mutually exclusive scenarios, dependent on the reduced row-echelon form D' which is row-equivalent to the augmented matrix representation D of the system (T_3) .

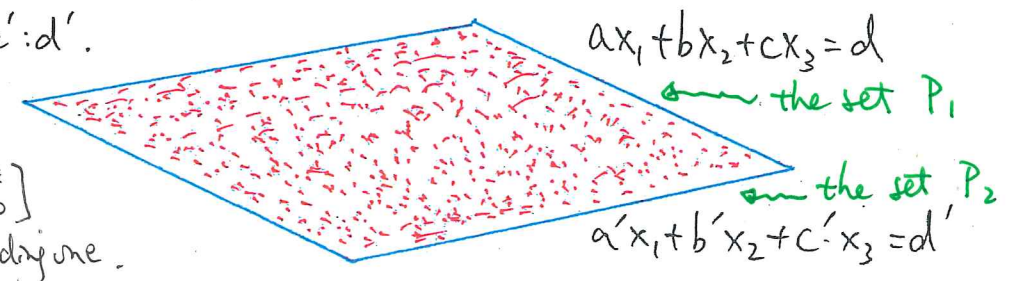
- ① Parallel, non-overlapping planes,
 $a:b:c = a':b':c'$ and
 $a:b:c:d \neq a':b':c':d'$
 $D = \begin{bmatrix} a & b & c & d \\ a' & b' & c' & d' \end{bmatrix}$
 $\rightarrow \dots \rightarrow D' = \begin{bmatrix} * & * & * & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$



- ② Non-parallel planes,
 $a:b:c \neq a':b':c'$
 $D = \begin{bmatrix} a & b & c & d \\ a' & b' & c' & d' \end{bmatrix}$
 $\rightarrow \dots \rightarrow D' = \begin{bmatrix} * & * & * & * \\ 0 & * & * & * \end{bmatrix}$
with two leading ones.



- ③ Coinciding planes,
 $a:b:c:d = a':b':c':d'$
 $D = \begin{bmatrix} a & b & c & d \\ a' & b' & c' & d' \end{bmatrix}$
 $\rightarrow \dots \rightarrow D' = \begin{bmatrix} * & * & * & * \\ 0 & 0 & 0 & 0 \end{bmatrix}$
with one leading one.



Suppose $a, b, c, d, a', b', c', d', a'', b'', c'', d''$ are real numbers, in which
 a, b, c are not all zero,
 a', b', c' are not all zero, and
 a'', b'', c'' are not all zero.

Denote by (S) the system

$$\begin{cases} ax_1 + bx_2 + cx_3 = d \\ a'x_1 + b'x_2 + c'x_3 = d' \\ a''x_1 + b''x_2 + c''x_3 = d'' \end{cases}$$

and denote by K the solution set of the system (S)

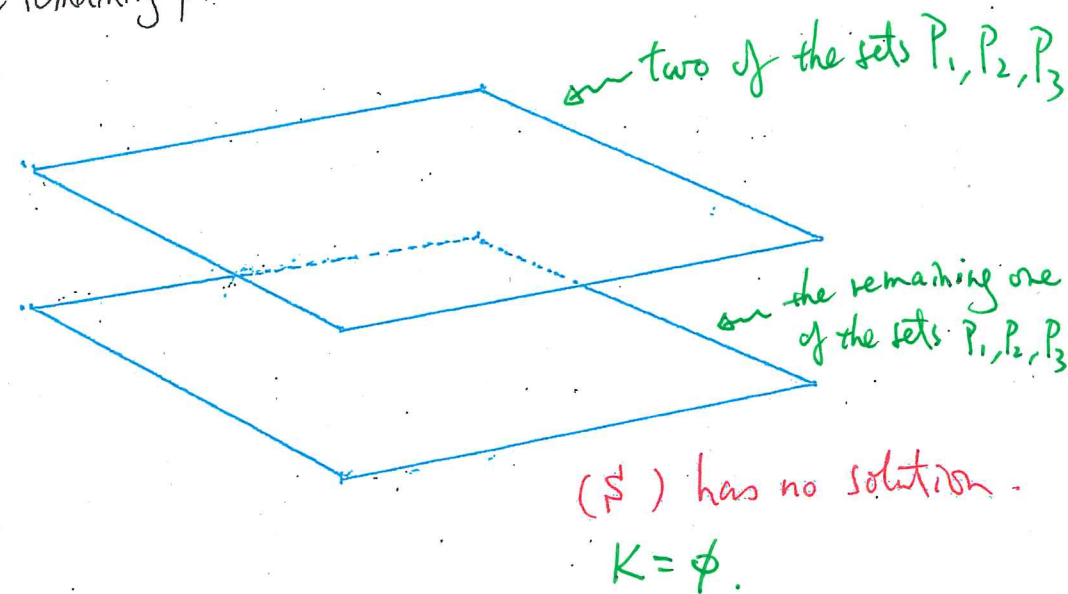
Further introduce the systems below and their respective solution sets:

System	Solution set
(U_1) $ax_1 + bx_2 + cx_3 = d$	P_1
(U_2) $a'x_1 + b'x_2 + c'x_3 = d'$	P_2
(U_3) $a''x_1 + b''x_2 + c''x_3 = d''$	P_3
(T_1) $\begin{cases} a'x_1 + b'x_2 + c'x_3 = d' \\ a''x_1 + b''x_2 + c''x_3 = d'' \end{cases}$	L_1
(T_2) $\begin{cases} ax_1 + bx_2 + cx_3 = d \\ a''x_1 + b''x_2 + c''x_3 = d'' \end{cases}$	L_2
(T_3) $\begin{cases} ax_1 + bx_2 + cx_3 = d \\ a'x_1 + b'x_2 + c'x_3 = d' \end{cases}$	L_3

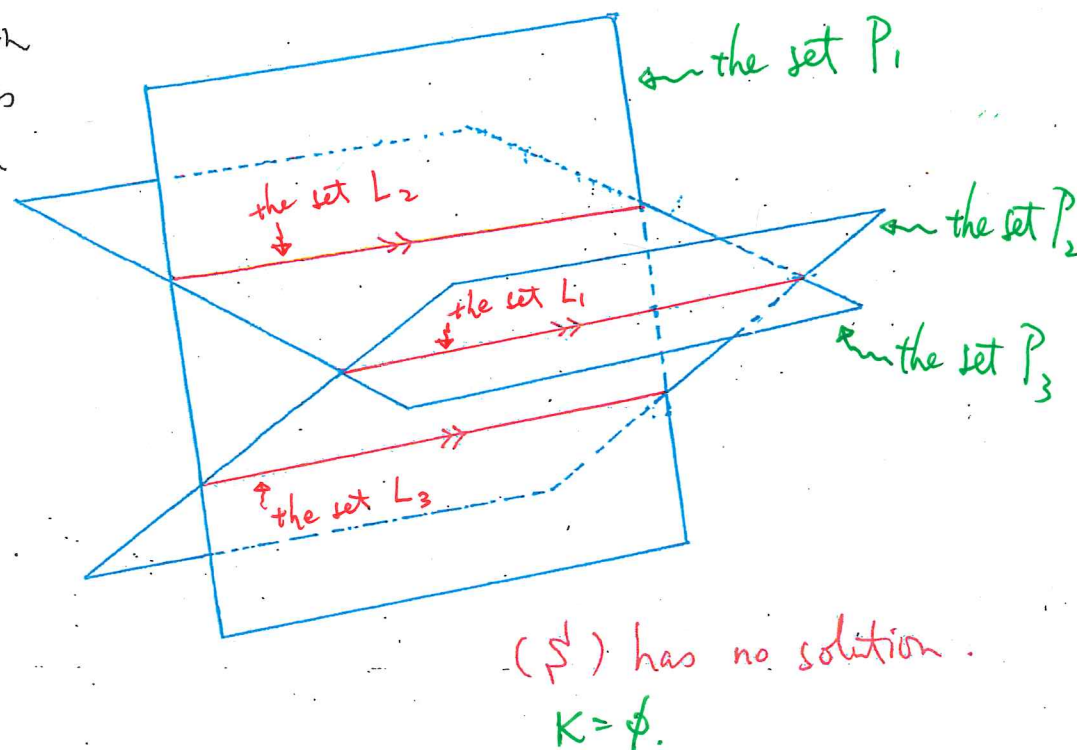
Then $L_1 = P_2 \cap P_3$, $L_2 = P_3 \cap P_1$, $L_3 = P_1 \cap P_2$, and
 $K = P_1 \cap P_2 \cap P_3 = L_1 \cap L_2 \cap L_3$.

There are various (mutually exclusive) scenarios, dependent on the reduced row-echelon form D' which is row-equivalent to the augmented matrix representation D of the system (S) .

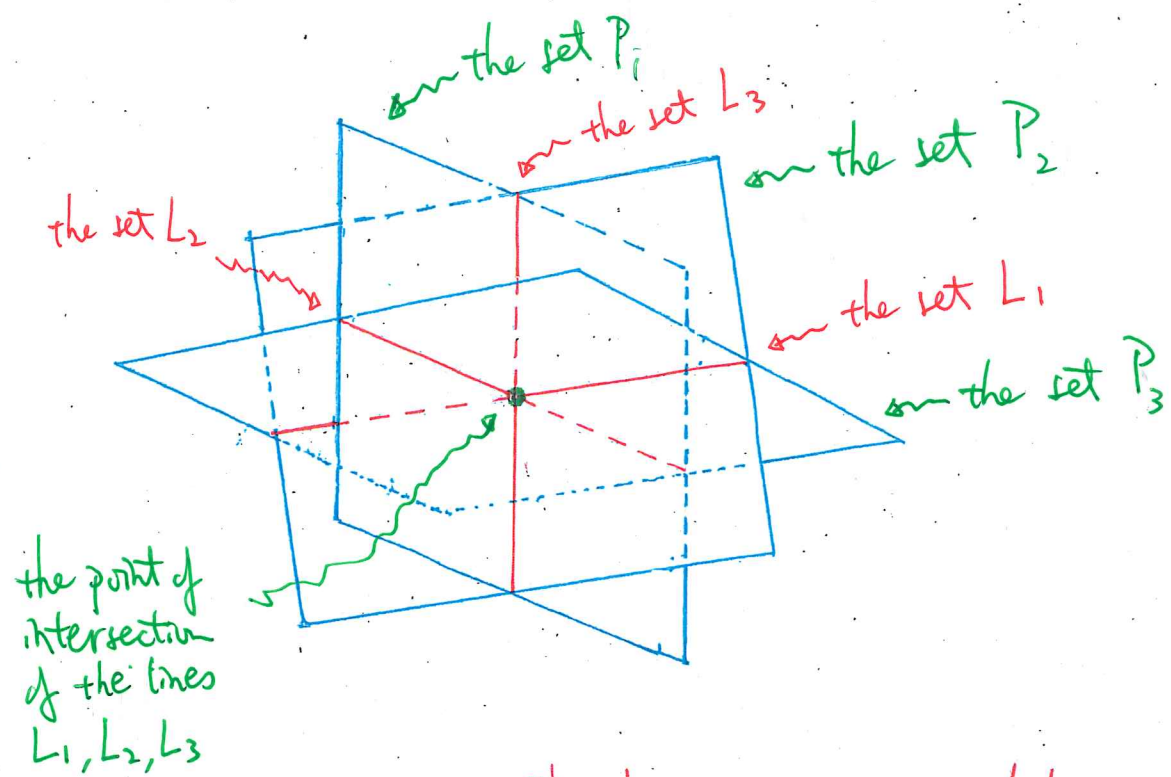
- ① Amongst the three planes, there are at least two parallel, non-overlapping planes. It does not matter what the remaining plane does.



- ② Every pair in the three planes intersects each other along a line. But the three lines are parallel to each other and are non-overlapping.



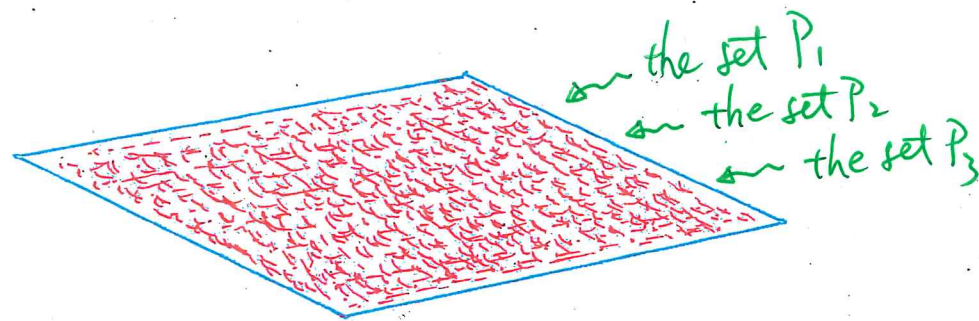
- (3) Every pair in the three planes intersects each other along a line. The three lines intersect each other at exactly one point.



(S) has a unique solution.

K is a set with exactly one element, which is given by the (one and only one) point at which the lines L_1, L_2 and L_3 meet each other.

- (5) The three planes coincide with each other.

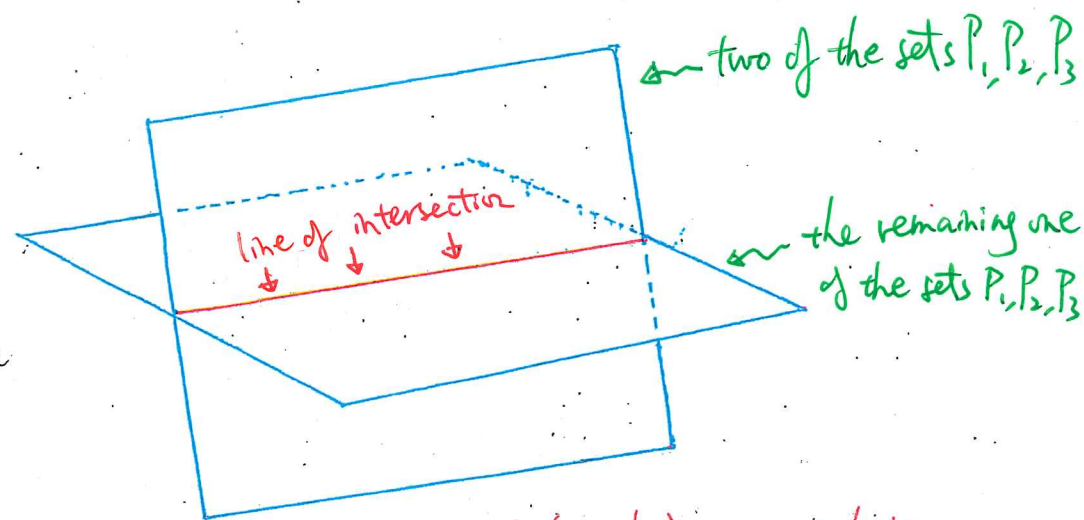


(S) has (infinitely) many solutions.

$$K = P_1 \cap P_2 \cap P_3 = P_1 = P_2 = P_3$$

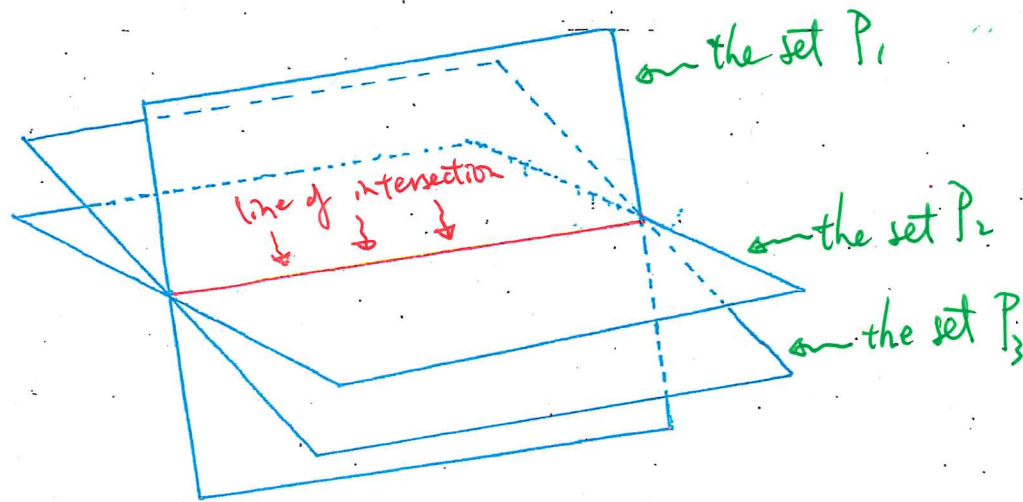
Also, $L_1 = L_2 = L_3 = K$.

- (4a) Two of the three planes coincide with each other, and the other plane intersects with it along a line.



(S) has (infinitely) many solutions.
 $K = P_1 \cap P_2 \cap P_3 = L_1 = L_2 = L_3$

- (4b) The three planes intersect each other along the same line.



(S) has (infinitely) many solutions
 $K = P_1 \cap P_2 \cap P_3 = L_1 = L_2 = L_3$