

Section 3. Standard Riemann Semigroup Approach

For the Cauchy problem for Burgers equation

$$\begin{cases} \partial_t u + \partial_x \left(\frac{u^2}{2} \right) = 0 \\ u(x, 0) = u_0(x), \end{cases} \quad (3.1)$$

The following contraction principle holds:

If $u_1(x, t)$, $u_2(x, t)$ are “right” solutions to (3.1), then

$$\|u_2(x, t) - u_1(x, t)\|_{L^1(\mathbb{R}^1)} \leq \|u_1(x, 0) - u_2(x, 0)\|_{L^1(\mathbb{R}^1)} \quad \forall t \geq 0$$

This can generate a semigroup $S_t u_0 = u(x, t)$.

B. Temple gave an example to show that one cannot obtain the L_1 -contraction principle for systems of conservation laws. However,

Definition 3.1: (Bressan): *The system (2.7) is said to admit a standard Riemann semi-group (SRSG). If for some C_0 and δ_0 , there exists a map $S_t : \mathcal{D} \times [0, \infty)' \rightarrow \mathcal{D}$ and constant L such that*

$$(1) \quad S_0 \bar{u} = \bar{u}, \quad \forall \bar{u} \in \mathcal{D}$$

$$(2) \quad S_\tau S_s \bar{u} = S_{\tau+s} \bar{u}, \quad \forall \bar{u} \in \mathcal{D}$$

$$(3) \quad \|S_t \bar{u} - S_t \bar{v}\|_{L^1(\mathbb{R})} \leq L \|\bar{u} - \bar{v}\|_{L^1(\mathbb{R})}$$

- (4) If $\bar{u} \in \mathcal{D}$ and \bar{u} is piecewise with finitely many jumps, then $\exists \tau = \tau(\bar{u}) > 0$ such that $\forall t \in [0, \tau]$, $(S_t \bar{u})(x) = u(x, t)$ must coincide with $u^R(x, t)$ which solves

$$\begin{cases} \partial_t u + \partial_x f(u) = 0 \\ u(x, t = 0) = \bar{u}(x) \end{cases}$$

by piecing together all Riemann solutions together.

Main Idea: If the system (2.7) admits a SRS, then every entropy weak solution obtained as a limit of piecewise constant approximate solutions in L^1 must coincide with a trajectory of the SRS.

Then the following statements are true:

- (1) all the trajectories of the SRSG are entropy weak solutions, i.e., S_t must be a solution operator.
- (2) SRSG must be unique.
- (3) the weak solution obtained by the front tracking method in Proposition 2.2 is unique and depends Lipschits continuously on its initial data.

Theorem 3.1: Assume that (2.7) admits a SRSG, $S : \mathcal{D} \times [0, \infty) \rightarrow \mathcal{D}$. Let $\{u^\nu\}$ be a sequence of approximate solutions constructed by the front tracking method, as given by Proposition 2.1, with $\varepsilon_i \rightarrow 0$, $\nu_i \rightarrow \infty$, suppose that

$$\begin{array}{lll} u^\nu(\cdot, 0) & \longrightarrow & u_0(\cdot) & \text{in } L^1 \\ u^\nu & \longrightarrow & u & \text{in } L^1_{loc}(\mathbb{R}^1 \times \mathbb{R}_+^1; \mathbb{R}^n) \end{array}$$

for $u_0 \in \mathcal{D}$. Then

$$u(x, t) = S_t u_0.$$

To prove this theorem, we need two lemmas.

Lemma 3.1: Let $u_{\pm} \in \Omega$ and $|\lambda| < \bar{\lambda}$. Let $w(x, t)$ be the self-similar solutions

$$\begin{cases} \partial_t w + \partial_x f(w) = 0 \\ w(x, t) = \begin{cases} u_- & x < 0 \\ u_+ & x > 0 \end{cases} \end{cases}$$

Set

$$\nu(x, t) = \begin{cases} u_- & \frac{x}{t} < \lambda \\ u_+ & \frac{x}{t} > \lambda \end{cases}$$

Then

$$(1) \quad \frac{1}{t} \int_{-\infty}^{+\infty} |\nu(x, t) - w(x, t)| dx = O(1) |u_+ - u_-|$$

(2) If, in addition, $u_+ = \exp\{\sigma \gamma_i\} u_-$, $\lambda = \lambda_i(u_+)$ for $\sigma > 0$, $i \in \{1, \dots, n\}$, then

$$\frac{1}{t} \int_{-\infty}^{\infty} |\nu(x, t) - w(x, t)| dx = O(1) \sigma^2$$

(3) If $\lambda = \tilde{\lambda}_i$, $\tilde{\lambda}_i$ is an eigenvalue of $f'(\tilde{u})$, and $\nabla f(\tilde{u})(u^+ - u^-) = \lambda(\tilde{u})(u^+ - u^-)$, then

$$\frac{1}{t} \int_{-\infty}^{\infty} |\nu(x, t) - w(x, t)| dx = O(1) |u_+ - u_-| (|u_+ - \tilde{u}| + |\tilde{u} - u_-|)$$

Lemma 3.2: Let S be SRS G . Let $u : \mathcal{D} \times [0, +\infty) \rightarrow \mathcal{D}$ whose values are piecewise constant with finitely many polygonal lines, say $x_\alpha(t)$, $\alpha = 1, \dots, m$, then

$$\|u(\cdot, T) - S_T u(\cdot, 0)\|_{L^1} \leq L \int_0^T \overline{\lim}_{h \rightarrow 0^+} \frac{\|u(t+h) - S_h u(t)\|_{L^1}}{h} dt \quad (\star)$$

Remark: There is a localized version of (\star) due to finite speed of propagation. For any given a, b , $b > a$, constants, define

$$I_t = (a + \bar{\lambda}t, b - \bar{\lambda}t) \text{ for } t < \frac{b-a}{2\bar{\lambda}},$$

$$\|u(t) - S_t u(0)\|_{L^1(I_t)} \leq L \int_0^t \overline{\lim}_{h \rightarrow 0^+} \frac{\|u(\tau+h) - S_h u(\tau)\|_{L^1(I_{\tau+h})}}{h} d\tau$$

We assume Lemma 3.1 and Lemma 3.2 for a moment and continue the proof.

Proof of Theorem 3.1 It suffices to show

$$\|u(T) - S_T u_0\|_{L^1} = 0 \quad \text{for any } T > 0.$$

This is equivalent to say $\overline{\lim}_{\nu \rightarrow +\infty} \|u^\nu(T) - S_T u_0\|_{L^1} = 0$. Note that

$$\begin{aligned} \|u^\nu(T) - S_T u_0\|_{L^1} &\leq \|u^\nu(T) - S_T u_0^\nu\|_{L^1} + \|S_T u_0^\nu - S_T u_0\|_{L^1} \\ &\leq \|u^\nu(T) - S_T u_0^\nu\|_{L^1} + L \|u_0^\nu - u_0\|_{L^1} \end{aligned}$$

It will suffice to prove that

$$\overline{\lim}_{\nu \rightarrow +\infty} \|u^\nu(T) - S_T u_0^\nu\|_{L^1} = 0$$

However, by Lemma 3.2,

$$\|u^\nu(T) - S_T u_0^\nu\|_{L^1} \leq L \int_0^T \overline{\lim}_{h \rightarrow 0^+} \frac{\|u^\nu(t+h) - S_h u^\nu(t)\|_{L^1}}{h} dt$$

It suffices to compute that

$$\text{for } t \in [0, T], \overline{\lim}_{h \rightarrow 0^+} \frac{\|u^\nu(t+h) - S_h u^\nu(t)\|_{L^1}}{h}.$$

Let $\mathcal{S} = \{\alpha \in \{1, \dots, m\}, \text{ such that } u^\nu(x_\alpha^-, t) = u_-^\nu, u^\nu(x_\alpha^+, t) = u_+^\nu \text{ are connected either by shock wave or contact discontinuity}\}.$

$\mathcal{R} = \{\alpha \in \{1, \dots, m\}, \text{ such that } u_-^\nu \text{ and } u_+^\nu \text{ corresponding to a rarefaction wave in the } k_\alpha\text{-th family, so that } \dot{x}_\alpha(t) = \lambda_{k_\alpha}(u_+^\nu), u_+^\nu = \exp(\varepsilon_\alpha \gamma_{k_\alpha}) u_-^\nu, \varepsilon_\alpha \in [0, \varepsilon]\}.$

Set $\alpha \in \mathcal{S} \cup \mathcal{R}$, $w^\alpha(x, t)$ satisfies

$$\begin{cases} \partial_t w^\alpha + \partial_x f(w^\alpha) = 0 \\ w^\alpha(x, t = 0) = \begin{cases} u_- = u^\nu(x_\alpha^-, t) \\ u_+ = u^\nu(x_\alpha^+, t) \end{cases} \end{cases}$$

Define

$$\begin{cases} \partial_t w^\beta + \partial_x f(w^\beta) = 0 \\ w^\beta(x, t = 0) = \begin{cases} u_- = u^\nu(x_\beta^-, t) \\ u_+ = u^\nu(x_\beta^+, t) \end{cases} \end{cases}$$

where $x = x_\beta(t)$ is associated with a pseudo-shock.

Note that if $t \in [0, T]$ such that t is NOT a node point (i.e. t is not a time two of x_α 's interact)

$$u(x, t + h) - S_h u(x, t) = 0$$

in a region away from a ρ -neighborhood of $x_\alpha \in \mathcal{R}$ and x_β for a non-physical wave for some $\rho > 0$ small. Therefore

$$\begin{aligned}
 & \overline{\lim}_{h \rightarrow 0^+} \frac{\|u^\nu(t+h) - S_h u^\nu(t)\|}{h} \\
 = & \sum_{\alpha \in \mathcal{R}} \lim_{h \rightarrow 0} \frac{1}{h} \int_{x_\alpha(t)-\rho}^{x_\alpha(t)+\rho} |u^\nu(t+h) - w^\alpha(x - x_\alpha(t), h)| dx \\
 & + \sum_{\beta} \frac{1}{h} \int_{x_\beta(t)-\rho}^{x_\beta(t)+\rho} |u^\nu(t+h) - w^\beta(x - x_\beta(t), h)| dx \\
 = & C \sum_{\alpha \in \mathcal{R}} |\varepsilon_\alpha|^2 + C \cdot \sum_{\beta} |u_\nu^- - u_\nu^+| \\
 \leq & C \cdot \varepsilon_\nu \sum_{\alpha \in \mathcal{R}} |\varepsilon_\alpha| + C \cdot \sum_{\beta} |u_\nu^- - u_\nu^+| \\
 \leq & \varepsilon_\nu (C \cdot T.V.u^\nu + C_1) \\
 \rightarrow & 0 \quad \text{as} \quad \nu \rightarrow \infty
 \end{aligned}$$

Proof of Lemma 3.1

$$\begin{aligned} (1) \quad & \frac{1}{t} \int_{-\infty}^{\infty} |w(x, t) - \nu(x, t)| dx = \frac{1}{t} \int_{-\bar{\lambda}t}^{\bar{\lambda}t} |w(x, t) - \nu(x, t)| dx \\ & = \frac{1}{t} \int_{-\bar{\lambda}t}^{\bar{\lambda}t} O(1) |u^- - u^+| dx = O(1) |u^- - u^+| \bar{\lambda}. \end{aligned}$$

$$(2) \quad u^+ = \exp\{\sigma\gamma_i\}(u^-), \quad \sigma \geq 0, \quad \lambda = \lambda_i(u^+)$$

Case 1: The i -th family is linearly degenerate, w is a contact discontinuity with speed $\lambda = \lambda_i(u^+) = \lambda_i(u^-)$,
 $w(x, t) = \nu(x, t)$.

Case 2: The i -th family is genuinely nonlinear. $\sigma > 0$, $w(x, t)$ is an i -th rarefaction wave.

$$\begin{aligned}
 & \frac{1}{t} \int_{-\infty}^{\infty} |w(x, t) - \nu(x, t)| dx \\
 = & \frac{1}{t} \int_{-\infty}^{\lambda_i(u^-)t} |w(x, t) - \nu(x, t)| dx \\
 & + \frac{1}{t} \int_{\lambda_i(u^-)t}^{\lambda_i(u^+)t} |w(x, t) - \nu(x, t)| dx \\
 & + \frac{1}{t} \int_{\lambda_i(u^+)t}^{+\infty} |w(x, t) - \nu(x, t)| dx \\
 = & \frac{1}{t} \int_{\lambda_i(u^-)t}^{\lambda_i(u^+)t} |w(x, t) - \nu(x, t)| dx \\
 = & O(1) |u^+ - u^-| \cdot |\lambda_i(u^+) - \lambda_i(u^-)| \\
 = & O(1)\sigma^2
 \end{aligned}$$

- (3) $\nabla f(\tilde{u})(u^+ - u^-) = \tilde{\lambda}_i(u^+ - u^-)$, $\tilde{\lambda}_i = \lambda_i(\tilde{u})$, therefore $u^+ - u^- = \theta r_i(\tilde{u})$.

Solving Riemann problem, $\exists w_0, w_1, \dots, w_n$ such that $w_0 = u_-$, $w_n = u_+$, such that w_j is connected w_{j-1} by an elementary wave. Let the strength of the j -th wave in $w(x, t)$ be $\sigma_j(\theta, \tilde{u})$.

$$\text{If } \tilde{u} = u^-, \left. \frac{\partial \sigma_j(\theta, u^-)}{\partial \theta} \right|_{\theta=0} = \delta_{ij}$$

$$\left| \frac{\partial \sigma_j(\theta, \tilde{u})}{\partial \theta} - \delta_{ij} \right| \leq O(1) (|\theta| + |u^- - \tilde{u}|)$$

Claim:

$$(i) \quad |\sigma_j(\theta, \tilde{u})| \leq O(1) |\theta| (|u^+ - \tilde{u}| + |u^- - \tilde{u}|) \text{ for } j \neq i;$$

$$(ii) \quad \begin{aligned} & \max(|w_i - u^+|, |w_{i-1} - u^-|) \\ & \leq O(1) |\theta| (|u^+ - \tilde{u}| + |u^- - \tilde{u}|); \end{aligned}$$

$$(iii) \quad \begin{aligned} & \max \left\{ |\lambda_i(w_i) - \tilde{\lambda}_i|, |\lambda_i(w_{i-1}) - \tilde{\lambda}_i| \right\} \\ & \leq O(1) (|u^+ - \tilde{u}| + |u^- - \tilde{u}|). \end{aligned}$$

Thus

$$\frac{1}{t} \int_{-\infty}^{\infty} |w(x, t) - \nu(x, t)| dx = \frac{1}{t} \int_{-\bar{\lambda}t}^{\bar{\lambda}t} |w(x, t) - \nu(x, t)| dx$$

Proof of Lemma 3.2

Step 1: Let the node points be at times $\tau_1, \tau_2, \dots, \tau_m$. Note that except at τ_i , then

$$\overline{\lim}_{h \rightarrow 0^+} \frac{\|u(t+h) - S_h u(t)\|_{L^1}}{h} \text{ is constant, } t \in (\tau_i, \tau_{i+1}).$$

Step 2: $\forall \varepsilon > 0$, fixed, let τ be defined as

$$\begin{aligned} \tau = & \max\{t \in [0, T] \mid \text{such that } \|S_{T-t} u(t) - S_T u(o)\|_{L^1} \\ & \leq L \left(\varepsilon t + \int_0^t \lim_{h \rightarrow 0^+} \frac{\|u(s+h) - S_h u(s)\|_{L^1}}{h} ds \right) \\ & + \varepsilon \sum_{\tau_i < t} 2^{-i} \} \end{aligned}$$

Fact 1: τ exists 1. Since $A \neq \emptyset$, due to $t = 0 \in A$.

Fact 2: $\tau \in A$, because the left hand side of the above expression is continuous, and right hand side is lower semi-continuous.

Fact 3: Lemma will be proved if we can show $\tau = T$.

Claim: $\tau = T$.

If not, $\tau < T$.

Case 1: $\exists j$, such that $\tau = \tau_j$.

Then by the continuity of semi-group S , $\exists \delta > 0$ such that

$$\begin{aligned} & \|S_{T-t} u(t) - S_T u(0)\|_{L^1} \\ \leq & \|S_{T-\tau} u(\tau) - S_T u(0)\|_{L^1} + \varepsilon 2^{-j} \quad t \in [\tau, \tau + \delta] \\ \leq & L \left(\varepsilon \tau + \int_0^\tau \overline{\lim}_{h \rightarrow 0^+} \frac{\|u(s+h) - S_h u(s)\|_{L^1}}{h} ds \right) \\ & + \varepsilon \sum_{\tau_i < \tau} 2^{-i} + \varepsilon 2^{-j} \\ \leq & L \left(\varepsilon t + \int_0^t \overline{\lim}_{h \rightarrow 0^+} \frac{\|u(s+h) - S_h u(s)\|_{L^1}}{h} ds \right) \\ & + \varepsilon \sum_{\tau_i < t} 2^{-i} \end{aligned}$$

This implies $t \in A$ contradiction.

Case 2: $\tau \notin \{\tau_i, i = 1, 2, \dots, m\}$

$\exists \delta^* > 0$, such that

$$\overline{\lim}_{h \rightarrow 0^+} \frac{\|S_h u(s) - u(s+h)\|_{L^1}}{h} = \text{const.} \quad \text{for } S \in [\tau, \tau + \delta^*]$$

We now choose δ^* small enough such that

$$\frac{\|u(\tau + \delta) - S_\delta u(\tau)\|}{\delta} \leq \varepsilon + \overline{\lim}_{h \rightarrow 0^+} \frac{\|u(\tau + h) - S_h u(\tau)\|}{h}, \delta \in [0, \delta^*]$$

$$\begin{aligned}
& \leq \|S_{T-(\tau+\delta)} u(\tau+\delta) - S_T u(0)\|_{L^1} \\
& \leq \|S_{T-(\tau+\delta)} u(\tau+\delta) - S_{T-(\tau+\delta)} S_\delta u(\tau)\|_{L^1} + \|S_{T-\tau} u(\tau) - S_T u(0)\|_{L^1} \\
& \leq L \|u(\tau+\delta) - S_\delta u(\tau)\|_{L^1} \\
& \quad + L \left(\varepsilon \tau + \int_0^\tau \lim_{h \rightarrow 0^+} \frac{\|u(s+h) - S_h u(s)\|_{L^1}}{h} ds \right) + \varepsilon \sum_{\tau_i < \tau} 2^{-i} \\
& \leq L \delta \left(\varepsilon + \overline{\lim}_{h \rightarrow 0^+} \frac{\|u(\tau+h) - S_h u(\tau)\|_{L^1}}{h} \right) \\
& \quad + L \left(\varepsilon \tau + \int_0^\tau \lim_{h \rightarrow 0^+} \frac{\|u(s+h) - S_h u(s)\|_{L^1}}{h} ds \right) + \varepsilon \sum_{\tau_j < \tau+\delta} 2^{-j} \\
& = L \left(\varepsilon(\tau+\delta) + \int_0^{\tau+\delta} \overline{\lim}_{h \rightarrow 0^+} \frac{\|S_h u(s) - u(s+h)\|_{L^1}}{h} ds \right) \\
& \quad + \varepsilon \sum_{\tau_j < \tau+\delta} 2^{-j}
\end{aligned}$$

Remark: The standard Riemann Semigroup for (2.7) exists. The existence follows from the construction of front tracking method summarized in Proposition 2.1.