3.3 Duality

3.3.1 Lagrangian and Dual Function

We consider a standard optimization problem (P):

$$
\min f(x)
$$

subject to $g_i(x) \le 0, \ i = 1, ..., h$

$$
h_j(x) = 0, \ j = 1, ..., k
$$

The optimal value p^* of (P) is called the primal optimal value. Definition: (Lagrangian) The Lagrangian associated with the above problem is defined as

$$
L(x, \lambda, \mu) = f(x) + \sum_{i=1}^{h} \lambda_i g_i(x) + \sum_{j=1}^{k} \mu_j h_j(x)
$$

The vectors λ, μ are called the *dual variables* or *Lagrange multipliers*.

Definition: (Dual function) The *dual function* is defined as

$$
q(\lambda, \mu) = \inf_{x} L(x, \lambda, \mu)
$$

Note that q is always concave, being the pointwise infimum of affine functions.

Let p^* be the optimal value of (P) . The dual function gives a lower bound on p^* .

Proposition: For all $\lambda \geq 0$ and μ , we have

$$
q(\lambda, \mu) \le p^*
$$

Proof. Let x be a feasible point. Then $g_i(x) \leq 0$ and $h_j(x) = 0$. Then

$$
\sum_{i=1}^{h} \lambda_i g_i(x) + \sum_{j=1}^{k} \mu_j h_j(x) \le 0
$$

Hence for all $\lambda \geq 0$ and μ ,

$$
q(\lambda, \mu) \le L(x, \lambda, \mu) = f(x) + \sum_{i=1}^{h} \lambda_i g_i(x) + \sum_{j=1}^{k} \mu_j h_j(x) \le f(x)
$$

Since this holds for all feasible points, we have $q(\lambda, \mu) \leq p^*$.

 \Box

We next consider the dual problem.

Definition:(Dual Problem) The following optimization problem (D) is called the *dual problem* associated to (P) :

$$
\max q(\lambda, \mu)
$$

subject to $\lambda \ge 0$

A pair (λ, μ) such that $\lambda \geq 0$ and $q(\lambda, \mu) > -\infty$ is called *dual feasible*. A optimal solution (λ^*, μ^*) is called *dual optimal*.

Example: (Linear Program)

Consider a standard linear program (LP):

$$
\min_{x \in \mathbb{R}^n} \langle c, x \rangle
$$

subject to $Ax = b$
 $x \ge 0$

The Lagrangian is given by

$$
L(x, \lambda, \mu) = c^{T} x - \sum_{i=1}^{n} \lambda_{i} x_{i} + \mu^{T} (Ax - b) = (A^{T} \mu + c - \lambda)^{T} x - b^{T} \mu
$$

If $c + A^T \mu - \lambda \neq 0$, then $L(x, \lambda, \mu)$ is unbounded below. Hence the dual function is given by

$$
q(\lambda, \mu) = \begin{cases} -b^T \mu & c + A^T \mu - \lambda = 0 \\ -\infty & \text{otherwise} \end{cases}
$$

Therefore, the dual problem is given by

$$
\max -b^T \mu
$$

subject to $A^T \mu + c - \lambda = 0$
 $\lambda \ge 0$

It can also be written in this form:

$$
\begin{aligned} \max & -b^T \mu \\ A^T + c\mu &\ge 0 \end{aligned}
$$

Example: Duality and Conjugate function Consider the following optimization problem

$$
\min f(x)
$$

subject to $Ax \le b$
 $Cx = d$

The dual function is

$$
q(\lambda, \mu) = \inf_{x} (f(x) + \lambda^{T} (Ax - b) + \mu^{T} (Cx - d))
$$

=
$$
-b^{T} \lambda - d^{T} \mu + \inf_{x} (f(x) + (A^{T} \lambda + C^{T} \mu)^{T} x)
$$

Note that

$$
\inf_{x} (f(x) + (A^T \lambda + C^T \mu)^T x) = -\sup_{x} (-(A^T \lambda + C^T \mu)^T x - f(x)) = -f^*(- (A^T \lambda + C^T \mu))
$$

Hence, we have

$$
q(\lambda, \mu) = -b^T \lambda - d^T \mu - f^*(-(A^T \lambda + C^T \mu))
$$

3.3.2 Strong and Weak Duality

Let d^* be the optimal value of the dual problem. We have the following inequality.

Proposition: (Weak Duality) Let p^* be the primal optimal value and d^* be the dual optimal value. Then

 $d^* \leq p^*$

The difference $p^* - d^*$ is called the *duality gap*. If $p^* = d^*$, then we say that *strong duality* holds.

This leads us to ask the question when do strong duality holds. Such conditions are called constraint qualification. We will study one simple qualification: Slater's condition.

Consider a convex problem of the form:

$$
\min f(x)
$$

subject to $g_i(x) \le 0, i = 1, ..., h$

$$
Ax = b
$$

where f, g_i are convex.

Slater's Condition: There exists $x \in \text{ri}(D)$ such that

$$
g_i(x) < 0, \ i = 1, \ldots, h, \ Ax = b
$$

where $D = \text{dom} f \cap (\cap_i \text{dom} g_i)$.

Theorem:(Slater's Theorem) If the problem is convex and Slater's condition is satisfied, then strong duality holds.

3.3.3 Geometric Interpretation

Consider the following set

 $A := \{(u, v, t)| \exists x \ g_i(x) \leq u_i, i = 1, ..., h, h_j(x) = v_j, j = 1, ..., k, f(x) \leq t\}$

We can show that A is convex if the problem is convex. Note that

$$
p^* = \inf\{t \mid (0,0,t) \in A\}
$$

that is the lowest point where A intersects the 'vertical'-axis. We can also interpret the dual function through this geometric setting:

$$
q(\lambda, \mu) = \inf \{ \langle (\lambda, \mu, 1), (u, v, t) \rangle | (u, v, t) \in A \}
$$

For fixed (λ, μ) , we can define a hyperplane

$$
\langle (\lambda,\mu,1),(u,v,t) \rangle = q
$$

Then $q(\lambda, \mu)$ is where a supporting hyperplane to A with 'slope' (λ, μ) intersects the 'vertical' axis.

Therefore, strong duality holds if and only if there is a nonvertical supporting hyperplane to A at $(0,0,p^*)$.

Figure 1: Geometric picture of the set G and dual function

Figure 2: Primal and dual optimal value

Figure 3: Geometric picture of the set A

Example: Consider the problem

$$
\min_{x,y \ge 0} e^{-\sqrt{xy}}
$$

subject to $x = 0$

The optimal value p^* is 1. The dual function is given by

$$
q(\lambda) = \inf_{x,y \ge 0} \{ e^{-\sqrt{xy}} + \lambda x \} = \begin{cases} 0 & \lambda \ge 0 \\ -\infty & \lambda < 0 \end{cases}
$$

Hence, the dual optimal value d^* is 0.

Therefore, the strong duality does not hold. Note that Slater's Condition is not satisfied for this example.

3.4 KKT conditions

Let's consider the general convex problem again

$$
\min f(x) \nsubject to $g_i(x) \le 0, \ i = 1, ..., h \nh_j(x) = 0, \ j = 1, ..., k$
$$

where are the functions are convex. We also assume that h_j are affine. Note that

$$
\sup_{\lambda \ge 0, \mu} L(x, \lambda, \mu) = \begin{cases} f(x) & g_i(x) \le 0, \ h_j(x) = 0 \\ \infty & \text{otherwise} \end{cases}
$$

Then $p^* = \inf_x \sup_{\lambda \geq 0, \mu} L(x, \lambda, \mu)$ On the other hand, $\overline{d^*} = \sup_{\lambda \geq 0,\mu} \inf_x L(x,\lambda,\mu)$. Therefore, strong duality is equivalent to

$$
\sup_{\lambda \ge 0, \mu} \inf_{x} L(x, \lambda, \mu = \inf_{x} \sup_{\lambda \ge 0, \mu} L(x, \lambda, \mu)
$$

Suppose strong duality holds. Let x^* be primal optimal and (λ^*, μ^*) be dual optimal. Then

$$
f(x^*) = q(\lambda^*, \mu^*)
$$

= $\inf_{x} (f(x) + \sum_{i=1}^h \lambda_i^* g_i(x) + \sum_{j=1}^k \mu_j^* h_j(x))$
 $\leq f(x^*) + \sum_{i=1}^h \lambda_i^* g_i(x^*) + \sum_{j=1}^k \mu_j^* h_j(x^*)$
 $\leq f(x^*)$

Therefore, we have equality for each line. In particular, we have

$$
\sum_{i=1}^{h} \lambda_i^* g_i(x^*) = 0
$$

Since each term is nonpositive, we have $\lambda_i^* g_i(x^*) = 0$ for all *i*. This is called complementary slackness.

Suppose all the functions are also differentiable. Then since x^* minimize $L(x, \lambda^*, \mu^*)$, we have

$$
\nabla_x L(x^*, \lambda^*, \mu^*) = 0
$$

That is

$$
\nabla f(x^*) + \sum_{i=1}^h \lambda_i^* \nabla g_i(x^*) + \sum_{j=1}^k \mu_j^* h_j(x^*) = 0
$$

Combining with the complementary slackness condition, we have the following Karush-Kuhn-Tucker (KKT) condition:

$$
\nabla f(x^*) + \sum_{i=1}^h \lambda_i^* \nabla g_i(x^*) + \sum_{j=1}^k \mu_j^* \nabla h_j(x^*) = 0
$$

$$
g_i(x^*) \le 0, \ i = 1, ..., h
$$

$$
h_j(x^*) = 0, \ j = 1, ..., k
$$

$$
\lambda_i^* \ge 0
$$

$$
\lambda_i^* g_i(x^*) = 0, \ i = 1, ..., h
$$

Conversely, suppose $x^*, (\lambda^*, \mu^*)$ satisfy the KKT conditions. Since $L(x, \lambda^*, \mu^*)$ is convex in x and $\nabla_x L(x^*, \lambda^*, \mu^*) = 0$, then x^* minimizes $L(x, \lambda^*, \mu^*)$. Then

$$
q(\lambda^*, \mu^*) = L(x^*, \lambda^*, \mu^*) = f(x^*) + \sum_{i=1}^h \lambda_i^* g_i(x^*) + \sum_{j=1}^k \mu_j^* h_j(x^*) = f(x^*)
$$

Therefore, there is no duality gap and x^* , (λ^*, μ^*) are primal optimal and dual optimal respectively.

To conclude, we have the following optimal condition:

Theorem: Consider the convex problem (P). Suppose strong duality holds. Then $x^*, (\lambda^*, \mu^*)$ are primal and dual optimal if and only if $x^*, (\lambda^*, \mu^*)$ satisfy the KKT conditions.

Remark: If the functions are not differentiable, we can replace the first KKT condition by $0 \in \partial f(x^*) + \sum_{i=1}^h \lambda_i^* \partial g_i(x^*) + \sum_{j=1}^k \mu_j^* \partial h_j(x^*).$

Example Consider the problem

$$
\min -xy
$$

subject to $x + y^2 \le 2$
 $x, y \ge 0$

The KKT condition can be written as

$$
-y + \lambda_1 - \lambda_2 = 0
$$

$$
-x + 2\lambda_1 y - \lambda_3 = 0
$$

$$
x + y^2 \le 2
$$

$$
x, y \ge 0
$$

$$
\lambda_1, \lambda_2, \lambda_3 \ge 0
$$

$$
\lambda_2 x = \lambda_3 y = 0
$$

$$
\lambda_1 (x + y^2 - 2) = 0
$$

In order to solve the KKT system, we separate to cases: Case 1 $\lambda_1 = 0$ Then $y + \lambda_2 = x + \lambda_3 = 0$. So $x = y = \lambda_2 = \lambda_3 = 0$. $f(0, 0) = 0$ **Case 2** $x + y^2 = 2$. Then at least one of x, y must be positive. **2a** $x > 0$. Then $\lambda_2 = 0$ and $y = \lambda_1$. So $3y^2 = 2 + \lambda_3 > 0$ by the second condition. Hence, $\lambda_3 = 0$ and $y = \sqrt{2/3}$, $x = 4/3$. $f(4/3, \sqrt{2/3}) = -\sqrt{32/27}.$ **2b** $y > 0$. Then $\lambda_3 = 0$. So, $x = 2\lambda_1 y > 0$. This is same as **2a**. Therefore the global minimum is obtained at $(4, /3, \sqrt{2/3})$.