

Lecture 4:

Recap: Let M be a smooth surface.

- A Riemannian metric g associated to M is defined:
For $\forall p \in M$, $g_p: T_p M \times T_p M \rightarrow \mathbb{R}$ defines an inner product $\Rightarrow \underbrace{\langle \vec{v}, \vec{w} \rangle}_{\text{inner product}} = g_p(\vec{v}, \vec{w})$ for all $\vec{v}, \vec{w} \in T_p M$

(From Linear Algebra, at each $p \in M$, g_p is associated to a 2×2 SPD matrix $\begin{pmatrix} g_{11}(p) & g_{12}(p) \\ g_{21}(p) & g_{22}(p) \end{pmatrix}$ and in every smooth local coordinates (x^1, x^2) ,

$$g_p = \sum_{i,j=1}^2 g_{ij}(p) dx^i dx^j.$$

g_{ij} 's are smooth)

- Any metric surface M is associated to an isothermal coordinates.

That's, let $\{(U_\alpha, z_\alpha)\}_{\alpha \in A}$ be the conformal atlas for M .

Then:
$$g = e^{\lambda(z_\alpha)} (dx_\alpha^2 + dy_\alpha^2)$$

- Any metric surface is a Riemann surface.

• $S_1 \xrightarrow{f} S_2$ f is conformal iff

$$\begin{array}{ccc} \downarrow z_\alpha & & \downarrow w_\beta \\ U_\alpha & \xrightarrow{f} & V_\beta \\ \tilde{f} & = & w_\beta \circ f \circ z_\alpha^{-1} \end{array}$$

\tilde{f} is conformal for all z_α, w_β

Basic theories of planar conformal maps

Theorem: (Riemann mapping) Suppose $D \subset \mathbb{C}$ is a simply-connected domain on the complex plane, the boundary ∂D has more than one point, $z_0 \in D$ is an arbitrary interior point. Then, there exists a unique conformal mapping $\phi: D \rightarrow \Delta$ from D to the unit disk Δ , such that $\phi(z_0) = 0$ and $\phi'(z_0) > 0$.

Remark: If $f: S \rightarrow \text{ID}$ and $g: S \rightarrow \text{ID}$ are disk conformal parameterizations of S , then: $g \circ f^{-1}$ is a conformal map between unit disk $\checkmark \mathbb{C}$
 $\therefore g \circ f^{-1}(z) = \frac{e^{i\theta} (z-a)}{1-\bar{a}z}$ for some $a, \theta \in (0, 2\pi)$
 $\therefore g = f \circ \phi$

Surface harmonic map: theories and computation

Basic theoretical background

1. Let $f: M \rightarrow \mathbb{R}$. The differential of f is defined as:

$$df_p(\vec{v}) \stackrel{\text{def}}{=} D_{\vec{v}} f \quad \text{for } \forall \vec{v} \in T_p M$$

$$\frac{d}{dt} f(\gamma(t)) \quad \text{where } \frac{d}{dt} \Big|_{t_0} \gamma(t) = \vec{v}$$

Under the coordinate chart (x^1, x^2) around p ,

$$df_p := \sum_{i=1}^2 \frac{\partial f}{\partial x^i}(p) dx^i$$

2. (Planar harmonic function) Let $\Omega \subseteq \mathbb{R}^2$ and let $u: \Omega \rightarrow \mathbb{R}$.

u is said to be a harmonic function if: $\Delta u = 0$

Harmonic map and energy minimization

Consider: $E(u) \stackrel{\text{def}}{=} \int_{\Omega} \langle \nabla u, \nabla u \rangle dx dy$

Suppose u minimizes $E(u)$, then:

$$\begin{aligned} 0 &= \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} E(u + \varepsilon h) = \left. \frac{d}{d\varepsilon} \right|_{\varepsilon=0} \int_{\Omega} \langle \nabla u + \varepsilon \nabla h, \nabla u + \varepsilon \nabla h \rangle dx dy \\ &= 2 \int_{\Omega} \langle \nabla u, \nabla h \rangle dx dy \end{aligned}$$

Fixing the boundary, we have $h \equiv 0$ on $\partial\Omega$.

Integration by part gives: $0 = 2 \int_{\Omega} h \Delta u dx dy$ for $\forall h$
 $h|_{\partial\Omega} \equiv 0$

$$\therefore \begin{cases} \Delta u \equiv 0 \\ u|_{\partial\Omega} = g \quad (\text{Boundary condition}) \end{cases}$$

Remark: • A harmonic function minimizes the harmonic energy $E(u) = \int_{\Omega} \langle \nabla u, \nabla u \rangle dx dy$

• A map $f: \Omega \subseteq \mathbb{R}^2 \rightarrow \Omega' \subseteq \mathbb{R}^2$ is said to be harmonic if $f \stackrel{\text{def}}{=} u + iv$, $\Delta u \equiv 0$ and $\Delta v \equiv 0$.

• A map $f: S \rightarrow \Omega \subseteq \mathbb{R}^2$ (where S is a Riemann surface) is a harmonic map if with respect to a conformal coordinate chart ϕ , $f \circ \phi$ is a harmonic map.

More concrete definition of harmonic map between Riemann surfaces

Definition: Let $f: M \rightarrow \mathbb{R}$ be a smooth function on M .

The Riemannian gradient ∇f_p at $p \in M$ is defined \Rightarrow for $\forall p \in M$, $\forall \vec{v} \in T_p M$, ∇f_p is a tangent vector at p

satisfying: $\langle \nabla f_p, \vec{v} \rangle_g = D_{\vec{v}} f$.

In any smooth coordinate (X^1, X^2) ,

$$\nabla f_p = \sum_{i,j=1}^2 g^{ij}(p) \frac{\partial f}{\partial x^i}(p) \frac{\partial}{\partial x^j} \Big|_p \quad \text{where (Check)}$$

(g^{ij}) is the inverse of (g_{ij}) .

Remark: Let $f: S \rightarrow \Omega \subseteq \mathbb{R}^2$. f is a harmonic map

if: f minimizes $E(f) = \int_S \langle \nabla f_p, \nabla f_p \rangle g$

(Harmonic energy)

How about harmonic energy between Riemann surfaces?

Let $f: (M, g) \rightarrow (N, h)$ be a homeomorphism.

Define: $E(f) = \frac{1}{2} \int_M \|df\|_h^2 \omega_g$ be the harmonic energy

where:

• ω_g is the area measure on M defined by the metric g

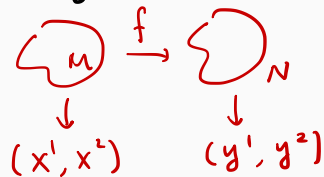
• $\|df\|_h^2 \stackrel{\text{def}}{=} \sum_{i=1}^2 h_{f(p)}(df_p(e_i), df_p(e_i))$,

$\{e_i\}$ is an orthonormal basis on $T_p M$

In local coordinate (x^1, x^2) on M and (y^1, y^2) on N ,

$$\|df_p\|_h^2 = \sum_{i,j=1}^2 \sum_{\alpha,\beta=1}^2 g^{ij}(p) h_{\alpha\beta}(f(p)) f_i^\alpha f_j^\beta \quad \text{where}$$

$$f_i^\alpha \stackrel{\text{def}}{=} \frac{\partial}{\partial x^i} (y^\alpha \circ f), \quad f_j^\beta \stackrel{\text{def}}{=} \frac{\partial}{\partial x^j} (y^\beta \circ f)$$



and $\omega_g = \sqrt{|g|} dx^1 dx^2$ and $|g| = \text{determinant of } (g_{ij})$

Definition: The homeomorphism $f: M \rightarrow N$ is a harmonic map if f minimizes the harmonic energy.

Important fact:

Theorem: Suppose a harmonic map $\varphi: (S, g) \rightarrow \Omega \subseteq \mathbb{R}^2$ satisfies:

① Ω is convex;

② the restriction of $\varphi: \partial S \rightarrow \partial \Omega$ on the boundary is homeomorphic

Then: φ is diffeomorphic in the interior of S .

Proof: By regularity theory of harmonic maps, we get the smoothness of the harmonic map. Assume $\varphi: (x, y) \rightarrow (u, v)$

is not homeomorphic, then there is an interior point $p \in \Omega$, the Jacobian matrix of φ is degenerated at p .

$\therefore \exists a, b \in \mathbb{R}$ (not all zero) such that:

$$a \nabla u(p) + b \nabla v(p) = 0$$



By $\Delta u = \Delta v = 0$, the auxiliary function

$f(z) = au(z) + bv(z)$ is also harmonic.

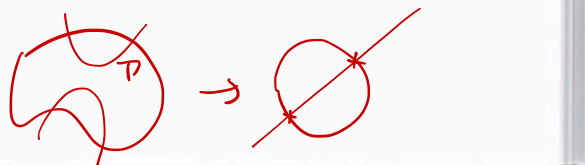
$\because \nabla f(p) = 0 \quad \therefore p$ is a saddle point of f .

Consider $T = \{z \in S \mid f(z) = f(p) - \varepsilon\}$ (level set of f near p)

T has two connected components, intersecting ∂S at 4 points.

But Ω is a planar convex domain, $\partial\Omega$ and the line $au + bv = \text{const}$ have two intersection points. By assumption, $\varphi|_{\partial S}$ is a homeomorphism. Contradiction.

$\therefore \varphi$ is homeomorphic.



Theorem: If $f: S \rightarrow \Omega \subseteq \mathbb{R}^2$ and $g: S \rightarrow \Omega$ are
both harmonic maps satisfying $f|_{\partial S} = g|_{\partial S} = h$
 \uparrow
convex
(given)

then: $f \equiv g$.

Computation of discrete harmonic map

Let M be a triangulated surface. A piecewise linear function or map is a function/map on M such that it is linear on each triangular face.

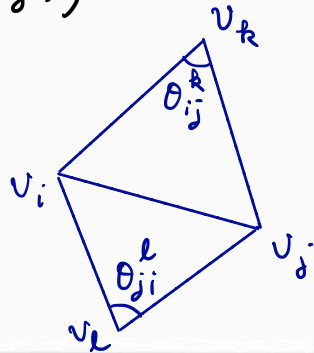
Theorem: Given a piecewise linear function $f: M \rightarrow \mathbb{R}$, then the harmonic energy of f is given by:

$$E(f) = \frac{1}{2} \sum_{[v_i, v_j] \in M} w_{ij} (f(v_i) - f(v_j))^2$$

where

$$w_{ij} = \cot \theta_{ij}^R + \cot \theta_{ji}^L$$

(Cotangent formula)



Definition: (Laplace operator) The discrete Laplacian Δ_{PL} on a piecewise linear function f is

$$\Delta_{PL} f(v_i) = \sum_{[v_i, v_j] \in M} w_{ij} (f(v_j) - f(v_i))$$

Hence, if f minimizes the discrete harmonic energy, then:

$$\Delta_{PL} f \equiv 0$$

Remark: The motivation of this definition is by taking the derivative of the discrete harmonic energy:

$$E(f) = \frac{1}{2} \sum_{[v_i, v_j] \in M} w_{ij} (f(v_j) - f(v_i))^2$$

Recall: The Euler-Lagrange eq^t of $\int_M |\nabla f|^2$ is given by $\Delta f = 0$.

Computational Algorithm for Disk Harmonic Maps

Input: A topological disk M ;

Output: A harmonic map $\varphi : M \rightarrow \mathbb{D}^2$

- 1 Construct boundary map to the unit circle, $g : \partial M \rightarrow \mathbb{S}^1$, g should be a homeomorphism;
- 2 Compute the cotangent edge weight;
- 3 for each interior vertex $v_i \in M$, compute Laplacian

$$\Delta\varphi(v_i) = \sum_{v_j \sim v_i} w_{ij}(\varphi(v_i) - \varphi(v_j)) = 0;$$

- 4 Solve the linear system, to obtain φ .