## THE CHINESE UNIVERSITY OF HONG KONG Department of Mathematics MATH3310 2022-2023 Homework Assignment 5 Suggested Solution

1. Consider the linear system  $Ax = k$ , where

$$
A = \begin{pmatrix} 1 & 0 & -\frac{1}{4} & -\frac{1}{4} \\ 0 & 1 & -\frac{1}{4} & -\frac{1}{4} \\ -\frac{1}{4} & -\frac{1}{4} & 1 & 0 \\ -\frac{1}{4} & -\frac{1}{4} & 0 & 1 \end{pmatrix} \text{ and } \mathbf{k} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}.
$$

Let  $\boldsymbol{x}^* = (1,1,1,1)^T$  be the solution of the linear system. Suppose  $\{\boldsymbol{x}^{(m)}\}_{m=1}^{\infty}$  and  $\{\boldsymbol{y}^{(m)}\}_{m=1}^{\infty}$  are the sequences of vectors obtained by the Jacobi method and Gauss-Seidel method respectively to solve the linear system with initialization  $\mathbf{x}^{(0)} = \mathbf{y}^{(0)} = (0,0,0,0)^T$ . Let  $\mathbf{e}^{(m)}_I$  $J^{(m)}_{J} := \boldsymbol{x}^{(m)} - \boldsymbol{x}^{*}$  and  $\bm{e}_{GS}^{(m)} := \bm{y}^{(m)} - \bm{x}^*$  be the error vectors at the m-th iteration for the Jacobi and Gauss-Seidel method respectively.

- (a) Show that:  $e_j^{(m)} = -2^{-m}(1, 1, 1, 1)^T$  for  $m \ge 1$ .
- (b) Show that:  $e_{GS}^{(m)} = -4^{-m}(2, 2, 1, 1)^T$  for  $m \ge 1$ .
- (c) Show that  $||e_{GS}^{(m)}||_2 < ||e_{J}^{(m)}||_2$  $\|J^{(m)}\|_2$  for  $m \geq 1$ . Hence, the Gauss-Seidel method converges faster than the Jacobi method.

## Solution:

(a) For Jacobi method, we have

$$
N = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}; P = \begin{pmatrix} 0 & 0 & 1/4 & 1/4 \\ 0 & 0 & 1/4 & 1/4 \\ 1/4 & 1/4 & 0 & 0 \\ 1/4 & 1/4 & 0 & 0 \end{pmatrix}
$$

$$
e_J^{(m)} = x^{(m)} - x^*
$$

so

$$
f_J^{(m)} = x^{(m)} - x^*
$$
  
=  $(N^{-1}P)^m e_J^{(0)}$   
=  $P^m e_J^{(0)}$   
=  $-\frac{1}{2^m} \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$ 

(b) For Gauss Seidel method, we have

$$
N = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -1/4 & -1/4 & 1 & 0 \\ -1/4 & -1/4 & 0 & 1 \end{pmatrix}; P = \begin{pmatrix} 0 & 0 & 1/4 & 1/4 \\ 0 & 0 & 1/4 & 1/4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}
$$

$$
e_{GS}^{(m)} = x^{(m)} - x^*
$$
  
=  $(N^{-1}P)^m e_{GS}^{(0)}$   
=  $\begin{pmatrix} 0 & 0 & 1/4 & 1/4 \\ 0 & 0 & 1/4 & 1/4 \\ 0 & 0 & 1/8 & 1/8 \\ 0 & 0 & 1/8 & 1/8 \end{pmatrix}$   $e_{GS}^{(0)}$   
=  $\begin{pmatrix} 0 & 0 & 1/4^m & 1/4^m \\ 0 & 0 & 1/4^m & 1/4^m \\ 0 & 0 & 1/(2 \cdot 4^m) & 1/(2 \cdot 4^m) \\ 0 & 0 & 1/(2 \cdot 4^m) & 1/(2 \cdot 4^m) \end{pmatrix} \begin{pmatrix} -1 \\ -1 \\ -1 \\ -1 \end{pmatrix}$   
=  $-\frac{1}{4^m} \begin{pmatrix} 2 \\ 2 \\ 1 \\ 1 \end{pmatrix}$ 

- (c) From the definition, we have  $||e_{GS}^{(m)}||_2^2 = \frac{4+4+1+1}{4^{2m}} = \frac{10}{4^{2m}};$  $\Vert e_{J}^{(m)}\Vert$  $\binom{m}{J}$  $\|_2^2 = \frac{1+1+1+1}{2^{2m}} = \frac{4 \cdot 4^{2m}}{4^{2m}}$  $4^{2m}$ Clearly, we have  $10 < 4 \cdot 4^{2m}$  for  $m > 1$ , hence  $||e_{GS}^{(m)}||_2 < ||e_{J}^{(m)}||$  $\|J^{(m)}\|_2$  for  $m > 1$ .
- 2. Consider the linear system  $Ax = b$ , where  $A \in \mathbb{R}^{n \times n}$  is symmetric positive definite. Consider:

$$
f(\boldsymbol{\eta}) = \frac{1}{2}\boldsymbol{\eta}^T A \boldsymbol{\eta} - \boldsymbol{b}^T \boldsymbol{\eta}
$$

- (a) For an iterative scheme  $\mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} + \alpha_k \mathbf{p}_k$ , where  $\mathbf{p}_k$  is a fixed direction, find  $\alpha_k$  such that  $f(\boldsymbol{x}^{(k+1)})$  is minimized.
- (b) The conjugate gradient method is given by

$$
\begin{aligned} \boldsymbol{x}^{(k+1)} &= \boldsymbol{x}^{(k)} + \alpha_k \boldsymbol{p}_k, \\ \boldsymbol{p}_{k+1} &= -\boldsymbol{r}_{k+1} - \beta_k \boldsymbol{p}_k, \\ \beta_k &= -\frac{\langle \boldsymbol{r}_{k+1}, \boldsymbol{p}_k \rangle_A}{\langle \boldsymbol{p}_k, \boldsymbol{p}_k \rangle_A} \end{aligned}
$$

where  $\alpha_k$  is in the form given by (a),  $r_k = Ax^{(k)} - b$ ,  $p_0 = -r_0$ ,  $\langle x, y \rangle_A = x \cdot Ay$ ,  $x^{(0)} \in \mathbb{R}^n$ is an arbitray initial guess. Provided that  $r_i \cdot r_j = 0$  and  $\langle p_i, p_j \rangle_A = 0$  for all  $i \neq j$ , show that  $\beta_k = -\frac{\boldsymbol{r}_{k+1}\cdot\hat{\boldsymbol{r}}_{k+1}}{\boldsymbol{r}_k\cdot\boldsymbol{r}_k}$  $\frac{+1\cdot \boldsymbol{r}_{k+1}}{\boldsymbol{r}_k\cdot \boldsymbol{r}_k}.$ 

## Solution:

- (a) Refer to Lecture 22.
- (b) Note

$$
\mathbf{r}_{k+1} = A\mathbf{x}_{k+1} - \mathbf{b}
$$
  
=  $A(\mathbf{x}_k + \alpha_k \mathbf{p}_k)\mathbf{b}$   
=  $A\mathbf{x}_k - \mathbf{b} + \alpha_k A \mathbf{p}_k$   
=  $\mathbf{r}_k + \alpha_k A \mathbf{p}_k$ 

so

So,

$$
\beta_{k+1} = -\frac{\langle \mathbf{r}_{k+1}, \mathbf{p}_{k} \rangle_{A}}{\langle \mathbf{p}_{k}, \mathbf{p}_{k} \rangle_{A}}
$$
  
\n
$$
= -\frac{\mathbf{r}_{k+1}^{T} A \mathbf{p}_{k}}{-(\mathbf{r}_{k} + \beta_{k-1} \mathbf{p}_{k-1})^{T} A \mathbf{p}_{k}}
$$
  
\n
$$
= \frac{\mathbf{r}_{k+1}^{T} (\mathbf{r}_{k+1} - \mathbf{r}_{k}) / \alpha_{k}}{\mathbf{r}_{k}^{T} A \mathbf{p}_{k} + \beta_{k-1} (\mathbf{p}_{k-1}^{T} A \mathbf{p}_{k})}
$$
  
\n
$$
= \frac{\mathbf{r}_{k+1}^{T} \mathbf{r}_{k+1} / \alpha_{k}}{\mathbf{r}_{k}^{T} (\mathbf{r}_{k+1} - \mathbf{r}_{k}) / \alpha_{k}}
$$
  
\n
$$
= -\frac{\mathbf{r}_{k+1}^{T} \mathbf{r}_{k+1}}{\mathbf{r}_{k}^{T} \mathbf{r}_{k}}
$$

3. Consider the gradient descent method for solving  $Ax = b$  with some  $\alpha \in \mathbb{R}$  and A to be a symmetric positive definite matrix:

$$
\begin{aligned} \boldsymbol{x}^{k+1} &= \boldsymbol{x}^k + \alpha \boldsymbol{d}^k \\ \boldsymbol{d}^k &= -(A\boldsymbol{x}^k - \boldsymbol{b}) \end{aligned}
$$

Prove that the method converges if and only if  $\alpha < \frac{2}{\lambda_j}$  for all j where  $\lambda_j$  are the eigenvalues of A.

Hint: suppose  $\eta$  is the solution to  $Ax = b$ , them  $\eta$  satisfies

$$
\eta = \eta + \alpha(A\eta - b).
$$

Using this equation, start with the error vector  $e^k = x^k - \eta$  to make some observation.

## Solution:

Suppose  $\eta$  is a solution to  $Ax = b$ . Then,

$$
ek = xk - \eta
$$
  
= x<sup>k-1</sup> - \alpha(Ax<sup>k-1</sup> - b) - \eta + \alpha(A\eta - b)  
= (I - \alpha A)x<sup>k-1</sup> - (I - \alpha A)\eta  
= (I - \alpha A)e<sup>k-1</sup>

Thus, like what we learnt in iterative methods, the method converges if and only if  $\rho(I - \alpha A) < 1$ . Suppose A has eigenvalues  $0 < \lambda_1 < \lambda_2 < \cdots < \lambda_{max}$ . The the eigenvalues of the matrix  $I - \alpha A$ are

 $1 - \alpha \lambda_1 > 1 - \alpha \lambda_2 > \cdots > 1 - \alpha \lambda_{max}$ 

To make sure  $\rho(I - \alpha A) < 1$ , we have to make sure

$$
|1 - \alpha \lambda_j| < 1 \text{ for all } j
$$
\n
$$
1 - \alpha \lambda_j < 1 \text{ and } 1 - \alpha \lambda_j > -1
$$

Thus, it means that  $\alpha \lambda_j < 2$  for all j. Thus,  $\alpha < \frac{2}{\lambda_{max}}$ .