

Homework 2 Q3

3. Sec. 1.7: Q7

Prove the following generalization of the replacement theorem. Let β be a basis for a vector space V , and let S be a linearly independent subset of V . There exists a subset S_1 of β such that $S \cup S_1$ is a basis for V .

① $\dim(V) = |\beta| < \infty$? Not necessarily.

② Even $|\beta| = \infty$, β could be a countable / uncountable set.

③ A wrong solution:

If $\dim(V) = \infty$, let $S_1 = \emptyset$

while $\text{span}(S \cup S_1) \neq V$

· select $v \in \beta$ st $S \cup S_1 \cup \{v\}$ L.I. and $v \notin \text{span}(S \cup S_1)$

$S_1 = S_1 \cup \{v\}$

Finally $S_1 = \{v_1, v_2, \dots\}$ and $S_1 \cup S$ is a basis for V

Let F be a field. X is a uncountable set

$V := \{f: X \rightarrow F : \text{all but finitely many } x \in X \text{ satisfy } f(x) = 0\}$

Define Addition and Scalar multiplication for V

$$(af + g)(x) = a \cdot f(x) + g(x) \quad \forall f, g \in V \quad \forall a \in F$$

Let $\beta = \{\delta_x : x \in X\} \subset V$ where $\delta_x(y) = \begin{cases} 1 & \text{if } y=x \\ 0 & \text{if } y \neq x \end{cases}$

It's easy to prove that

- β is a uncountable set
- β is a basis for V .

Thus, we construct a vector space whose basis is a uncountable set

Homework 2 Q4

4. (Extension to Sec. 2.1: Q18) Please find **ALL** linear transformations $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that $N(T) = R(T)$.

• If $N(T) = R(T)$ $\dim(R(T)) = \dim(N(T)) = 1$

$\forall \vec{x} \in \mathbb{R}^2$ $T^2(\vec{x}) = T(\underbrace{T(\vec{x})}_{\in R(T) = N(T)}) = \vec{0} \in \mathbb{R}^2$ $\Rightarrow T^2 = T_0$

$\Rightarrow T \neq T_0$

Claim: $N(T) = R(T) \Leftrightarrow T^2 = T_0$ and $T \neq T_0$.

• If $T^2 = T_0$, $T \neq T_0$.

$\forall \vec{y} \in R(T) \exists \vec{x} \in \mathbb{R}^2$ s.t. $\vec{y} = T(\vec{x})$

$T(\vec{y}) = T(T(\vec{x})) = T^2(\vec{x}) = T_0(\vec{x}) = \vec{0}$

Thus $\vec{y} \in N(T)$ and $R(T) \subset N(T)$

Besides $\begin{cases} T \neq T_0 \Rightarrow \dim(R(T)) \geq 1 \\ T^2 = T_0 \Rightarrow \dim(R(T)) \leq 1 \end{cases} \Rightarrow \dim(R(T)) = 1$

$\Rightarrow \dim(N(T)) = 2 - 1 = 1$

Thus $R(T) = N(T)$

To find the concrete form of T ,
we use the fact:

T is a linear transformation from \mathbb{R}^2 to \mathbb{R}^2

$\Leftrightarrow T(\vec{x}) = A \cdot \vec{x}$, where $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in \mathbb{R}^{2 \times 2}$

Recall that $N(T) = R(T) \Leftrightarrow T^2 = T_0$ and $T \neq T_0$.

$$T(\vec{x}) = A^2 \vec{x} \quad \text{where} \quad A^2 = \begin{pmatrix} a^2+bc & ab+bd \\ ac+cd & d^2+bc \end{pmatrix}$$

$$T^2 = T_0 \Leftrightarrow A^2 = O_{2 \times 2} \Leftrightarrow \begin{cases} a^2+bc = 0 \\ ab+bd = 0 \\ ac+cd = 0 \\ d^2+bc = 0 \end{cases}$$

$$T \neq T_0 \Leftrightarrow A \neq O_{2 \times 2}$$

Case 1: $b=0 \Rightarrow a=d=0$

$$\text{so } A = \begin{pmatrix} 0 & 0 \\ c & 0 \end{pmatrix} \quad \text{where } c \neq 0.$$

Case 2: $b \neq 0 \Rightarrow a=-d$.

$$\text{Besides, } (\det A)^2 = \det A^2 = \det O_{2 \times 2} = 0$$

$$\text{So } ad-bc = \det A = 0, \quad c = -a^2/b$$

$$\text{Thus, } A = \begin{pmatrix} a & b \\ -a^2/b & -a \end{pmatrix} \quad \text{where } b \neq 0, a \in \mathbb{R}$$

see 2.4 Q22

22. Let c_0, c_1, \dots, c_n be distinct scalars from an infinite field F . Define $T: P_n(F) \rightarrow F^{n+1}$ by $T(f) = (f(c_0), f(c_1), \dots, f(c_n))$. Prove that T is an isomorphism.

$$\left(\int_0^1 f(x) dx, \int_1^2 f(x) dx, \dots, \int_n^{n+1} f(x) dx \right)$$

Proof: Recall T is an isomorphism
 $\Leftrightarrow T$ is linear, 1-1, onto

• linear.

• 1-1. $\forall f \in N(T)$.

$$\vec{0} = T(f) = \left(\int_0^1 f(x) dx, \dots, \int_n^{n+1} f(x) dx \right)$$

$$\text{i.e. } \int_k^{k+1} f(x) dx = 0, \quad k=0, \dots, n$$

$$\text{By MVT, } \exists c_k \in (k, k+1) \text{ s.t. } \int_k^{k+1} f(x) dx = f(c_k)(k+1-k)$$

So \exists distinct c_0, c_1, \dots, c_n s.t.

$$f(c_0) = f(c_1) = \dots = f(c_n) = 0.$$

Since f is a polynomial of degree at most n .

we have $f(x) = 0 \quad \forall x$. Thus $N(T) = \{0\}$

• onto.

$$\begin{aligned} \dim(F^{n+1}) &= n+1 = \dim(P_n(F)) \\ &= \dim(N(T)) + \dim(R(T)) \\ &= \dim(R(T)) \end{aligned}$$

$$R(T) \subset F^{n+1} \quad \text{Thus } R(T) = F^{n+1}$$

See 2-4 Q25

25. Let V be a nonzero vector space over a field F , and suppose that S is a basis for V . (By the corollary to Theorem 1.13 (p. 60) in Section 1.7, every vector space has a basis). Let $\mathcal{C}(S, F)$ denote the vector space of all functions $f \in \mathcal{F}(S, F)$ such that $f(s) = 0$ for all but a finite number of vectors in S . (See Exercise 14 of Section 1.3.) Let $\Psi: \mathcal{C}(S, F) \rightarrow V$ be the function defined by

$$\Psi(f) = \sum_{s \in S, f(s) \neq 0} f(s)s.$$

Prove that Ψ is an isomorphism. Thus every nonzero vector space can be viewed as a space of functions.

Proof:

• 1-1 $\forall f \in N(\Psi), \Psi(f) = 0 \in V$

suppose $f \neq 0$ at $\{s_1, \dots, s_k\} \subset S$

$$0 = \Psi(f) = f(s_1) \cdot s_1 + \dots + f(s_k) \cdot s_k. \quad \star$$

since $\{s_1, \dots, s_k\}$ is L.I.

\star has a unique solution $f(s_1) = \dots = f(s_k) = 0$

Thus $f = 0$ and $N(\Psi) = \{0\}$

• onto. $\forall v \in V = \text{span}(S)$.

$$\exists \{s_1, \dots, s_k\} \subset S, \{a_1, \dots, a_k\} \subset F$$

$$\text{st } v = \sum_{i=1}^k a_i \cdot s_i$$

define $f(x) = \begin{cases} a_i & \text{if } x = s_i \\ 0 & \text{elsewhere.} \end{cases}$

Then $f \in \mathcal{C}(S, F)$ and $\Psi(f) = v$.