

Lecture 7:

Discrete Fourier Transform:

Definition:

$$e^{j\theta} = \cos \theta + j \sin \theta$$

The 2D DFT of a $M \times N$ image $g = (g(k, l))_{k,l}$, where $0 \leq k \leq M-1$,

$0 \leq l \leq N-1$ is defined as:

$$\hat{g}(m, n) = \frac{1}{MN} \sum_{k=0}^{M-1} \sum_{l=0}^{N-1} g(k, l) e^{-j2\pi \left(\frac{km}{M} + \frac{ln}{N} \right)}$$

$$\Rightarrow \hat{g} = u g u$$

Remark: The inverse of DFT is given by:

$$g(p, q) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} \hat{g}(m, n) e^{j2\pi \left(\frac{pm}{M} + \frac{qn}{N} \right)}$$

↑
no $\frac{1}{MN}$!

DFT of g

(no -ve sign)

Why is DFT useful in imaging:

1. DFT of convolution:

Recall:
$$g * w(n, m) = \sum_{n'=0}^{N-1} \sum_{m'=0}^{N-1} g(n-n', m-m') w(n', m')$$

$$(g, w \in M_{N \times N}(\mathbb{R}))$$

Then, the DFT of $g * w = MN \text{DFT}(g) \text{DFT}(w)$

∴ DFT of convolution can be reduced to simple multiplication!

Recall: Shift-invariant image transformation = 2D convolution.

∴ Easy computation/manipulation of shift-invariant transf.
after DFT!!

2. Average value of image

$$\text{Average value of } g = \bar{g} = \frac{1}{N^2} \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} g(k, l) = \underbrace{\frac{1}{N^2} \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} g(k, l) e^{-j2\pi(\omega)}}_{\hat{g}(0, 0)}$$

3. DFT of a rotated image

Consider a $N \times N$ image g .

$$\text{Then: } \hat{g}(m, n) = \frac{1}{N^2} \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} g(k, l) e^{-j2\pi\left(\frac{km+ln}{N}\right)}$$

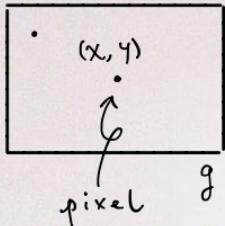
Write k and l in polar coordinates:

$$k \equiv r \cos \theta ; \quad l \equiv r \sin \theta$$

Similarly, write $m \equiv w \cos \phi ; \quad n \equiv w \sin \phi$.

$$\text{Note that: } km + ln = rw (\cos \theta \cos \phi + \sin \theta \sin \phi) = rw \cos(\theta - \phi).$$

Denote $\mathcal{P}(g) = \{(r, \theta) : (r \cos \theta, r \sin \theta) \text{ is a pixel of } g\}$
(Polar coordinate set of g)



If $\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$, then $(r, \theta) \in \mathcal{P}(g)$.

Then: $\hat{g}(m, n) = \hat{g}(\omega, \phi)$ = $\frac{1}{N^2} \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} g(r, \theta) e^{-j2\pi \left(\frac{rw \cos(\theta - \phi)}{N} \right)}$

Identify $\hat{g}(m, n)$ with $\hat{g}(\omega, \phi)$
 Identify $g(k, l)$ with $g(r, \theta)$

Consider a rotated image $\tilde{g}(r, \theta) = g(r, \theta + \theta_0)$ where θ is defined between $-\theta_0$ to $\frac{\pi}{2} - \theta_0$.

\therefore image g is rotated clockwise by θ_0 .

DFT of \tilde{g} is:

$$\hat{\tilde{g}}(\omega, \phi) = \frac{1}{N^2} \sum_{(r, \theta) \in \mathcal{P}(\tilde{g})} \tilde{g}(r, \theta) e^{-j2\pi \left(\frac{rw \cos(\theta - \phi)}{N} \right)} = \frac{1}{N^2} \sum_{(r, \tilde{\theta}) \in \mathcal{P}(g)} g(r, \tilde{\theta}) e^{-j2\pi \left(\frac{rw \cos(\tilde{\theta} - \theta_0 - \phi)}{N} \right)}$$

$\tilde{g}(r, \underbrace{\theta + \theta_0}_{\tilde{\theta}})$

$\therefore \hat{\tilde{g}}(\omega, \phi) = \hat{g}(\omega, \phi + \theta_0)$. (ϕ is also defined between $-\theta_0$ to $\frac{\pi}{2} - \theta_0$)

4. DFT of a shifted image

Let $g = (g(k', l'))$ be a $N \times N$ image, where the indices are taken as:

$$-k_0 \leq k' \leq N-1-k_0 \quad \text{and} \quad -l_0 \leq l' \leq N-1-l_0$$

Let \tilde{g} be shifted image of g defined as:

$$\tilde{g}(k, l) = g(k - k_0, l - l_0) \quad \text{where } 0 \leq k \leq N-1$$

$$\begin{aligned} \text{Then: } \hat{\tilde{g}}(m, n) &= \frac{1}{N^2} \sum_{k=0}^{N-1} \sum_{l=0}^{N-1} g(k - k_0, l - l_0) e^{-j2\pi(\frac{km+ln}{N})} \\ &= \frac{1}{N^2} \sum_{k'=-k_0}^{N-1-k_0} \sum_{l'=-l_0}^{N-1-l_0} g(k', l') e^{-j2\pi(\frac{k'm+l'n}{N})} e^{-j2\pi(\frac{k_0 m + l_0 n}{N})} \\ &\quad \underbrace{\hat{g}(m, n)}_{\text{in red}} \end{aligned}$$

$$\therefore \hat{\tilde{g}}(m, n) = \hat{g}(m, n) e^{-j2\pi(\frac{k_0 m + l_0 n}{N})}$$

Remark: $\hat{g}(m - m_0, n - n_0) = \text{DFT}\left(g \times e^{j2\pi(\frac{m_0 k + n_0 l}{N})}\right)$ with carefully chosen indices!

Mathematics of JPEG

Consider a $N \times N$ image f . Extend f to a $2M \times 2N$ image \tilde{f} , whose indices are taken from $[-M, M - 1]$ and $[-N, N - 1]$.

Define $f(k, l)$ for $-M \leq k \leq M - 1$ and $-N \leq l \leq N - 1$ such that

$$f(-k - 1, -l - 1) = f(k, l) \quad \} \text{ Reflection about } (-1/2, -1/2)$$

$$\begin{aligned} f(-k - 1, l) &= f(k, l) \\ f(k, l - 1) &= f(k, l) \end{aligned} \quad \} \text{ Reflection about the axis } k = -1/2 \text{ and } l = -1/2$$

Example:

	9	8	7	7	8	9	$k = -3$	$f(-1, 1)$
	6	5	4	4	5	6	$k = -2$	"
	3	2	1	1	2	3	$k = -1$	$f(0, 1)$
	3	2	1	1	2	3	$k = 0$	
	6	5	4	4	5	6	$k = 1$	
	9	8	7	7	8	9	$k = 2$	

Reflection about $(-1/2, -1/2)$. $l = -3 \ l = -2 \ l = -1 \ l = 0 \ l = 1 \ l = 2$

$f(-2, -2)$ $f(1, 1)$ $f(-1, 1)$ $f(0, 1)$ $f(1, 1)$ $f(2, 2)$

$k = -1/2$ $k = -1/2$ $k = -1/2$ $k = 1/2$ $k = 1/2$ $k = 1/2$

Reflection about the axis $k = -1/2$.

Make the extension as a reflection about $(0, 0)$, the axis $k=0$ and the axis $\lambda=0$.
Done by shifting the image by $(\frac{1}{2}, \frac{1}{2})$

After shifting

9	8	7	7	8	9	$\frac{1}{2} + (-3)$
6	5	4	4	5	6	$\frac{1}{2} + (-2)$
3	2	1	1	2	3	$\frac{1}{2} + (-1)$
3	2	1	1	2	3	$\frac{1}{2} + 0$
6	5	4	4	5	6	$\frac{1}{2} + 1$
9	8	7	7	8	9	$\frac{1}{2} + 2$
$\frac{1}{2} + -3$	$\frac{1}{2} + -2$	$\frac{1}{2} + -1$	$\frac{1}{2} + 0$	$\frac{1}{2} + 1$	$\frac{1}{2} + 2$	

λ

κ

Now, we compute the DFT of (shifted) \tilde{f} :

$$\begin{aligned} F(m, n) &= \frac{1}{(2M)(2N)} \sum_{k=-M}^{M-1} \sum_{l=-N}^{N-1} f(k, l) e^{-j \frac{2\pi}{2M} m(k + \frac{1}{2})} e^{-j \frac{2\pi}{2N} n(l + \frac{1}{2})} \\ &= \frac{1}{4MN} \sum_{k=-M}^{M-1} \sum_{l=-N}^{N-1} f(k, l) e^{-j(\frac{\pi}{M} m(k + \frac{1}{2}) + \frac{\pi}{N} n(l + \frac{1}{2}))} \\ &= \frac{1}{4MN} \left(\underbrace{\sum_{k=-M}^{-1} \sum_{l=-N}^{-1}}_{A_1} + \underbrace{\sum_{k=-M}^{-1} \sum_{l=0}^{N-1}}_{A_2} + \underbrace{\sum_{k=0}^{M-1} \sum_{l=-N}^{-1}}_{A_3} + \underbrace{\sum_{k=0}^{M-1} \sum_{l=0}^{N-1}}_{A_4} \right) \\ &\quad f(k, l) e^{-j(\frac{\pi}{M} m(k + \frac{1}{2}) + \frac{\pi}{N} n(l + \frac{1}{2}))} \end{aligned}$$

After some messy simplification, we can get:

$$A_1 + A_2 + A_3 + A_4 = \frac{1}{MN} \sum_{k=0}^{M-1} \sum_{l=0}^{N-1} f(k, l) \cos \left[\frac{m\pi}{M} \left(k + \frac{1}{2} \right) \right] \cos \left[\frac{n\pi}{N} \left(l + \frac{1}{2} \right) \right]$$

Definition: (Even symmetric discrete cosine transform [EDCT])

Let f be a $M \times N$ image, whose indices are taken as $0 \leq k \leq M - 1$ and $0 \leq l \leq N - 1$.

The **even symmetric discrete cosine transform (EDCT)** of f is given by:

$$\hat{f}_{ec}(m, n) = \frac{1}{MN} \sum_{k=0}^{M-1} \sum_{l=0}^{N-1} f(k, l) \cos \left[\frac{m\pi}{M} \left(k + \frac{1}{2} \right) \right] \cos \left[\frac{n\pi}{N} \left(l + \frac{1}{2} \right) \right]$$

with $0 \leq m \leq M - 1, 0 \leq n \leq N - 1$

Remark: • Smart idea to get a decomposition consisting only of cosine function
(by reflection and shifting!)

- Can be formulated in matrix form
- Again, it is a separable image transformation.

- The inverse of EDCT can be explicitly computed. More specifically, the **inverse EDCT** is defined as:

$$f(k, l) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} C(m) C(n) \hat{f}_{ec}(m, n) \cos \frac{\pi m(2k+1)}{2M} \cos \frac{\pi n(2l+1)}{2N} \quad (**)$$

where $C(0) = 1, C(m) = C(n) = 2$ for $m, n \neq 0$

Also involving cosine functions only!

- Formula $(**)$ can be expressed as matrix multiplication:

$$f = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} \hat{f}_{ec}(m, n) \vec{T}_m \vec{T}'_n^T$$

elementary images under EDCT!

where: $\vec{T}_m = \begin{pmatrix} T_m(0) \\ T_m(1) \\ \vdots \\ T_m(M-1) \end{pmatrix}, \vec{T}'_n = \begin{pmatrix} T'_n(0) \\ T'_n(1) \\ \vdots \\ T'_n(N-1) \end{pmatrix}$ with $T_m(k) = C(m) \cos \frac{\pi m(2k+1)}{2M}$

and $T'_n(k) = C(n) \cos \frac{\pi n(2k+1)}{2N}$.

This is what JPEG does !!

Note:

(Spatial domain)

$$I * g$$

(Linear filtering:
Linear combination of
neighborhood pixel
values)

$$\downarrow \text{DFT}$$

(Frequency domain)

$$MN \hat{I} \odot \hat{g}$$

pixel-wise
multiplication

(Modifying the
Fourier coefficients
by multiplication)

Image enhancement in the frequency domain:

- Goal:
1. Remove high-frequency components (low-pass filter) for image denoising.
noise
 2. Remove low-frequency components (high-pass filter) for the extraction of image details.
non-edge

High/Low frequency components of \hat{F}

Let F be a $N \times N$ image, $N = \text{even}$. Let $\hat{F} = \text{DFT of } F$.

$$\therefore \hat{F}(k, l) = \frac{1}{N^2} \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} F(m, n) e^{-j \frac{2\pi}{N} (m k + n l)}$$

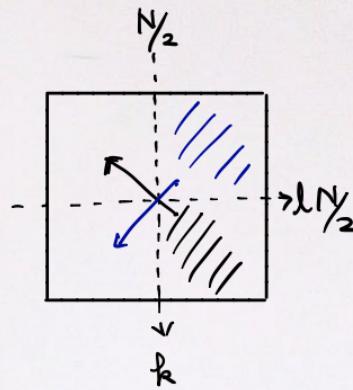
\uparrow
Fourier coefficients of F at (k, l)

Observe that : for $0 \leq k, l \leq \frac{N}{2} - 1$

$$\begin{aligned} \hat{F}\left(\frac{N}{2} + k, \frac{N}{2} + l\right) &= \frac{1}{N^2} \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} F(m, n) e^{-j \frac{2\pi}{N} \left(m\left(\frac{N}{2} + k\right) + n\left(\frac{N}{2} + l\right)\right)} \\ &= \frac{1}{N^2} \sum_{m=0}^{N-1} \sum_{n=0}^{N-1} F(m, n) (-1)^{m+n} e^{-j \frac{2\pi}{N} \left(m(-k) + n(-l)\right)} \end{aligned}$$

$$= \frac{1}{N^2} \overbrace{\sum_{m=0}^{N-1} \sum_{n=0}^{N-1} F(m,n) e^{-j\frac{2\pi}{N}(m(\frac{N}{2}-k) + n(\frac{N}{2}-l))}}^{\hat{F}(\frac{N}{2}-k, \frac{N}{2}-l)}$$

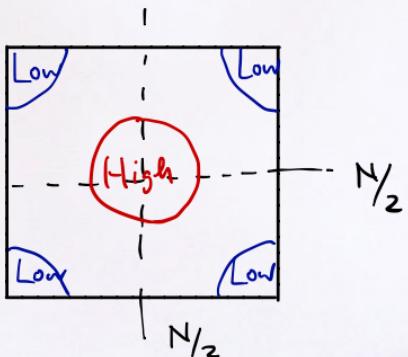
∴ Computing part of \hat{F} can determine the rest !!



Observation:

1. When k and l are close to $\frac{N}{2}$, $\hat{F}\left(\frac{N}{2} + k, \frac{N}{2} + l\right)$ is associated to $e^{j\frac{2\pi}{N}((\frac{N}{2}+k)m+(\frac{N}{2}+l)n)}$
 \therefore Fourier coefficients at the bottom right are associated to low frequency components!
2. Similarly, we can check that Fourier coefficients at the 4 corners are associated to low frequency components.
3. Fourier coefficients in the middle are associated to high-frequency components

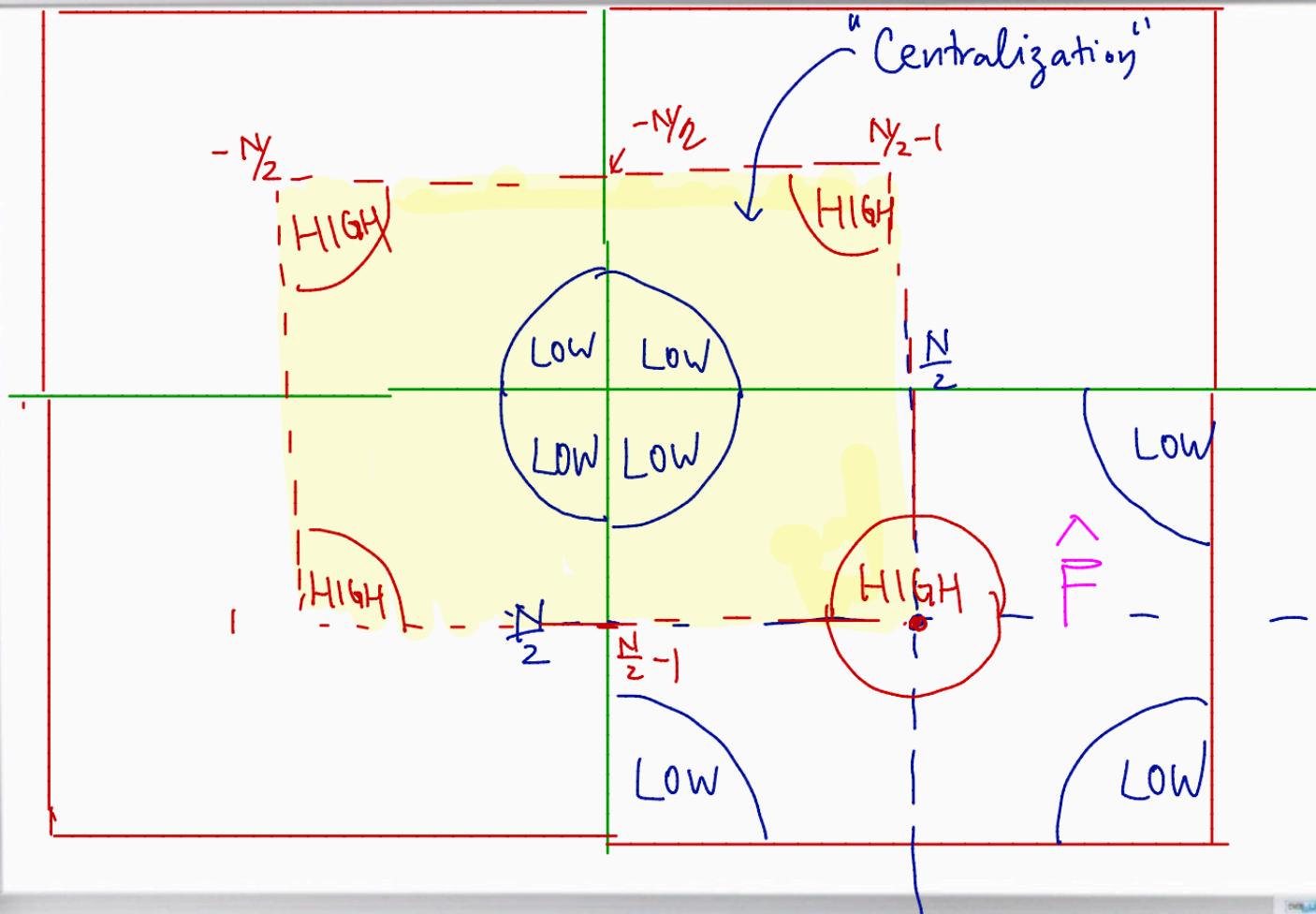
$$e^{j\frac{2\pi}{N}(\frac{N}{2}m+\frac{N}{2}n)} \\ = e^{j\pi(m+n)} = (-1)^{m+n}$$



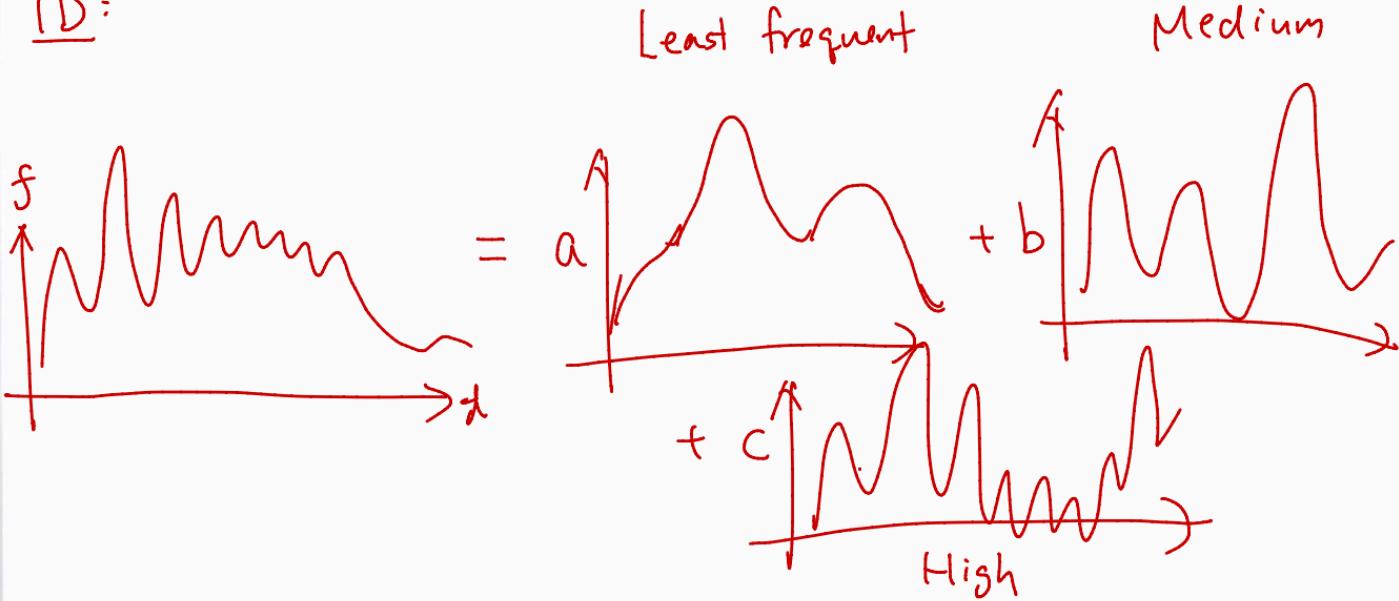
\therefore High-pass filtering
 Remove coefficients at 4 corners
 Low-pass filtering
 Remove " coefficients at the center

Low-frequency
 $\therefore (k, l) \approx (0, 0)$

$$\begin{aligned}
 & e^{j\frac{2\pi}{N}(\frac{N}{2}k+m+\frac{N}{2}l+n)} \\
 & \text{where } (k', l') \\
 & \cos\left(\frac{2\pi}{N}(km+ln)\right) + \\
 & i \sin\left(\frac{2\pi}{N}(km+ln)\right)
 \end{aligned}$$



1D:



To remove noise, truncate c ((let $c=0$)