# CENG 3420 Computer Organization & Design

# Lecture 09: Datapath

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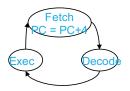
(Textbook: Chapters 4.1 - 4.4)

Spring 2022

#### The Processor: Datapath & Control

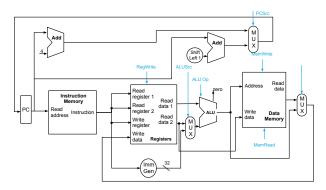


- We're ready to look at an implementation of RISC-V
- Simplified to contain only:
  - Memory-reference instructions: 1w, sw
  - Arithmetic-logical instructions: add, addu, sub, subu, and, or, xor, nor, slt, sltu
  - Arithmetic-logical immediate instructions: addi, addiu, andi, ori, xori, slti, sltiu
  - Control flow instructions: beq, j
- Generic implementation:
  - Use the program counter (PC)
  - To supply the instruction address and fetch the instruction from memory (and update the PC)
  - Decode the instruction (and read registers)
  - Execute the instruction





- Two types of functional units:
  - elements that operate on data values (combinational)
  - elements that contain state (sequential)

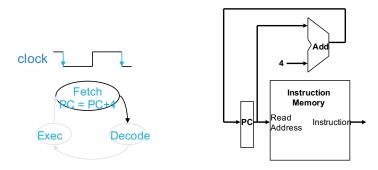


- Single cycle operation
- Split memory (Harvard) model one memory for instructions and one for data

# **Fetching Instructions**



- 1 Reading the instruction from the Instruction Memory
- 9 Updating the PC value to be the address of the next (sequential) instruction
- 8 PC is updated every clock cycle, so it does not need an explicit write control signal
- Instruction Memory is read every clock cycle, so it doesn't need an explicit read control signal





- 1) Sending the fetched instruction's opcode and function field bits to the control unit
- 2 Reading two values from the Register File
- (Register File addresses are contained in the instruction)





- Both RegFile read ports are active for all instructions during the Decode cycle
- Using the rs1 and rs2 instruction field addresses
- Since haven't decoded the instruction yet, don't know what the instruction is
- Just in case the instruction uses values from the RegFile do "work ahead" by reading the two source operands



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#### Question

Which instructions do make use of the RegFile values?



#### EX-1

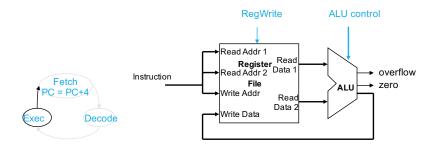
All instructions (except j) use the ALU after reading the registers. Please analyze memory-reference, arithmetic, and control flow instructions.



#### R format operations: add, sub, sll, slt, xor, srl, sra, or, and

31	$25\ 24$	20  19	$15 \ 14 \qquad 1$	2 11	76	0
funct7	rs2	rs1	funct3	rd	opcode	R-type

- Perform operation (op, funct3 or funct7) on values in rs1 and rs2
- Store the result back into the Register File (into location rd)
- Note that Register File is not written every cycle (e.g. sw), so we need an explicit write control signal for the Register File

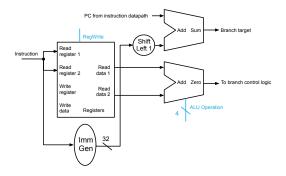




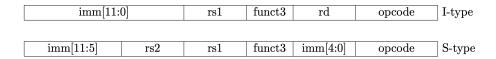
Remember the R format instruction slt

```
slt t0, s0, s1 # if s0 < s1
# then t0 = 1
# else t0 = 0</pre>
```

• Where does the 1 (or 0) come from to store into t 0 in the Register File at the end of the execute cycle?





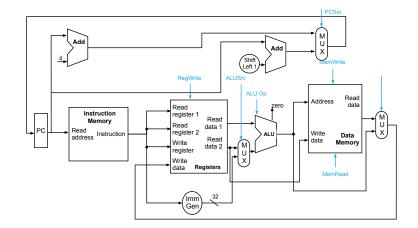


Load and store operations have to

- compute a memory address by adding the base register (in rs1) to the 12-bit signed offset field in the instruction
  - base register was read from the Register File during decode
  - offset value in the low order 12 bits of the instruction must be sign extended to create a 32-bit signed value
- store value, read from the Register File during decode, must be written to the Data Memory
- load value, read from the Data Memory, must be stored in the Register File

#### Executing Load and Store Operations (cont.)







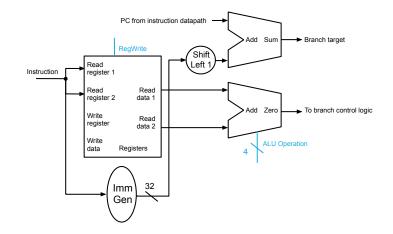
$\operatorname{imm}[12]$ $\operatorname{imm}[10:5]$ rs2	rs1 funct3	imm[4:1]   imm[11	opcode	B-type
---	------------	-------------------	--------	--------

#### Branch operations have to

- compare the operands read from the Register File during decode (rs1 and rs2 values) for equality (zero ALU output)
- The 12-bit B-immediate encodes signed offsets in multiples of 2 bytes.
- The 12-bit immediate offset is sign-extended and added to the address of the branch instruction to give the target address.

#### Executing Branch Operations (cont.)







Γ	imm[20]	imm[10:1]	imm[11]	imm[19:12]	rd	opcode	J-type
	[-0]	[-0:-]	[]	[-•·]		- P	] • • • • • •

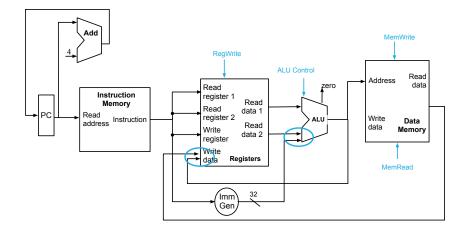
- jal
- The J-immediate encodes a signed offset in multiples of 2 bytes.
- The offset is sign-extended and added to the address of the jump instruction to form the jump target address.



- Assemble the datapath elements, add control lines as needed, and design the control path
- Fetch, decode and execute each instruction in one clock cycle single cycle design
  - no datapath resource can be used more than once per instruction, so some must be duplicated (e.g., why we have a separate Instruction Memory and Data Memory)
  - to share datapath elements between two different instruction classes will need multiplexors at the input of the shared elements with control lines to do the selection
- Cycle time is determined by length of the longest path

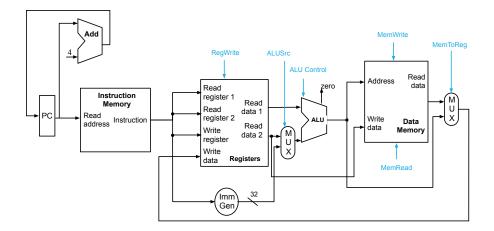
#### **Multiplex Insertion**



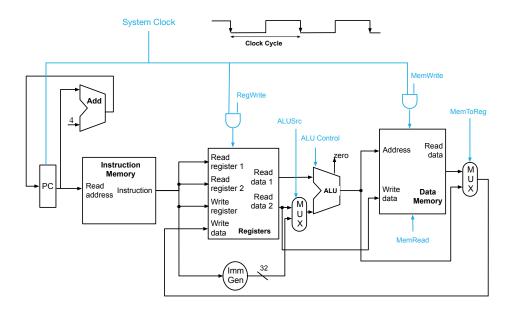


#### **Multiplex Insertion**



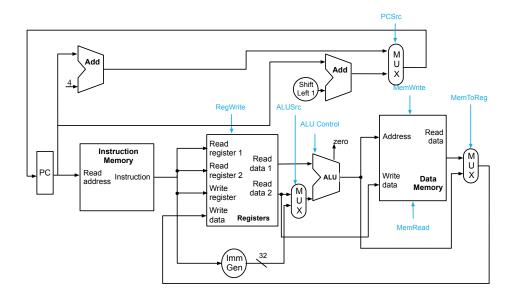






#### Adding the Branch Portion







- We wait for everything to settle down
  - ALU might not produce "right answer" right away
  - Memory and RegFile reads are combinational (as are ALU, adders, muxes, shifter, signextender)
  - Use write signals along with the clock edge to determine when to write to the sequential elements (to the PC, to the Register File and to the Data Memory)
- The clock cycle time is determined by the logic delay through the longest path
- (We are ignoring some details like register setup and hold times)

- Selecting the operations to perform (ALU, Register File and Memory read/write)
- Controlling the flow of data (multiplexor inputs)
- Information comes from the 32 bits of the instruction

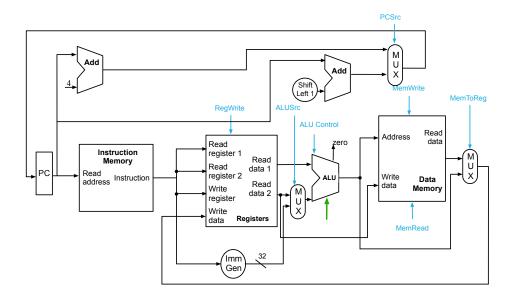
	31	25	24 20	19	15  14	$12 \ 11$	76	0
	fun	ct7	rs2	rs1	funct	3 rd	opcoe	de R-type
		imm[11:	0]	rs1	funct	t3 rd	opco	de I-type
Obser	vations	5:				·	·	

- opcode field always in bits 6-0
- address of two registers to be read are always specified by the rs1 and rs2 fields (bits 19–15 and 24–20)
- base register for lw and sw always in rs1 (bits 19–15)



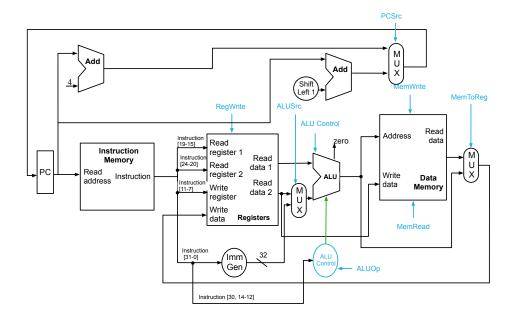
# (Almost) Complete Single Cycle Datapath





# (Almost) Complete Single Cycle Datapath







ALU's operation based on instruction type and function code<sup>1</sup>

	Europetiana
ALU control	Function
input	
0000	and
0001	or
0010	xor
0011	nor
0110	add
1110	subtract
1111	set on less than

<sup>&</sup>lt;sup>1</sup>Notice that we are using different encodings than in the book

#### EX: ALU Control



Controlling the ALU uses of multiple decoding levels

- main control unit generates the ALUOp bits
- ALU control unit generates ALUcontrol bits

Instr op	funct	ALUOp	action	ALUcontrol
lw	XXXXXX	00		
sw	XXXXXX	00		
beq	XXXXXX	01		
add	100000	10	add	0110
subt	100010	10	subtract	1110
and	100100	10	and	0000
or	100101	10	or	0001
xor	100110	10	xor	0010
nor	100111	10	nor	0011
slt	101010	10	slt	1111



F5	F4	F3	F2	F1	F0	ALU Op <sub>1</sub>	ALU Op <sub>0</sub>	ALU control <sub>3</sub>	ALU control <sub>2</sub>	ALU control <sub>1</sub>	ALU control <sub>0</sub>
Х	Х	Х	Х	Х	Х	0	0	0	1	1	0
Х	Х	Х	Х	Х	Х	0	1	1	1	1	0
Х	Х	0	0	0	0	1	0	0	1	1	0
Х	Х	0	0	1	0	1	0	1	1	1	0
Х	Х	0	1	0	0	1	0	0	0	0	0
Х	Х	0	1	0	1	1	0	0	0	0	1
Х	Х	0	1	1	0	1	0	0	0	1	0
Х	Х	0	1	1	1	1	0	0	0	1	1
Х	Х	1	0	1	0	1	0	1	1	1	1



F5	F4	F3	F2	F1	F0	ALU Op <sub>1</sub>	ALU Op <sub>0</sub>	ALU control <sub>3</sub>	ALU control <sub>2</sub>	ALU control <sub>1</sub>	ALU control <sub>0</sub>
Х	Х	Х	Х	Х	Х	0	0		1	1	0
Х	Х	Х	Х	Х	Х	0	1	1	1	1	9
Х	Х	0	0	0	0	1	0	0	/1	1	0 \
Х	Х	0	0	1	0	1	0	1	1	1	0
Х	Х	0	1	0	0	1	0	0	0	0	0
Х	Х	0	1	0	1	1	0	0	0	0	1
Х	Х	0	1	1	0	1	0	0	0	1	0 /
Х	Х	0	1	1	1	1	0	0	6	1	1/
Х	Х	1	0	1	0	1	0		1	1	1

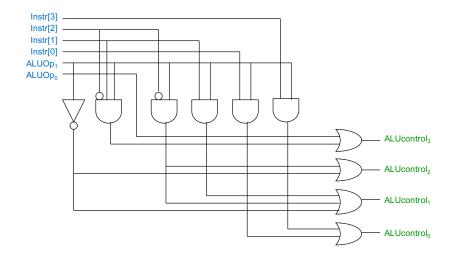
Add/subt

Mux control

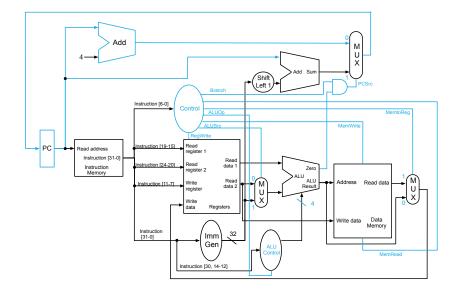
#### ALU Control Logic



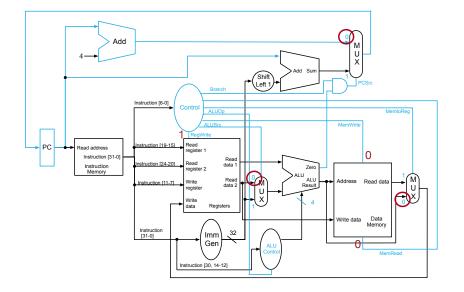
From the truth table can design the ALU Control logic



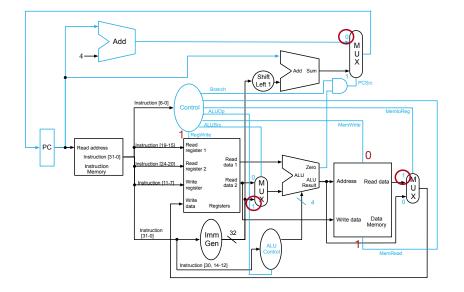




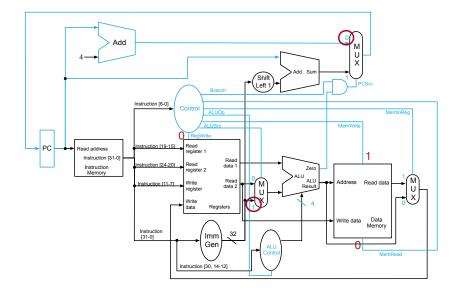




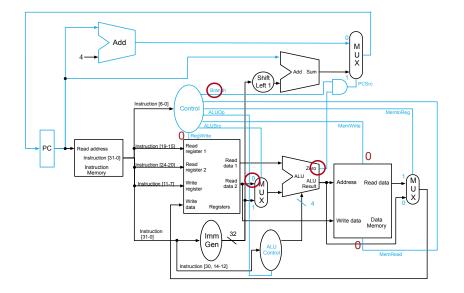














Instr	RegDst	ALUSrc	MemReg	RegWr	MemRd	MemWr	Branch	ALUOp
<b>R-type</b>	1	0	0	1	0	0	0	10
<b>lw</b> 100011	0	1	1	1	1	0	0	00
<b>sw</b> 101011	Х	1	X	0	0	1	0	00
<b>beq</b> 000100	X	0	X	0	0	0	1	01

# Control Unit Logic



