

NEAR-OPTIMAL MAP INFERENCE
FOR
DETERMINANTAL POINT PROCESSES

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IMAGE SEARCH: "JAGUAR"

Relevance
only:



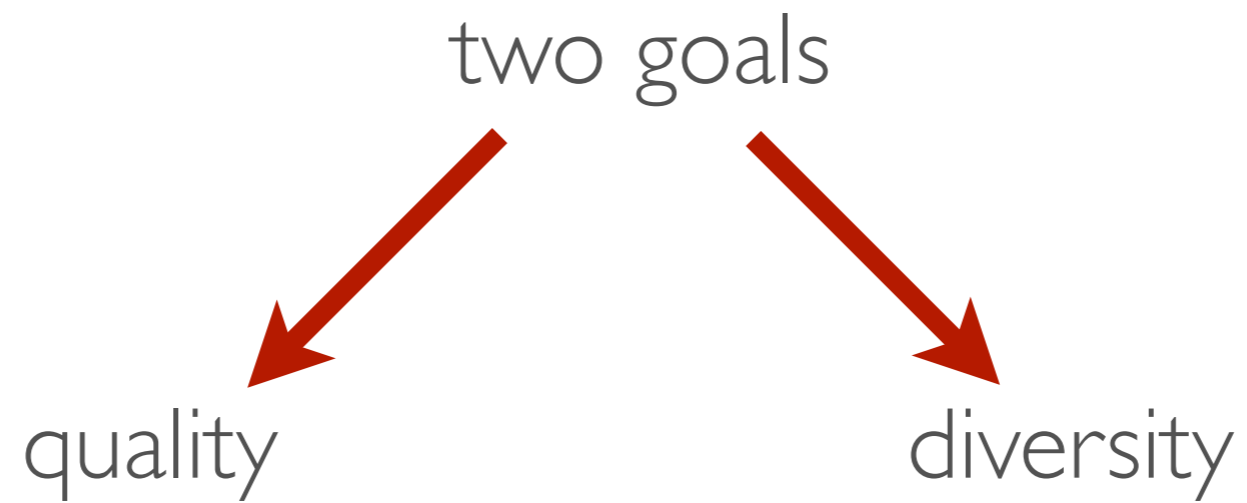
...

Relevance
+ diversity:



...

TASK: SUBSET SELECTION



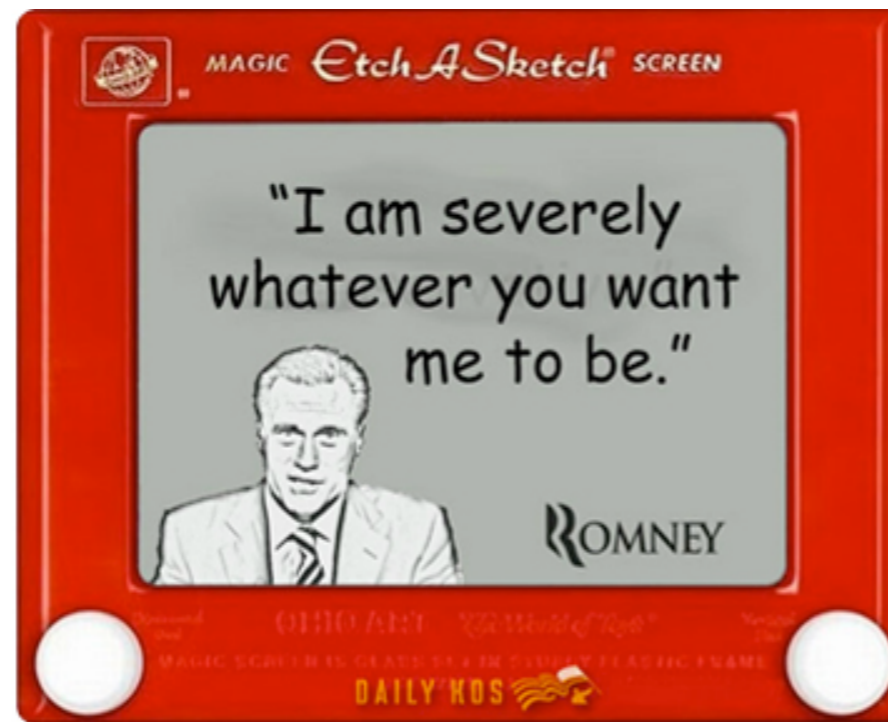
MATCHED SUMMARIZATION

Task:

Given a set of documents, select a set of doc pairs such that:

- 1) the pairs are high-quality (docs within a pair are similar), and
- 2) the overall set of pairs is diverse.

MATCHED SUMMARIZATION



Ground set: All possible (old, new) pairs.

- ▶ **Old (topic = bailout): Let Detroit go bankrupt.**
- ▶ **New (topic = bailout) : I'm not willing to sit back and say 'Too bad for Michigan'.**
- ▶ **Old (topic = bailout): Let Detroit go bankrupt.**
- ▶ **New (topic = abortion): The right next step ... is to see Roe vs Wade overturned.**

Quality only:

- ▶ **Old (topic = bailout): Let Detroit go bankrupt.**
- ▶ **New (topic = bailout): I'm not willing to sit back and say 'Too bad for Michigan'.**

- ▶ **Old (topic = bailout): I think there is need for economic stimulus.**
- ▶ **Old (topic = bailout): I have never supported the President's recovery act.**

- ▶ **Old (topic = bailout): TARP ought to be ended.**
- ▶ **New (topic = bailout): TARP got paid back and it kept the financial system from collapsing.**

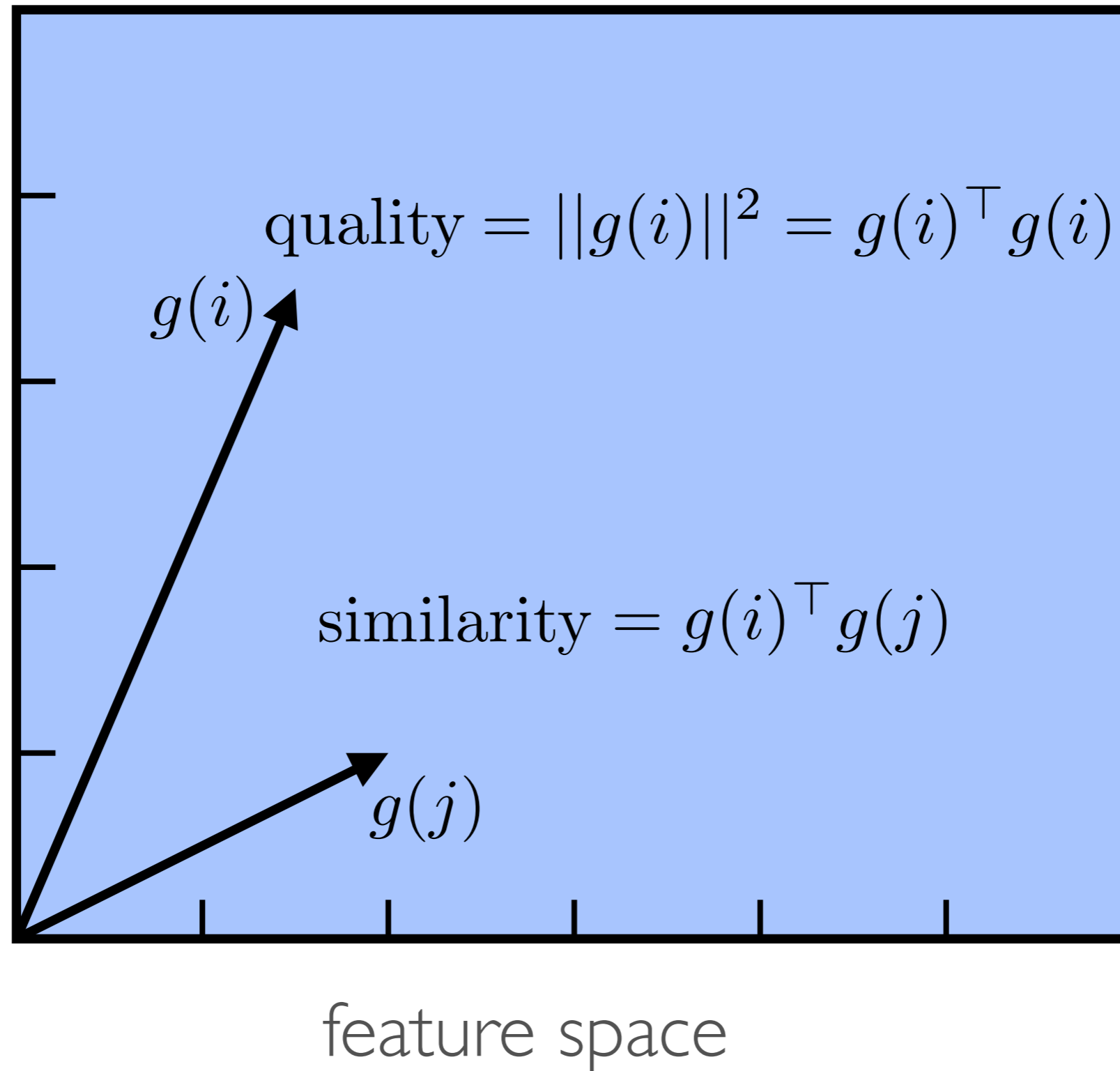
Quality + diversity:

- ▶ **Old (topic = bailout): Let Detroit go bankrupt.**
- ▶ **New (topic = bailout): I'm not willing to sit back and say 'Too bad for Michigan'.**

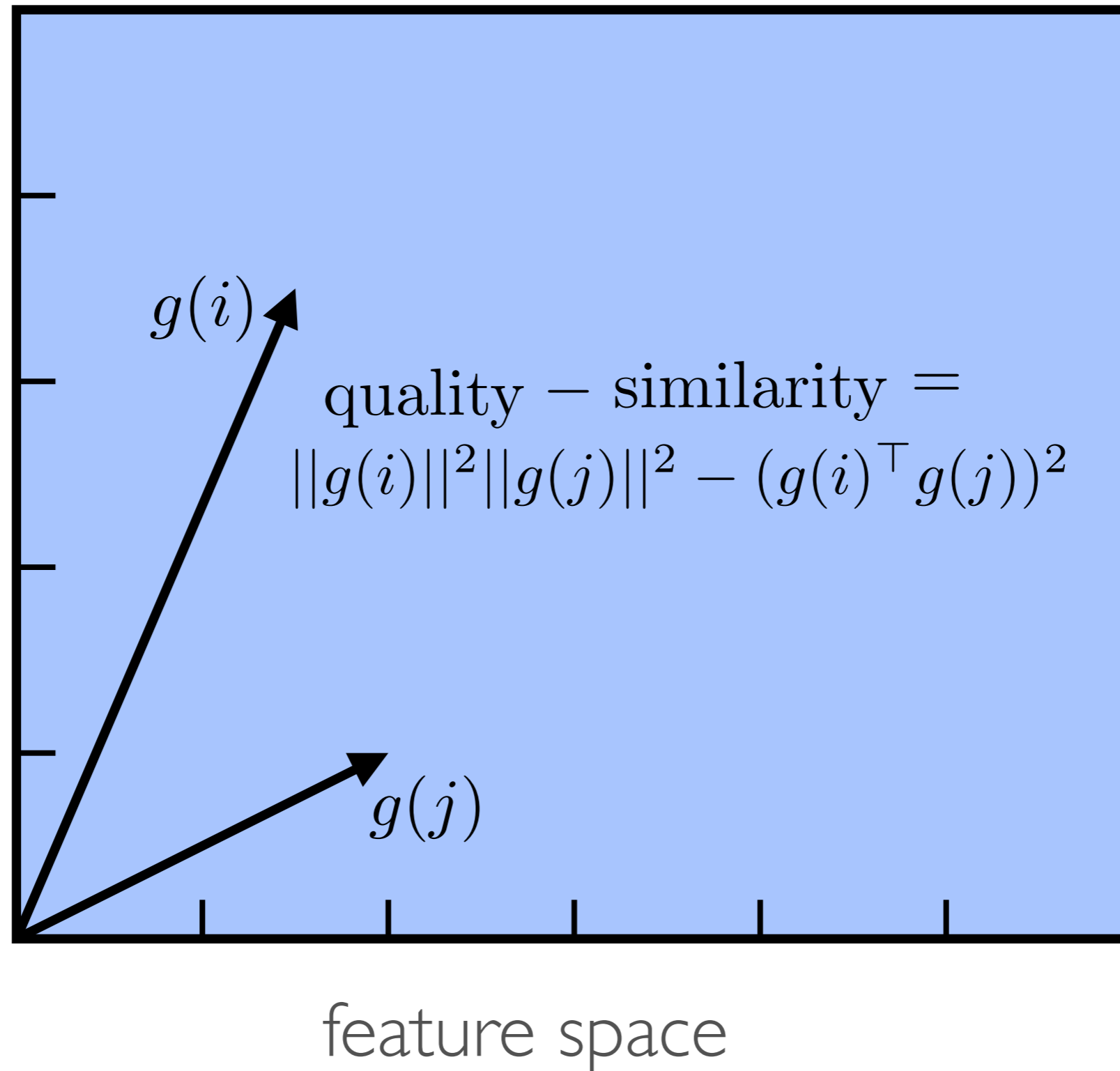
- ▶ **Old (topic = abortion): I will preserve and protect a woman's right to choose.**
- ▶ **New (topic = abortion): The right next step ... is to see Roe vs Wade overturned.**

- ▶ **Old (topic = gun control): I just signed a major piece of legislation extending the ban on certain assault weapons.**
- ▶ **New (topic = gun control): I do not support any new legislation of an assault weapon ban nature.**

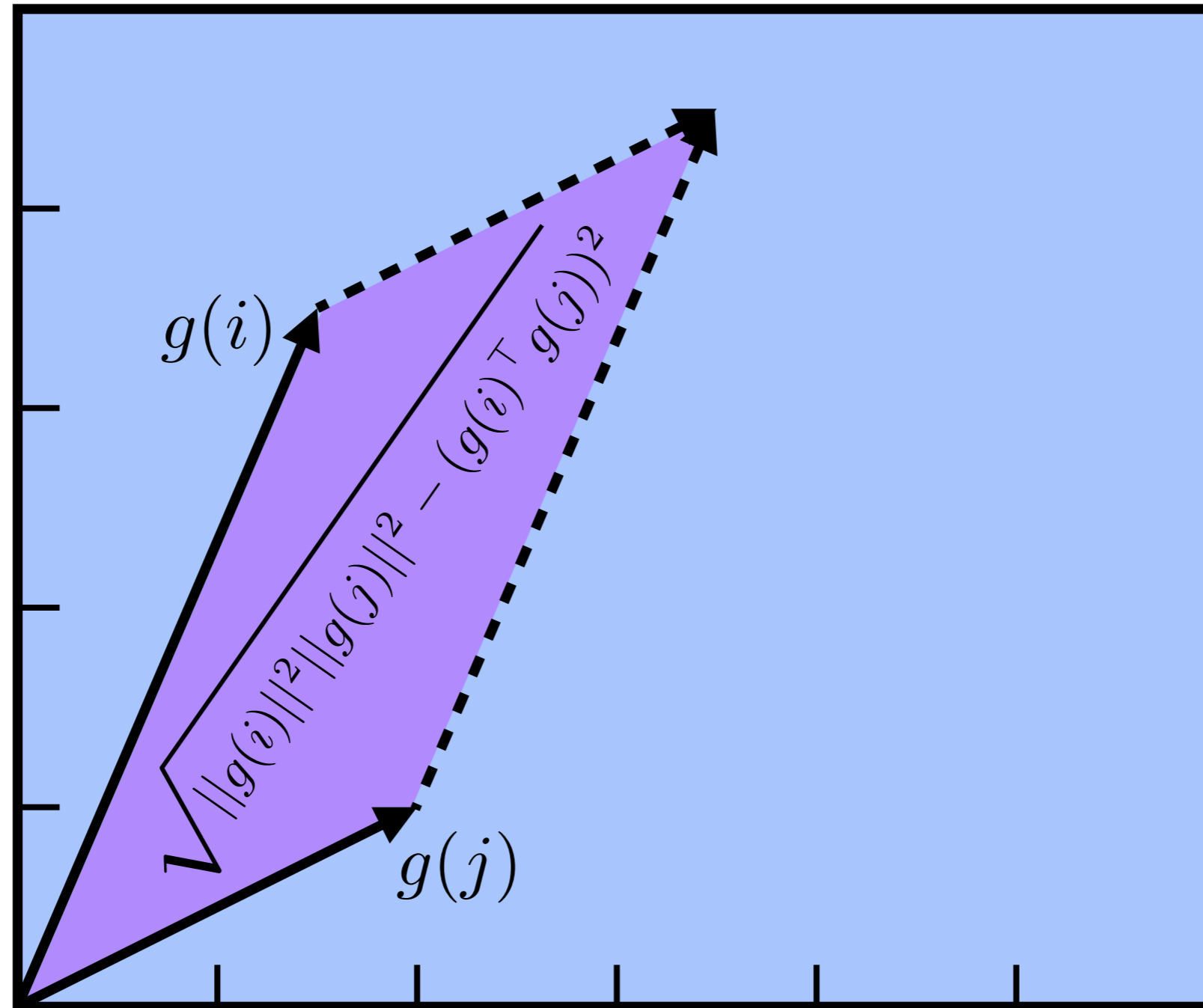
FORMALIZING



FORMALIZING



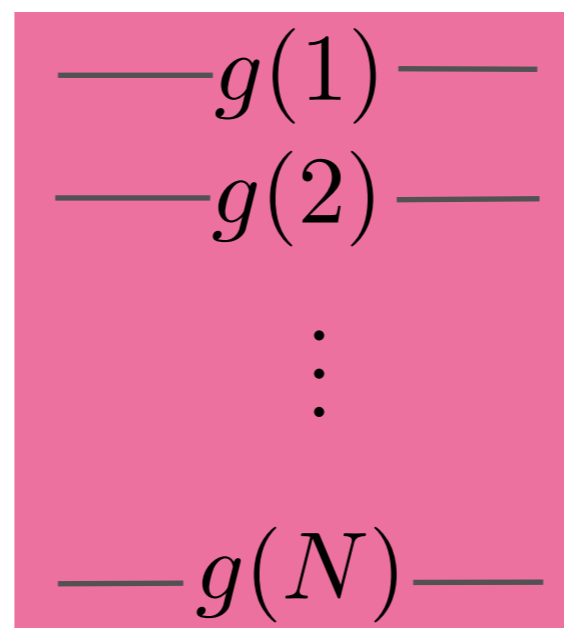
FORMALIZING



AREA AS A DET

$$\|g(i)\|^2 \|g(j)\|^2 - (g(i)^\top g(j))^2$$

$$= \det \begin{pmatrix} \|g(i)\|^2 & g(i)^\top g(j) \\ g(i)^\top g(j) & \|g(j)\|^2 \end{pmatrix}$$


$$\begin{array}{c} \text{---}g(1)\text{---} \\ \text{---}g(2)\text{---} \\ \vdots \\ \text{---}g(N)\text{---} \end{array}$$

AREA AS A DET

$$\|g(i)\|^2 \|g(j)\|^2 - (g(i)^\top g(j))^2$$

$$= \det \begin{pmatrix} \|g(i)\|^2 & g(i)^\top g(j) \\ g(i)^\top g(j) & \|g(j)\|^2 \end{pmatrix}$$

$$= \det \left(\begin{array}{|c|c|} \hline \text{---}g(i)\text{---} & \text{---} \\ \hline \text{---}g(j)\text{---} & \text{---} \\ \hline \end{array} \begin{array}{|c|c|} \hline \text{---} \\ \hline g(i) \text{---} \\ \hline \text{---} \\ \hline g(j) \text{---} \\ \hline \end{array} \right)$$

VOLUME AS A DET

“goodness” of $\{i, j\}$ = quality & diversity of $\{i, j\}$
 $\propto \text{area}(\{i, j\})^2$

volume₁ = length

volume₂ = area

volume₃ = 3D-volume

$$|Y| = d \rightarrow \text{volume}_d(Y)^2 \propto \det((GG^\top)_Y)$$

for positive semi-definite $L = GG^\top$

$$\mathcal{P}(Y) \propto \det(L_Y)$$

VOLUME AS A DET

“goodness” of $\{i, j\}$ = quality & diversity of $\{i, j\}$
 $\propto \text{area}(\{i, j\})^2$

**Determinantal
Point
Process**

$$|Y| = d \rightarrow \text{volume}_d(Y)^2 \propto \det((GG^\top)_Y)$$

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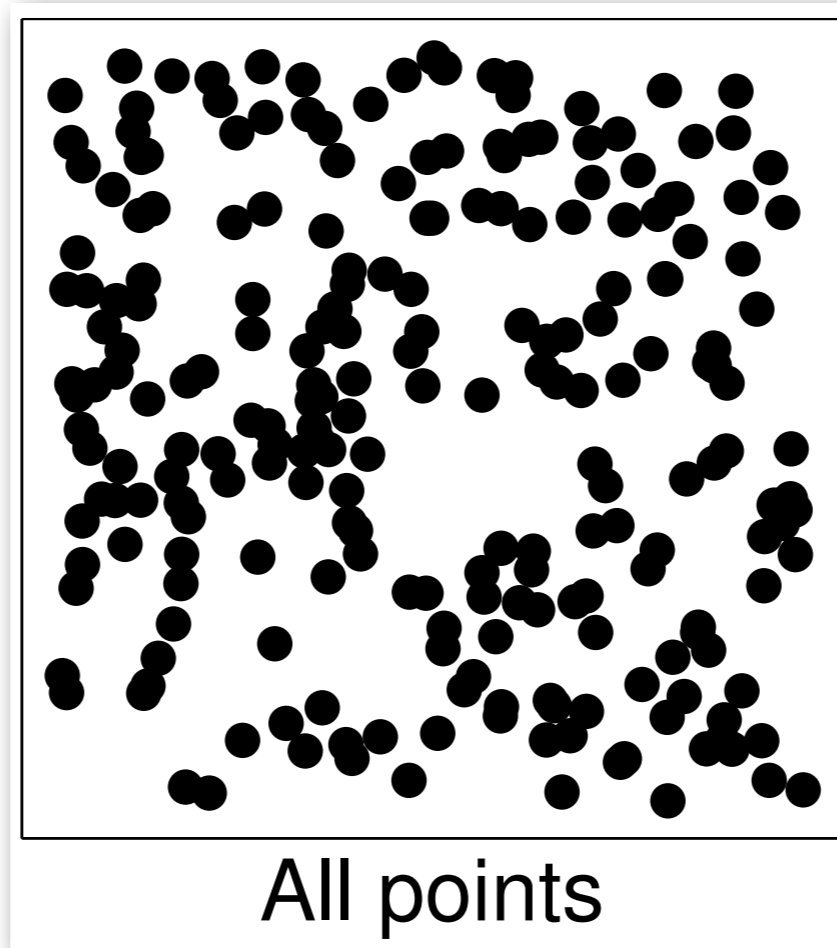
DPP INFERENCE

- Exact and efficient $O(N^3)$
 - normalization: $\sum_Y \det(L_Y) = \det(L + I)$
 - marginalization: $\mathcal{P}(A \subseteq Y)$
 - conditioning: $\mathcal{P}(A \mid B \subseteq Y)$
 - sampling: $Y \sim \mathcal{P}(Y) \propto \det(L_Y)$

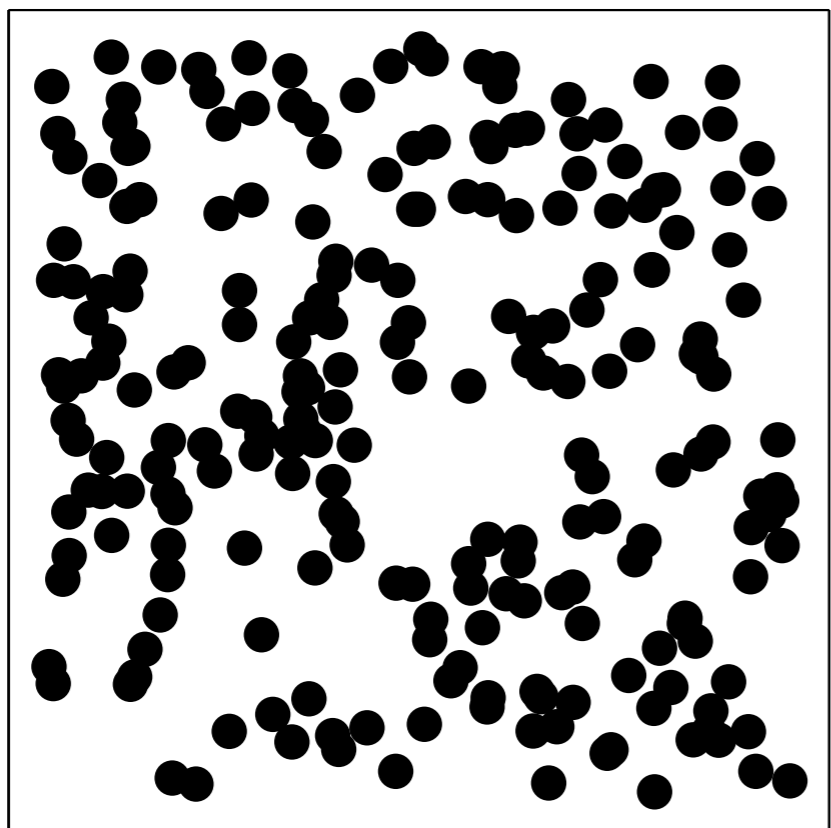
DPP INFERENCE

What about DPP MAP?

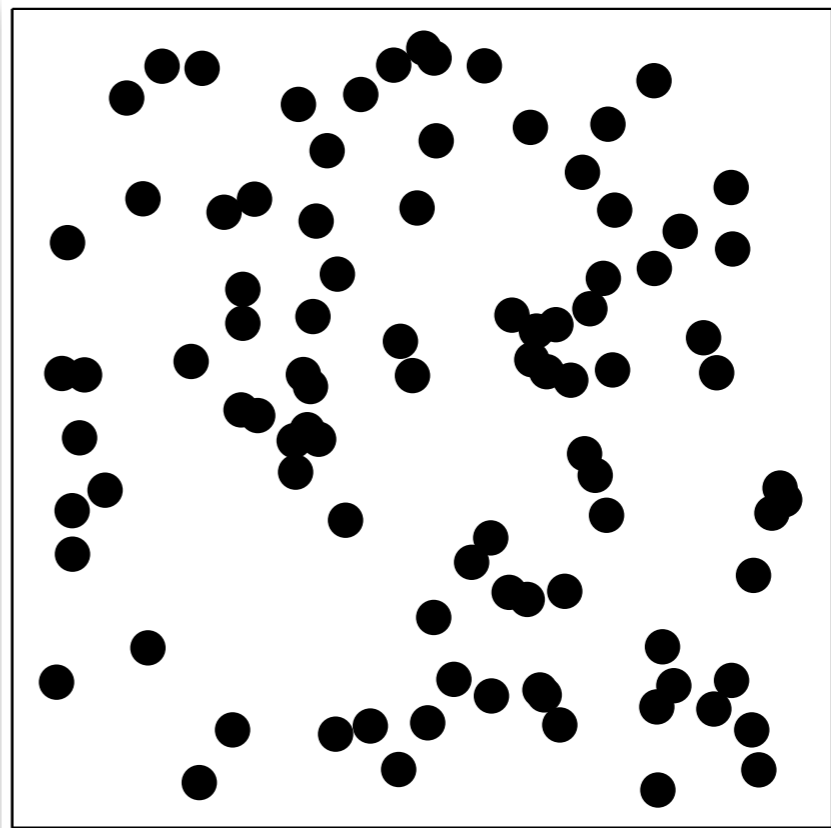
$$\arg \max_Y \det(L_Y)$$



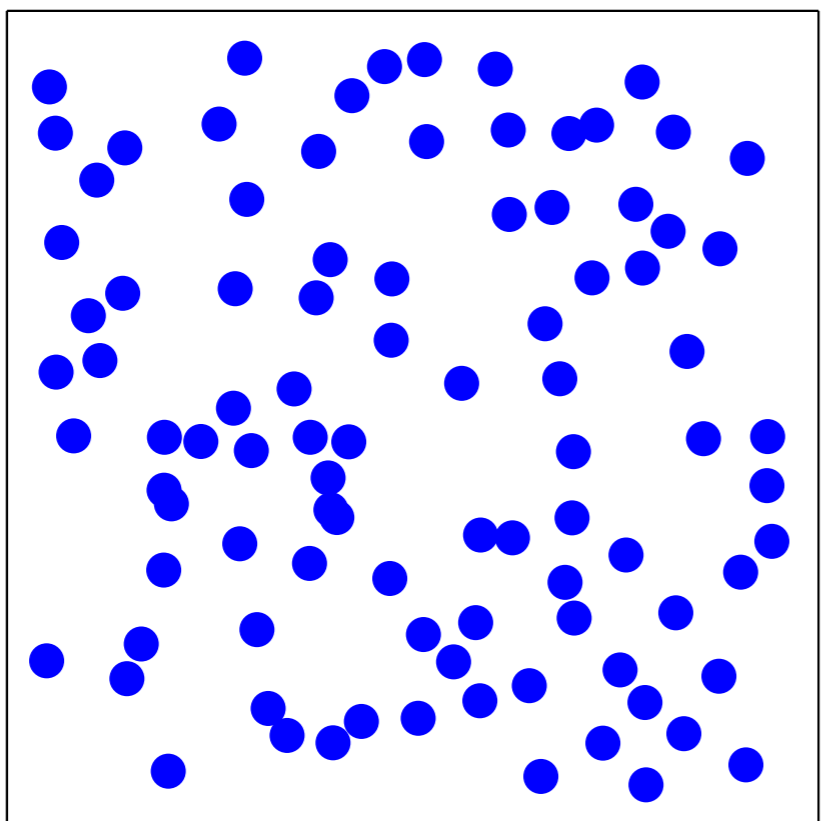
$$g(i)^\top g(j) = L_{ij} = \exp(-\|p_i - p_j\|^2)$$



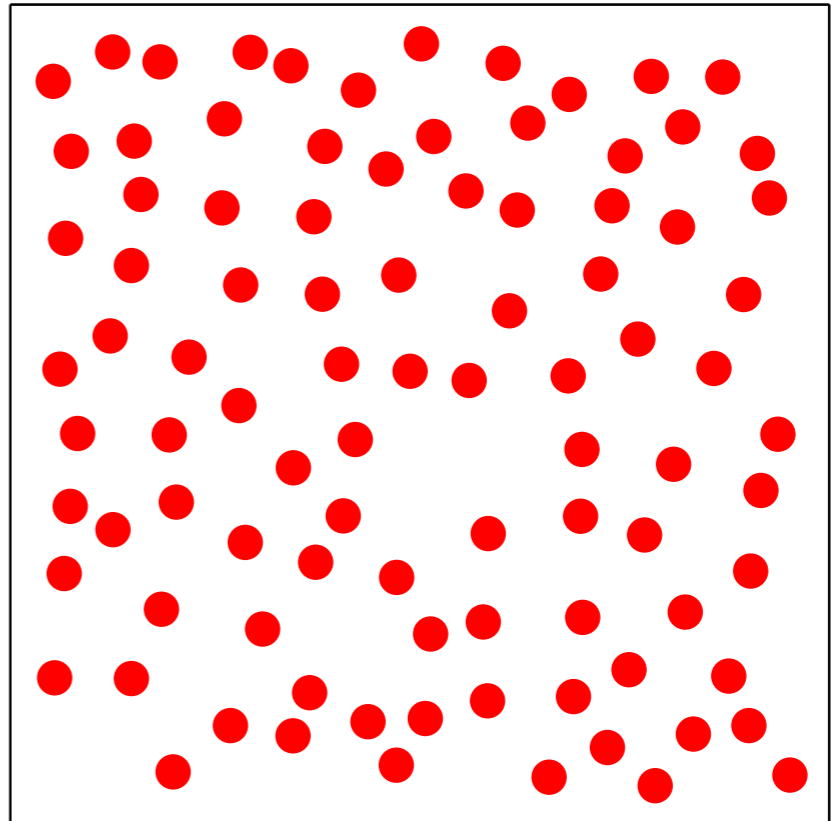
All points



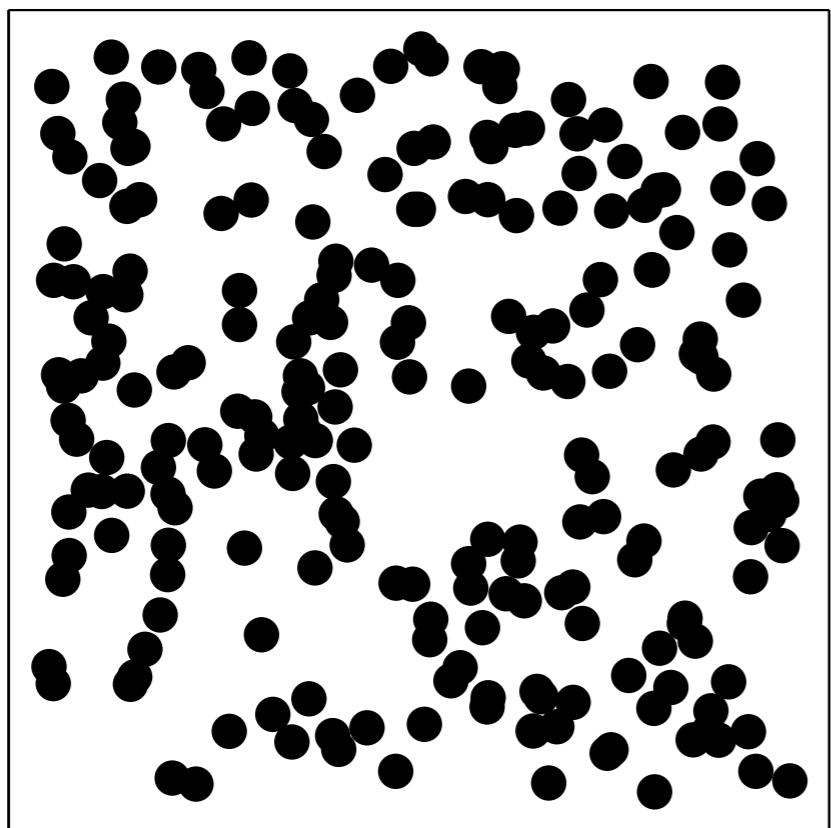
Independent sample



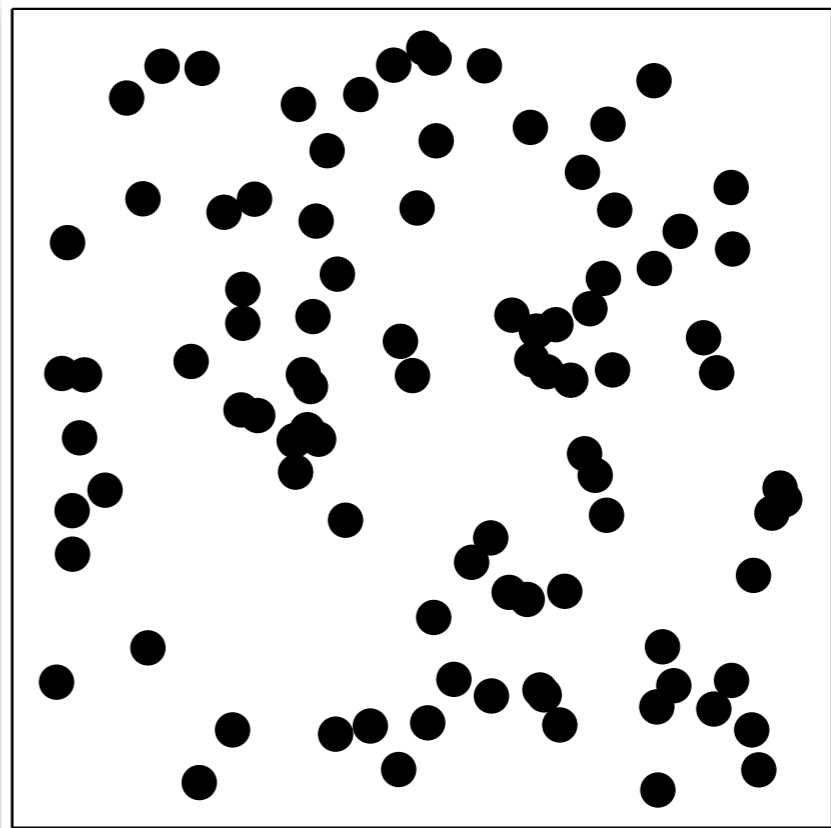
DPP sample



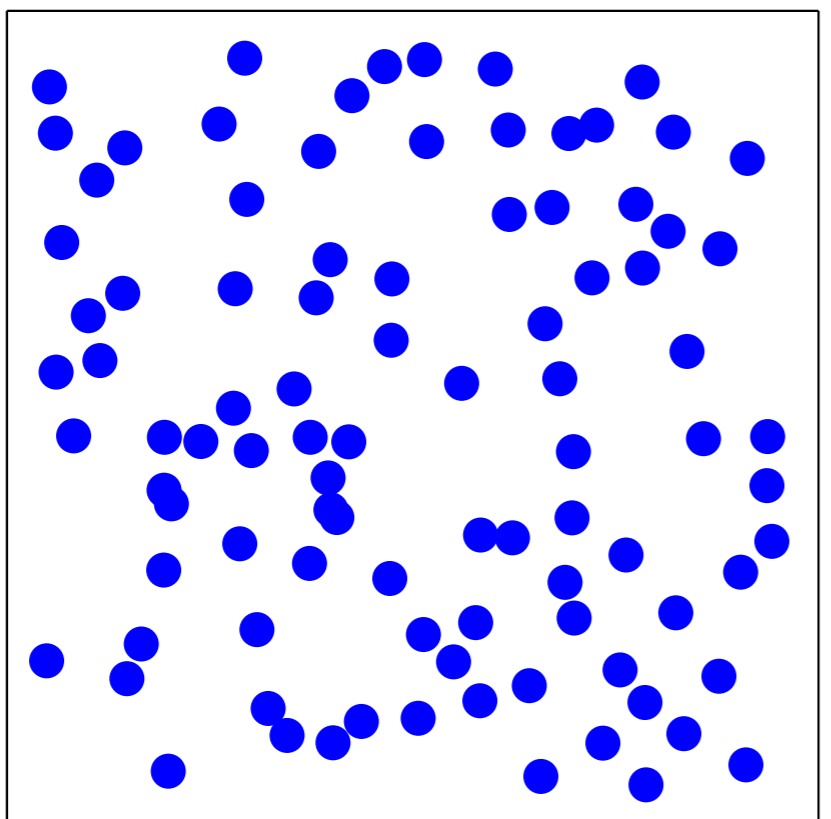
DPP (approx) MAP



All points



Independent sample



DPP sample



DPP (approx) MAP

SUBMODULARITY TO THE RESCUE

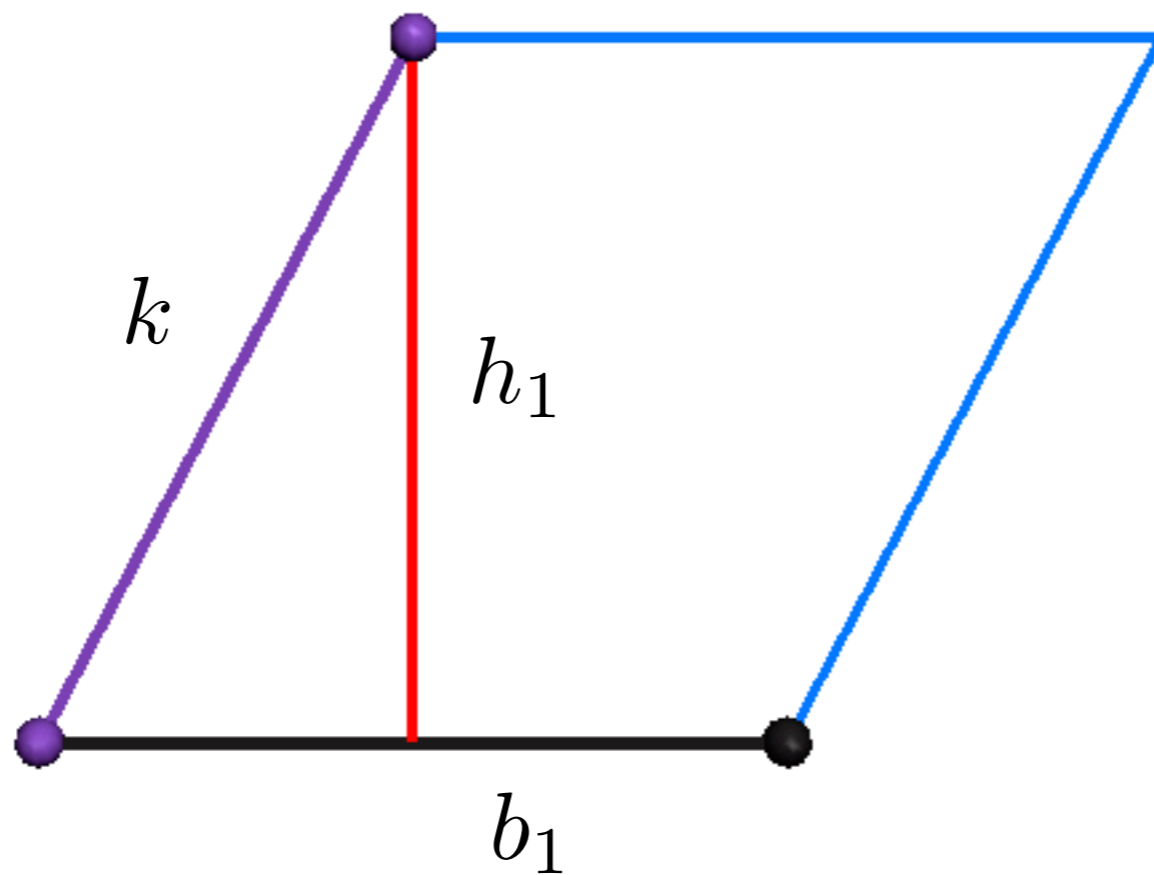
$f(Y) = \det(L_Y)$ is log-submodular

Diminishing returns:

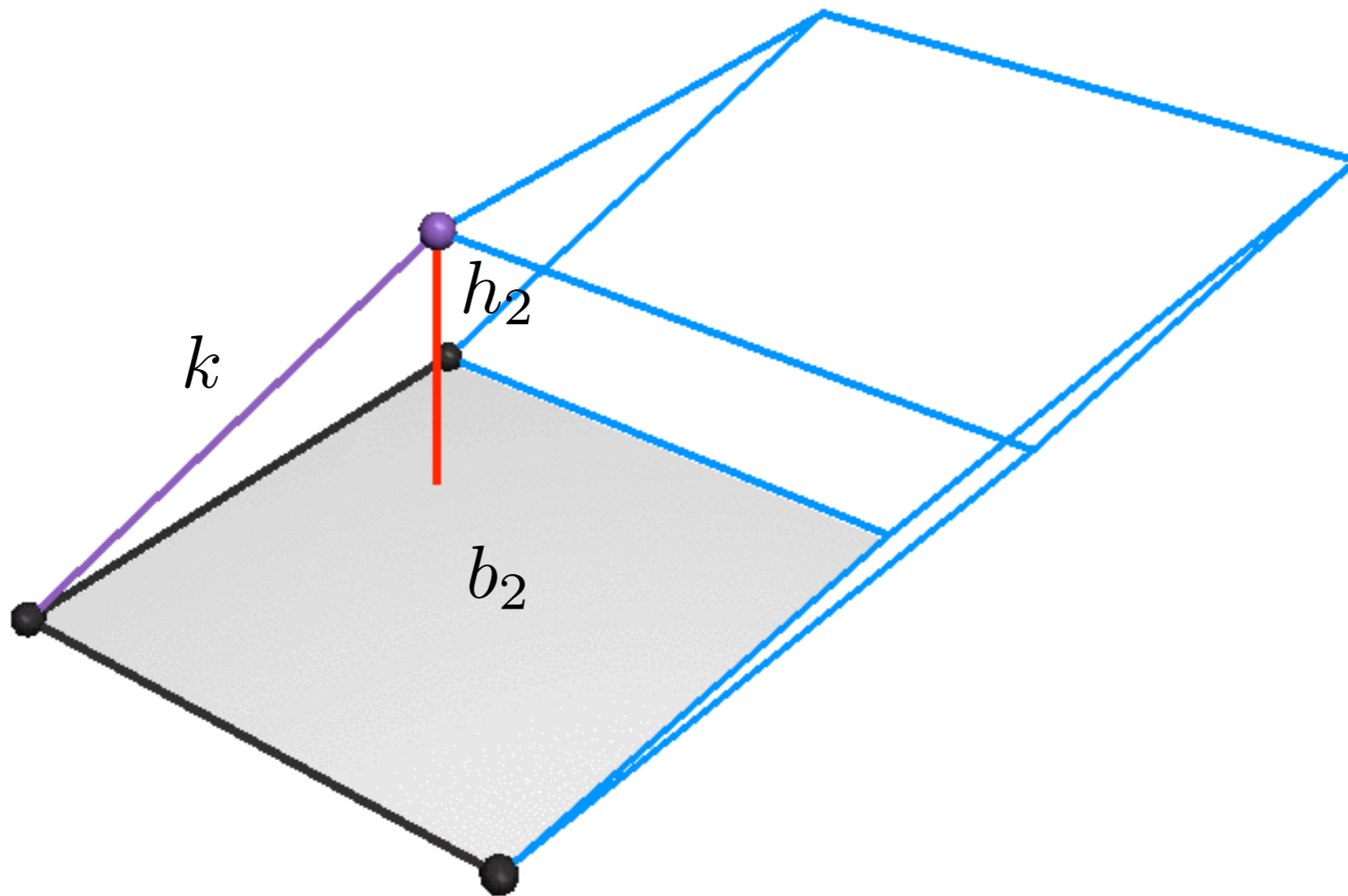
$$\frac{f(Y \cup \{k\})}{f(Y)} \leq \frac{f(X \cup \{k\})}{f(X)}$$

$$X \subseteq Y, k \notin Y$$

$$\frac{\text{vol}(X \cup \{k\})}{\text{vol}(X)} = \frac{b_1 h_1}{b_1} = h_1$$

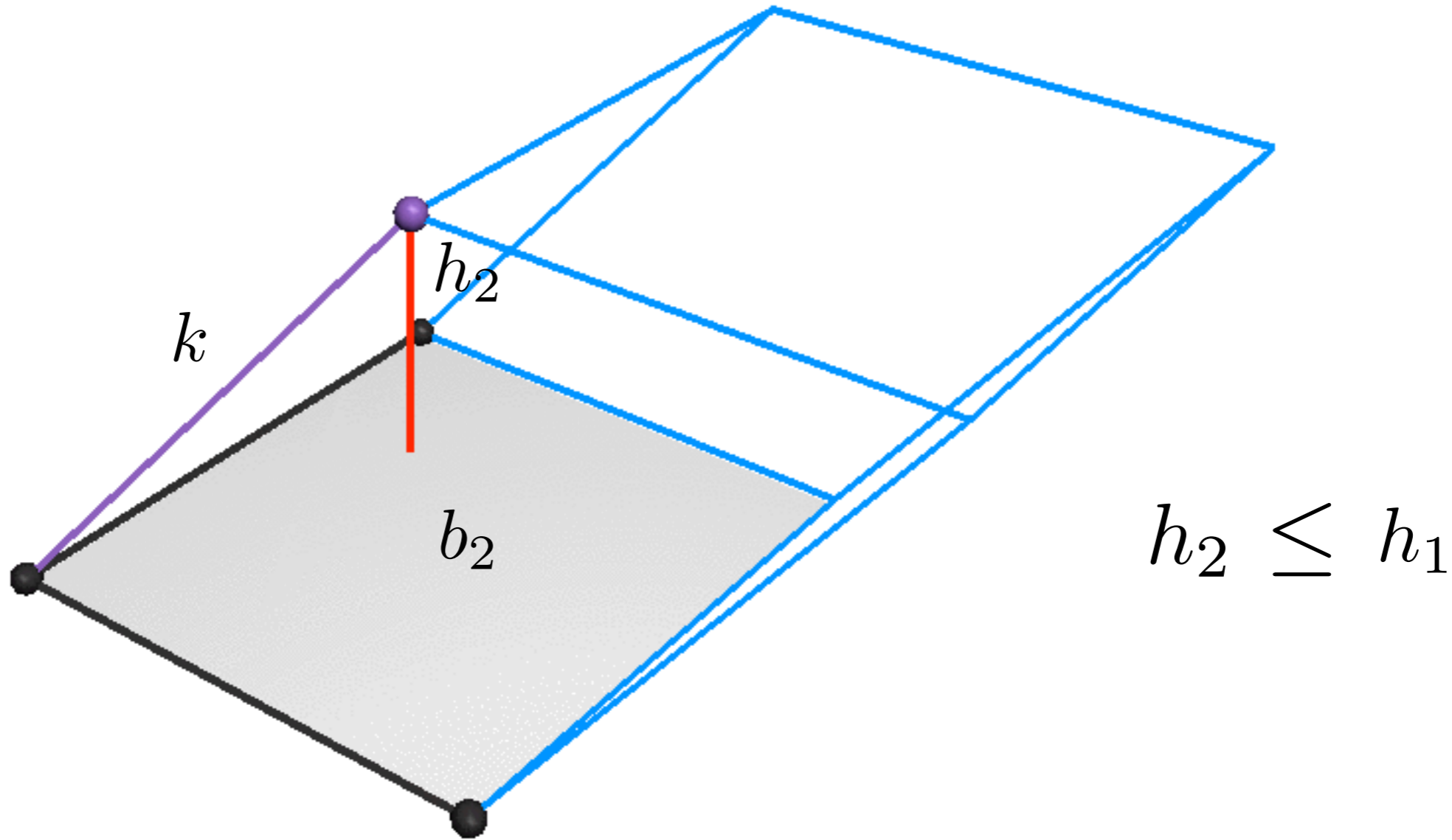


$$\frac{\text{vol}(X \cup \{k\})}{\text{vol}(X)} = \frac{b_1 h_1}{b_1} = h_1$$



$$\frac{\text{vol}(Y \cup \{k\})}{\text{vol}(Y)} = \frac{b_2 h_2}{b_2} = h_2$$

$$\frac{\text{vol}(X \cup \{k\})}{\text{vol}(X)}$$



$$h_2 \leq h_1$$

$$\frac{\text{vol}(Y \cup \{k\})}{\text{vol}(Y)}$$

MONOTONICITY

$$X \subseteq Y \implies f(X) \leq f(Y)$$

Det is non-monotone: $\det(L_X) > \det(L_Y)$ for some X, Y



PRIOR WORK

Monotone:

“greedy” $(1 - 1/e)$ -approx
Nemhauser and Wolsey (1978)

Non-monotone:

“symmetric greedy” $1/2$ -approx
Buchbinder et al. (2012)



Performs poorly in practice

Non-monotone + constraints:

“multilinear” $1/4$ -approx sans constraints,
various (lesser) guarantees dependent on constraint type
Chekuri et al. (2011)

PRIOR WORK

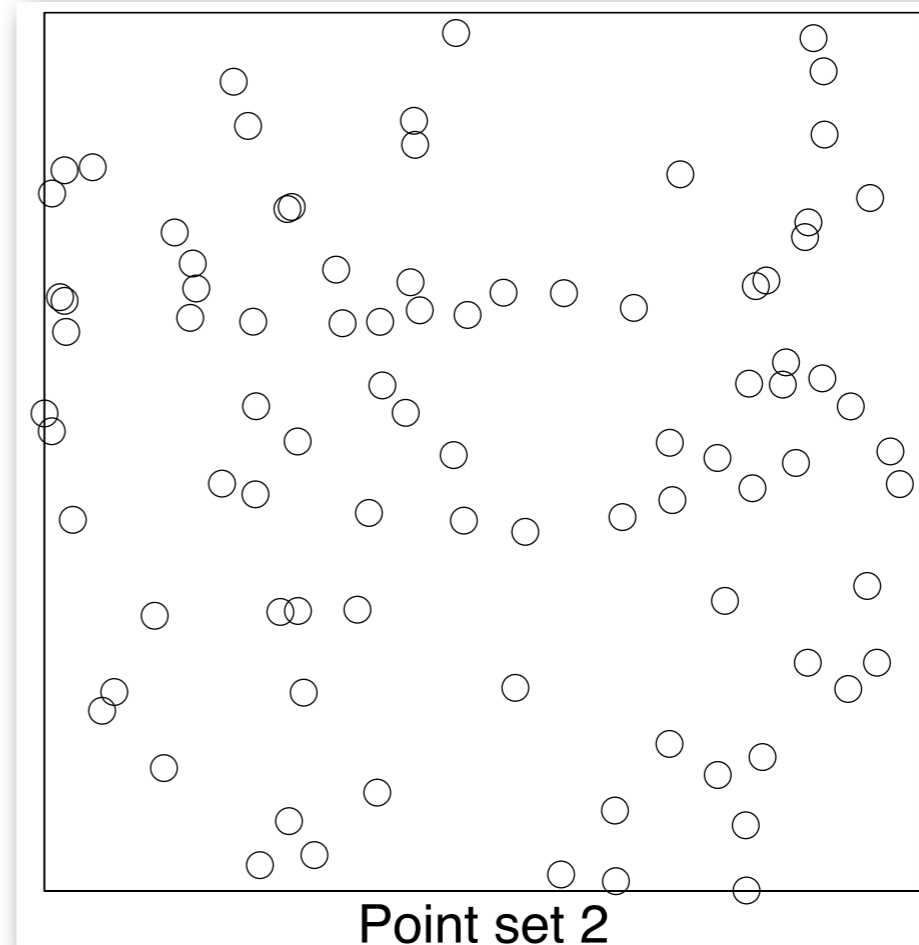
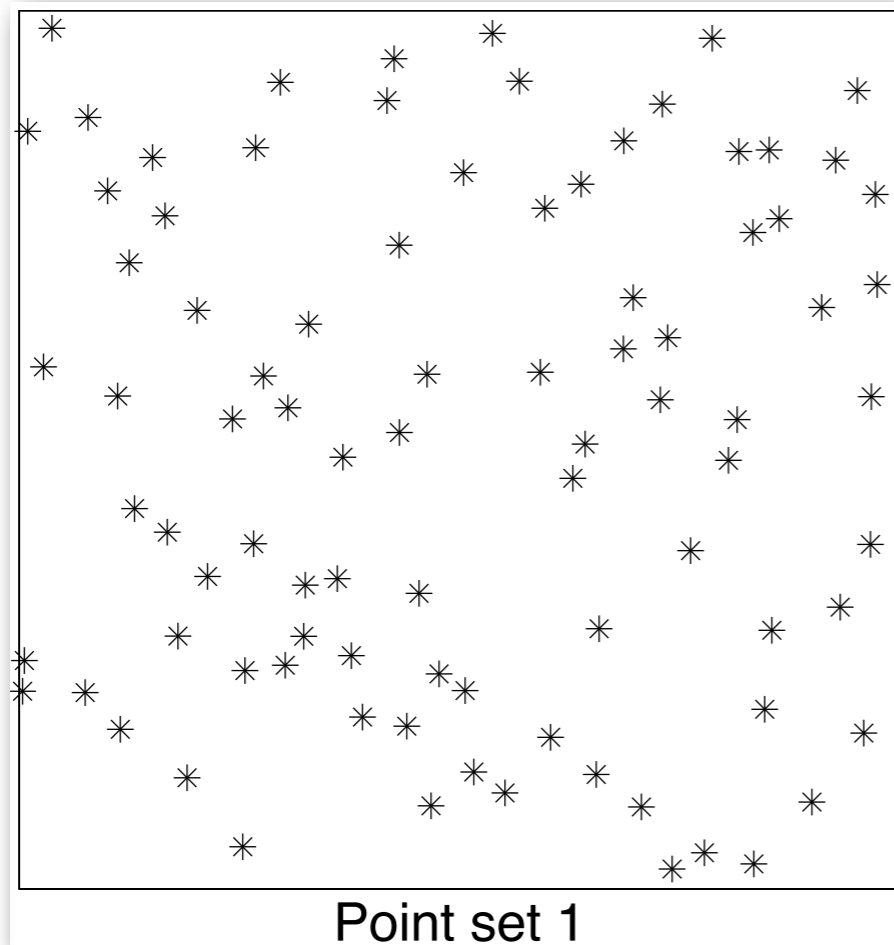
Non-monotone + constraints:

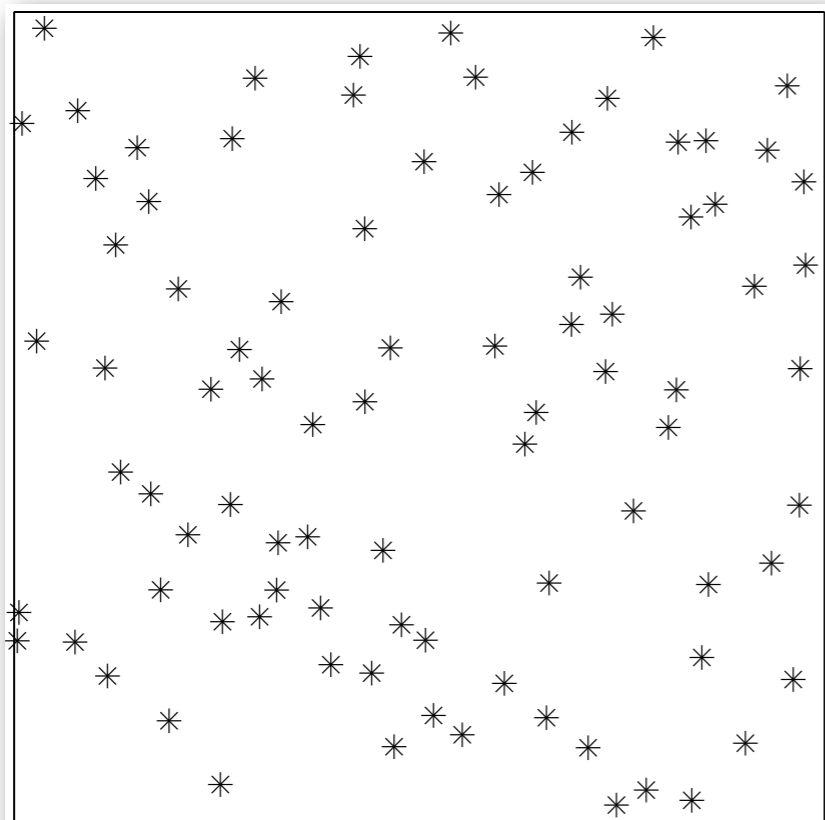
“multilinear” 1/4-approx sans constraints,
various (lesser) guarantees dependent on constraint type
Chekuri et al. (2011)

$$\arg \max_Y \det(L_Y) \quad \longrightarrow \quad \arg \max_{Y \in S} \det(L_Y)$$

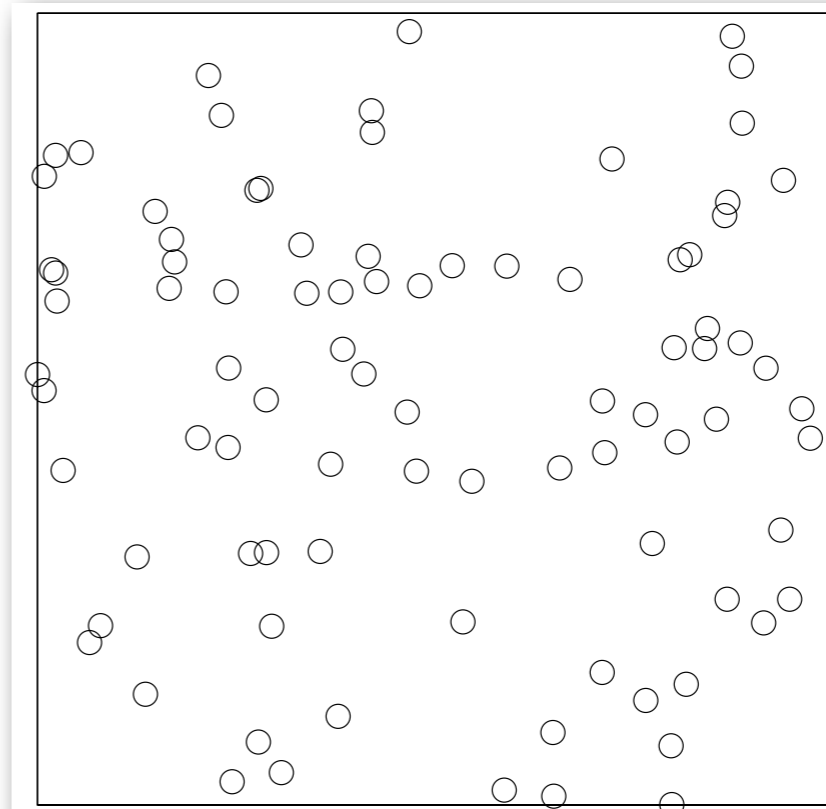
where S is a solvable polytope

IMAGE COMPARISON WITH CONSTRAINTS

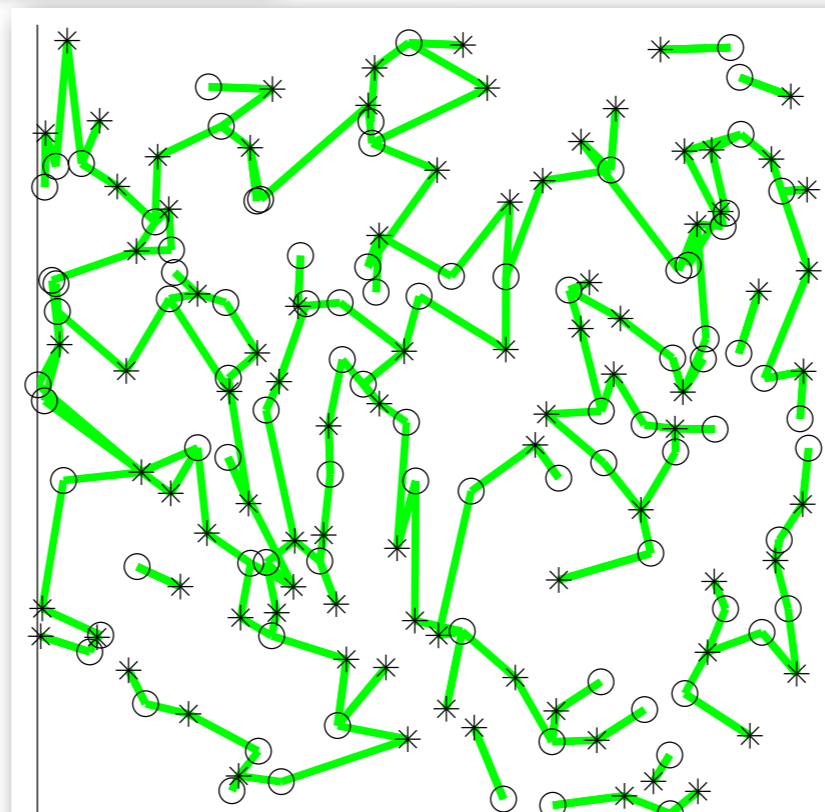




Point set 1

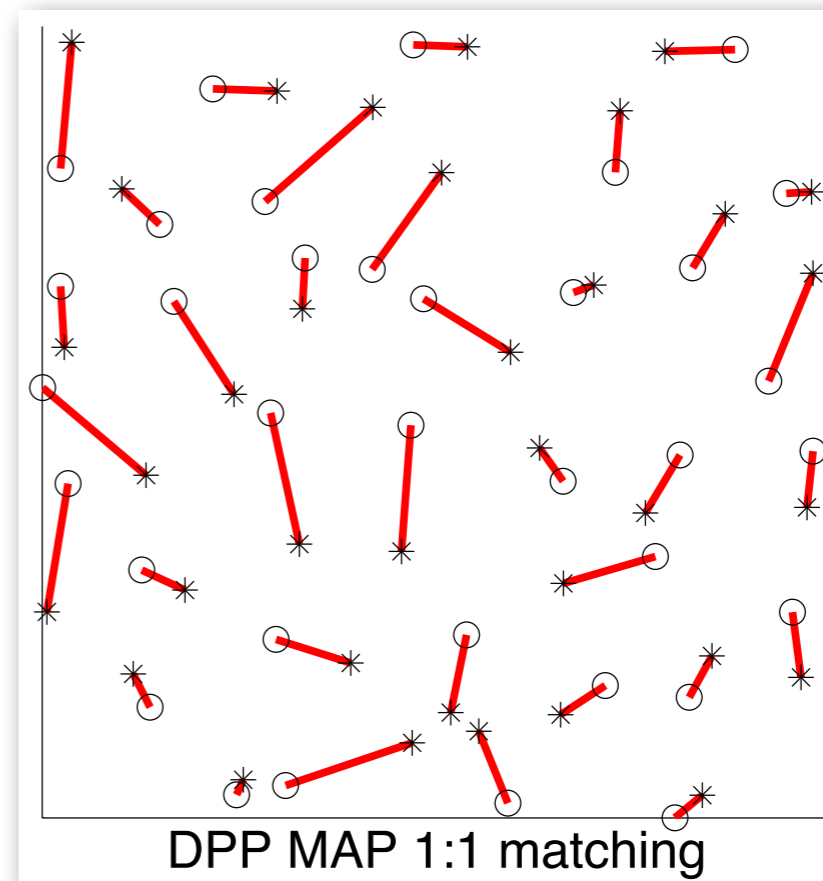
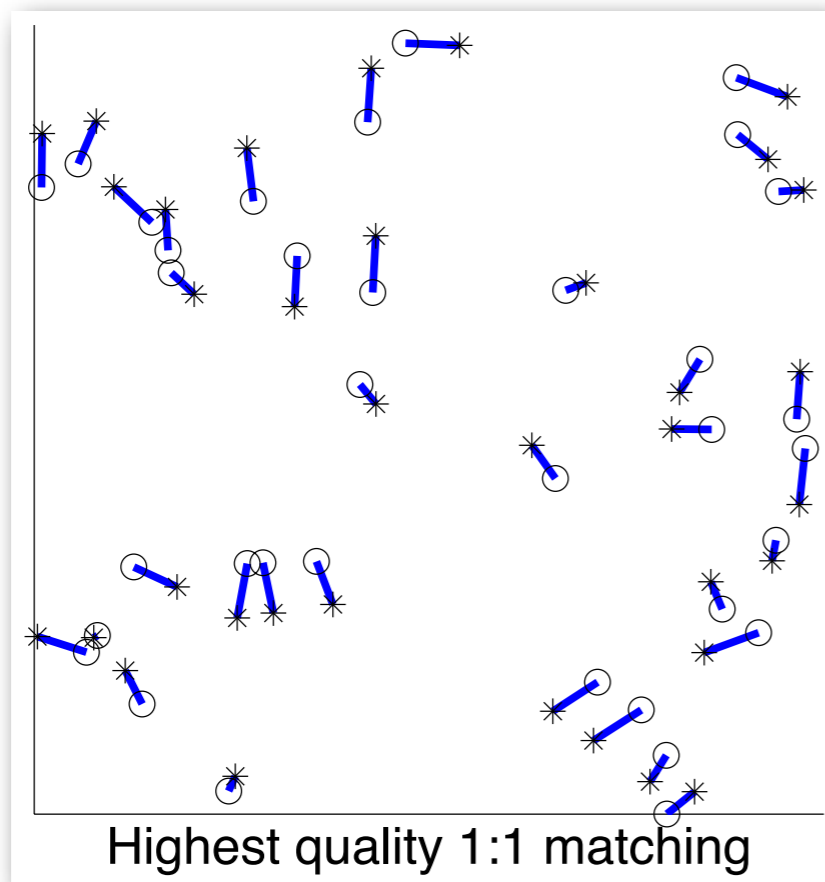
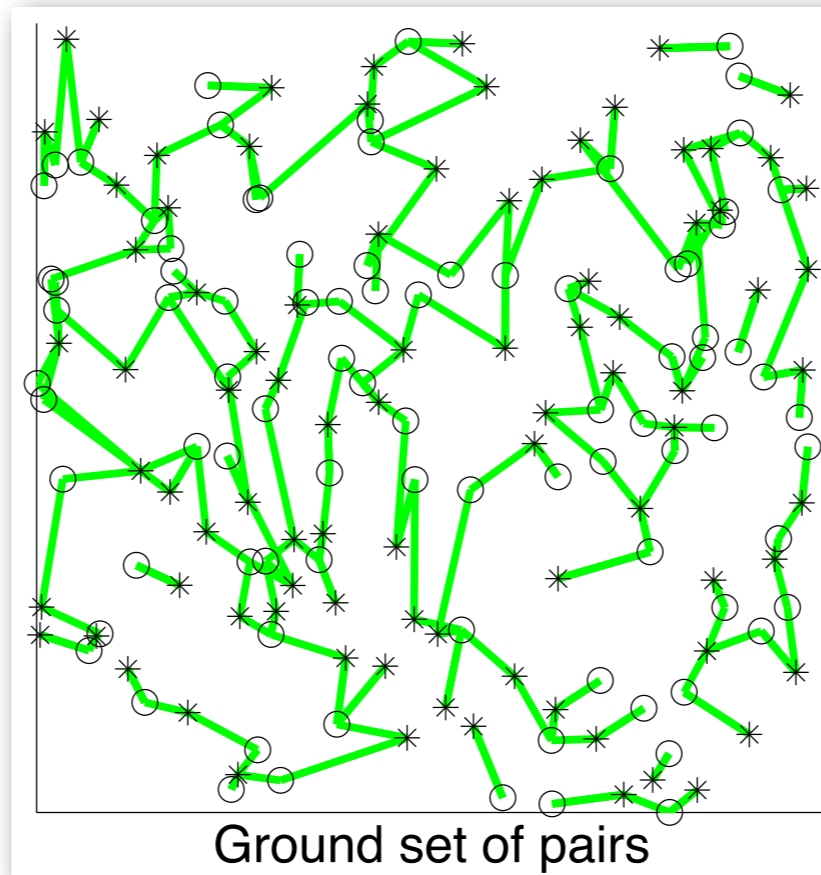


Point set 2



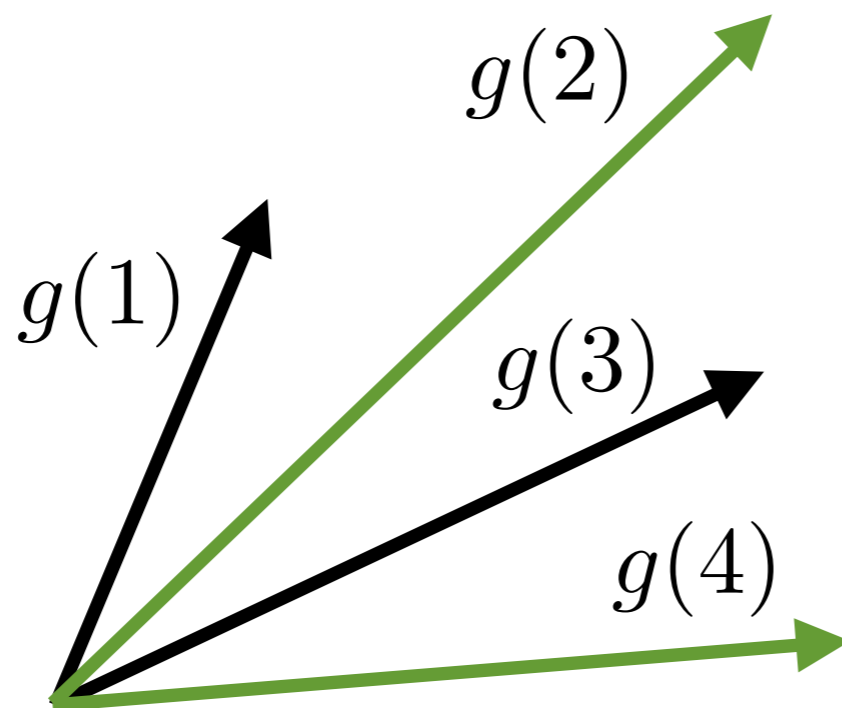
Ground set of pairs

$Y \in$ matching polytope



CHEKURI ET AL. 2011

Step 1: Relax inclusion-exclusion



$$Y = \{2, 4\}$$

$$\mathbf{x} = [0, 1, 0, 1]$$

$$x_i \in [0, 1]$$

CHEKURI ET AL. 2011

Step 2: Extend objective

$$F(\mathbf{x}) = E_{\mathbf{x}}[\log f(Y)] \quad \text{multilinear extension}$$


log-submodular, like $\det(L_Y)$

CHEKURI ET AL. 2011

Step 2: Extend objective

$$F(\mathbf{x}) = E_{\mathbf{x}}[\log f(Y)] \quad \text{multilinear extension}$$

$$= \sum_Y \prod_{i \in Y} x_i \prod_{i \notin Y} (1 - x_i) \log f(Y)$$



p_Y

CHEKURI ET AL. 2011

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2^N subsets

CHEKURI ET AL. 2011

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2^N subsets

Step 3: Optimize using gradient-based methods $\frac{\partial F(\mathbf{x})}{\partial \mathbf{x}}$

Step 4: If unconstrained, solution will already be integer;

else, round solution: $x_i \in [0, 1] \rightarrow x_i \in \{0, 1\}$

CHEKURI ET AL. 2011

Step 2: Extend objective

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2^N subsets \implies Monte Carlo required

Step 3: Optimize using gradient-based methods $\frac{\partial F(\mathbf{x})}{\partial \mathbf{x}}$

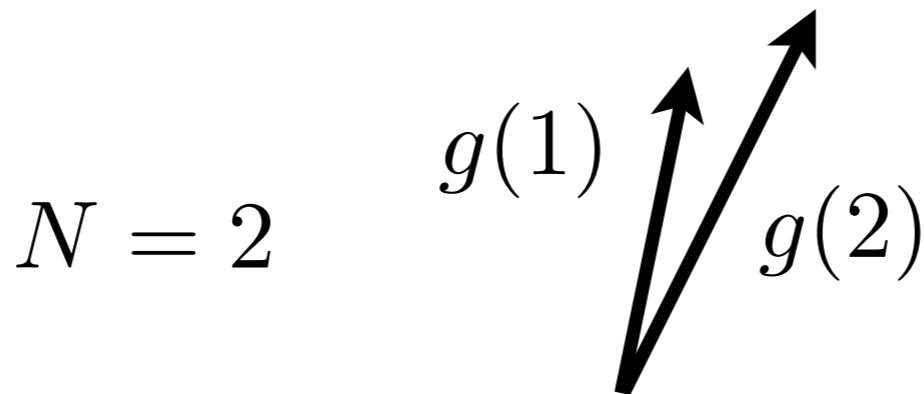
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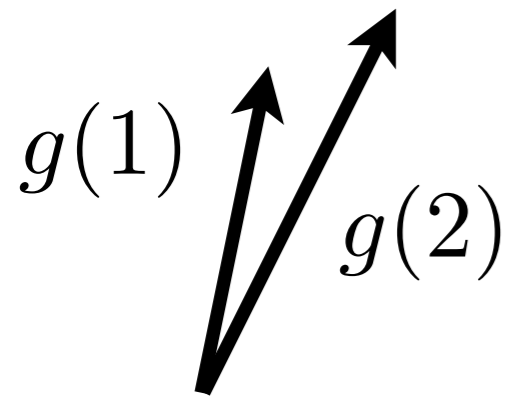
else, round solution: $x_i \in [0, 1] \rightarrow x_i \in \{0, 1\}$

SOFTMAX EXTENSION

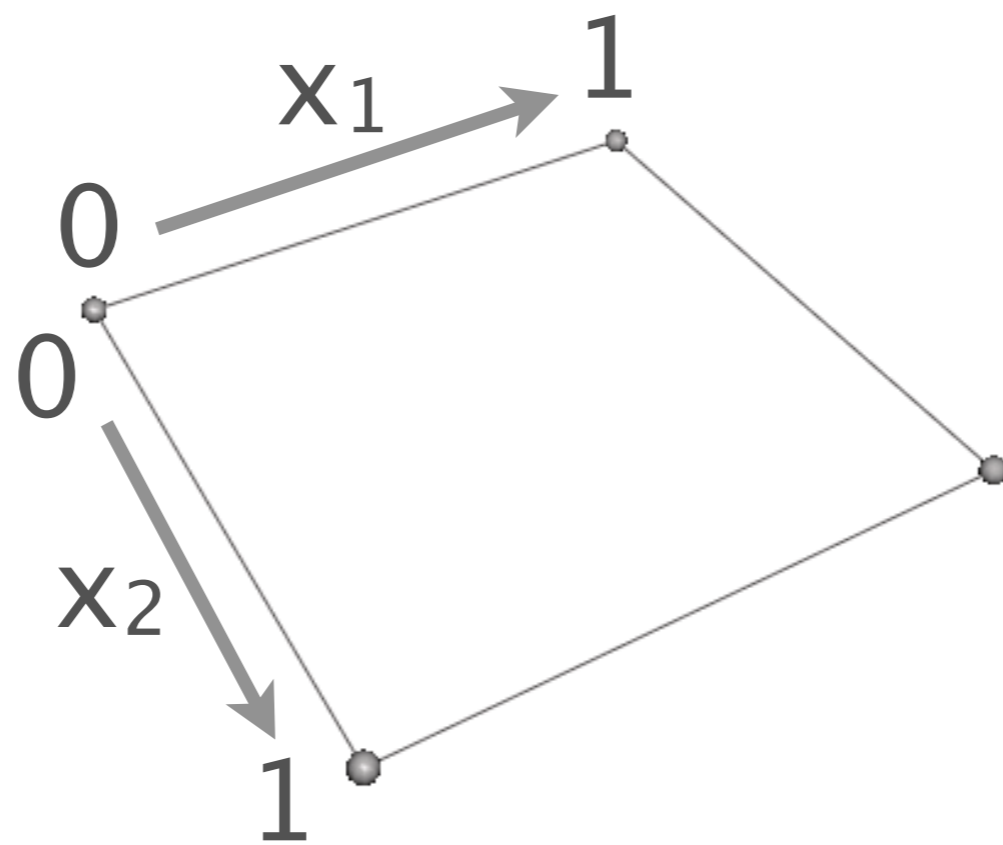
Multilinear: $F(\mathbf{x}) = \sum_Y \prod_{i \in Y} x_i \prod_{i \notin Y} (1 - x_i) \log f(Y)$

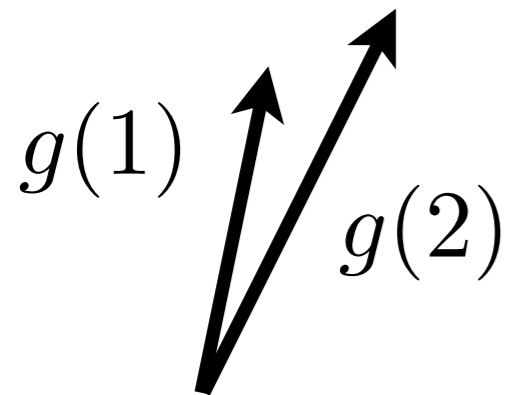
Softmax: $\tilde{F}(\mathbf{x}) = \log \sum_Y \prod_{i \in Y} x_i \prod_{i \notin Y} (1 - x_i) f(Y)$



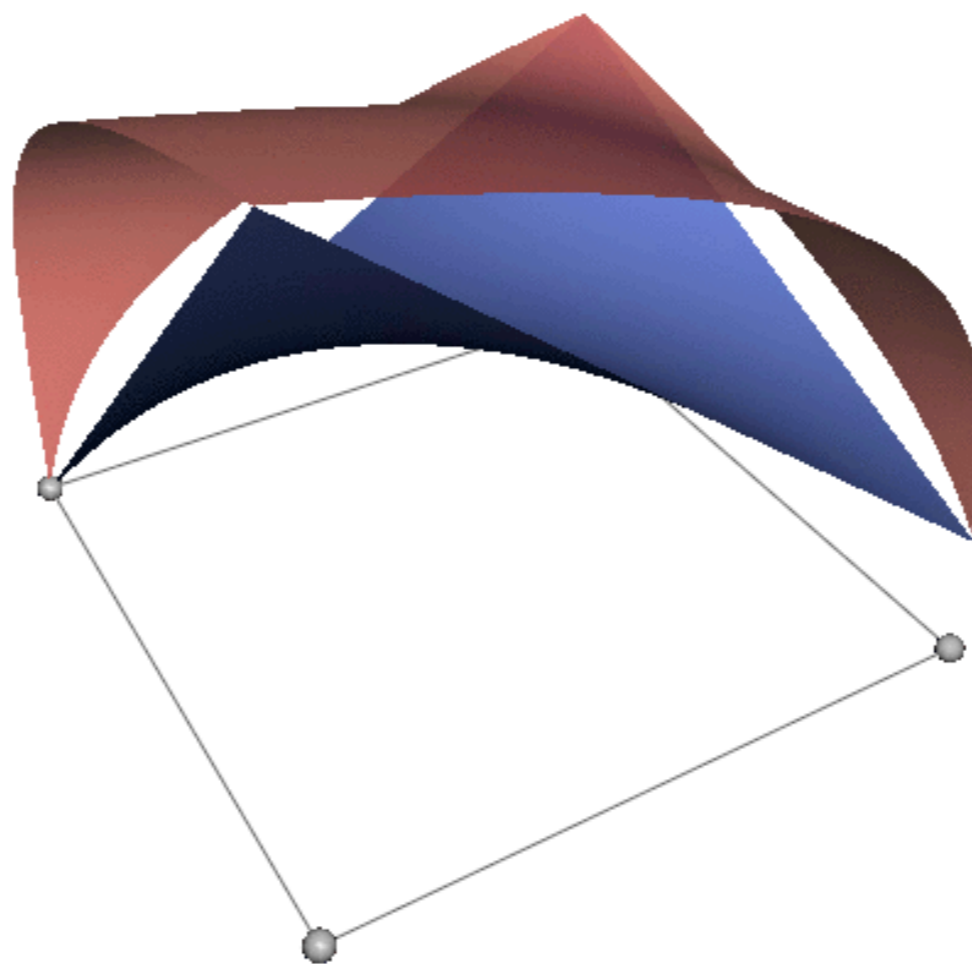


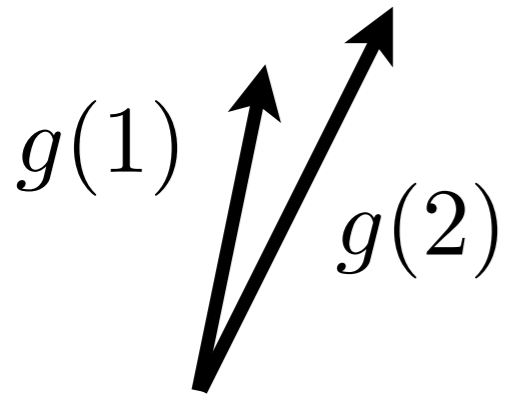
Relaxed domain



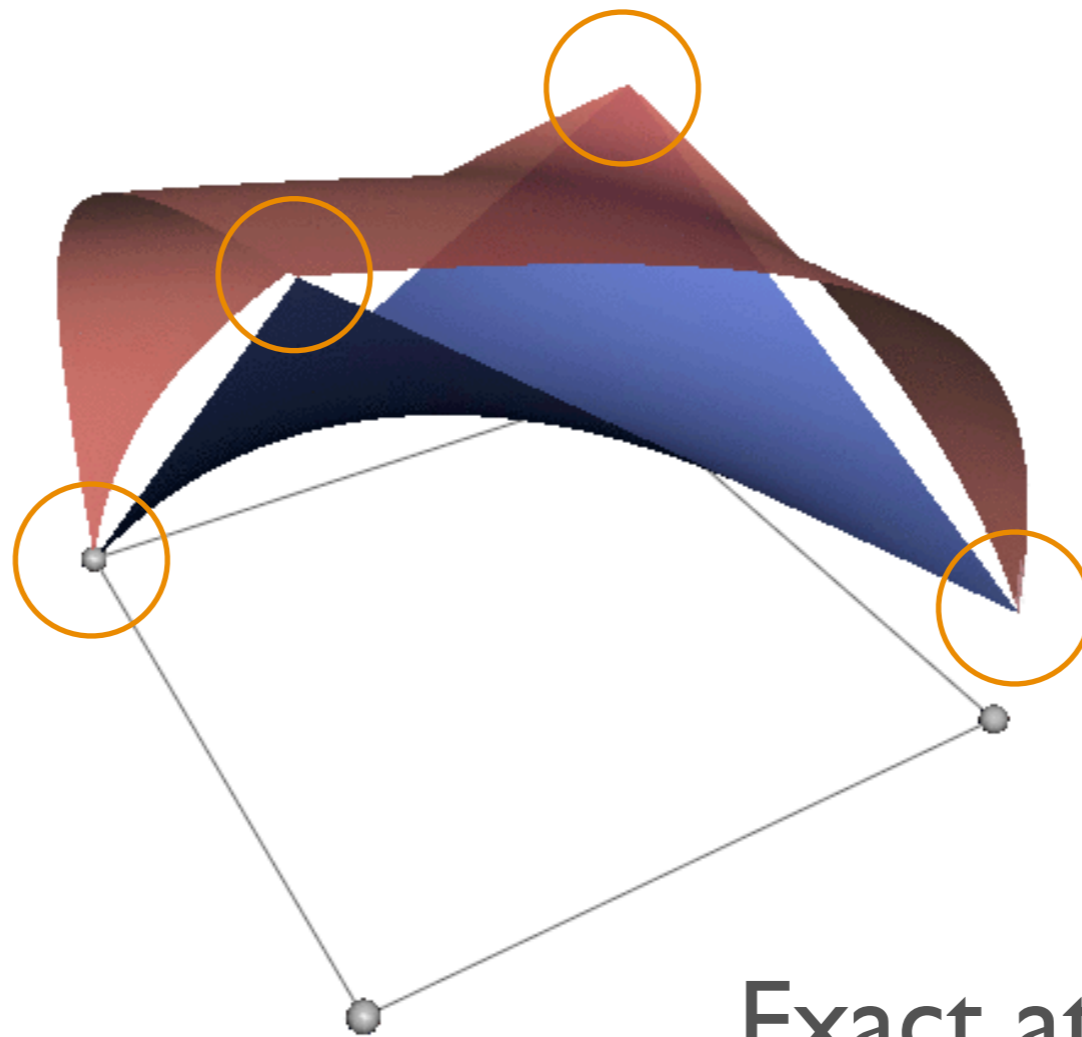


Softmax extension
Multilinear extension






Softmax extension
Multilinear extension

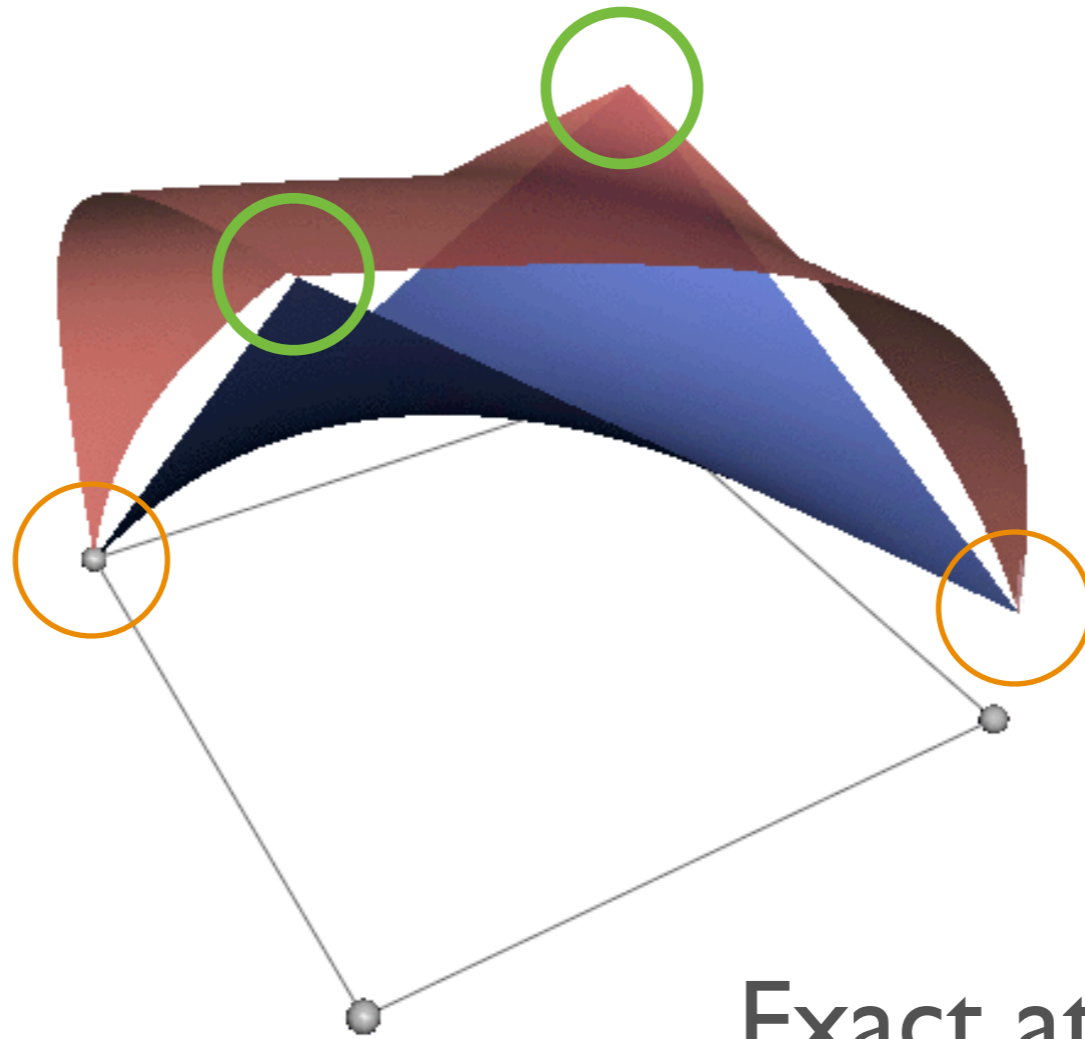


Exact at integral points

$g(1)$ $g(2)$



Softmax extension
Multilinear extension



SOFTMAX EXTENSION

$$\tilde{F}(\mathbf{x}) = \log \sum_Y \prod_{i \in Y} x_i \prod_{i \notin Y} (1 - x_i) f(Y)$$

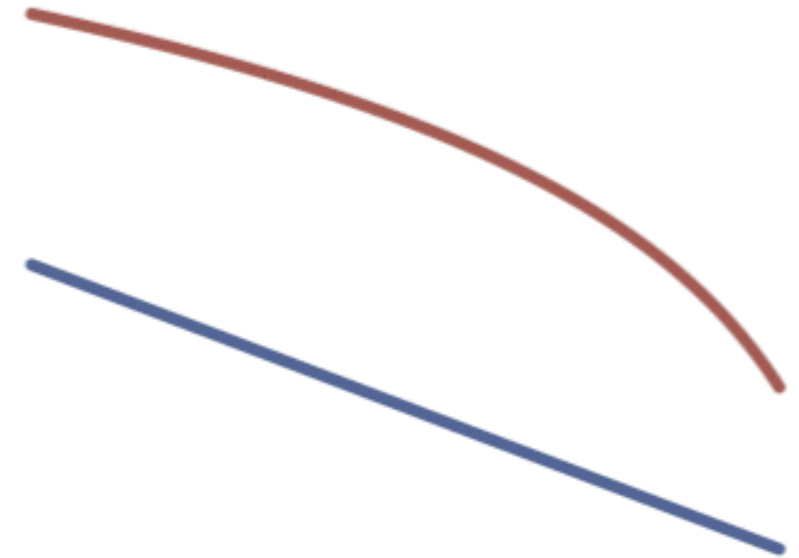
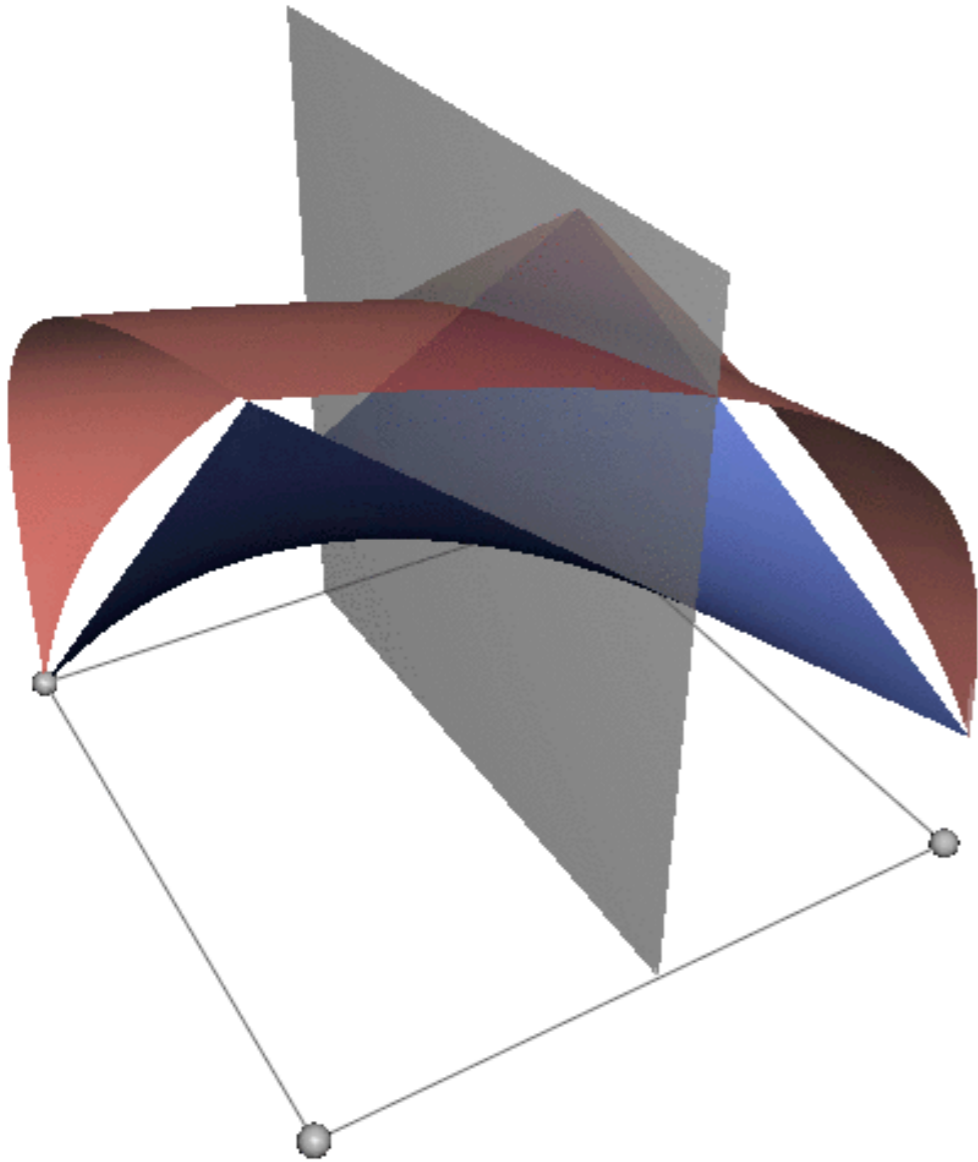
Theorem:

Efficiently computable for $f(Y) = \det(L_Y)$

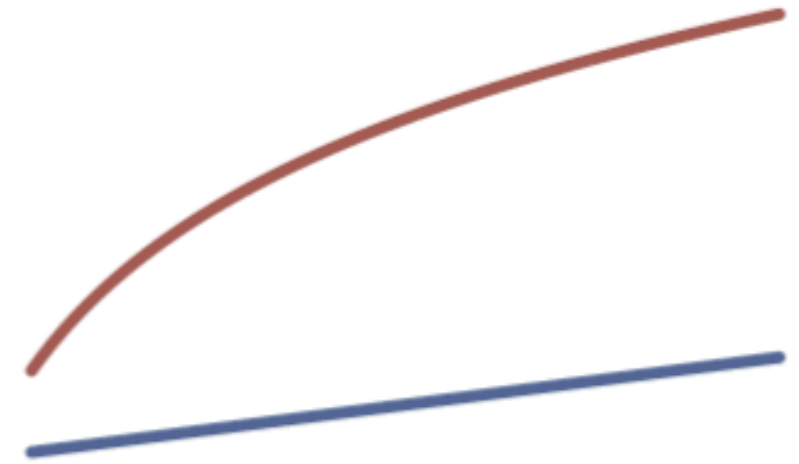
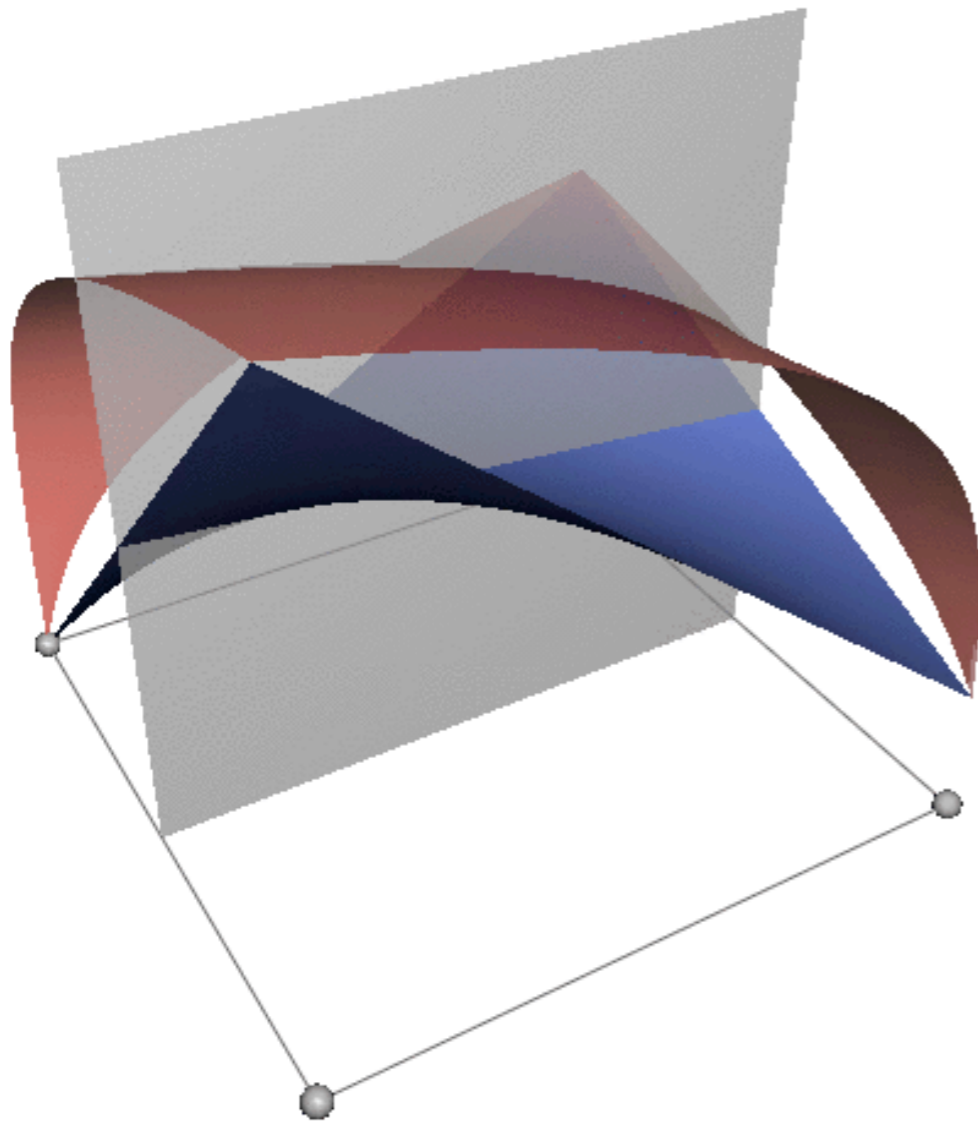
$$O(N^3)$$

$$\tilde{F}(\mathbf{x}) = \det(\text{diag}(\mathbf{x})(L - I) + I)$$

Concave in all-positive/all-negative directions



Not necessarily concave in other directions



APPROXIMATION GUARANTEE

Theorem: Concavity in all-positive directions

+ Submodularity \implies

$$\text{LOCAL OPT of } \tilde{F} \geq \frac{1}{4} \max_{\mathbf{x}} \tilde{F}(\mathbf{x}) \geq \frac{1}{4} \max_Y \log \det(L_Y)$$

Theorem: In the unconstrained case, LOCAL OPT will be integer (no rounding necessary).

Constrained: No guarantees, but in practice pipage
 $\max_{Y \in \mathcal{S}}$ rounding and thresholding work well.

BASELINE

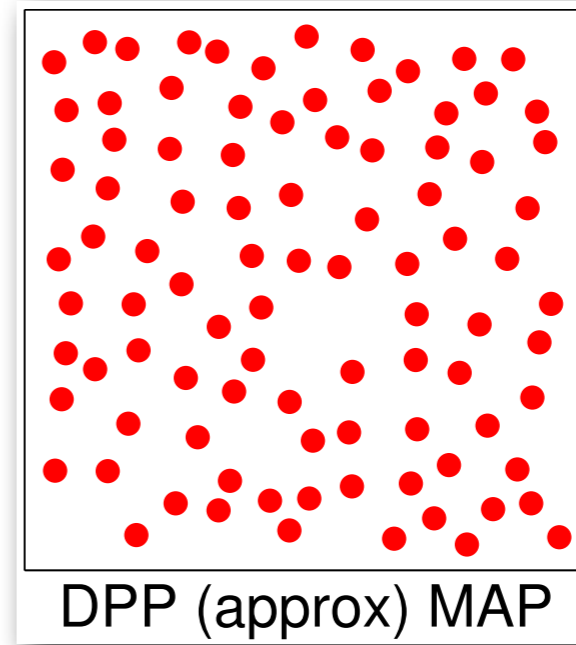
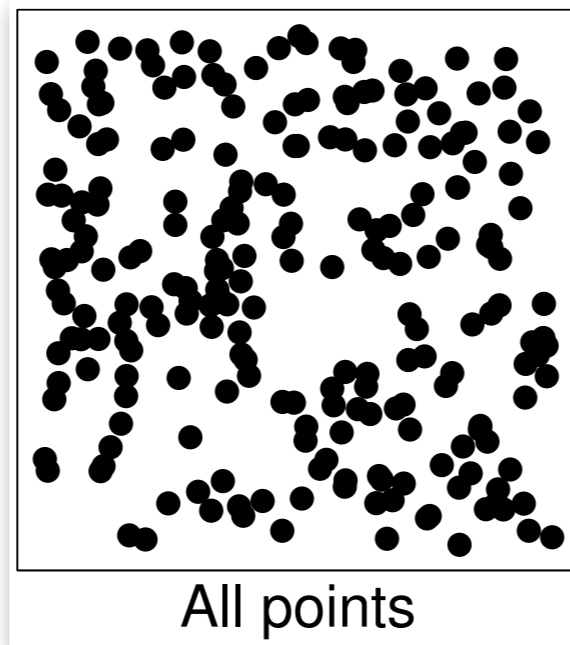
Monotone:

“greedy” $(1 - 1/e)$ -approx
Nemhauser and Wolsey (1978)

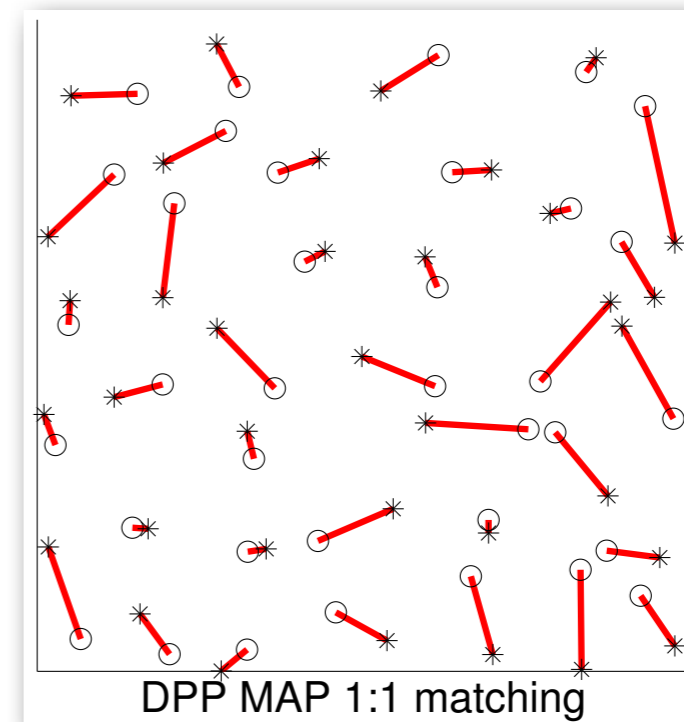
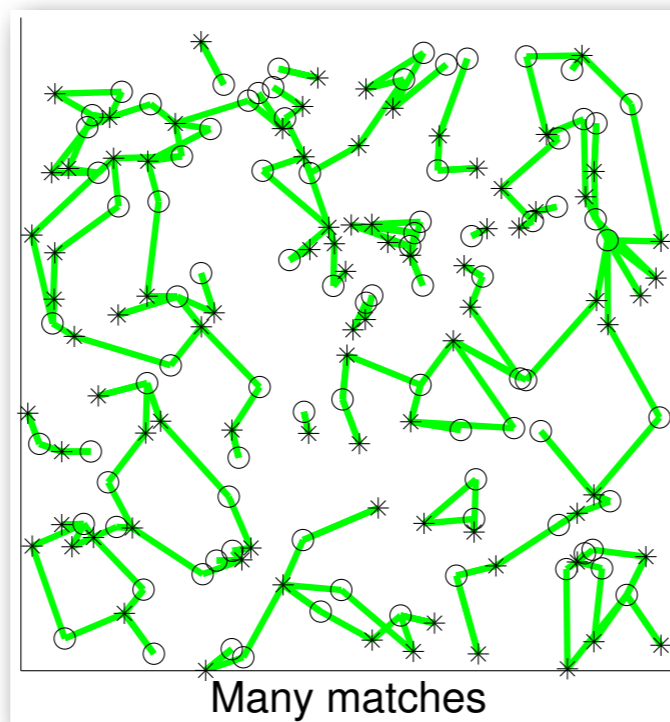
Basic idea: Start from $Y = \{\}$ and find the single item to add that most increases the score. Iterate until no remaining item increases the score.

SYNTHETIC EXPERIMENTS

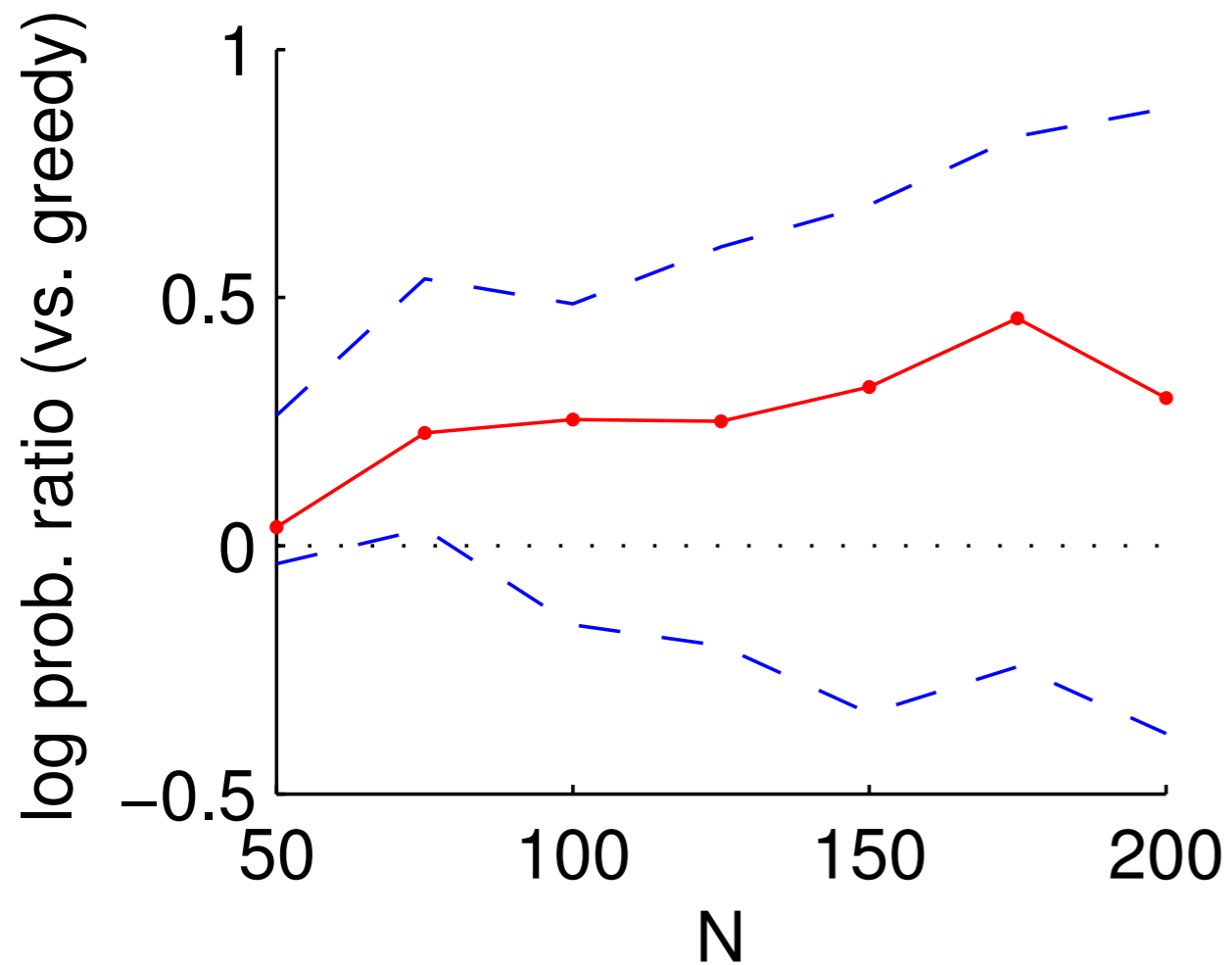
Unconstrained
 \max_Y



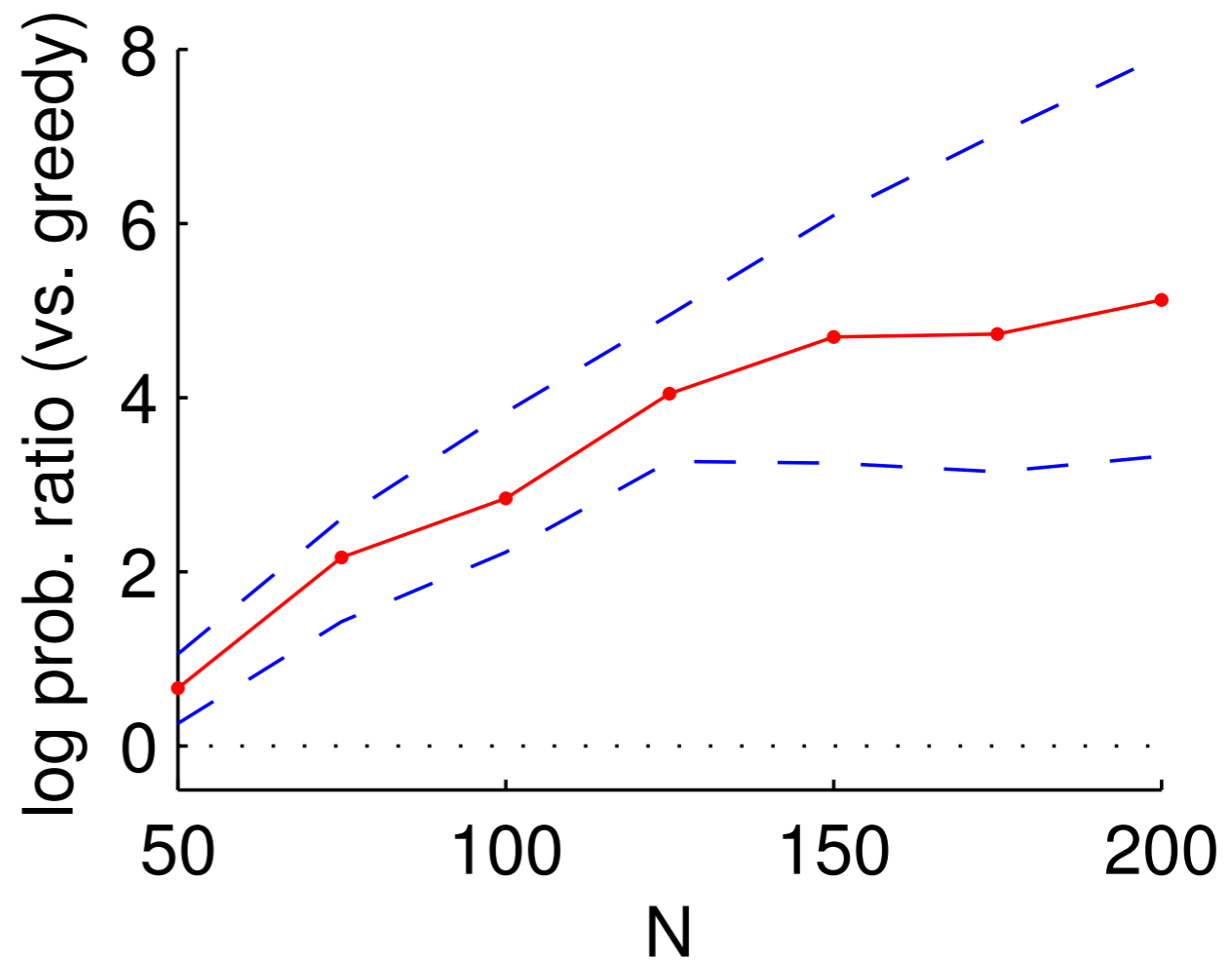
Constrained
 $\max_{Y \in S}$



EFFECTIVENESS EVAL



Unconstrained
 \max_Y



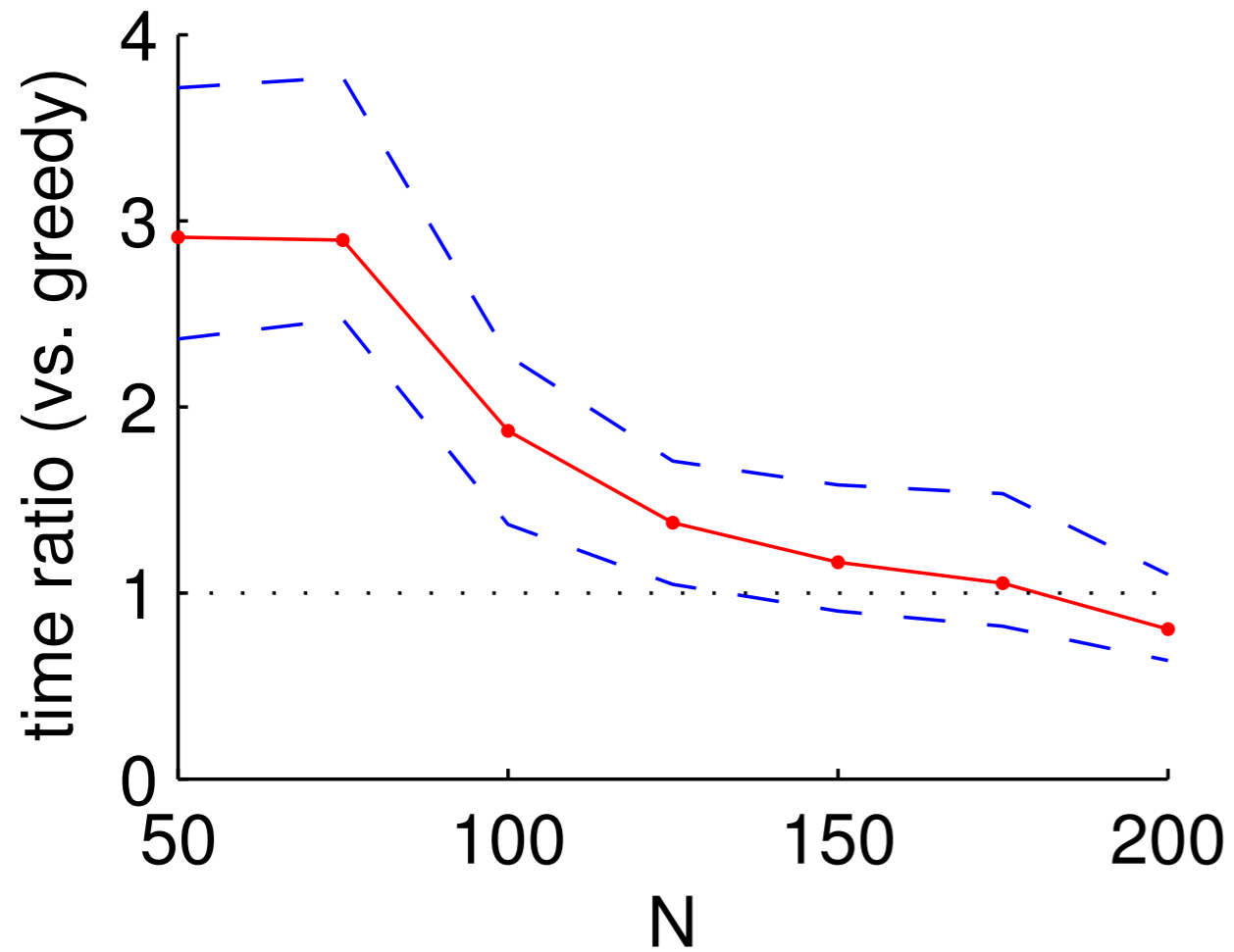
Constrained
 $\max_{Y \in S}$

EFFICIENCY EVAL

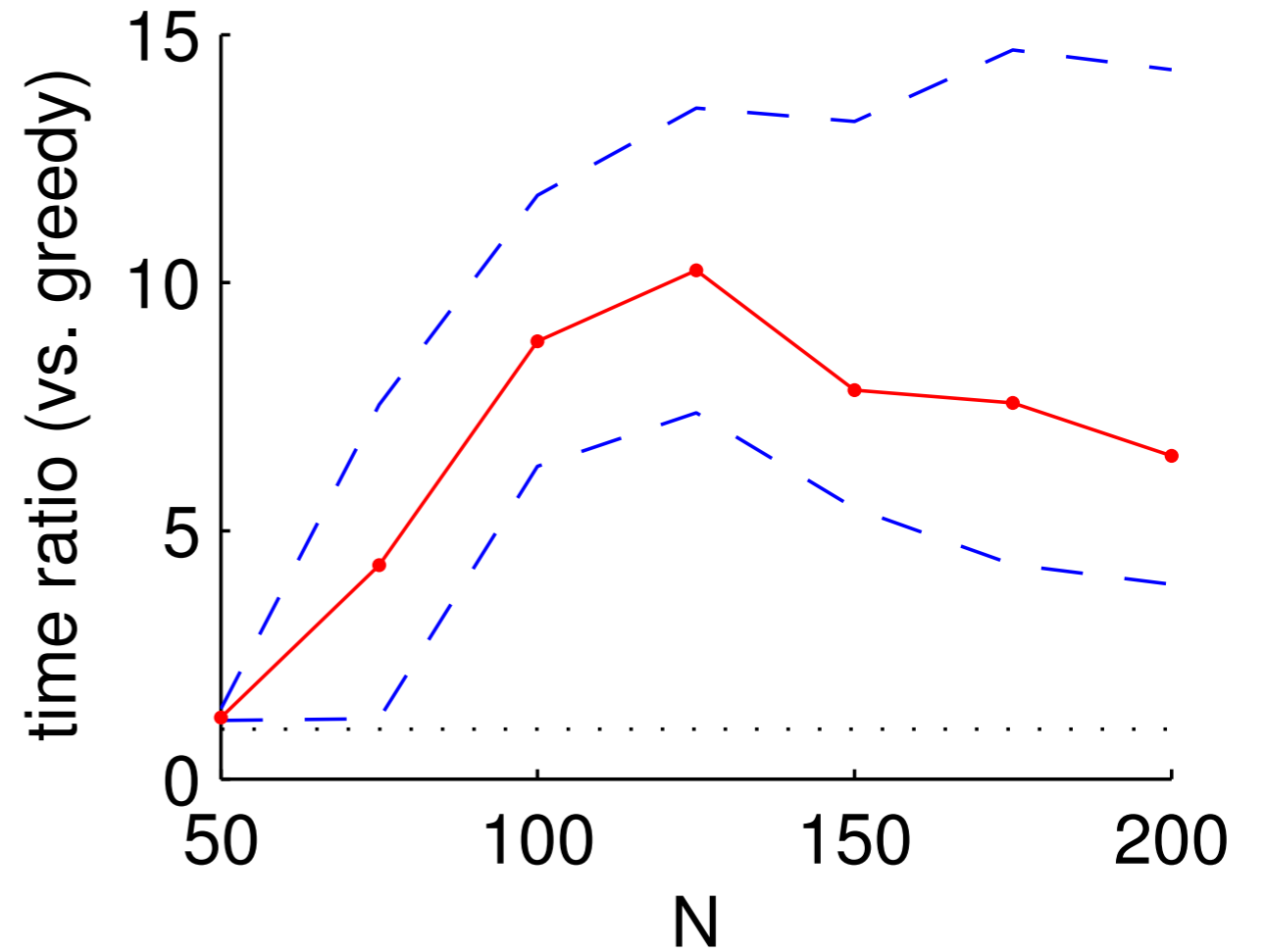
Naive greedy algorithm: $O(N^5)$

Optimized version: $O(N^4)$

EFFICIENCY EVAL



Unconstrained
 \max_Y



Constrained
 $\max_{Y \in S}$

MATCHED SUMMARIZATION

20 Republican primary debates



Average of 179 quotes per candidate

MATCHED SUMMARIZATION





- ▶ **R1 (taxes): No tax on interest, dividends, or capital gains.**
- ▶ **R2 (law): We're not going to have Sharia law applied in U.S. courts.**
- ▶ **R3 (healthcare): I will ... grant a waiver from Obamacare to all 50 states.**
- ▶ **R4 (aid): We're spending more on foreign aid than we ought to.**
- ▶ **R5 (healthcare): If you think what we did in Massachusetts and what President Obama did are the same, boy, take a closer look.**



- ▶ **S1 (taxes): I don't believe in a zero capital gains tax rate.**
- ▶ **S2 (taxes): Manufacture in America, you aren't going to pay any taxes.**
- ▶ **S3 (aid): Zeroing out foreign aid ... that's absolutely the wrong course.**
- ▶ **S4 (ethanol): I voted against ethanol subsidies my entire time in Congress.**
- ▶ **S5 (healthcare): Obamacare ... is going to blow a hole in the budget.**

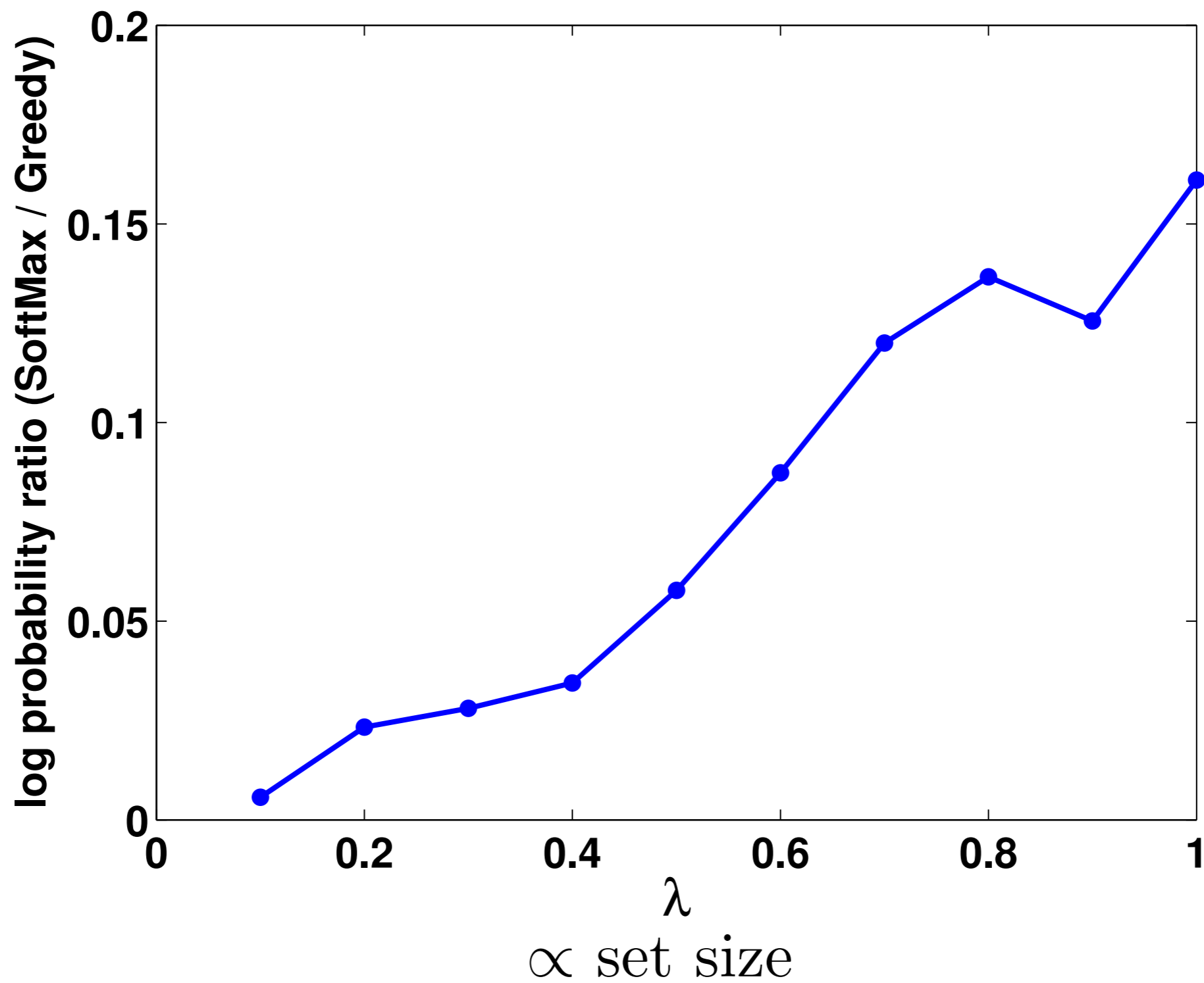
Matched summary

- ▶ **R1 (taxes): No tax on interest, dividends, or capital gains.**
- ▶ **S1 (taxes): I don't believe in a zero capital gains tax rate.**

- ▶ **R3 (healthcare): I will ... grant a waiver from Obamacare to all 50 states.**
- ▶ **S5 (healthcare): Obamacare ... is going to blow a hole in the budget.**

- ▶ **R4 (aid): We're spending more on foreign aid than we ought to.**
- ▶ **S3 (aid): Zeroing out foreign aid ... that's absolutely the wrong course.**

PERFORMANCE



SUMMARY

**Efficient, effective approximate DPP MAP
algorithm for subset selection problems**

Code + data:

<http://www.seas.upenn.edu/~jengi/dpp-map.html>

SUMMARY

Code + data:

<http://www.seas.upenn.edu/~jengid/dpp-map.html>

Future work:

- Other applications:

- sensor selection

- [A. Krause, A. Singh, and C. Guestrin. Near-Optimal Sensor Placements in Gaussian Processes, 2008.]

- text summarization

- [H. Lin and J. Bilmes. Multi-Document Summarization via Budgeted Maximization of Submodular Functions, 2010.]

- Other submodular functions for which the softmax extension is efficiently computable?

Poster W35