

## Notes 13: Local graph partitioning

### 1. SMALL SPARSE CUT

Given an undirected graph  $G$  with positive edge weights, consider the problem of finding a small sparse cut: a vertex set  $S$  with small conductance  $\varphi(S)$  and has small size:

$$\operatorname{argmin} \{ \varphi(S) \mid S \subseteq V, |S| \leq \delta n \}$$

This is sometimes motivated by finding a small community in a social network.

The spectral partitioning algorithm of Cheeger–Alon–Milman can find a set of small conductance, but the set may be large (containing up to half of the vertices).

We will study an algorithm with the following guarantee: If a graph  $G$  has a subset  $S$  with small conductance, then the algorithm will find a subset  $T$  with  $|T| \leq 16|S|$  and  $\varphi(T) \leq O\left(\sqrt{\varphi(S) \log |S|}\right)$ .

Compared with Cheeger–Alon–Milman, we gain in the guarantee that  $T$  is small, but we pay an extra  $\sqrt{\log |S|}$  factor in conductance.

### 2. ANALYTIC SPARSITY

For simplicity we consider only  $d$ -regular graphs, and further assume  $d$  is normalized to be 1. The proof of Cheeger–Alon–Milman inequality shows that given any  $x \in \mathbb{R}^V$ , we can find a sparse cut  $T \subseteq \operatorname{supp}(x) = \{i \in V \mid x_i \neq 0\}$  and  $\varphi(T) \leq \sqrt{2R(x)}$ , where  $R(x) = x^\top \mathcal{L}x / x^\top x$ .

If we can solve the problem of minimizing Rayleigh quotient over vector  $x \in \mathbb{R}^V$  of small support,

$$\operatorname{argmin} \{ R(x) \mid x \in \mathbb{R}^V, |\operatorname{supp}(x)| \leq \delta n \},$$

then sweep cut algorithm of Cheeger–Alon–Milman outputs a desired subset  $T$  from  $x$ . But the combinatorial sparsity condition  $|\operatorname{supp}(x)| \leq \delta n$  is difficult to work with.

The idea is to relax the combinatorial sparsity condition to the analytic sparsity condition

$$\|x\|_1^2 \leq \delta n \|x\|_2^2.$$

This condition is satisfied whenever  $|\operatorname{supp}(x)| \leq \delta n$  (by Cauchy–Schwarz). Also, if  $x$  is the probability vector of a distribution  $\mu$ , then  $\|x\|_1^2 = 1$ , and

$$\|x\|_2^2 = \sum_{i \in V} \mu(i)^2 = \mathbb{P}_{i \sim \mu, j \sim \mu} [i = j]$$

is the collision probability of  $\mu$  (the probability for two independent samples from  $\mu$  to coincide). In particular, if  $x$  is the probability vector of the uniform distribution over a subset  $S \subseteq V$ , then  $\|x\|_2^2 = \sum_{i \in S} 1/|S|^2 = 1/|S|$ . Therefore the ratio  $\|x\|_1^2 / \|x\|_2^2$  is a robust way to measure the size of the support of a distribution.

Turns out any analytically sparse vector with small Rayleigh quotient can be “rounded” into a combinatorially sparse vector with small Rayleigh quotient.

### 3. ALGORITHM OUTLINE

At a high level, the algorithm is as follows:

- (1) For every vertex  $i$ , run lazy random walk from  $i$  for  $t$  steps for some  $t$  depending on  $\varphi(S)$
- (2) Truncate  $t$ -step lazy walk probability vector  $\pi_t$  into a vector with small support
- (3) Apply Cheeger–Alon–Milman sweep cut to this vector and output a small sparse cut

Why do we expect this algorithm to work? If the random walk starts at a vertex  $i \in S$ , since  $\varphi(S)$  is small, most of the probability mass of  $\pi_t^\top = \mathbb{1}_i^\top W^t$  will stay inside  $S$ . Here  $W$  is the transition matrix of the lazy random walk, and  $\mathbb{1}_i$  is the indicator vector for vertex  $i$  (the probability vector for the initial distribution of starting the random walk at  $i$ ). After some time  $t$ , the lazy random walk should have become close to the “stationary distribution” in  $S$ . Therefore Cheeger–Alon–Milman thresholding should reveal  $S$ .

To analyze step (1), we will show that  $\pi_t$  has small Rayleigh quotient, provided the collision probability  $\|\pi_t\|_2^2$  is not too small (due to having substantial mass in  $S$ ).

To analyze step (2), we will show that if there is a small sparse cut  $S$ , then  $\pi_t$  will be analytically sparse for some starting vertex  $i \in S$ . Further, an analytically sparse vector can be truncated to a combinatorially sparse vector with similar Rayleigh quotient.

To analyze step (3), we apply a lemma in proving Cheeger–Alon–Milman inequality.

#### 4. COLLISION PROBABILITY AND RAYLEIGH QUOTIENT

We keep track of how the collision probability  $\|\pi_t\|_2^2$  changes over time.

- Initially,  $\|\pi_0\|_2^2 = \|\mathbb{1}_i\|_2^2 = 1$ .
- $\|\pi_{t+1}\|_2^2 = \|W\pi_t\|_2^2 \leq \|\pi_t\|_2^2$ , as  $W$  has all eigenvalues bounded by 1 in magnitude. So collision probability  $\|\pi_t\|_2^2$  can only decrease over time.
- $\|\pi_t\|_2^2 \rightarrow \|\mathbb{1}/n\|_2^2 = 1/n$  as  $t$  grows.

In fact, the ratio  $\|\pi_{t+1}\|_2^2/\|\pi_t\|_2^2$  is nondecreasing in  $t$ , so  $\|\pi_t\|_2^2$  converges to  $\|\mathbb{1}/n\|_2^2$  more and more slowly over time. This is proved in the following claim.

**Claim 4.1.**  $\frac{\|\pi_{t+1}\|_2^2}{\|\pi_t\|_2^2} \leq \frac{\|\pi_{t+2}\|_2^2}{\|\pi_{t+1}\|_2^2}$ .

*Proof.* Let  $\lambda_1, \dots, \lambda_n$  be the eigenvalues of  $W$  and  $v_1, \dots, v_n$  be its orthonormal eigenvectors. Using the eigen-expansion  $\pi_t = \sum_{1 \leq \ell \leq n} c_\ell \lambda_\ell^t v_\ell$  of  $\pi_t$ , we have  $\|\pi_t\|_2^2 = \sum_{1 \leq \ell \leq n} c_\ell^2 \lambda_\ell^{2t}$ . The desired inequality is  $\|\pi_{t+1}\|_2^4 \leq \|\pi_{t+2}\|_2^2 \|\pi_t\|_2^2$ , and it becomes

$$\left( \sum_{1 \leq \ell \leq n} c_\ell^2 \lambda_\ell^{2t+2} \right)^2 \leq \left( \sum_{1 \leq \ell \leq n} c_\ell^2 \lambda_\ell^{2t+4} \right) \left( \sum_{1 \leq \ell \leq n} c_\ell^2 \lambda_\ell^{2t} \right),$$

which follows by Cauchy–Schwarz.  $\square$

What happens when  $\|\pi_t\|_2^2$  decreases slowly?  $\|\pi_{t+1}\|_2^2/\|\pi_t\|_2^2$  will be close to 1, or equivalently  $1 - (\|\pi_{t+1}\|_2^2/\|\pi_t\|_2^2)$  is close to 0. We can express

$$1 - \frac{\|\pi_{t+1}\|_2^2}{\|\pi_t\|_2^2} = 1 - \frac{\|W\pi_t\|_2^2}{\|\pi_t\|_2^2} = \frac{\pi_t^\top (I - W^\top W) \pi_t}{\pi_t^\top \pi_t} = \frac{\pi_t^\top \mathcal{L}' \pi_t}{\pi_t^\top \pi_t}$$

as the Rayleigh quotient  $R_{\mathcal{L}'}(\pi_t)$  for the matrix  $\mathcal{L}' = I - W^2$ . Turns out  $\mathcal{L}'$  is the normalized Laplacian of some graph  $H$ ! This graph  $H$  is the two-step lazy random walk, where every step in  $H$  corresponds to two consecutive steps in  $W$ . More precisely,  $H$  also has vertex set  $V$ , and every edge  $(i, k)$  in  $H$  corresponds to a length-2 path  $(i, j), (j, k)$  in the lazy random walk  $W$ . The weight  $w_{ik}$  of  $(i, k)$  in  $H$  is  $w_{ij}w_{jk}$ , the product of weights of the two edges in the path in  $W$ .  $H$  has normalized adjacency matrix  $W^2$ . We won't prove these claims about  $H$  since our proof does not depend on them, and will leave them as easy exercises.

This means when  $\|\pi_t\|_2^2$  decreases slowly at time  $t$ , the probability vector  $\pi_t$  corresponds two small Rayleigh quotient (hence a sparse cut, by Cheeger–Alon–Milman) in the two-step lazy random walk graph  $H$ .

We can translate small Rayleigh quotient  $R_{\mathcal{L}'}(\pi_t)$  (for the two-step walk) into small Rayleigh quotient  $R(\pi_t)$  (for the original lazy walk) using the following claim:

**Claim 4.2.** For any  $x \in \mathbb{R}^V$  and lazy random walk transition  $W$ ,  $x^\top W^2 x \leq x^\top W x$ . Therefore

$$R_{\mathcal{L}'}(x) = \frac{x^\top (I - W^2) x}{x^\top x} \geq \frac{x^\top (I - W) x}{x^\top x} = R(x).$$

*Proof.*  $W = I^{-1}W$  coincides with the normalized adjacency matrix of  $G$ , since  $G$  is assumed to be 1-regular, so the degree matrix is  $I$ .

Since  $W$  is lazy,  $W = \frac{1}{2}I + \frac{1}{2}W'$ , where  $W'$  is the transition/normalized adjacency matrix of the non-lazy random walk on  $G$ . Then  $W - W^2 = \frac{1}{4}I - \frac{1}{4}(W')^2 = \frac{1}{4}\mathcal{L}_{W'} \succcurlyeq 0$ .  $\square$

The above claim is the only place we require the random walk to be lazy.

We get the following upperbound on Rayleigh quotient  $R(\pi_{t-1})$  if we can lower bound the collision probability  $\|\pi_t\|_2^2$ .

**Proposition 4.3.**  $R(\pi_{t-1}) \leq 1 - \|\pi_t\|_2^{2/t}$ .

*Proof.* Since  $\|\pi_0\|_2^2 = 1$ ,

$$\|\pi_t\|_2^2 = \frac{\|\pi_t\|_2^2}{\|\pi_0\|_2^2} = \frac{\|\pi_t\|_2^2}{\|\pi_{t-1}\|_2^2} \frac{\|\pi_{t-1}\|_2^2}{\|\pi_{t-2}\|_2^2} \cdots \frac{\|\pi_1\|_2^2}{\|\pi_0\|_2^2} \leq \left( \frac{\|\pi_t\|_2^2}{\|\pi_{t-1}\|_2^2} \right)^t,$$

where the inequality is [Claim 4.1](#). This inequality and [Claim 4.2](#) implies

$$R(\pi_{t-1}) \leq R_{\mathcal{L}'}(\pi_{t-1}) = 1 - \frac{\pi_{t-1}^\top W^\top W \pi_{t-1}}{\pi_{t-1}^\top \pi_{t-1}} = 1 - \frac{\|\pi_t\|_2^2}{\|\pi_{t-1}\|_2^2} \leq 1 - \|\pi_t\|_2^{2/t}. \quad \square$$

## 5. TRUNCATING ANALYTICALLY SPARSE VECTOR

**Lemma 5.1.** *Suppose  $x \in \mathbb{R}_{\geq 0}^V$  satisfies  $\|x\|_1^2 \leq s\|x\|_2^2$ . Then it can be truncated into a vector  $y \in \mathbb{R}_{\geq 0}^V$  with  $|\text{supp}(y)| \leq 4s$  and  $R(y) \leq 2R(x)$ .*

*Proof.* By scaling, assume  $\|x\|_2^2 = s$  and  $\|x\|_1 \leq s$ .

Let  $y \in \mathbb{R}_{\geq 0}^V$  be the vector  $y_i = \max\{x_i - 1/4, 0\}$ .

Then  $s \geq \|x\|_1 \geq \sum_{i \in \text{supp}(y)} x_i \geq |\text{supp}(y)| \frac{1}{4}$ , because every  $i \in \text{supp}(y)$  contributes  $x_i \geq 1/4$  to  $\|x\|_1$ . Hence  $|\text{supp}(y)| \leq 4s$ .

We will compare  $R(y)$  and  $R(x)$ , where  $R(x) = \frac{x^\top \mathcal{L}x}{x^\top x} = \frac{\sum_{(i,j) \in E} (x_i - x_j)^2}{d \sum_{i \in V} x_i^2}$ .

For the numerator,  $(y_i - y_j)^2 \leq (x_i - x_j)^2$  because truncation can only reduce the difference. Hence  $y^\top \mathcal{L}y \leq x^\top \mathcal{L}x$ .

For the denominator, we have  $y_i^2 \geq x_i^2 - \frac{1}{2}x_i$ , so

$$\sum_{i \in V} y_i^2 \geq \sum_{i \in V} x_i^2 - \frac{1}{2} \sum_{i \in V} x_i \geq s - \frac{1}{2}s = \frac{s}{2} = \frac{1}{2} \sum_{i \in V} x_i^2.$$

Hence  $y^\top y \geq x^\top x/2$ .

Therefore  $R(y) = y^\top \mathcal{L}y / y^\top y \leq x^\top \mathcal{L}x / (x^\top x/2) = 2R(x)$ . □

## 6. ANALYTICALLY SPARSE VECTOR FROM SMALL SPARSE CUT

Given a probability  $\pi$  over  $V$ , we write  $\pi(S) = \sum_{i \in S} \pi(i)$  to denote its total probability in  $S \subseteq V$ .

**Claim 6.1.** *If initial distribution  $\mu_0 = \mathbb{1}_S / |S|$  is uniform over subset  $S$ , and  $\mu_t = W^t \mu_0$ , then  $\mu_t(S) \geq 1 - t\varphi(S)$ .*

*Proof.* We lowerbound  $\mu_t(S)$  by the probability the random walk stays inside  $S$  for all  $t$  steps. We will upperbound the probability it leaves  $S$  in any of the  $t$  steps.

Every vertex  $i$  in the initial distribution  $\mu_0$  carries  $\mu_0(i) = 1/|S|$  probability. Since the graph is  $d$ -regular, an edge going out of  $S$  carries  $\frac{w_{ij}}{d|S|}$  probability out of  $S$ . Total probability escaping out of  $S$  in the first step is  $\sum_{i \in S, j \in \bar{S}} \frac{w_{ij}}{d|S|} = \varphi(S)$ .

We can finish the proof if the escape probability for every step is at most  $\varphi(S)$ . This is true by repeating the above calculations (changing “=” to “ $\leq$ ”), and observing every vertex  $i$  at any time  $t$  carries probability  $\mu_t(i)$  at most  $1/|S|$ .

Why is  $\mu_i(t) \leq 1/|S|$  for any  $i$  and any  $t$ ? This is true for initially  $t = 0$  for all vertices  $i$ . For future time steps,  $\mu_i(t+1)$  is a weighted average of  $\mu_j(t)$  over neighbors  $j$  of  $i$ , so it remains true for time  $t+1$ . □

**Corollary 6.2.** *There is a starting point  $i \in S$  such that if  $\pi_0^{(i)} = \mathbb{1}_i$  and  $\pi_t^{(i)} = W^t \pi_0^{(i)}$ , then  $\pi_t^{(i)}(S) \geq 1 - t\varphi(S)$ .*

*Proof.* The uniform distribution  $\mu_0$  over  $S$  is the average, over a uniformly random  $i \in S$ , of initial distributions  $\mathbb{1}_i$  starting from a single vertex  $i$  in  $S$ , because  $\mu_0 = \frac{\mathbb{1}_S}{|S|} = \mathbb{E}_{i \sim \mu_0}[\mathbb{1}_i]$ .

Now  $\mu_t(S)$  is the same averaging of  $\pi_t^{(i)}(S)$ , because

$$\mu_t(S) = (W^t \mu_0)(S) = \left( W^t \mathbb{E}_{i \sim \mu_0} [\mathbb{1}_i] \right) (S) = \mathbb{E}_{i \sim \mu_0} [W^t \mathbb{1}_i](S) = \mathbb{E}_{i \sim \mu_0} [\pi_t^{(i)}(S)].$$

The key observation here is that the  $t$ -step lazy random walk  $W^t$  is a linear operator, so taking average first and then  $t$ -step walk is the same as taking  $t$ -step walk first

Some vertex  $i$  in  $S$  must achieve staying probability  $\pi_t^{(i)}(S)$  at least the average  $\mu_t(S)$ .  $\square$

**Lemma 6.3.** *For any distribution  $\pi$ , its collision probability  $\|\pi\|_2^2 \geq \pi(S)^2/|S|$ .*

*Proof.* Expand  $\|\pi\|_2^2$  and apply Cauchy–Schwarz,

$$\|\pi\|_2^2 \geq \sum_{j \in S} \pi(j)^2 \geq \frac{1}{|S|} \left( \sum_{j \in S} \pi(j) \right)^2 = \frac{1}{|S|} \pi(S)^2.$$

This Cauchy–Schwarz inequality implies that the distribution over  $S$  with the smallest collision probability is the uniform distribution, and has collision probability  $1/|S|$ .  $\square$

## 7. ALGORITHM

We know the graph contains a small subset  $S$  with conductance  $\varphi(S)$ . **Corollary 6.2** implies that if we are lucky to choose  $i \in S$  as the starting point of our random walk, then even after  $t + 1 = 1/2\varphi(S)$  steps, there is still  $\pi_{t+1}(S) \geq 1/2$  probability mass of staying in  $S$ .

**Lemma 6.3** then implies the collision probability  $\|\pi_{t+1}\|_2^2 \geq 1/4|S|$ .

**Proposition 4.3** gives the following upperbound on Rayleigh quotient:

$$R(\pi_t) \leq 1 - \|\pi_{t+1}\|_2^{2/(t+1)} \leq 1 - \frac{1}{(4|S|)^{2\varphi(S)}} = 1 - \exp(-2\varphi(S) \ln(4|S|)) = O(\varphi(S) \ln |S|),$$

where the last equality is due to  $1 - e^{-x} = O(x)$  for small  $x$  near 0.

$\pi_t$  is analytically sparse and has sparsity ratio  $\|\pi_t\|_1^2/\|\pi_t\|_2^2 = 1/\|\pi_t\|_2^2 \leq 1/\|\pi_{t+1}\|_2^2 \leq 4|S|$ .

**Lemma 5.1** truncates  $\pi_t$  to some nonnegative vector  $y$  with  $|\text{supp}(y)| \leq 16|S|$  and  $R(y) = O(\varphi(S) \ln |S|)$ .

Cheeger–Alon–Milman outputs a super-level set  $T = \{i \in V \mid y_i > r\}$  of  $y$  with  $|T| \leq 16|S|$  and  $\varphi(T) \leq \sqrt{2R(y)} = O(\sqrt{\varphi(S) \ln |S|})$ .

## 8. SMALL-SET EXPANSION

The above conductance guarantee has an extra  $\sqrt{\log |S|}$  factor. Is there an efficient approximation algorithm whose approximation factor is independent of the size of  $S$ ?

Such an algorithm, if exists, will solve the Small-Set-Expansion problem, defined as follows:

Small-Set-Expansion

**Parameters:** conductance bound  $\varepsilon$  and size bound  $\delta$   
**Input:** regular undirected graph  $G$   
**Goal:** decide between the following two cases:  
 (Yes) Some  $S \subseteq V$  with  $|S| \leq \delta n$  satisfies  $\varphi(S) \leq \varepsilon$   
 (No) All  $S \subseteq V$  with  $|S| \leq 16\delta n$  satisfies  $\varphi(S) \geq 1 - \varepsilon$

You may think of the problem as asking if a graph has a hidden small “community” (subset with small conductance). And it only asks for deciding between two extreme cases of conductance: either some small subset has conductance very close to 0, or all small subsets have conductance very close to 1.

A conjecture known as Small-Set-Expansion Hypothesis says that Small-Set-Expansion is hard to solve.

**Conjecture 8.1** (Raghavendra and Steurer 2010). *For every  $\varepsilon > 0$ , there is  $\delta > 0$  such that Small-Set-Expansion with parameters  $\varepsilon$  and  $\delta$  is NP-hard.*

In particular, if Small-Set-Expansion Hypothesis holds and  $P \neq NP$ , then no efficient algorithm can avoid the dependence on  $|S|$ .

Small-Set-Expansion Hypothesis also implies the Unique-Games Conjecture, a central open problem in approximation algorithms that we will not define here. The latter conjecture says that certain constraint satisfaction problem called Unique-Games is NP-hard to approximate.

If Unique-Games Conjecture holds and  $P \neq NP$ , then a simple SDP algorithm will be the best approximation algorithm for many problems. A consequence is that Goemans–Williamson rounding algorithm for MaxCut (with approximation factor  $0.878\dots$ ) will be optimal.