

Optical Proximity Correction with Hierarchical Bayes Model

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Outline

- **Background**
- **OPC with Linear Regression**
- **Hierarchical Bayes Model (HBM)**
- **Markov Chain Monte Carlo (MCMC)**
- **Experimental results**
- **Conclusion**

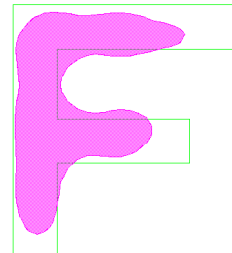
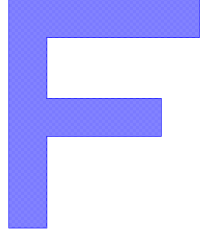
Optical Proximity Correction

- Issue: Conventional OPC consumes very long time
- Goal: High accurate correction in short runtime

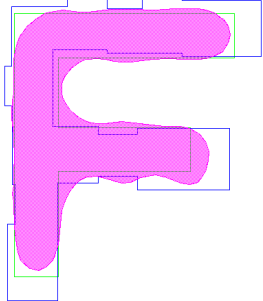
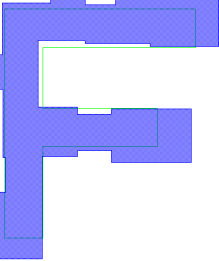
Mask image

Printed image

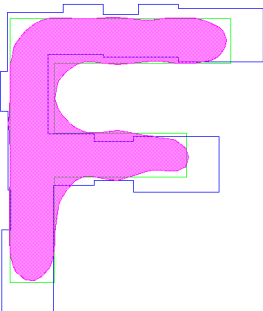
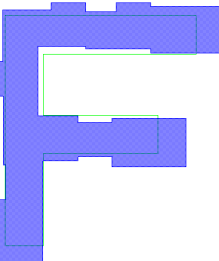
Iteration : 0



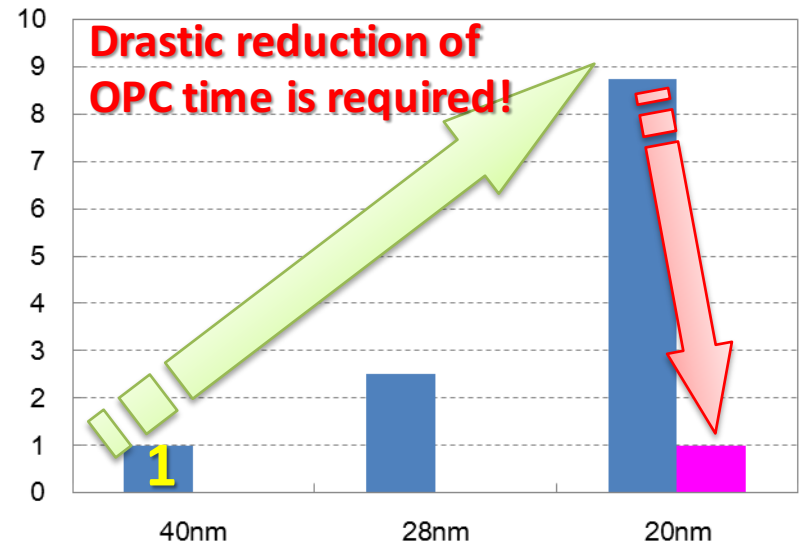
Iteration : 3



Iteration : 5



Ratio of model-based OPC time
(normalized by 40nm node)



Technology node

Model-based OPC is the most widely used technique

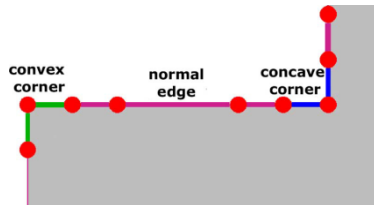
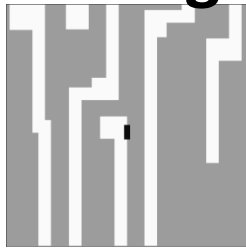
Related works

- Inverse lithography



D. S. Abrams, et al., SPIE, 2006

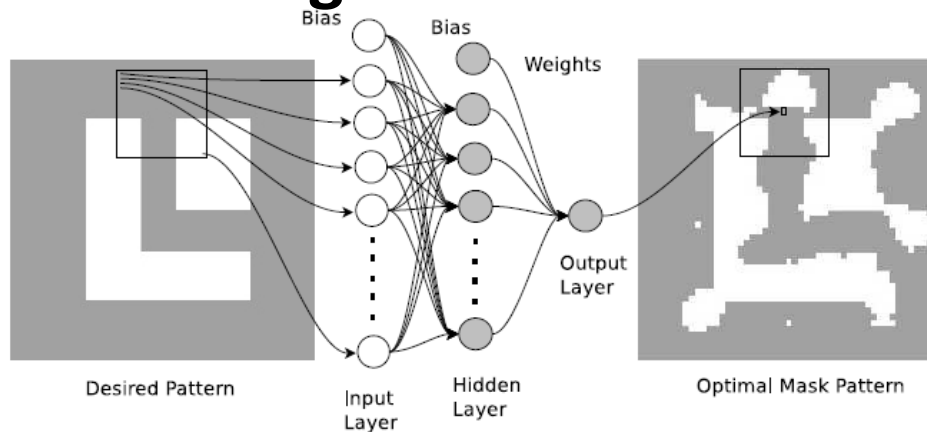
- Linear regression



$$y = \beta x + \epsilon$$

Allan Gu, et al., IEEE, 2008

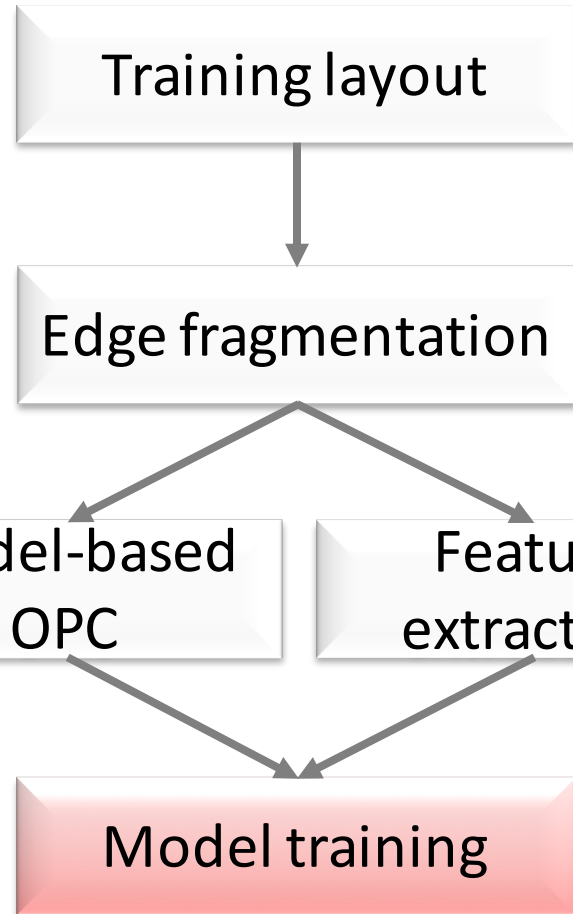
- Nonlinear regression



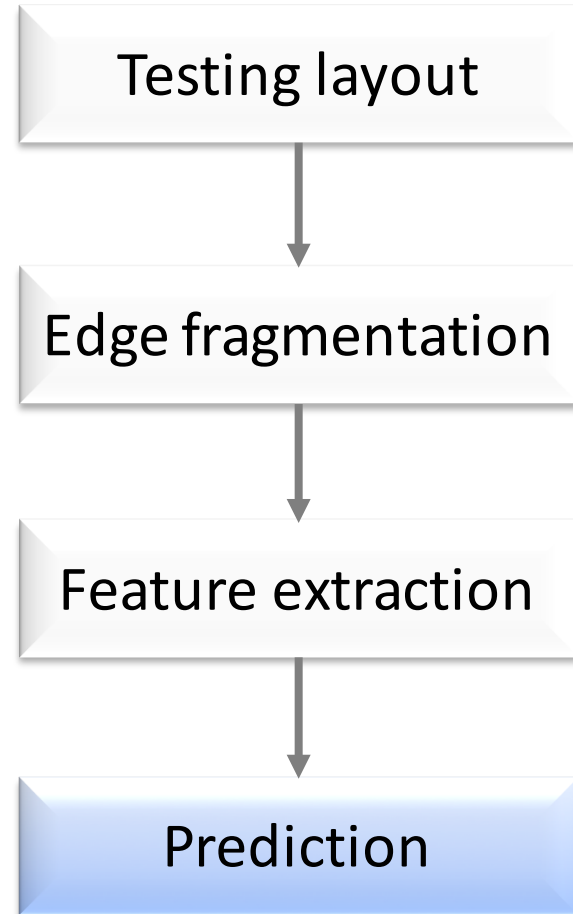
Rui Luo, Journal of Optics, 2013

Regression-based OPC

Learning phase



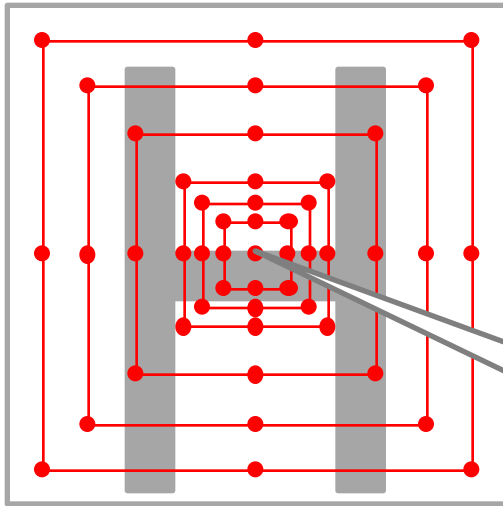
Testing phase



OPC with Linear Regression

Layout feature

Concentric square sampling (CSS)



$$\mathbf{x} = (0, 1, 0, 0, 1, \dots, v_j)^T$$

v_j : pixel value of j-th dimension

Linear model

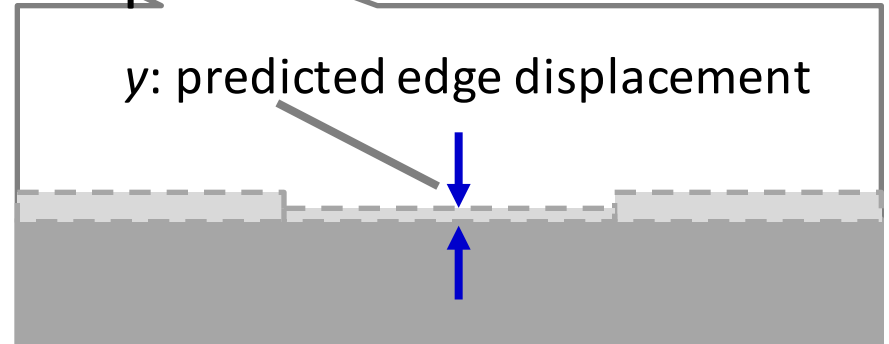
$$y(\mathbf{x}, \mathbf{w}) = w_0 + \sum_{j=1}^D w_j x_j$$

Least squares solution

$$\mathbf{w} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

Output

y : predicted edge displacement



Pros and Cons

- **Fast runtime**
- **Reasonable prediction accuracy**
- **Easy to understand**

- **Over-fitting, especially even with small data**
- **Required a large amount of training data**
- **Cannot model complex phenomena**

OPC with Hierarchical Bayes Model (HBM)

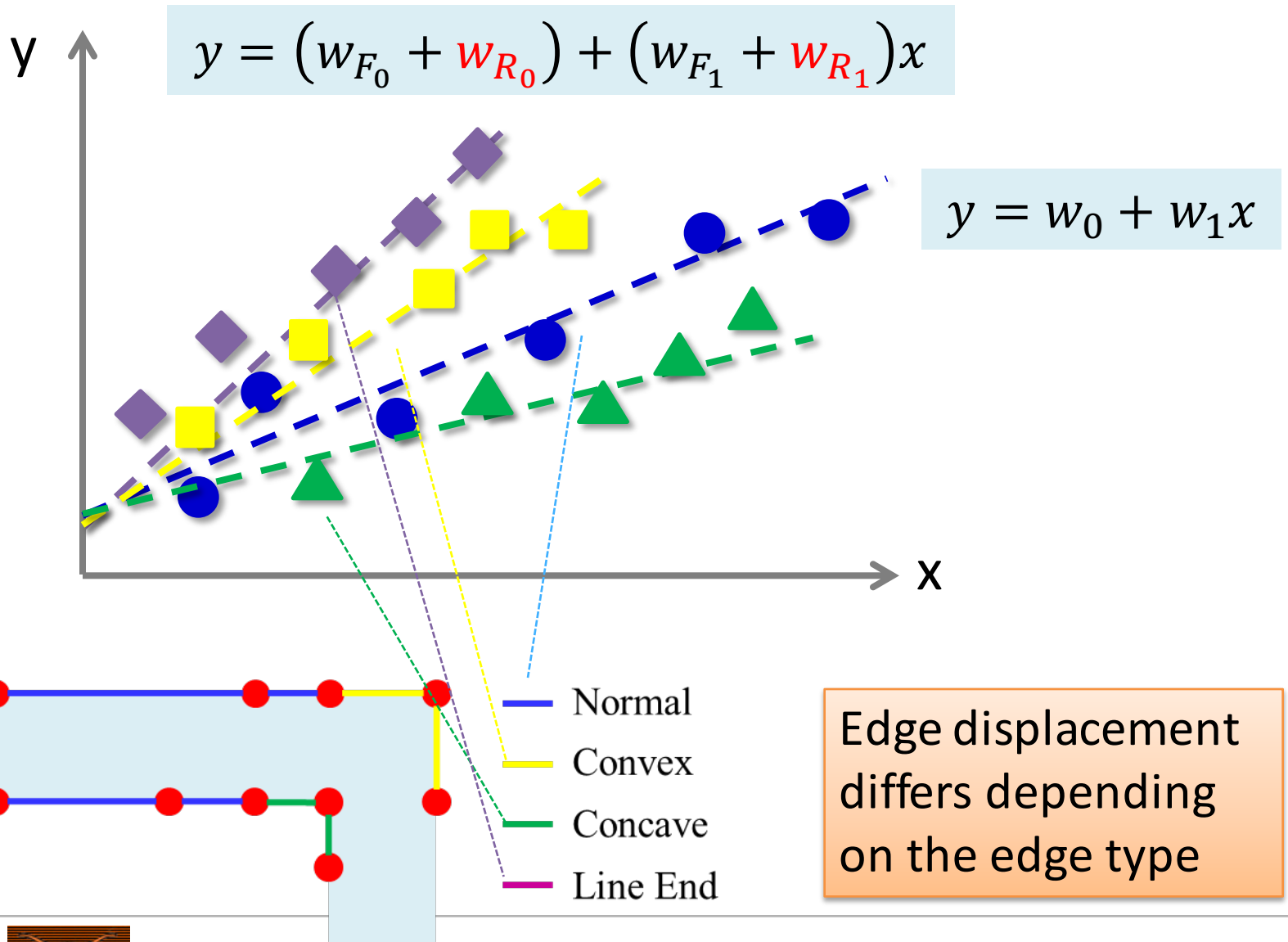
- **Fast runtime**
- **Reasonable prediction accuracy**
- **Easy to understand**

- **Prevent over-fitting**
- **Model complicated phenomena with small amount of data**

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Regression example



GLM vs GLMM

Generalized Linear Model

#dimensions

$$y(\mathbf{x}, \mathbf{w}) = \sum_{j=0}^D w_j x_j$$

Parameter

Feature vector

Generalized Linear Mixed Model

$$y(\mathbf{x}, \mathbf{w}_F, \mathbf{w}_R) = \sum_{j=0}^D (w_{Fj} + w_{Rj}) x_j$$

Fixed effects

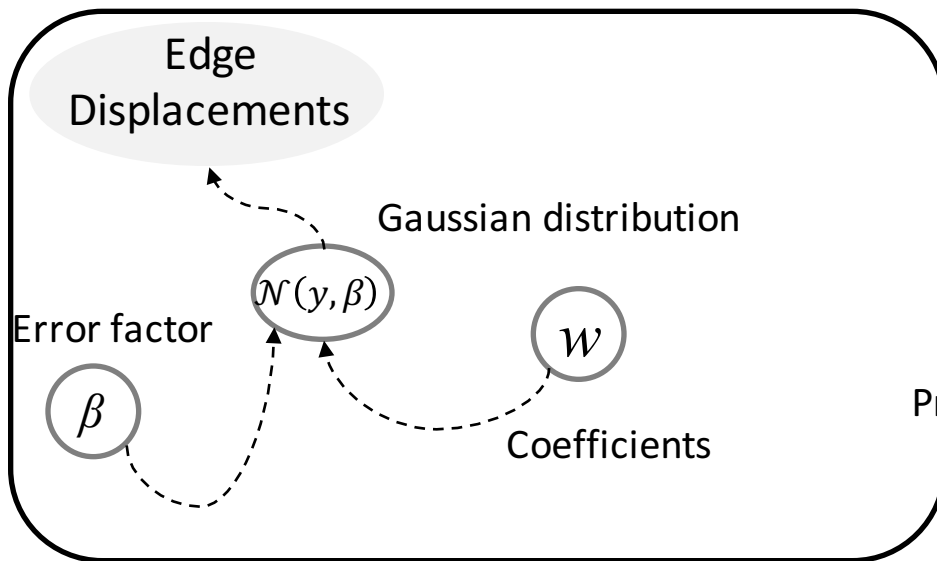
Random effects

Solution: Maximum likelihood estimation

Concept of Hierarchical Bayes Model (HBM)

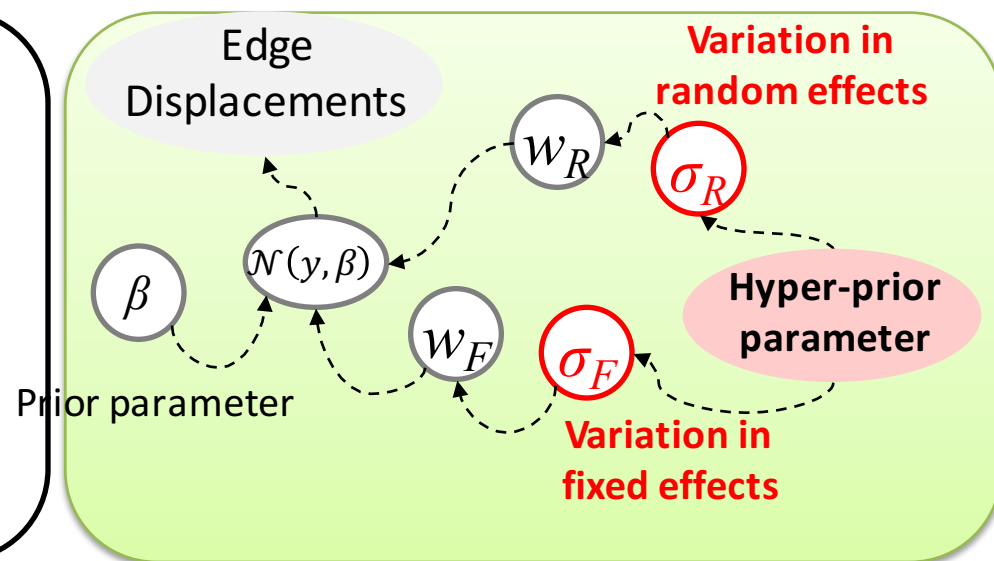
Generalized Linear Model

$$y(\mathbf{x}, \mathbf{w}) = \sum_{j=1}^D w_j x_j$$



Introduction of hidden variables

$$y(\mathbf{x}, \mathbf{w}_F, \mathbf{w}_R) = \sum_{j=1}^D (w_{Fj} + w_{Rj}) x_j$$



Solution: Maximum likelihood estimation

Solution: MCMC

Hierarchical Bayes Model (HBM)

Model

$$p(\mathbf{y}|\mathbf{x}, \boldsymbol{\theta}) = \mathcal{N}(y(\mathbf{x}, \boldsymbol{\theta}), \sigma_y)$$

Prior distributions

$$w_{f_j} \sim \mathcal{N}(0, \sigma_f)$$

$$w_{r_j} \sim \mathcal{N}(0, \sigma_r)$$

$$\sigma_y \sim \mathcal{U}(0, 10^4)$$

Hyper-prior distributions

$$\sigma_f \sim \mathcal{U}(0, 10^4)$$

$$\sigma_r \sim \mathcal{U}(0, 10^4)$$

Non-informative hyper-prior

Posterior distribution

$$p(\boldsymbol{\theta}|\mathbf{y}) \propto \prod_{i=1}^N \prod_{j=0}^D p(y_i|\theta_j) p(w_{f_j}|\sigma_f) p(w_{r_j}|\sigma_r) p(\sigma_y) p(\sigma_f) p(\sigma_r)$$

Hierarchical Bayes

Bayes' theorem

$$p(\boldsymbol{\theta}|\mathbf{y}) \propto p(y|\boldsymbol{\theta}) p(\boldsymbol{\theta})$$

Posterior Likelihood Prior

Posterior distribution for OPC model

$$p(\boldsymbol{\theta}|\mathbf{y}) \propto \prod_{i=1}^N \prod_{j=0}^D p(y_i|\theta_j) p(w_{f_j}|\sigma_f) p(w_{r_j}|\sigma_r) p(\sigma_y) p(\sigma_f) p(\sigma_r)$$

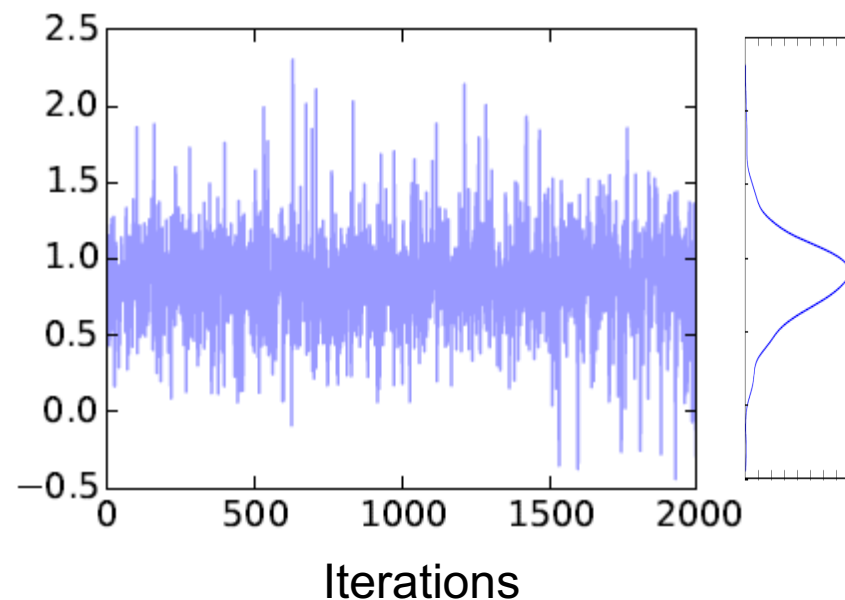
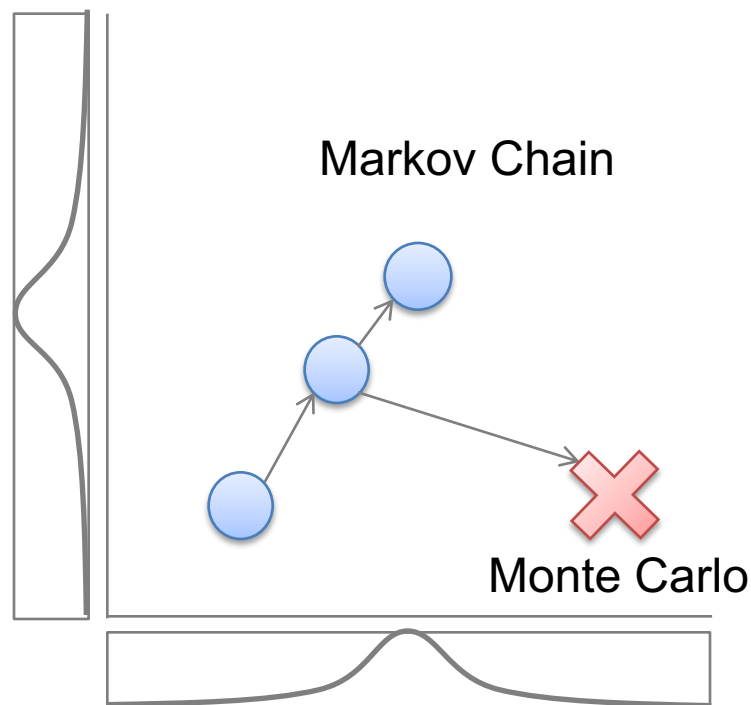
Likelihood Priors Hyper-priors

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Markov Chain Monte Carlo (MCMC)

- **Markov Chain**
 - Next state is defined based on the previous state
- **Monte Carlo**
 - Stochastic algorithm

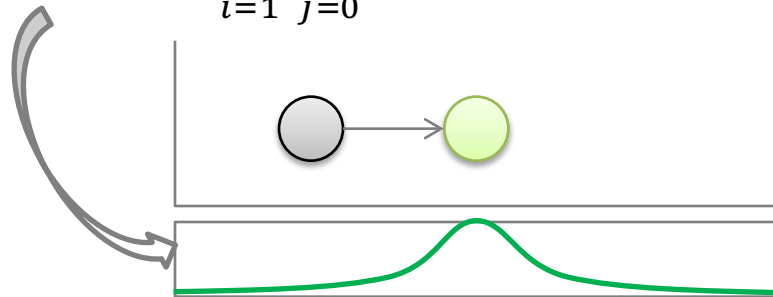


Markov Chain Monte Carlo (MCMC)

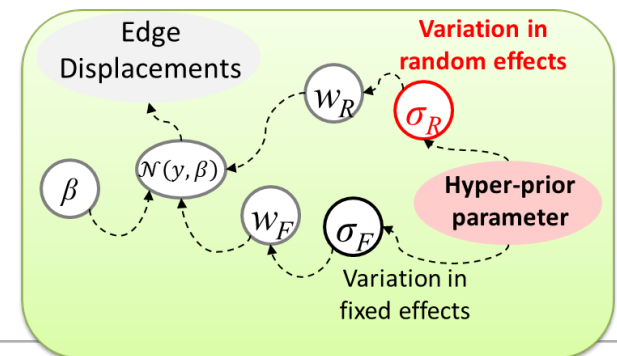
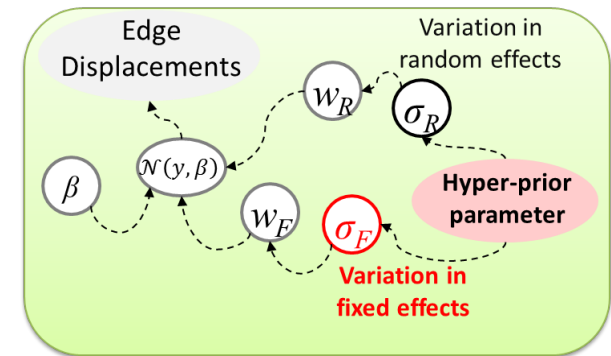
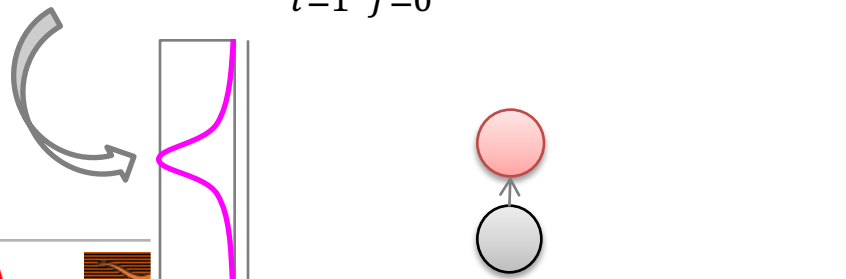
- All parameters are fixed except sampling parameter

$$p(\theta | \mathbf{y}) \propto \prod_{i=1}^N \prod_{j=0}^D p(y_i | \theta_j) p(w_{F_j} | \sigma_F) p(w_{R_j} | \sigma_R) p(\sigma_y) p(\sigma_F) p(\sigma_R)$$

$$p(\sigma_F | \dots) \propto \prod_{i=1}^N \prod_{j=0}^D p(y_i | \theta_j) p(w_{F_j} | \sigma_F) p(\sigma_F)$$



$$p(\sigma_R | \dots) \propto \prod_{i=1}^N \prod_{j=0}^D p(y_i | \theta_j) p(w_{R_j} | \sigma_R) p(\sigma_R)$$



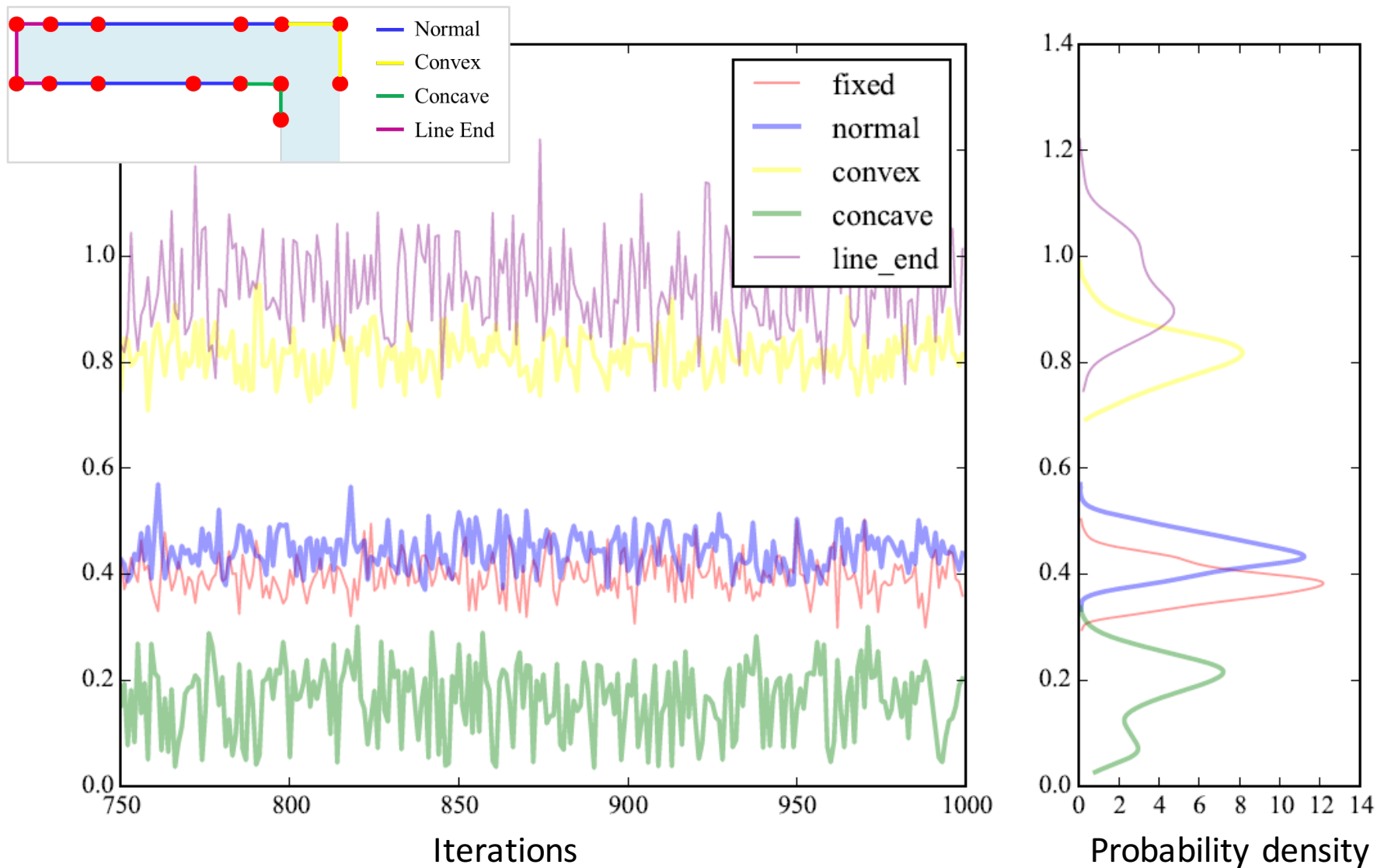
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Experiments

- **Model training**
 - Motif : **Layout A** (training layout)
- **Comparison with linear/nonlinear regression**
 - Motif : **Layout A** (training), **Layout B** (testing)
 - Algorithms: linear regression (LR), support vector regression (SVR)
- **Comparison with model-based OPC**
 - Motif : **Layout B** (testing)
 - Optical model : 32nm node ($\lambda=193\text{nm}$, $\text{NA}=1.35$)
 - Model-based OPC : Calibre nmOPC

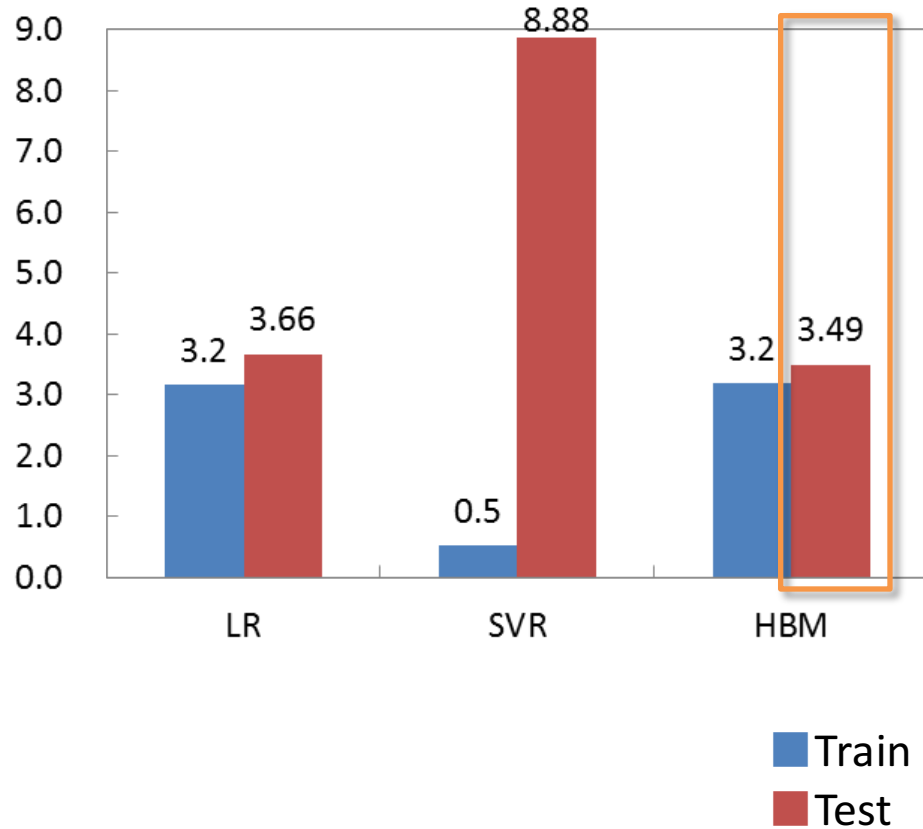
Sampling results of hidden parameters



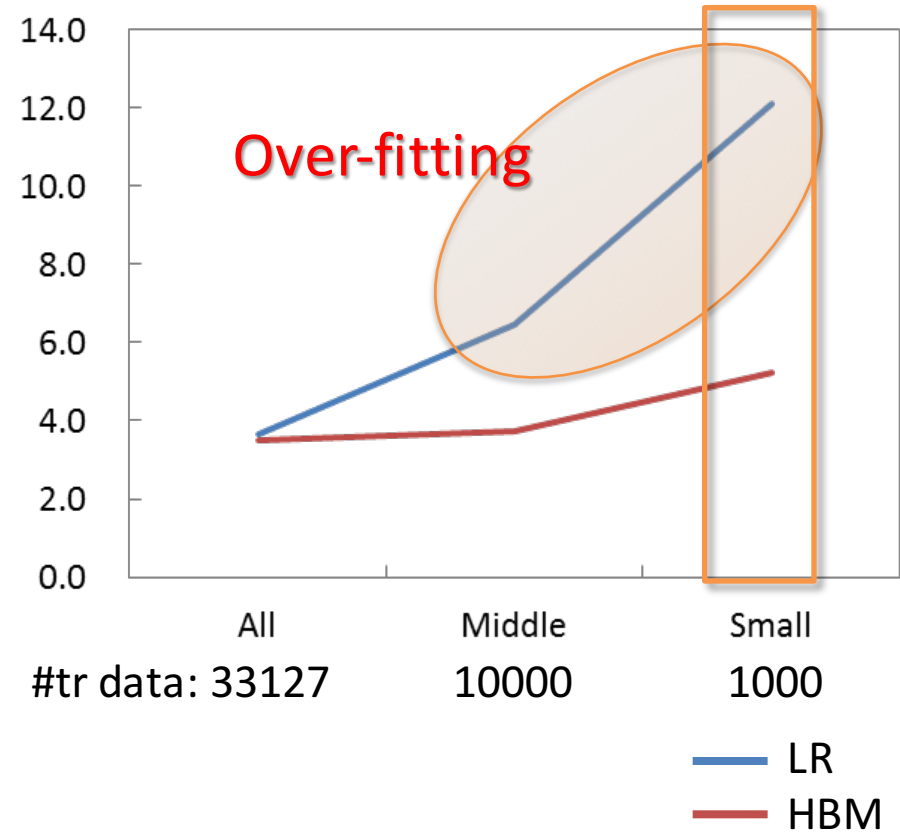
Clear difference among edge types

Comparison with linear/nonlinear regression

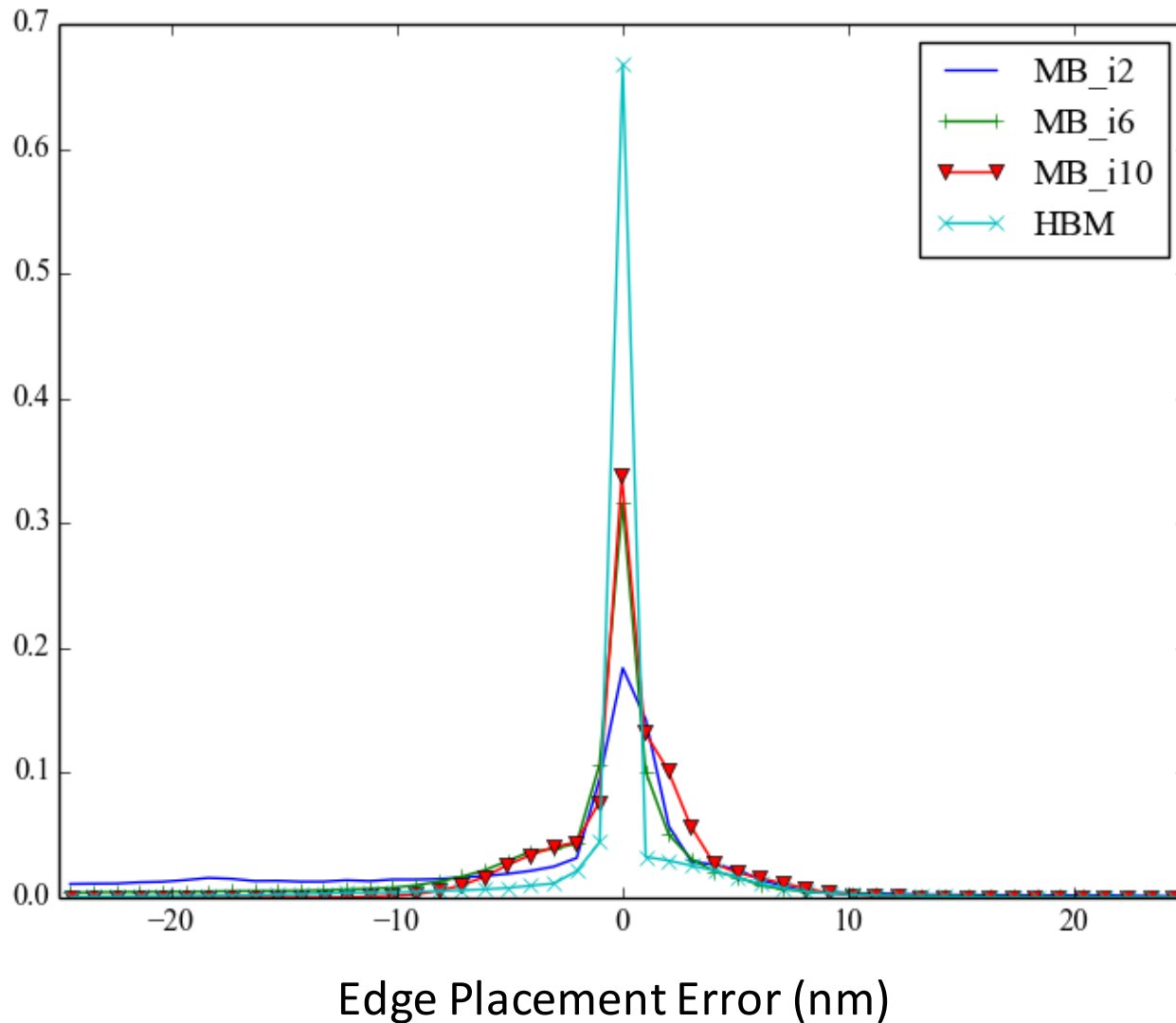
RMSE (nm)
(Root mean square error)



Prediction error
(RMSE @ Test layout)

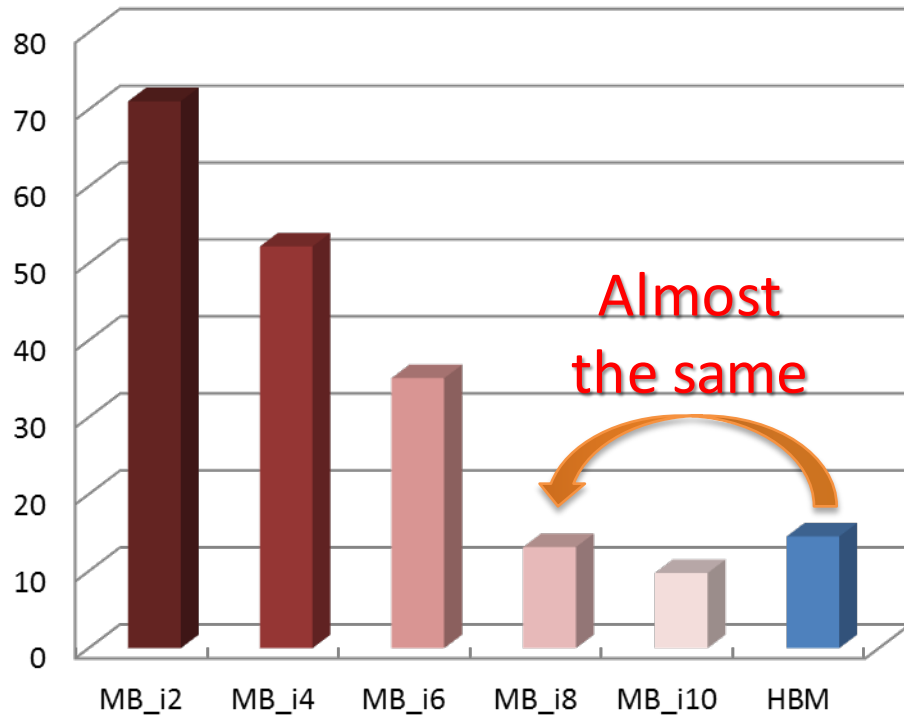


Comparison with model-based OPC (1/2)

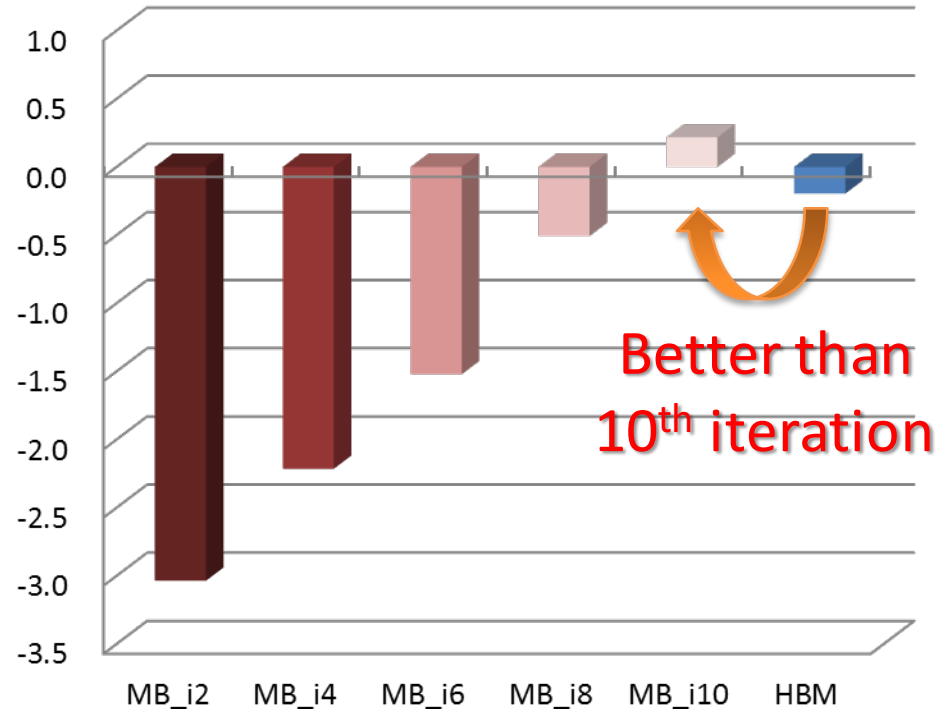


Comparison with model-based OPC (2/2)

Variance



Mean



The number of iterations of model-based OPC can be reduced **2**.

Conclusion

- **Toshiba** and **UTDA** developed a new Regression-based OPC using **hierarchical Bayes model (HBM)**.
- **The experimental results showed:**
 - High accurate prediction model can be achieved with **small amount of data** while preventing **over-fitting**.
 - The number of iterations in model-based OPC can be reduced **2**.