

Exercises: Orthogonal and Symmetric Matrices

Problem 1. Consider the following set S of column vectors:

$$S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ \cos \theta \\ \sin \theta \end{bmatrix}, \begin{bmatrix} x \\ y \\ z \end{bmatrix} \right\}$$

Find all the possible $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ that makes S an orthogonal set.

Solution. For S to be orthogonal, the vectors in S must be mutually orthogonal to each other. We therefore have:

$$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$
$$\begin{bmatrix} 0 \\ \cos \theta \\ \sin \theta \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ z \end{bmatrix} = 0$$

which gives the following set of equations on variables x, y, z :

$$\begin{aligned} x &= 0 \\ (\cos \theta)y + (\sin \theta)z &= 0. \end{aligned}$$

The set of solutions $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ is:

$$\left\{ \begin{bmatrix} 0 \\ -\frac{\sin \theta}{\cos \theta}t \\ t \end{bmatrix} \mid t \in \mathbb{R} \right\}.$$

Problem 2. Consider the following matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 0 & x \\ 0 & \cos \theta & y \\ 0 & \sin \theta & z \end{bmatrix}$$

Find all the possible $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ that makes \mathbf{A} orthogonal.

Solution. Recall that \mathbf{A} is orthogonal if and only if both conditions below are satisfied:

- All column vectors are mutually orthogonal.
- All column vectors have unit length.

In Problem 1, we have already obtained the set of $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ satisfying the first bullet:

$$\left\{ \begin{bmatrix} 0 \\ -\frac{\sin \theta}{\cos \theta} t \\ t \end{bmatrix} \mid t \in \mathbb{R} \right\}.$$

To satisfy the second bullet, we need:

$$\begin{aligned} x^2 + y^2 + z^2 &= 1 \Rightarrow \\ \left(-\frac{\sin \theta}{\cos \theta} t \right)^2 + t^2 &= 1 \Rightarrow \\ t^2 &= (\cos \theta)^2 \end{aligned} \tag{1}$$

which means that $t = \cos \theta$ or $t = -\cos \theta$. Hence, there are only two $\begin{bmatrix} x \\ y \\ z \end{bmatrix}$ that can make \mathbf{A} orthogonal:

$$\begin{bmatrix} 0 \\ -\sin \theta \\ \cos \theta \end{bmatrix}, \begin{bmatrix} 0 \\ \sin \theta \\ -\cos \theta \end{bmatrix}$$

Problem 3. Prove: if matrix \mathbf{A} is orthogonal, then its determinants must be either 1 or -1 .

Solution.

$$\begin{aligned} \det(\mathbf{I}) &= 1 \Rightarrow \\ \det(\mathbf{A}\mathbf{A}^{-1}) &= 1 \Rightarrow \\ (\text{by } \mathbf{A}^{-1} = \mathbf{A}^T) \det(\mathbf{A}\mathbf{A}^T) &= 1 \Rightarrow \\ \det(\mathbf{A}) \cdot \det(\mathbf{A}^T) &= 1 \Rightarrow \\ (\text{as } \det(\mathbf{A}) = \det(\mathbf{A}^T)) \det(\mathbf{A}) \cdot \det(\mathbf{A}) &= 1 \Rightarrow \end{aligned}$$

which completes the proof.

Problem 4. Prove: if matrices \mathbf{A} and \mathbf{B} are both orthogonal, then \mathbf{AB} is also orthogonal.

Solution. It suffices to prove that

$$\begin{aligned} (\mathbf{AB})(\mathbf{AB})^T &= \mathbf{I} \Leftrightarrow \\ (\mathbf{AB})(\mathbf{B}^T \mathbf{A}^T) &= \mathbf{I} \end{aligned}$$

Since \mathbf{A} and \mathbf{B} are both orthogonal, we know: $\mathbf{A}\mathbf{A}^T = \mathbf{I}$ and $\mathbf{B}\mathbf{B}^T = \mathbf{I}$. Therefore, $\mathbf{A}(\mathbf{B}\mathbf{B}^T)\mathbf{A}^T = \mathbf{A}\mathbf{A}^T = \mathbf{I}$.

Problem 5. Prove: if an $n \times n$ matrix \mathbf{A} is orthogonal, then (i) \mathbf{A}^{-1} definitely exists, and (ii) \mathbf{A}^{-1} must also be orthogonal.

Solution. Since \mathbf{A} is orthogonal, its row vectors form an orthogonal set, which therefore is linearly independent. This means that \mathbf{A} has rank n , meaning that \mathbf{A}^{-1} definitely exists.

To prove that \mathbf{A}^{-1} is orthogonal, we need to prove $\mathbf{A}^{-1} \cdot (\mathbf{A}^{-1})^T = \mathbf{I}$. For this purpose, note that since \mathbf{A} is orthogonal, we have $\mathbf{A}\mathbf{A}^T = \mathbf{I}$, namely $\mathbf{A}^{-1} = \mathbf{A}^T$. Equipped with this fact, we can show $\mathbf{A}^{-1} \cdot (\mathbf{A}^{-1})^T = \mathbf{I}$ as follows:

$$\begin{aligned} \mathbf{I}^T &= \mathbf{I} \Rightarrow \\ (\mathbf{A}^{-1}\mathbf{A})^T &= \mathbf{I} \Rightarrow \\ \mathbf{A}^T(\mathbf{A}^{-1})^T &= \mathbf{I} \Rightarrow \\ \mathbf{A}^{-1} \cdot (\mathbf{A}^{-1})^T &= \mathbf{I} \end{aligned} \tag{2}$$

which completes the proof.

Problem 6. Diagonalize the following matrix

$$\mathbf{A} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

into \mathbf{QBQ}^{-1} where \mathbf{B} is a diagonal matrix, and \mathbf{Q} is an orthogonal matrix. You need to give the details of only \mathbf{Q} and \mathbf{B} , namely, you do not need to give the details of \mathbf{Q}^{-1} .

Solution. We aim to obtain three eigenvectors of \mathbf{A} — denote them as $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ respectively — that are mutually orthogonal to each other and have lengths 1.

To start with, find the eigenvalues of \mathbf{A} : $\lambda_1 = 1$ and $\lambda_2 = -1$.

Now, obtain the eigenspace of λ_1 :

$$\left\{ \begin{bmatrix} u \\ u \\ v \end{bmatrix} \mid u, v \in \mathbb{R} \right\}.$$

This set has dimension 2. We will first take from the set two eigenvectors \mathbf{x}_1 and \mathbf{x}_2 that are orthogonal to each other. For this purpose, first set \mathbf{x}_1 to an arbitrary non-zero vector, e.g., $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$.

Regarding $\mathbf{x}_2 = \begin{bmatrix} u \\ u \\ v \end{bmatrix}$, we ensure orthogonality between \mathbf{x}_1 and \mathbf{x}_2 by requiring their dot product to be 0:

$$\begin{aligned} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} u \\ u \\ v \end{bmatrix} &= 0 \Rightarrow \\ u + u &= 0 \Rightarrow \\ u &= 0. \end{aligned}$$

Note that there is no constraint on v . We can set v to be any value such that \mathbf{x}_2 is not a zero-vector, e.g., $v = 1$ which gives $\mathbf{x}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$. Finally, normalize \mathbf{x}_1 and \mathbf{x}_2 to have length 1, which gives:

$$\mathbf{v}_1 = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix} \text{ and } \mathbf{v}_2 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

Next, obtain the eigenspace of λ_2 :

$$\left\{ \begin{bmatrix} -t \\ t \\ 0 \end{bmatrix} \mid t \in \mathbb{R} \right\}.$$

This set has dimension 1. Take an arbitrary eigenvector from the set, e.g., $\mathbf{x}_3 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$. Normalizing

this vector to have length 1 gives $\mathbf{v}_3 = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$.

Therefore:

$$\mathbf{Q} = \begin{bmatrix} 1/\sqrt{2} & 0 & -1/\sqrt{2} \\ 1/\sqrt{2} & 0 & 1/\sqrt{2} \\ 0 & 1 & 0 \end{bmatrix}$$

$$\mathbf{B} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{bmatrix}.$$

Problem 7. Suppose that an $n \times n$ matrix \mathbf{A} can be computed as \mathbf{QBQ}^{-1} where \mathbf{Q} is an $n \times n$ orthogonal matrix, and \mathbf{B} is an $n \times n$ diagonal matrix. Prove: \mathbf{A} is a symmetric matrix.

Solution. We aim to prove that $\mathbf{A} = \mathbf{A}^T$. Towards this purpose, we compute \mathbf{A}^T as follows:

$$\begin{aligned} \mathbf{A}^T &= (\mathbf{QBQ}^{-1})^T \Rightarrow \\ \mathbf{A}^T &= (\mathbf{Q}^{-1})^T \mathbf{B}^T \mathbf{Q}^T \end{aligned} \tag{3}$$

Since \mathbf{Q} is an orthogonal matrix, we have: $\mathbf{Q}^{-1} = \mathbf{Q}^T$. Hence:

$$(3) = (\mathbf{Q}^T)^T \mathbf{B}^T \mathbf{Q}^{-1} = \mathbf{QBQ}^{-1} = \mathbf{A}.$$

This completes the proof.