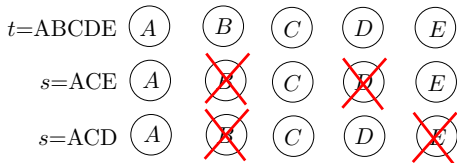


# Dynamic Programming: Finding Recursive Structures

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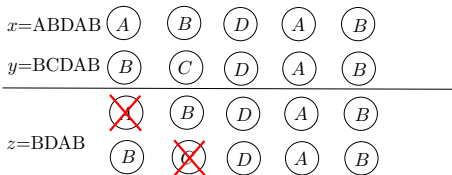
A string  $s$  is a **subsequence** of another string  $t$  if either  $s = t$  or we can convert  $t$  to  $s$  by deleting characters.



## The Longest Common Subsequence Problem

Given two strings  $x$  and  $y$ , find a common subsequence  $z$  of  $x$  and  $y$  with the maximum length.

- $z$  is a **longest common subsequence** (LCS) of  $x$  and  $y$ .



**Remark:** If  $x = \emptyset$  (empty string) or  $y = \emptyset$ , their (only) LCS is  $\emptyset$ .

The key to solving the problem is to identify its underlying **recursive structure**.

Specifically, how the original problem is related to subproblems.

$n$  = the length of  $x$ ;  $m$  = the length of  $y$

**Theorem (LCS Theorem):** Let  $z$  be any LCS of  $x$  and  $y$ , and  $k$  the length of  $z$ . Then:

- 1 If  $x[n] = y[m]$   
then  $z[k] = x[n]$  (hence, also  $= y[m]$ ) and  
 $z[1 : k - 1]$  is an LCS of  $x[1 : n - 1]$  and  $y[1 : m - 1]$ .
- 2 If  $x[n] \neq y[m]$ , then **at least** one of the following holds:
  - $z$  is an LCS of  $x[1 : n - 1]$  and  $y$
  - $z$  is an LCS of  $x$  and  $y[1 : m - 1]$ .

Next, we will prove the theorem.

**Lemma 1:** If  $z[k] \neq x[n]$ , then  $z$  is a subsequence of  $x[1 : n - 1]$ .

**Proof:** As  $z$  is a subsequence of  $x$ , we can convert  $x$  to  $z$  by deleting characters repeatedly. The conversion must have deleted  $x[n]$ ; otherwise,  $x[n]$  must be the last character of  $z$ , which contradicts  $z[k] \neq x[n]$ .

It thus follows that we can obtain  $z$  by repeatedly deleting characters from  $x[1 : n - 1]$  and, hence,  $z$  is a subsequence of  $x[1 : n - 1]$ .  $\square$

## Proof of Statement 1 (in the LCS Theorem):

**Claim:** If  $x[n] = y[m]$ , then  $z[k] = x[n]$ .

Assume that  $x[n] = y[m]$  but  $z[k] \neq x[n]$ . By Lemma 1,  $z$  is a common subsequence of  $x[1 : n - 1]$  and  $y[1 : m - 1]$ . Now, we can obtain a common subsequence  $z' = z \circ x[n]$  of  $x$  and  $y$ . However,  $z'$  will be a length- $(k + 1)$  common subsequence of  $x$  and  $y$ , contradicting the fact that  $z$  is an LCS of  $x$  and  $y$ .

**Remark:**  $\circ$  means string concatenation. For example,  $ABC \circ DEF = ABCDEF$ .

## Proof of Statement 1:

**Claim:** If  $x[n] = y[m]$ , then  $z[1 : k - 1]$  is an LCS of  $x[1 : n - 1]$  and  $y[1 : m - 1]$ .

Assume that  $z[1 : k - 1]$  is not an LCS of  $x[1 : n - 1]$  and  $y[1 : m - 1]$ . Thus,  $x[1 : n - 1]$  and  $y[1 : m - 1]$  have an LCS  $z'$  with length at least  $k$ .

However,  $z' \circ x[n]$  will be a length- $(k + 1)$  common subsequence of  $x$  and  $y$ , contradicting the fact that  $z$  is an LCS of  $x$  and  $y$ .  $\square$



## Proof of Statement 2:

Because  $x[n] \neq y[m]$ , at least one of the following is false:

- $z[k] = x[n]$
- $z[k] = y[m]$ .

Consider first  $z[k] \neq x[n]$ .

We argue that  $z$  must be an LCS of  $x[1 : n - 1]$  and  $y$ .

- By Lemma 1,  $z$  is a subsequence of  $x[1 : n - 1]$ . Since  $z$  is also a subsequence of  $y$ ,  $z$  is a common subsequence of  $x[1 : n - 1]$  and  $y$ .
- Suppose that  $z$  is not an LCS of  $x[1 : n - 1]$  and  $y$ . Thus,  $x[1 : n - 1]$  and  $y$  have an LCS  $z'$  of length at least  $k + 1$ . This means that  $x$  and  $y$  have a common subsequence of length  $k + 1$ , contradicting the fact that  $z$  is an LCS of  $x$  and  $y$ .

A symmetric argument proves the statement when  $z[k] \neq y[m]$ . □

## Matrix-Chain Multiplication

You are given an algorithm  $\mathcal{A}$  that, given an  $a \times b$  matrix  $\mathbf{A}$  and a  $b \times c$  matrix  $\mathbf{B}$ , can calculate  $\mathbf{AB}$  in  $O(abc)$  time. You need to use  $\mathcal{A}$  to calculate the product of  $\mathbf{A}_1\mathbf{A}_2\dots\mathbf{A}_n$  where  $\mathbf{A}_i$  is an  $a_i \times b_i$  matrix for  $i \in [1, n]$ . This implies that  $b_{i-1} = a_i$  for  $i \in [2, n]$ , and the final result is an  $a_1 \times b_n$  matrix.

A trivial strategy is to apply  $\mathcal{A}$  to evaluate the product from left to right. However, we may be able to reduce the cost by following a different multiplication order.

## Example

Consider  $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3$  where  $\mathbf{A}_1$  and  $\mathbf{A}_2$  are  $m \times m$  matrices, but  $\mathbf{A}_3$  is  $m \times 1$ .

There are two multiplication orders:

- $(\mathbf{A}_1\mathbf{A}_2)\mathbf{A}_3$ .

The cost of computing  $\mathbf{B} = \mathbf{A}_1\mathbf{A}_2$  is  $O(m \cdot m \cdot m) = O(m^3)$  and  $\mathbf{B}$  is an  $m \times m$  matrix. The cost of  $\mathbf{B}\mathbf{A}_3$  is  $O(m \cdot m \cdot 1) = O(m^2)$ . The total cost is  $O(m^3)$ .

- $\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3)$ .

The cost of computing  $\mathbf{B} = \mathbf{A}_2\mathbf{A}_3$  is  $O(m \cdot m \cdot 1) = O(m^2)$  and  $\mathbf{B}$  is an  $m \times 1$  matrix. The cost of  $\mathbf{A}_1\mathbf{B}$  is  $O(m \cdot m \cdot 1) = O(m^2)$ . The total cost is  $O(m^2)$ .

**Parenthesizing**  $\mathbf{A}_1\mathbf{A}_2\dots\mathbf{A}_n$  at  $\mathbf{A}_k$  for some  $k \in [1, n - 1]$  converts the expression to  $(\mathbf{A}_1\dots\mathbf{A}_k)(\mathbf{A}_{k+1}\dots\mathbf{A}_n)$ , after which you can parenthesize each of  $\mathbf{A}_1\dots\mathbf{A}_i$  and  $\mathbf{A}_{i+1}\dots\mathbf{A}_n$  recursively.

A **fully parenthesized product** is

- either a single matrix or
- the product of two fully parenthesized products.

For example, if  $n = 4$ , then  $(\mathbf{A}_1\mathbf{A}_2)(\mathbf{A}_3\mathbf{A}_4)$  and  $((\mathbf{A}_1\mathbf{A}_2)\mathbf{A}_3)\mathbf{A}_4$  are fully parenthesized, but  $\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4)$  is not.

A fully parenthesized product determines a multiplication order that, in turn, determines the computation cost.

**Goal:** Design an algorithm to find in  $O(n^3)$  time a fully parenthesized product with the smallest cost.

## Recursive Structure

By parenthesizing at  $\mathbf{A}_k$ , we obtain

$$\underbrace{(\mathbf{A}_1 \dots \mathbf{A}_k)}_{\mathbf{B}_1} \underbrace{(\mathbf{A}_{k+1} \dots \mathbf{A}_n)}_{\mathbf{B}_2},$$

where  $\mathbf{B}_1$  is an  $a_1 \times b_k$  matrix and  $\mathbf{B}_2$  is an  $a_{k+1} \times b_n$  matrix.

The total cost is

$$\text{cost of computing } \mathbf{B}_1 + \text{cost of computing } \mathbf{B}_2 + O(a_1 b_k b_n).$$

We define  $cost(i, j)$ , where  $1 \leq i \leq j \leq n$ , to be the smallest achievable cost for calculating  $\mathbf{A}_i \dots \mathbf{A}_j$ . Our objective is to calculate  $cost(1, n)$ .

If we parenthesize  $\mathbf{A}_i \dots \mathbf{A}_j$  at  $\mathbf{A}_k$ , we obtain

$$\underbrace{(\mathbf{A}_i \dots \mathbf{A}_k)}_{cost(i, k)} \underbrace{(\mathbf{A}_{k+1} \dots \mathbf{A}_j)}_{cost(k+1, j)}.$$

The total cost is

$$cost(i, k) + cost(k + 1, j) + O(a_i b_k b_j).$$

To attain  $cost(i, j)$ , we should try all possible parenthesizations of  $\mathbf{A}_i \dots \mathbf{A}_j$ . This implies:

$$cost(i, j) = \begin{cases} O(1) & \text{if } i = j \\ \min_{k=i}^{j-1} (cost(i, k) + cost(k+1, j) + O(a_i b_k b_j)) & \text{if } i < j \end{cases}$$

By dyn. programming, we can compute  $cost(1, n)$  in  $O(n^3)$  time.

Consider  $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4$  where  $\mathbf{A}_1$  and  $\mathbf{A}_2$  are  $m \times m$  matrices,  $\mathbf{A}_3$  is  $m \times 1$ , and  $\mathbf{A}_4$  is  $1 \times m$ .

$i \backslash j$	1	2	3	4
1				<i>cost(1, 4)</i>
2	0			
3	0	0		
4	0	0	0	



After solving all subproblems, we obtain:

$i \backslash j$	1	2	3	4
1	$O(1)$	$O(m^3)$	$O(m^2)$	$O(m^2)$
2	0	$O(1)$	$O(m^2)$	$O(m^2)$
3	0	0	$O(1)$	$O(m^2)$
4	0	0	0	$O(1)$

Next, we apply the “piggyback technique” to generate an optimal parenthesization.

Define  $bestSub(i, j) =$

- nil, if  $i = j$ ;
- $k$ , if the best parenthesization for  $\mathbf{A}_i \mathbf{A}_{i+1} \dots \mathbf{A}_j$  is  $(\mathbf{A}_i \dots \mathbf{A}_k)(\mathbf{A}_{k+1} \dots \mathbf{A}_j)$ .

$i \backslash j$	1	2	3	4
1	$O(1)$	$O(m^3)$	$O(m^2)$	$O(m^2)$
2	0	$O(1)$	$O(m^2)$	$O(m^2)$
3	0	0	$O(1)$	$O(m^2)$
4	0	0	0	$O(1)$

After  $cost(i, j)$  is ready for all  $i, j$ , we can compute all  $bestSub(i, j)$  in  $O(n^3)$  time.

$i \backslash j$	1	2	3	4
1	$O(1)$	$O(m^3)$	$O(m^2)$	$O(m^2)$
2	0	$O(1)$	$O(m^2)$	$O(m^2)$
3	0	0	$O(1)$	$O(m^2)$
4	0	0	0	$O(1)$

$\mathbf{A}_1: m \times m$

$\mathbf{A}_2: m \times m$

$\mathbf{A}_3: m \times 1$

$\mathbf{A}_4: 1 \times m$

### Example:

$bestSub(1, 4) = 3$ , i.e., the best way to calculate  $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4$  is  $(\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3)\mathbf{A}_4$ .

Similarly,  $bestSub(1, 3) = 1$ , i.e., the best way to calculate  $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3$  is  $\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3)$ .

Therefore, an optimal fully parenthesized product of  $\mathbf{A}_1\mathbf{A}_2\mathbf{A}_3\mathbf{A}_4$  is  $(\mathbf{A}_1(\mathbf{A}_2\mathbf{A}_3))\mathbf{A}_4$ .