

Thm 3.5 (Implicit Function Theorem)

Let U be an open set in $\mathbb{R}^n \times \mathbb{R}^m$,

$F: U \rightarrow \mathbb{R}^m$ is a C^1 -map.

Suppose that $(p_0, q_0) \in U$ satisfies $F(p_0, q_0) = 0$,

and $D_y F(p_0, q_0)$ is invertible in \mathbb{R}^m .

Then

(1) \exists an open set of the form $V_1 \times V_2 \subset U$ containing (p_0, q_0) and a C^1 -map

$$\varphi: V_1 \subset \mathbb{R}^n \rightarrow V_2 \subset \mathbb{R}^m$$

such that $F(x, \varphi(x)) = 0, \forall x \in V_1$.

(2) $\varphi: V_1 \rightarrow V_2$ is C^k when F is $C^k, 1 \leq k \leq \infty$.

(3) Moreover, if ψ is another C^1 -map in some open set Ω containing p_0 to V_2 satisfying

$F(x, \psi(x)) = 0$ and $\psi(p_0) = q_0$, then

$$\psi \equiv \varphi \text{ on } \Omega \cap V_1.$$

Recall: If $F = \begin{pmatrix} f^1(x^1, \dots, x^n, y^1, \dots, y^m) \\ \vdots \\ f^m(x^1, \dots, x^n, y^1, \dots, y^m) \end{pmatrix}$, then

$$D_y F = \begin{pmatrix} \frac{\partial f^1}{\partial y^1} & \cdots & \frac{\partial f^1}{\partial y^m} \\ \vdots & & \vdots \\ \frac{\partial f^m}{\partial y^1} & \cdots & \frac{\partial f^m}{\partial y^m} \end{pmatrix} \text{ is } m \times m \text{ \& can be regarded as a linear transformation from } \mathbb{R}^m \text{ to } \mathbb{R}^m.$$

PF of Implicit Function Theorem:

$$\text{Define } \underline{\Phi} = \underbrace{\bigcup}_{\psi} \mathbb{C}^{\mathbb{R}^n \times \mathbb{R}^m} \rightarrow \underbrace{\mathbb{R}^n \times \mathbb{R}^m}_{\psi}$$

$$(x, y) \longmapsto (x, F(x, y))$$

$$\text{where } x = \begin{pmatrix} x^1 \\ \vdots \\ x^n \end{pmatrix} \in \mathbb{R}^n, \quad y = \begin{pmatrix} y^1 \\ \vdots \\ y^m \end{pmatrix} \in \mathbb{R}^m.$$

Clearly $\underline{\Phi}$ is C^k if F is C^k .

$$\text{In fact } \underline{\Phi} = \begin{pmatrix} x^1 \\ \vdots \\ x^n \\ f^1(x^1, \dots, x^n, y^1, \dots, y^m) \\ \vdots \\ f^m(x^1, \dots, x^n, y^1, \dots, y^m) \end{pmatrix}$$

$$\Rightarrow D\underline{\Phi} = \left(\begin{array}{ccc|ccc} 1 & & & & & \\ & \ddots & & & & \\ & & 1 & & & \\ \hline & & & & & 0 \\ \frac{\partial f^1}{\partial x^1} & \cdots & \frac{\partial f^1}{\partial x^n} & \frac{\partial f^1}{\partial y^1} & \cdots & \frac{\partial f^1}{\partial y^m} \\ \vdots & & \vdots & \vdots & & \vdots \\ \frac{\partial f^m}{\partial x^1} & \cdots & \frac{\partial f^m}{\partial x^n} & \frac{\partial f^m}{\partial y^1} & \cdots & \frac{\partial f^m}{\partial y^m} \end{array} \right)$$

Since $D_y F \Big|_{(p_0, q_0)} = \begin{pmatrix} \frac{\partial f^1}{\partial y^1} & \cdots & \frac{\partial f^1}{\partial y^m} \\ \vdots & & \vdots \\ \frac{\partial f^m}{\partial y^1} & \cdots & \frac{\partial f^m}{\partial y^m} \end{pmatrix}$ is invertible in \mathbb{R}^m ,

$D\Phi \Big|_{(p_0, q_0)}$ is invertible in $\mathbb{R}^n \times \mathbb{R}^m$.

Applying Inverse Function Theorem, \exists local C^1 -inverse

$$\Psi = (\Psi_1, \Psi_2) : W \subset \mathbb{R}^n \times \mathbb{R}^m \longrightarrow V,$$

where W and V are open nbds. of $\Phi(p_0, q_0) = (p_0, 0)$ and (p_0, q_0) respectively, and is C^k when F is C^k .

By shrinking the nbds, we may assume V is of the form $V_1 \times V_2$, where V_1 open in \mathbb{R}^n containing p_0 ; V_2 open in \mathbb{R}^m containing q_0 .

Now $\forall (x, z) \in W$,

$$\Phi(\Psi_1(x, z), \Psi_2(x, z)) = (x, z)$$

$$\parallel \\ (\Psi_1(x, z), F(\Psi_1(x, z), \Psi_2(x, z)))$$

$$\therefore \begin{cases} x = \Psi_1(x, z) \\ z = F(\Psi_1(x, z), \Psi_2(x, z)) \end{cases}$$

$$\Rightarrow z = F(x, \Psi_2(x, z))$$

In particular, we can take $z=0$ & hence

$$F(x, \Psi_2(x, 0)) = 0, \quad \forall x = \Psi_1(x, 0) \in V_1.$$

$$\therefore \varphi: V_1 \rightarrow V_2 = x \mapsto \Psi_2(x, 0)$$

is the required map st.

$$F(x, \varphi(x)) = 0 \quad \text{and is } C^k \text{ when } F \text{ is } C^k.$$

We've proved (1) & (2).

For (3), we observe that the continuity of DF

\Rightarrow we may assume (by shrinking V_1 & V_2 further)

that $\int_0^1 D_y F(x, y_1 + t(y_2 - y_1)) dt$ is nonsingular

for (x, y_1) & $(x, y_2) \in V_1 \times V_2$.

Now if $\psi: \Omega \rightarrow \mathbb{R}^m$ (C^1 -map) is another map

$$\text{st. } F(x, \psi(x)) = 0 \quad \& \quad \psi(p_0) = q_0,$$

$$\text{then } 0 = F(x, \psi(x)) - F(x, \varphi(x))$$

$$= \left(\int_0^1 D_y F(x, \varphi(x) + t(\psi(x) - \varphi(x))) dt \right) (\psi(x) - \varphi(x))$$

($\psi(p_0) = q_0$ guarantees $\psi(x) \in \mathcal{V}_2$)

$\therefore \int_0^1 D_y F(x, \varphi(x) + t(\psi(x) - \varphi(x))) dt$ nonsingular

$\Rightarrow \psi(x) \equiv \varphi(x), \forall x \in \Omega \cap \mathcal{V}_1$. ~~##~~

eg 3.10: $F: \mathbb{R}^5 \rightarrow \mathbb{R}^2 = \begin{pmatrix} x \\ y \\ z \\ u \\ v \end{pmatrix} \mapsto \begin{pmatrix} xy^2 + xzu + yv^2 - 3 \\ u^3yz + 2xv - u^2v^2 - 2 \end{pmatrix}$

$$D_{\begin{pmatrix} y \\ u \\ v \end{pmatrix}} F = \begin{pmatrix} xz & & zuv \\ 3u^2yz - 2uv^2 & & 2x - 2u^2v \end{pmatrix}$$

$$\det D_{\begin{pmatrix} y \\ u \\ v \end{pmatrix}} F = xz(2x - 2u^2v) - 2yuv(3u^2yz - 2uv^2)$$

$$\det D_{\begin{pmatrix} y \\ u \\ v \end{pmatrix}} F \Big|_{\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}} = -2 \neq 0$$

\therefore Implicit Function Thm $\Rightarrow \exists \varphi: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ s.t.

$$\varphi \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \quad \left(\varphi = \begin{pmatrix} \varphi^1 \\ \varphi^2 \end{pmatrix} \right)$$

and $F \begin{pmatrix} x \\ y \\ z \\ \varphi^1(x,y,z) \\ \varphi^2(x,y,z) \end{pmatrix} = 0$.

Note that Inverse Function Thm \Leftrightarrow Implicit Function Thm

(\Rightarrow) done!

To see (\Leftarrow):

$$F: U \subset \mathbb{R}^n \rightarrow \mathbb{R}^n, F(y_0) = p_0 \in \mathbb{R}^n, y_0 \in U$$

define $\tilde{F}: \mathbb{R}^n \times U \rightarrow \mathbb{R}^n$
 $(x, y) \mapsto x - F(y).$

Then $\tilde{F}(p_0, y_0) = 0 \Leftrightarrow p_0 = F(y_0)$

$D_y \tilde{F} = -DF$ invertible in \mathbb{R}^n (at (p_0, y_0)).

\therefore Implicit Function Thm \Rightarrow

$$\exists \varphi: V_1 \rightarrow V_2 \quad \left(\begin{array}{l} V_1 \text{ open nbd. of } p_0 \\ V_2 \text{ open nbd. of } y_0 \end{array} \right)$$

such that

$$0 = \tilde{F}(x, \varphi(x)) = x - F(\varphi(x))$$

i.e. $\forall x \in V_1, \exists \varphi(x) \in V_2 \subset \mathbb{R}^n$ s.t.

$$\begin{cases} \varphi(y_0) = y_0 \\ F(\varphi(x)) = x \end{cases}$$

$\therefore \varphi = (F|_{V_2})^{-1}$. (is C^k when F is C^k)

§3.4 Picard-Lindelöf Theorem for Differential Equations

Let f be a function defined on

$$R = [t_0 - a, t_0 + a] \times [x_0 - b, x_0 + b] \quad \text{where } (t_0, x_0) \in \mathbb{R}^2$$

and $a, b > 0$. We consider Cauchy Problem

(Initial Value Problem)

$$(3.6) \quad \begin{cases} \frac{dx}{dt} = f(t, x) \\ x(t_0) = x_0 \end{cases}$$

i.e. find a function $x(t)$ defined in a perhaps smaller interval $x: [t_0 - a', t_0 + a'] \rightarrow [x_0 - b, x_0 + b]$

such that

$$\begin{cases} x(t) \text{ is differentiable,} \\ x(t_0) = x_0, \text{ and} \\ \frac{dx}{dt}(t) = f(t, x(t)), \quad \forall t \in [t_0 - a', t_0 + a'] \end{cases}$$

for some $0 < a' \leq a$.

eg 3.11 Consider $\begin{cases} \frac{dx}{dt} = 1 + x^2 \\ x(0) = 0 \end{cases}$

Here $f(t, x) = 1 + x^2$ is smooth on $[-a, a] \times [-b, b]$ for any $a, b > 0$. However, the solution $x(t) = \tan t$

defined only on $(-\frac{\pi}{2}, \frac{\pi}{2})$. \therefore Even for nice f , we may still have $a' < a$.

Recall: (i) f defined in $R = [t_0 - a, t_0 + a] \times [x_0 - b, x_0 + b]$ satisfies the Lipschitz condition (uniform in t) if $\exists L > 0$ s.t. $\forall (t, x_1), (t, x_2) \in R$,
 $|f(t, x_1) - f(t, x_2)| \leq L|x_1 - x_2|$.

(i') In particular, $f(t, \cdot)$ is lip. cts in x , $\forall t \in [t_0 - a, t_0 + a]$

(i'') L is called a Lipschitz constant.

(iv) If L is a lip. constant for f , then any $L' > L$ is also a lip. constant.

(v) Not all cts. functions satisfy the lip. condition.

eg: $f(t, x) = t x^{1/2}$ is cts, but not lip. near 0.

(vi) If $f(t, x) : \overset{R}{[t_0 - a, t_0 + a] \times [x_0 - b, x_0 + b]} \rightarrow \mathbb{R}$ is C^1 , then $f(t, x)$ satisfies the lip. condition:

$$|f(t, x_2) - f(t, x_1)| = \left| \frac{\partial f}{\partial x}(t, y) (x_2 - x_1) \right| \text{ for some } y \in [x_0 - b, x_0 + b] \\ \leq L|x_2 - x_1|,$$

where $L = \max \left\{ \left| \frac{\partial f}{\partial x}(t, x) \right| : (t, x) \in R \right\}$.

Thm 3.6 (Picard-Lindelöf Theorem)

Let f be continuous function on $R = [t_0 - a, t_0 + a] \times [x_0 - b, x_0 + b]$
($(t_0, x_0) \in \mathbb{R}^2$, $a, b > 0$) satisfies the Lipschitz condition
on R . Then $\exists a' \in (0, a]$ and $x \in C^1[t_0 - a', t_0 + a']$
such that

$$x_0 - b \leq x(t) \leq x_0 + b, \quad \forall t \in [t_0 - a', t_0 + a']$$

and solving the Cauchy Problem (3.6).

Furthermore, x is the unique solution in $[t_0 - a', t_0 + a']$.

Note: One will see in the following proof that a' can be
taken to be any number satisfying

$$0 < a' < \min \left\{ a, \frac{b}{M}, \frac{1}{L} \right\}$$

where $M = \sup \{ |f(t, x)| : (t, x) \in R \}$ &

$L = \text{Lip. const. for } f.$

Prop 3.7: Setting as in Thm 3.6, every solution x of (3.6)

from $[t_0 - a', t_0 + a']$ to $[x_0 - b, x_0 + b]$ satisfies

the equation $\boxed{x(t) = x_0 + \int_{t_0}^t f(t, x(t)) dt} \quad (3.7)$

(Pf: Obvious.)

Proof of Picard-Lindelöf Theorem:

For $a' > 0$ to be chosen later, we let

$$\Sigma = \{ \varphi \in C[t_0 - a', t_0 + a'] : \varphi(t_0) = x_0, \varphi(t) \in [x_0 - b, x_0 + b] \}$$

and uniform metric d_∞ on Σ .

First note that Σ is closed subset in the complete metric space $(C[t_0 - a', t_0 + a'], d_\infty)$. Hence

(Σ, d_∞) is complete.

Define T on Σ by

$$(T\varphi)(t) = x_0 + \int_{t_0}^t f(s, \varphi(s)) ds$$

(This is well-defined as $\varphi(s) \in [x_0 - b, x_0 + b]$.)

Clearly $T\varphi \in C[t_0 - a', t_0 + a']$ & $(T\varphi)(t_0) = x_0$.

To show $T\varphi \in \Sigma$, we need to show that

$$(T\varphi)(t) \in [x_0 - b, x_0 + b].$$

Let $M = \sup_{(t,x) \in R} |f(t,x)|$ and consider

$$\begin{aligned} |(T\varphi)(t) - x_0| &= \left| \int_{t_0}^t f(s, \varphi(s)) ds \right| \leq M |t - t_0| \\ &\leq M a'. \end{aligned}$$

So if we choose $0 < a' \leq \frac{b}{M}$, then

$$|(T\varphi)(t) - x_0| \leq b$$

$$\Rightarrow T\varphi \in \mathcal{X}.$$

This is, for $0 < a' \leq \frac{b}{M}$, $T: \mathcal{X} \rightarrow \mathcal{X}$ is a self-map

from a complete metric space (\mathcal{X}, d_∞) to itself.

To see whether T is a contraction, we check

$$|(T\varphi_2 - T\varphi_1)(t)| = \left| \left(x_0 + \int_{t_0}^t f(s, \varphi_2(s)) ds \right) - \left(x_0 + \int_{t_0}^t f(s, \varphi_1(s)) ds \right) \right|$$

$$\leq \int_{t_0}^t |f(s, \varphi_2(s)) - f(s, \varphi_1(s))| ds$$

$$\leq L \int_{t_0}^t |\varphi_2(s) - \varphi_1(s)| ds \quad \text{by Lip. condition}$$

$$\leq L (t - t_0) \sup_{[t_0 - a', t + a']} |\varphi_2(s) - \varphi_1(s)|$$

$$\leq L a' d_\infty(\varphi_2, \varphi_1)$$

Therefore, if $La' = \gamma < 1$, then T is a contraction:

$$\begin{aligned} d_\infty(T\varphi_2, T\varphi_1) &\leq La' d_\infty(\varphi_2, \varphi_1) \\ &= \gamma d_\infty(\varphi_2, \varphi_1). \end{aligned}$$

In conclusion,

