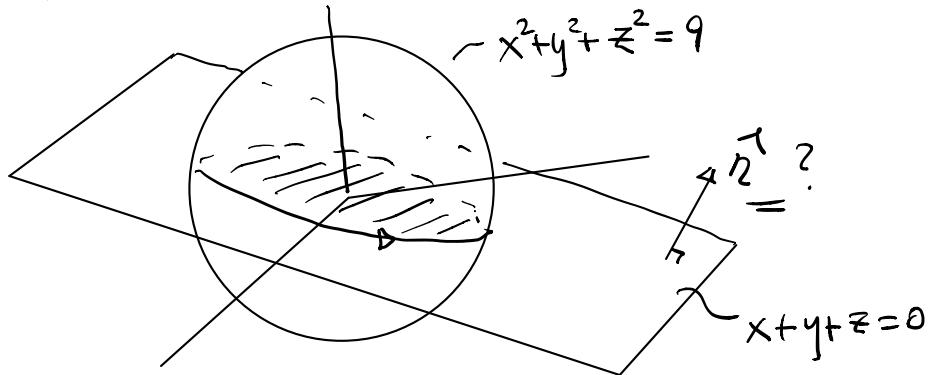


eg62 Let $\vec{F} = \hat{i} - \hat{x}\hat{j}$ (same \vec{F} as in eg61, new surface & new boundary curve)



$$S_4 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 \leq 9, x + y + z = 0\}$$

boundary curve of S_4 : $C_4 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 9, x + y + z = 0\}$

Find $\oint_{C_4} \vec{F} \cdot d\vec{r}$ (with direction of C_4 given as in the figure.)

Solu: Apply Stokes' Thm

$$\oint_{C_4} \vec{F} \cdot d\vec{r} = \iint_{S_4} (\vec{\nabla} \times \vec{F}) \cdot \hat{n} \, d\sigma$$

\hat{n} is the normal to S_4

is given by the coefficient of
the const. of the plane

i.e. $\hat{n} = \frac{\hat{i} + \hat{j} + \hat{k}}{\sqrt{3}}$

$$= \iint_{S_4} (-2\hat{k}) \cdot \frac{\hat{i} + \hat{j} + \hat{k}}{\sqrt{3}} \, d\sigma$$

$$= -\frac{2}{\sqrt{3}} \iint_{S_4} d\sigma = -\frac{2}{\sqrt{3}} \text{Area}(S_4)$$

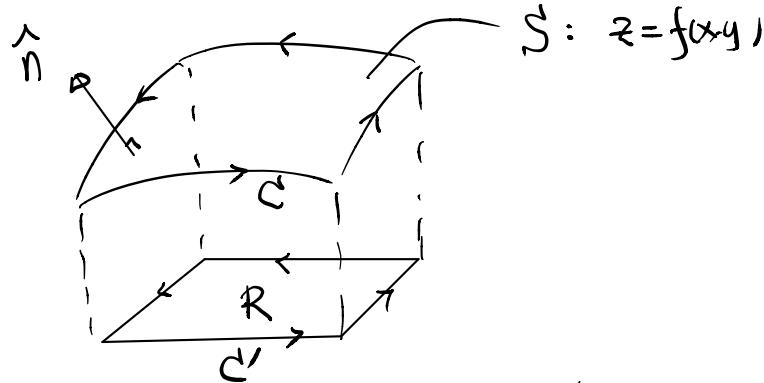
$$= -\frac{2}{\sqrt{3}} (\pi \cdot 3^2) = -\frac{18\pi}{\sqrt{3}}$$

X

Proof of Stokes' Thm

Special case: S is a graph given by

$z = f(x, y)$ over a region R with upward normal



Assume C is the boundary of S , and C' is the boundary of R (anti-clockwise oriented wrt the normal of S and the plane respectively)

Parametrize the graph as

$$\vec{r}(x, y) = x\hat{i} + y\hat{j} + f(x, y)\hat{k}, \quad (x, y) \in R$$

Then as before

$$\begin{cases} \vec{r}_x = \hat{i} + \frac{\partial f}{\partial x}\hat{k} \\ \vec{r}_y = \hat{j} + \frac{\partial f}{\partial y}\hat{k} \end{cases}$$

$$\Rightarrow \vec{r}_x \times \vec{r}_y = -\frac{\partial f}{\partial x}\hat{i} - \frac{\partial f}{\partial y}\hat{j} + \underbrace{\hat{k}}_{\text{(upward)}} \quad (\text{upward})$$

Hence $\hat{n} = \frac{\vec{r}_x \times \vec{r}_y}{|\vec{r}_x \times \vec{r}_y|}$ is the upward normal of S ,

$$\text{and } dS = |\vec{r}_x \times \vec{r}_y| dx dy = |\vec{r}_x \times \vec{r}_y| dA \quad \text{C area element of } R$$

Let $\vec{F} = M\hat{i} + N\hat{j} + L\hat{k}$ be the C^1 vector field.

$$\begin{aligned} \text{Then } \iint_S (\nabla \times \vec{F}) \cdot \hat{n} d\sigma &= \iint_R (\nabla \times \vec{F})(\vec{F}(xy)) \cdot \frac{\vec{r}_x \times \vec{r}_y}{|\vec{r}_x \times \vec{r}_y|} \cdot |\vec{r}_x \times \vec{r}_y| dA \\ &= \iint_R [(L_y - N_z)\hat{i} + (M_z - L_x)\hat{j} + (N_x - M_y)\hat{k}] \cdot [-\frac{\partial f}{\partial x}\hat{i} - \frac{\partial f}{\partial y}\hat{j} + \hat{k}] dA \\ &= \iint_R [-f_x(L_y - N_z) - f_y(M_z - L_x) + (N_x - M_y)] dx dy \end{aligned}$$

For the line integral

$$\begin{aligned} \oint_C \vec{F} \cdot d\vec{r} &= \oint_C M dx + N dy + L dz \\ &\xrightarrow{\text{parametrized by } (xy) \in C'} = \oint_{C'} M dx + N dy + L df \quad (z = f(x, y)) \\ &= \oint_{C'} M dx + N dy + L(f_x dx + f_y dy) \\ &= \oint_C (M + L f_x) dx + (N + L f_y) dy. \end{aligned}$$

Precisely: If C' is parametrized by
 $\vec{r}(t) = (x(t), y(t))$ for $a \leq t \leq b$.

Then C is parametrized by

$$\begin{aligned} \vec{F}(t) &= (x(t), y(t), f(x(t), y(t))) \\ &= x(t)\hat{i} + y(t)\hat{j} + f(x(t), y(t))\hat{k}, \quad a \leq t \leq b \end{aligned}$$

$$\Rightarrow \oint_C \vec{F} \cdot d\vec{r} = \int_a^b \left[M(\vec{r}(t)) x'(t) + N(\vec{r}(t)) y'(t) + L(\vec{r}(t)) \frac{d}{dt} f(x(t), y(t)) \right] dt$$

$$= \int_a^b [Mx' + Ny' + L(f_x x' + f_y y')] dt$$

$$= \int_a^b [(M + Lf_x)x' + (N + Lf_y)y'] dt$$

$$= \oint_{C'} (M + Lf_x) dx + (N + Lf_y) dy$$

Then by Green's Thm

$$\oint_C \vec{F} \cdot d\vec{r} = \oint_{C'} (M + Lf_x) dx + (N + Lf_y) dy$$

$$= \iint_R \left[\frac{\partial}{\partial x} (N + Lf_y) - \frac{\partial}{\partial y} (M + Lf_x) \right] dA$$

$$= \iint_R \left\{ \begin{aligned} & \left. \frac{\partial}{\partial x} [N(x, y, f(x, y)) + L(x, y, f(x, y)) f_y(x, y)] \right\} dA \\ & - \left. \frac{\partial}{\partial y} [M(x, y, f(x, y)) + L(x, y, f(x, y)) f_x(x, y)] \right\} dA \end{aligned} \right.$$

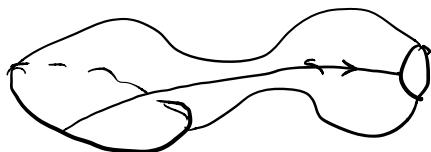
$$= \iint_R \left[\begin{aligned} & (N_x + N_z f_x) + (L_x + L_z f_x) \underline{f_y} + L \cancel{f_y x} \\ & - [M_y + M_z f_y] + (L_y + L_z f_y) \underline{f_x} + L \cancel{f_x y} \end{aligned} \right] dA$$

$$= \iint_R [-f_x(L_y - N_z) - f_y(M_z - L_x) + (N_x - M_y)] dA$$

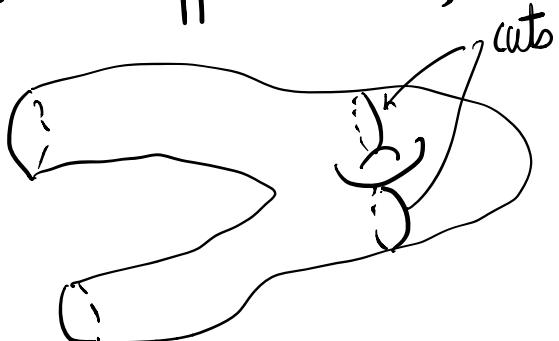
$$= \iint_S (\vec{\nabla} \times \vec{F}) \cdot \hat{n} d\sigma. \quad \text{This proves the case of } C^2 \text{ graph.}$$

General case: Divides S into finitely many pieces which are graphs (in certain projection).

[This includes S with many boundary components as in the Green's Thm]

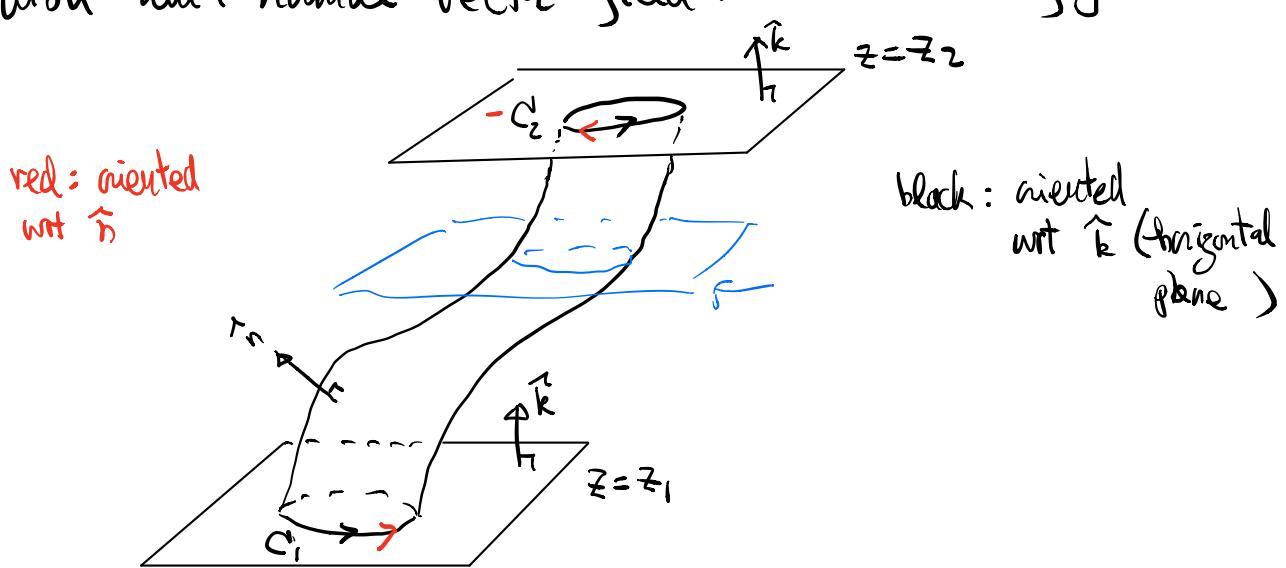


Note: Stokes' Thm applies to surfaces like the following



eg 63: Let \vec{F} be a vector field such that $\vec{\nabla} \times \vec{F} = 0$

and defined on a region containing the surface S with unit normal vector field \hat{n} as in the figure:



The boundary C of S has 2 components C_1 and C_2 at the

level $z=z_1$ & $z=z_2$ respectively.

If both C_1, C_2 oriented anticlockwise with respect to the "horizontal planes".

Then when C oriented with respect to \hat{n} (the surface normal)

$$\text{we have } C = C_1 - C_2$$

And Stokes' Thm \Rightarrow

$$O = \iint_S (\vec{\nabla} \times \vec{F}) \cdot \hat{n} d\sigma = \oint_C \vec{F} \cdot d\vec{r}$$

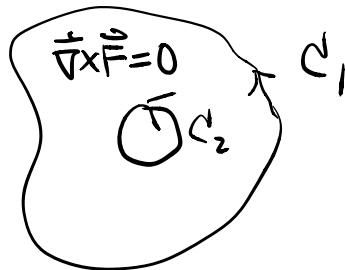
\swarrow oriented wrt \hat{n} .

$$= \oint_{C_1} \vec{F} \cdot d\vec{r} - \oint_{C_2} \vec{F} \cdot d\vec{r}$$

$\swarrow \nearrow$
oriented wrt "horizontal plane"

$$\Rightarrow \oint_{C_1} \vec{F} \cdot d\vec{r} = \oint_{C_2} \vec{F} \cdot d\vec{r}$$

Compare this with Green's Thm on plane region with one hole :



$$\Rightarrow \oint_{C_1} \vec{F} \cdot d\vec{r} = \oint_{C_2} \vec{F} \cdot d\vec{r} \quad (\text{check!})$$

$\swarrow \nearrow$
anti-clockwise wrt "plane". (not see region as a surface).

Proof of Thm 10 (3-dim'l case)

Only the " \Leftarrow " part remains to be proved:

By assumption $\vec{F} = M\hat{i} + N\hat{j} + L\hat{k}$ satisfies the system of eqts in the cor. to the Thm 9, that is

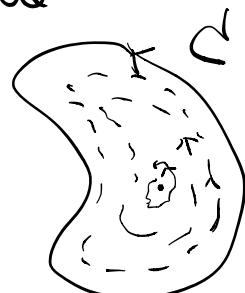
$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}, \quad \frac{\partial N}{\partial z} = \frac{\partial L}{\partial y}, \quad \text{and} \quad \frac{\partial L}{\partial x} = \frac{\partial M}{\partial z}.$$

Hence $\vec{\nabla} \times \vec{F} = 0$

let C be a simple closed curve in a simply-connected region D

Then C can be deformed to a point inside D

The process of deformation gives an
oriented surface $S \subset D$ such that



the boundary of $S = C$.

$$\begin{aligned} \text{By Stokes' Thm, } \oint_C \vec{F} \cdot d\vec{r} &= \iint_S (\vec{\nabla} \times \vec{F}) \cdot \hat{n} d\sigma \\ &= 0 \quad (\text{since } \vec{\nabla} \times \vec{F} = 0) \end{aligned}$$

Then Thm 9 $\Rightarrow \vec{F}$ is conservative. \times

Summary

$n = 2$

Tangential form of Green's Thm

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_R (\vec{\nabla} \times \vec{F}) \cdot \hat{k} dA$$

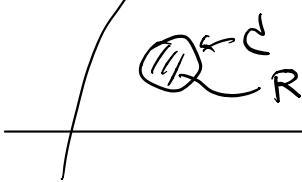
$n = 3$

Stokes' Thm

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S (\vec{\nabla} \times \vec{F}) \cdot \hat{n} d\sigma$$

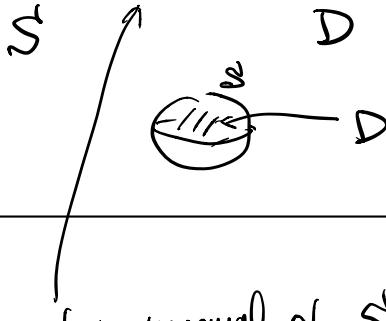
Normal form of Green's Thm

$$\oint_C \vec{F} \cdot \hat{n} ds = \iint_R \vec{\nabla} \cdot \vec{F} dA$$



Divergence Thm (next topic)

$$\iint_S \vec{F} \cdot \hat{n} d\sigma = \iiint_D \vec{\nabla} \cdot \vec{F} dv$$



"flux": by definition \hat{n} is the
"outward" normal of curve "C"
in the "plane".

surface normal of S , "outward"
pointing which can be defined
when S encloses a solid region D

Thm 13 (Divergence Theorem)

Let \vec{F} be a C^1 vector field on $\Omega \stackrel{\text{open}}{\subseteq} \mathbb{R}^3$ no boundary
 S be a piecewise smooth oriented closed surface
 enclosing a (solid) region $D \subseteq \Omega$.

Let \hat{n} be the outward pointing unit normal vector field on S .

Then

$$\iint_S \vec{F} \cdot \hat{n} d\sigma = \iiint_D \operatorname{div} \vec{F} dv = \iiint_D \vec{\nabla} \cdot \vec{F} dv$$

Eg 64 Verify Divergence Thm for

$$\vec{F} = x\hat{i} + y\hat{j} + z\hat{k}$$

$$S = \{x^2 + y^2 + z^2 = a^2\} \quad (a > 0)$$

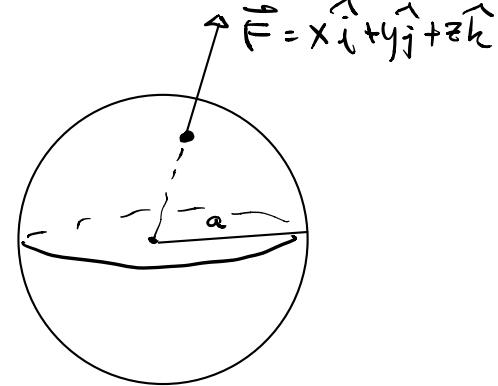
(sphere = S_a^2 2-dim'l sphere of radius a centered at $(0,0,0)$)

D = solid ball bounded by S .

Soln: At $(x, y, z) \in S$

$$\hat{n} = \frac{x\hat{i} + y\hat{j} + z\hat{k}}{\sqrt{x^2 + y^2 + z^2}} = \frac{1}{a}(x\hat{i} + y\hat{j} + z\hat{k}) \quad \text{is the outward pointing unit normal}$$

$$\iint_S \vec{F} \cdot \hat{n} d\sigma = \iint_S (x\hat{i} + y\hat{j} + z\hat{k}) \cdot \frac{1}{a}(x\hat{i} + y\hat{j} + z\hat{k}) d\sigma$$



$$= \iint_S a \, d\sigma = a \text{Area}(S) = 4\pi a^3 \quad (\text{check!})$$

On the other hand

$$\begin{aligned} \operatorname{div} \vec{F} &= \vec{\nabla} \cdot \vec{F} = \left(\hat{i} \frac{\partial}{\partial x} + \hat{j} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} \right) \cdot (\hat{x}i + \hat{y}j + \hat{z}k) \\ &= \frac{\partial x}{\partial x} + \frac{\partial y}{\partial y} + \frac{\partial z}{\partial z} = 3 \end{aligned}$$

$$\Rightarrow \iiint_D \operatorname{div} \vec{F} \, dV = \iiint_D 3 \, dV = 3 \operatorname{Vol}(D) = 3 \cdot \frac{4\pi a^3}{3} = 4\pi a^3$$

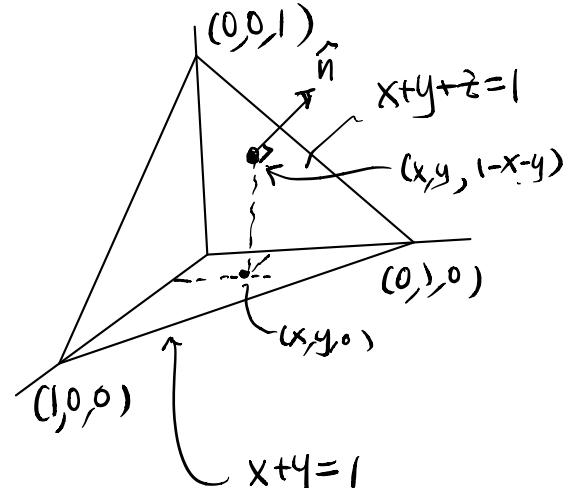
$$= \iint_S \vec{F} \cdot \hat{n} \, d\sigma \quad \times$$

eg65 $\vec{F} = x \sin y \hat{i} + (\cos y + z) \hat{j} + z^2 \hat{k}$

Compute outward flux of \vec{F} across
the boundary ∂T of

$$T = \left\{ (x, y, z) \in \mathbb{R}^3 : \begin{array}{l} x+y+z \leq 1 \\ x, y, z \geq 0 \end{array} \right\}$$

(tetrahedron)



$$\begin{aligned} \text{Soh: } \operatorname{div} \vec{F} &= \vec{\nabla} \cdot \vec{F} = \frac{\partial}{\partial x} (x \sin y) + \frac{\partial}{\partial y} (\cos y + z) + \frac{\partial}{\partial z} (z^2) \\ &= 2z \quad (\text{check!}) \end{aligned}$$

Divergence Thm

$$\Rightarrow \iint_{\partial T} \vec{F} \cdot \hat{n} \, d\sigma = \iiint_T \operatorname{div} \vec{F} \, dV$$

$$= \int_0^1 \int_0^{1-x} \int_0^{1-x-y} z \, dz \, dy \, dx$$

$$= \frac{1}{12} \text{ (check!)}$$

eg66: Let S_1, S_2 be 2 surfaces with common boundary curve C such that $S_1 \cup S_2$ forms a closed surface enclosing a solid region D (without hole)

Suppose \hat{n} is the outward normal of the solid region D . Then

the orientation of C with

respect to (S_1, \hat{n}) and (S_2, \hat{n}) are opposite (since " \hat{b} " pointing to opposite side)

Stokes' Thm \Rightarrow

$$\iint_{S_1} (\vec{\nabla} \times \vec{F}) \cdot \hat{n} \, d\sigma = \oint_C \vec{F} \cdot d\vec{r}$$

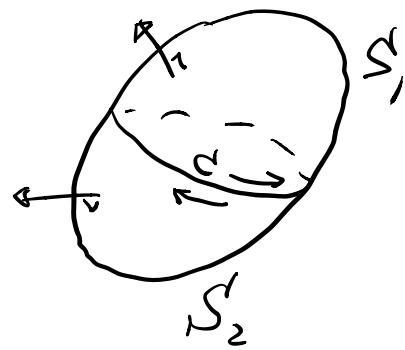
(← +ve oriented wrt (S_1, \hat{n}))

$$= - \oint_C \vec{F} \cdot d\vec{r}$$

(← +ve oriented wrt (S_2, \hat{n}))

$$= - \iint_{S_2} (\vec{\nabla} \times \vec{F}) \cdot \hat{n} \, d\sigma$$

$$\Rightarrow \iint_{S_1 \cup S_2} (\vec{\nabla} \times \vec{F}) \cdot \hat{n} \, d\sigma = 0 \quad \left(\text{see eg61(c) for explicit example} \right)$$



Divergence Thm \Rightarrow

$$\iiint_D \operatorname{div}(\vec{\nabla} \times \vec{F}) dV = \iint_{S_1 \cup S_2} (\vec{\nabla} \times \vec{F}) \cdot \hat{n} d\sigma = 0.$$

(true for "any" C^2 vector field \vec{F} defined on "any" D)

It is consistent with $\boxed{\vec{\nabla} \cdot (\vec{\nabla} \times \vec{F}) = 0} \quad | \text{ (Ex!)}$
A C^2 vector field

i.e. $\boxed{\operatorname{div}(\operatorname{curl} \vec{F}) = 0}$

Compare : $\boxed{\operatorname{curl}(\operatorname{grad} f) = 0 \Leftrightarrow \vec{\nabla} \times (\vec{\nabla} f) = 0}$