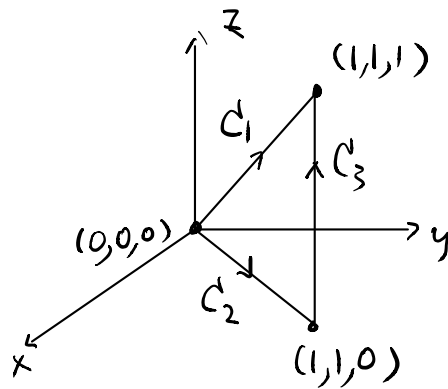


eg34: let $f(x,y,z) = x - 3y^2 + z$ (again)

C_1, C_2, C_3 are line segments as in the figure



We already did $\int_{C_1} f ds = 0$ (eg32)

One can similarly calculate

$$\begin{aligned} \int_{C_2 \cup C_3} f ds &= \int_{C_2} f ds + \int_{C_3} f ds \\ &= -\frac{\sqrt{2}}{2} - \frac{3}{2} \quad (\text{ex!}) \end{aligned}$$

(for instance $\int_{C_3} f ds = \int_0^1 (1 - 3(1)^2 + t) dt$)
(what parametrization?)

The observation is $\int_{C_1} f ds = 0 \neq \int_{C_2 \cup C_3} f ds$

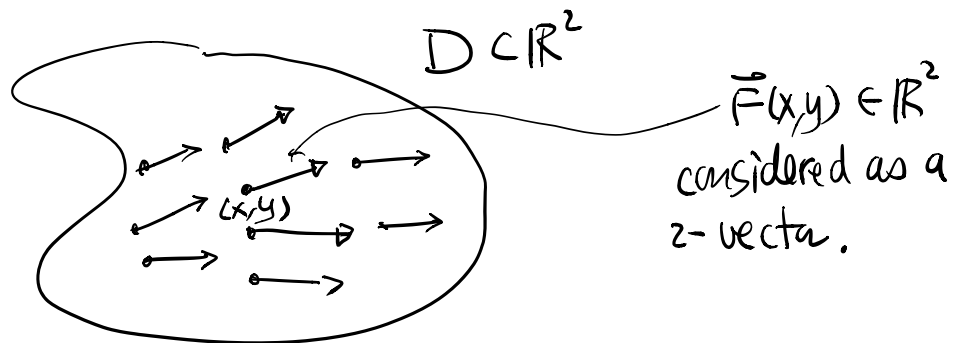
even C_1 & $C_2 \cup C_3$ have the same beginning and end points!

(Remark: different from 1-variable calculus)

Conclusion: Line integral of a function depends, not only on the end points, but also the path.

Vector Fields

Def 10 = Let $D \subset \mathbb{R}^2$ or \mathbb{R}^3 be a region, then a vector field on D is a mapping $\vec{F}: D \rightarrow \mathbb{R}^2$ or \mathbb{R}^3 respectively



In component form:

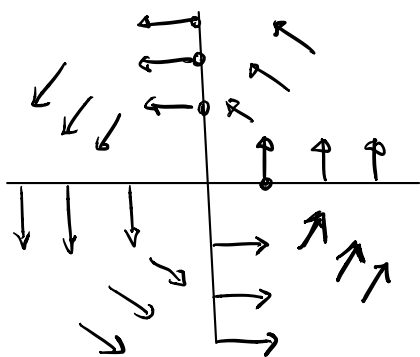
$$\mathbb{R}^2: \vec{F}(x, y) = M(x, y)\hat{i} + N(x, y)\hat{j}$$

$$\mathbb{R}^3: \vec{F}(x, y, z) = M(x, y, z)\hat{i} + N(x, y, z)\hat{j} + L(x, y, z)\hat{k}$$

where M, N, L are functions on D called the components of \vec{F} .

eg 35
$$\vec{F}(x, y) = \frac{-y\hat{i} + x\hat{j}}{\sqrt{x^2 + y^2}} \quad \text{on } \mathbb{R}^2 \setminus \{(0, 0)\}$$
$$= -\sin\theta\hat{i} + \cos\theta\hat{j} \quad (\text{in polar coordinates})$$

Properties of \vec{F}



(i) $|\vec{F}(x,y)| = 1$

(ii) $\vec{F} \perp \vec{r}(x,y) = x\hat{i} + y\hat{j}$
 $= r(\cos\theta\hat{i} + \sin\theta\hat{j})$

(Ex: sketch $\vec{F}(x,y) = x\hat{i} + y\hat{j}$)

*

eg36 (Gradient vector field of a function)

(i) $f(x,y) = \frac{1}{2}(x^2 + y^2)$

$$\vec{\nabla} f(x,y) \stackrel{\text{def}}{=} \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) = (x, y) = x\hat{i} + y\hat{j}$$

$$= \vec{r}(x,y) (= \vec{r})$$

(ii) $f(x,y,z) = x$

$$\vec{\nabla} f(x,y,z) \stackrel{\text{def}}{=} \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) = (1, 0, 0) = \hat{i}$$

eg37 (Vector field along a curve)

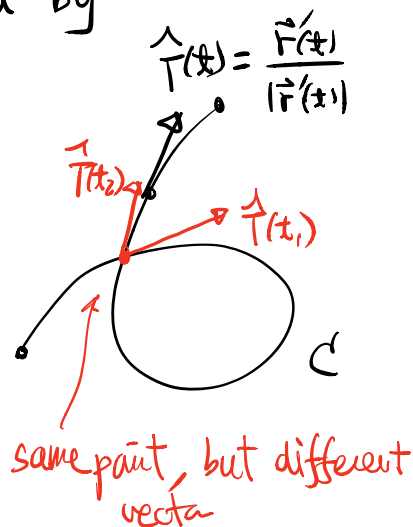
Let C be a curve in \mathbb{R}^2 parametrized by

$$\vec{r} : [a, b] \rightarrow \mathbb{R}^2$$

$$\downarrow \qquad \downarrow$$

$$t \mapsto (x(t), y(t)) = \vec{r}(t)$$

Recall: \hat{T} = unit tangent vector field along C

$$= \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$$


Note: this \hat{T} defined only on C (for a general curve),
but not outside C .

(vector field along a curve may not come from a vector field
on a region.)

Remark: for eg 37.

If we use $ds = |\vec{r}'(t)| dt$, then

$$\hat{T} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{\frac{d\vec{r}}{dt}}{\frac{ds}{dt}} = \frac{d\vec{r}}{ds} \quad \begin{array}{l} \text{(by Chain rule)} \\ \text{(if } s \text{ is a function)} \end{array}$$

where "arc-length s " is defined
(up to an additive constant) by

$$s(t) = \int_{t_0}^t |\vec{r}'(t)| dt,$$

A parametrization of a curve C by arc-length s
is called arc-length parametrization:

$\vec{r}(s) =$ arc-length parametrization

$$\Rightarrow \left| \frac{d\vec{r}}{ds}(s) \right| = 1$$

Def 11 A vector field is defined to be

continuous / differentiable / C^k if the component functions are.

eg 38 : $\vec{F}(x,y) = \vec{F}(x,y) = x\hat{i} + y\hat{j}$ is C^∞

$\vec{F}(x,y) = \frac{-y\hat{i} + x\hat{j}}{\sqrt{x^2+y^2}}$ is not continuous in \mathbb{R}^2
(but continuous in $\mathbb{R}^2 \setminus \{0,0\}$)

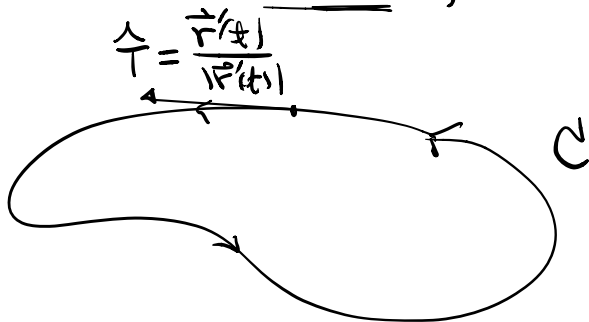
Line integral of vector field

Ref 12: Let C be a curve with "orientation" given by a parametrization $\vec{r}(t)$ with $\vec{r}'(t) \neq 0, \forall t$. Define the line integral of a vector field \vec{F} along C to be

$$\int_C \vec{F} \cdot \hat{T} ds$$

where $\hat{T} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$ is the unit tangent vector field along C .

i.e. C is oriented in the direction of $\vec{r}'(t)$ or \hat{T} at every point



Note: If $\vec{r}: [a, b] \rightarrow \mathbb{R}^n$ ($n=2$ or 3) then

$$\begin{aligned}\int_C \vec{F} \cdot \hat{T} ds &= \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{\vec{r}'(t)}{|\vec{r}'(t)|} \cdot |\vec{r}'(t)| dt \\ &= \int_a^b \vec{F}(\vec{r}(t)) \cdot \underbrace{\vec{r}'(t)}_{d\vec{r}} dt\end{aligned}$$

\therefore naturally, we denote $\boxed{d\vec{r} = \hat{T} ds}$

and $\boxed{\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r}}$

eg 38: $\vec{F}(x, y, z) = z\hat{i} + xy\hat{j} - y^2\hat{k}$

$$C: \vec{r}(t) = t^2\hat{i} + t\hat{j} + \sqrt{t}\hat{k}, \quad 0 \leq t \leq 1$$

Then $d\vec{r} = (2t\hat{i} + \hat{j} + \frac{1}{2\sqrt{t}}\hat{k}) dt$

and
$$\begin{aligned}\int_C \vec{F} \cdot \hat{T} ds &= \int_C \vec{F} \cdot d\vec{r} \\ &= \int_C (z\hat{i} + xy\hat{j} - y^2\hat{k}) \cdot (2t\hat{i} + \hat{j} + \frac{1}{2\sqrt{t}}\hat{k}) dt \\ &= \int_0^1 (\sqrt{t}\hat{i} + (t^2)(t)\hat{j} - (t)^2\hat{k}) \cdot (2t\hat{i} + \hat{j} + \frac{1}{2\sqrt{t}}\hat{k}) dt \\ &= \int_0^1 (2t\sqrt{t} + t^3 - \frac{t^{\frac{3}{2}}}{2}) dt = \frac{17}{20} \quad (\text{check!})\end{aligned}$$

~~*~~

In components form:

Line integral of $\vec{F} = M\hat{i} + N\hat{j}$ along

$$C: \vec{r}(t) = g(t)\hat{i} + h(t)\hat{j}$$

can be expressed as

$$\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_a^b \left(\vec{F} \cdot \frac{d\vec{r}}{dt} \right) dt$$

$$= \int_a^b (Mg' + Nh') dt$$

$$\left(\text{more explicitly: } \int_a^b [M(g(t), h(t))g'(t) + N(g(t), h(t))h'(t)] dt \right)$$

Note that, $\begin{cases} x = g(t) \\ y = h(t) \end{cases}$

$$\Rightarrow \begin{cases} dx = g'(t) dt \\ dy = h'(t) dt \end{cases}$$

$$\therefore \int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_a^b M dx + N dy$$

Similarly, for 3-dim

$$\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_a^b M dx + N dy + L dz$$

$$\left(\text{for } \vec{F} = M\hat{i} + N\hat{j} + L\hat{k} \right)$$

Another way to justify the notation:

$$\vec{r} = (x, y, z) \quad \text{the position vector}$$

$$\Rightarrow \boxed{d\vec{r} = (dx, dy, dz)} \quad (\text{naturally notation})$$

$$\begin{aligned} \text{Then } \int_C \vec{F} \cdot \hat{T} ds &= \int_C \vec{F} \cdot d\vec{r} = \int_C (M, N, L) \cdot (dx, dy, dz) \\ &= \int_C M dx + N dy + L dz. \end{aligned}$$

eg 39: Evaluate $I = \int_C -y dx + z dy + 2x dz$

where $C: \vec{r}(t) = \cos t \hat{i} + \sin t \hat{j} + t \hat{k} \quad (0 \leq t \leq 2\pi)$
 $= (\cos t, \sin t, t)$

Soln: $d\vec{r} = (-\sin t, \cos t, 1) dt$

$$\begin{aligned} \Rightarrow I &= \int_0^{2\pi} [(-\sin t)(-\sin t) + t \cos t + 2(\cos t)(1)] dt \\ &= \dots = \pi \quad (\text{check!}) \quad \times \times \end{aligned}$$

Physics

(1) \vec{F} = Force field

C = oriented curve

then

$$W = \int_C \vec{F} \cdot \hat{T} ds$$

is the workdone in moving an object along C .

(2) \vec{F} = velocity vector field of fluid

C = oriented curve

Then

$$\text{Flow} = \int_C \vec{F} \cdot \hat{T} ds$$



Flow along the curve C .

If C is "closed", the flow is also called a circulation.

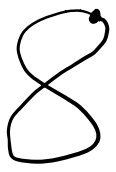

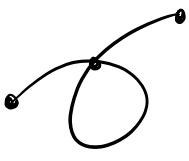
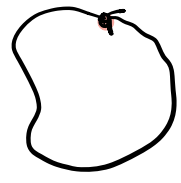
Def 13 = A curve is said to be

(i) simple if it does not intersect with itself except possibly at end points.

(ii) closed if starting point = end point.

(iii) simple closed curve if it is both simple and closed.

Note:

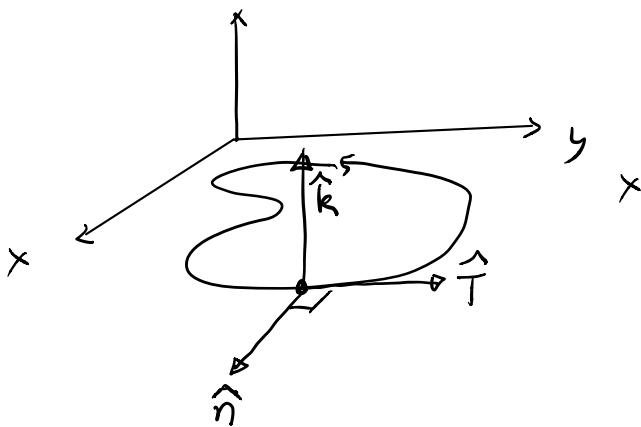
				
simple	NO	Yes	NO	Yes
closed	Yes	NO	NO	Yes

(3) \vec{F} = velocity of fluid

C = oriented plane curve ($C \subset \mathbb{R}^2$)

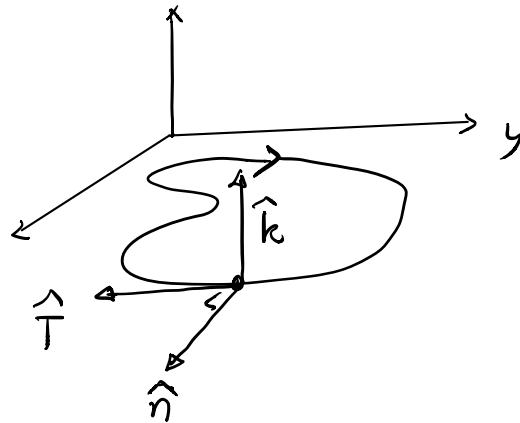
with parametrization $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j}$

\hat{n} = outward-pointing unit normal (vector) to the curve C



$$\hat{n} = \hat{T} \times \hat{k}$$

if C is of anti-clockwise orientation



$$\hat{n} = -\hat{T} \times \hat{k}$$

if C is of clockwise orientation.

Formula for \hat{n} (wrt the parametrization $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}$)

$$\text{Recall } \hat{T} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{x'(t)\hat{i} + y'(t)\hat{j}}{|\vec{r}'(t)|}$$

$$\left(\text{in arc-length parametrization } = \hat{T} = \frac{d\vec{r}}{ds} = \frac{dx}{ds}\hat{i} + \frac{dy}{ds}\hat{j} \right)$$

Anti-clockwise:

$$\hat{n} = \hat{T} \times \hat{k} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{x'}{|\vec{r}'|} & \frac{y'}{|\vec{r}'|} & 0 \\ 0 & 0 & 1 \end{vmatrix}$$

$$\Rightarrow \hat{n} = \frac{y'(t)\hat{i} - x'(t)\hat{j}}{|\vec{r}'(t)|} \quad \left(\text{or } \hat{n} = \frac{dy}{ds}\hat{i} - \frac{dx}{ds}\hat{j} \right)$$

Clockwise:

$$\hat{n} = \frac{-y'(t)\hat{i} + x'(t)\hat{j}}{|\vec{r}'(t)|} \quad \left(\text{or } \hat{n} = -\frac{dy}{ds}\hat{i} + \frac{dx}{ds}\hat{j} \right)$$

Flux of \vec{F} across C def $\int_C \vec{F} \cdot \hat{n} ds$

) (amount of fluid getting out of the closed curve C)

$$\text{If } \vec{F} = M(x,y)\hat{i} + N(x,y)\hat{j}$$

$$\text{and } \vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}$$

is anti-clockwise parametrization of C (closed curve)

Then

Flux of \vec{F} across C

$$= \oint_C (M\hat{i} + N\hat{j}) \cdot \left(\frac{dy}{ds}\hat{i} - \frac{dx}{ds}\hat{j} \right) ds$$

$$= \oint_C M dy - N dx$$

- Remark:
- \oint : curve is closed & in anti-clockwise direction
 - \oint = curve is closed & in clockwise direction
(not a common notation)
 - But in some books, only " \oint " is used, NO arrow,
Then one needs to determine the orientation from
the context.
 - Convention : If no orientation is mentioned,
" \oint " without arrow means anti-clockwise
orientation (positive orientation)