

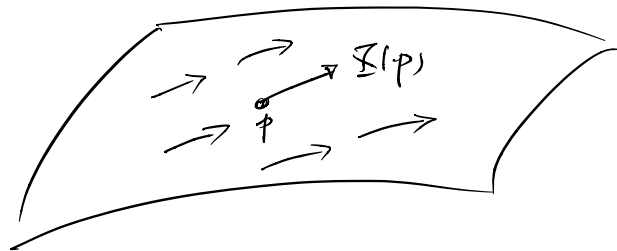
Def: A (smooth) vector field \mathbb{X} on a manifold M is a smooth section of the tangent bundle TM ,

i.e. $\mathbb{X}: M \rightarrow TM$ is a smooth map s.t.

$$\mathbb{X}(p) \in T_p M$$

i.e. $\pi \circ \mathbb{X} = \text{Id}_M$

$$\begin{array}{ccc} & TM & \\ \mathbb{X} \uparrow & & \downarrow \pi \\ & M & \end{array}$$

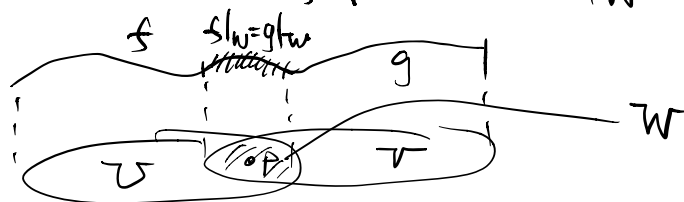


1.5 Tangent vectors as derivations

Let M be a smooth manifold, $p \in M$, consider C^∞ functions defined in a nbd. of p . Then we can define an equivalence relation (Ex!)

$$f: U \rightarrow \mathbb{R} \sim g: V \rightarrow \mathbb{R} \quad (p \in U \cap V)$$

$$\Leftrightarrow \exists \text{ nbd } W \subset U \cap V \text{ of } p \text{ s.t. } f|_W = g|_W$$



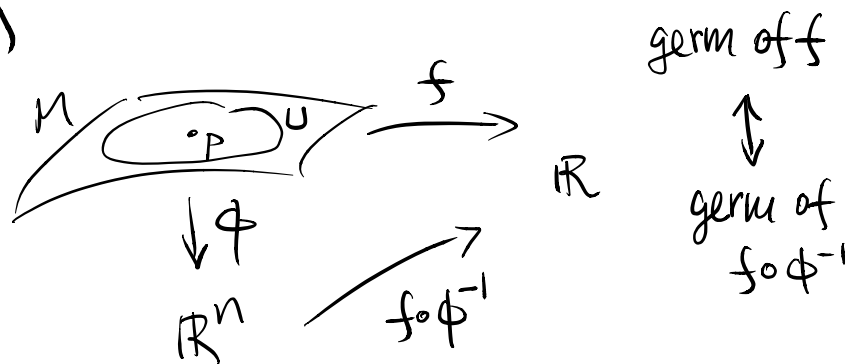
Def: The equivalence classes for this relation are the germs of C^∞ functions at p . The space of germs of C^∞ functions at p is denoted by $\mathcal{E}_p^\infty(M)$.

Similarly, we can define $\mathcal{E}_p^0(M)$, $\mathcal{E}_p^k(M) \approx \mathcal{E}_p^\omega(M)$ germs of continuous, C^k , and (real) analytic functions resp. at p .

Remark: • Space of functions has linear structure (and a product structure)
 \Rightarrow corresponding space of germs is a vector space (with a product structure)

- If M is a C^k manifold ($0 \leq k \leq \infty$), then
 $\mathcal{E}_p^k(M) \cong \mathcal{E}_0^k(\mathbb{R}^n)$ (vector space isomorphism)

Pf (Sketch)



Def: A derivation on $\mathcal{C}_p^k(M)$ is a linear map

$$\delta: \mathcal{C}_p^k(M) \rightarrow \mathbb{R} \text{ such that } \forall f, g \in \mathcal{C}_p^k(M)$$

$$\delta(fg) = f(p)\delta(g) + g(p)\delta(f),$$

where $fg =$ product of the germs f & g
(Ex: How to define fg ?)

Notation: We denote the set of derivations on $\mathcal{C}_p^k(M)$
by $\mathcal{D}_p^k(M)$, or $\mathcal{D}_p(M)$ if k is clear.

Thm: Any derivation of $\mathcal{C}_0^\infty(\mathbb{R}^n)$ can be written as

$$\delta(f) = \sum_{j=1}^n \delta(x^j) \frac{\partial f}{\partial x^j}(0)$$

germ \nearrow $\delta(x^j)$ \nwarrow germ of the coordinate function x^j .
is a function representing the germ f .

Hence $\dim(\mathcal{D}_0^\infty(\mathbb{R}^n)) = n$.

PF: \forall germ $f \in \mathcal{C}_0^\infty(\mathbb{R})$, f is represented by a C^∞ function, denoted by f again, in a nbd. of 0.

$$\text{Then } f(x) - f(0) = \int_0^1 \frac{d}{dt} f(tx) dt$$

$$= \int_0^1 \sum_{j=1}^n \frac{\partial f}{\partial x^j}(tx) x^j dt$$

$$= \sum_{j=1}^n x^j h_j(x)$$

where $h_j(x) = \int_0^1 \frac{\partial f}{\partial x^j}(tx) dt$ is C^∞

Then $\delta(f) = \delta(f - f(0))$, since $\delta(\text{const.}) = 0$ (Ex!)

$$= \delta\left(\sum_{j=1}^n x^j h_j(x)\right)$$

$$= \sum_{j=1}^n \left[\delta(x^j) h_j(0) + \cancel{(x^j|_0)} \delta(h_j) \right]$$

$$= \sum_{j=1}^n \delta(x^j) \frac{\partial f}{\partial x^j}(0) \quad \#$$

Lemma: $\forall \xi \in T_p M$, $L_\xi(f) \stackrel{\text{def}}{=} (D_p f)(\xi)$, $\forall f \in C_p^\infty(M)$
 Then $L_\xi \in \mathcal{D}_p(M)$.

(where $D_p f$ is the differential of a representation of f defined similarly as in Diff. Geom using defn 1 of vector)

(Pf = Ex!)

Thm: $T_p M \xrightarrow{\psi} \mathcal{D}_p(M)$ is an isomorphism
 $\xi \mapsto L_\xi$ (as vector spaces)

Pf: • $\xi \mapsto L_\xi$ is clearly linear.

• $\text{Ker}(\xi \mapsto L_\xi) = 0$

Pf: Let (U, ϕ) be a chart for M around p with $\phi(p) = 0 \in \mathbb{R}^n$. Then ξ can be

represented by $\xi = (U, \phi, u)$ with $u \in T_0 \mathbb{R}^n \cong \mathbb{R}^n$.

$\Rightarrow \forall C^\infty$ function f in a nbd. around p

$$L_\xi(f) = D_0(f \circ \phi^{-1})(u) \quad (\text{Ex!})$$

$$= \sum_{j=1}^n u^j \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(0)$$

where $u = (u^1, \dots, u^n)$

If $\xi \in \text{Ker}(\xi \mapsto L_\xi)$, then $\forall f$

$$0 = \sum_{j=1}^n u^j \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(0)$$

$$\Rightarrow u^j = 0, \forall j \Rightarrow \xi = 0 \quad \cdot \times$$

• Finally $\text{Im}(\xi \mapsto L_\xi) = \mathcal{D}_p(M)$

Pf: $\forall \delta \in \mathcal{D}_p(M) \cong \mathcal{D}_0(\mathbb{R}^n)$,

By previous thm \Rightarrow

$$\delta(f) = \sum_{j=1}^n \delta(x^j) \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(0)$$

$$\therefore \delta = L_{\xi} \text{ for } \xi = \left[(U, \phi, \begin{pmatrix} \delta(x^1) \\ \vdots \\ \delta(x^n) \end{pmatrix}) \right] \in T_p M. \quad \#$$

Remark: In particular, we have $\dim T_p M = n$
with basis corresponds to $\left\{ \frac{\partial}{\partial x^j} \Big|_0 \right\}$ in local
coordinates.

$$\left(\text{where } \frac{\partial}{\partial x^j} \Big|_0 \in \mathcal{D}_0(\mathbb{R}^n) \text{ s.t. } \begin{pmatrix} \delta(x^1) \\ \vdots \\ \delta(x^n) \end{pmatrix} = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \end{pmatrix} \leftarrow \begin{matrix} j\text{th} \\ \text{place} \end{matrix} \right)$$

Convention: If (U, ϕ) is a chart around p , and
 (x^1, \dots, x^n) are the corresponding coordinate functions

$$x^j = U \xrightarrow{\phi} \mathbb{R}^n \xrightarrow{\pi_j} \mathbb{R}$$

We denote

$$\left(\frac{\partial}{\partial x^j} \right)_p (f) \stackrel{\text{def}}{=} \frac{\partial}{\partial x^j} (f \circ \phi^{-1})(\phi(p))$$

In this notation

$$L_{\xi} = \sum_{j=1}^n u^j \left(\frac{\partial}{\partial x^j} \right)_p \text{ for } \xi = \left[(U, \phi, u) \right] \in T_p M.$$

Hence $\left(\frac{\partial}{\partial x^j}\right)_p$ can be regarded as a vector in $T_p M$

$\Rightarrow \frac{\partial}{\partial x^j}$ is a vector field on $U \subset M$.

If X^1, \dots, X^n are smooth functions, then

$$X = \sum_{j=1}^n X^j \frac{\partial}{\partial x^j} \text{ is a vector field on } U$$

corresponding to

$$L_X: C^\infty(U) \rightarrow C^\infty(U) \text{ defined by}$$

$$\boxed{(L_X f)(p) = \sum_{j=1}^n X^j(p) \left(\frac{\partial f}{\partial x^j}\right)_p.}$$

Thm: The map $X \mapsto L_X$ is an isomorphism between the vector spaces $\Gamma(TM)$ = set of smooth vector fields on M and $\mathfrak{D}(M)$, where $\mathfrak{D}(M)$ = set of derivations δ on M defined by

(i) $\delta: C^\infty(M) \rightarrow C^\infty(M)$ linear;

(ii) $\delta(fg) = f\delta(g) + g\delta(f)$.

(Pf: Omitted)

(Caution: Analog statement for complex manifold is not true, since cut-off functions are needed.)

Note: If $\delta_1, \delta_2 \in \mathcal{D}(M)$, then $\delta_1 \circ \delta_2 \notin \mathcal{D}(M)$

Lemma: If $\delta_1, \delta_2 \in \mathcal{D}(M)$, then

$$\delta_1 \circ \delta_2 - \delta_2 \circ \delta_1 \in \mathcal{D}(M)$$

(Pf: Ex!)

Def: Let X, Y be vector fields on M . Then $[X, Y]$, the bracket of X and Y , is a vector field corresponding to the derivation $L_X \circ L_Y - L_Y \circ L_X$.

i.e.

$$L_{[X, Y]} = L_X \circ L_Y - L_Y \circ L_X$$

Local formula for $[X, Y]$

If $X = \sum_{i=1}^n X^i \frac{\partial}{\partial x^i}$, $Y = \sum_{j=1}^n Y^j \frac{\partial}{\partial x^j}$ in some local coordinates

then
$$L_X f = \sum_i X^i \frac{\partial f}{\partial x^i}$$

$$\Rightarrow L_Y(L_X f) = \sum_{j,i} \left[Y^j X^i \frac{\partial^2 f}{\partial x^j \partial x^i} + Y^j \frac{\partial X^i}{\partial x^j} \frac{\partial f}{\partial x^i} \right]$$

Similarly for $L_X(L_Y f)$

$$\Rightarrow (L_X L_Y - L_Y L_X) f = \sum_{i,j} \left(X^j \frac{\partial Y^i}{\partial x^j} - Y^j \frac{\partial X^i}{\partial x^j} \right) \frac{\partial f}{\partial x^i}$$

$$\Rightarrow \boxed{\begin{aligned} [X, Y] &= \sum_i Z^i \frac{\partial}{\partial x^i} \\ \text{where } Z^i &= \sum_j (X^j \frac{\partial Y^i}{\partial x^j} - Y^j \frac{\partial X^i}{\partial x^j}) \end{aligned}}$$

Lemma (Jacobi Identity) For vector fields X, Y, Z ,

$$[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$$

(Pf: Trivial)

1.6 Vector Bundles and Tensors

Def: Let E & B be 2 smooth manifolds and

$\pi: E \rightarrow B$ be a smooth map.

(π, E, B) is a vector bundle of rank n if

- π is surjective

- \exists open covering $(U_i)_{i \in \Lambda}$ of B and

diffeomorphisms $h_i: \pi^{-1}(U_i) \rightarrow U_i \times \mathbb{R}^n$ such that

$$\forall x \in U_i, h_i(\pi^{-1}(x)) = \{x\} \times \mathbb{R}^n$$

(hence $\pi^{-1}(x)$ can be regarded as a vector space)

- and such that $\forall i, j \in \Lambda$, the diffeomorphisms

$$h_i \circ h_j^{-1} : (U_i \cap U_j) \times \mathbb{R}^n \rightarrow (U_i \cap U_j) \times \mathbb{R}^n$$

are of the form

$$h_i \circ h_j^{-1}(x, v) = (x, g_{ij}(x)v)$$

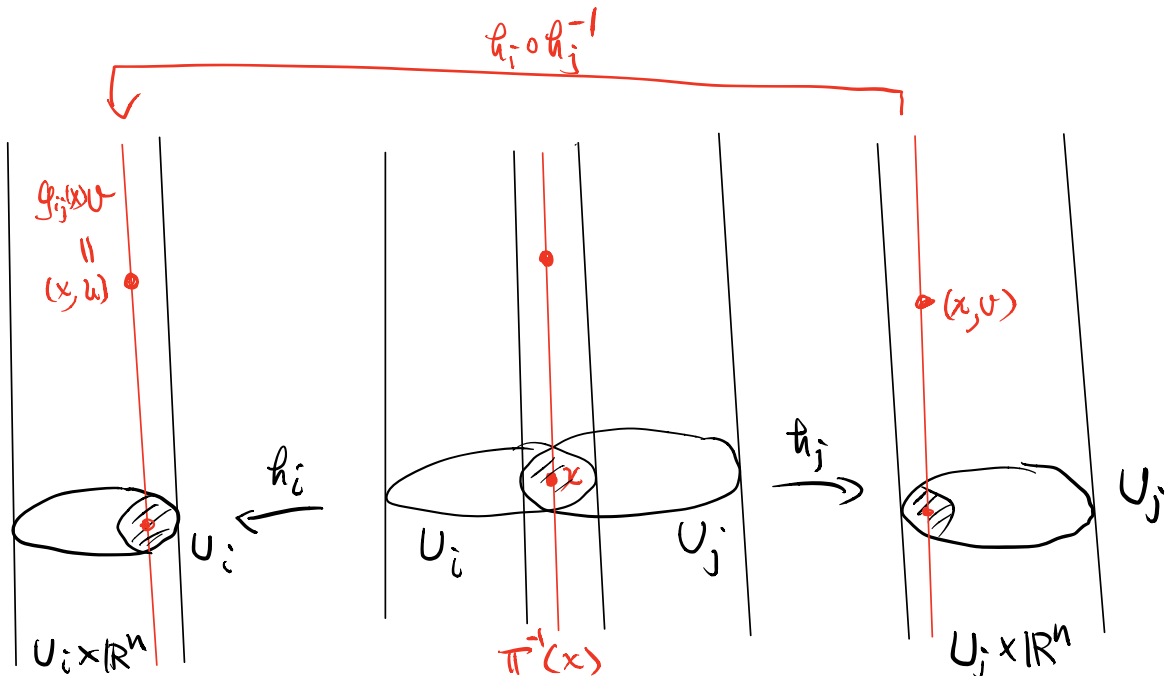
where $g_{ij} : U_i \cap U_j \rightarrow GL(n, \mathbb{R})$.

Terminology: $E = \text{total space}$

$B = \text{base}$

$\mathbb{R}^n \simeq \pi^{-1}(x) = \text{fibre}$

$h_i = \text{local trivialization}$



eg: (Trivial Bundle) : $\pi = M \times \mathbb{R}^n \rightarrow M$
 $(x, v) \mapsto x$

eg Tangent bundle of M : $TM = \coprod_{p \in M} T_p M$
 (exercise)

Def: (a) A vector bundle of rank n , $\pi: E \rightarrow B$, is trivial if \exists diffeomorphism

$$h: E \rightarrow B \times \mathbb{R}^n$$

st. $h|_{\pi^{-1}(x)} \rightarrow \{x\} \times \mathbb{R}^n$ is a vector isomorphism.

(b) A (global) section of the bundle is a smooth map

$$s: B \rightarrow E \text{ such that}$$

$$\pi \circ s = \text{id}_B$$

$$\begin{array}{c} E \\ \pi \downarrow \uparrow s \\ B \end{array}$$

eg: vector field $X \in \Gamma(M) (= \Gamma(TM))$ is a section of the tangent bundle TM .

Tensor Product

Def: Let E, F be 2 finite dimensional vector spaces, then $E \otimes F$, the tensor product of E & F , is defined as the vector space, unique up to isomorphism, such that \forall vector space G ,

$$L(E \otimes F, G) \stackrel{\text{isom}}{\cong} L_2(E \times F, G)$$

$$\left(\begin{array}{l} \text{linear transformations} \\ \text{from } E \otimes F \text{ to } G \end{array} \right) \quad \left(\begin{array}{l} \text{bilinear maps from} \\ E \times F \text{ to } G \end{array} \right)$$

Remark: \exists a bilinear map $\otimes : E \times F \rightarrow E \otimes F$ such that if $\{e_i\}$ = basis for E , and $\{f_j\}$ = basis for F ,

then $\{e_i \otimes f_j\}_{i,j}$ is a basis for $E \otimes F$.

Hence for $u = \sum_i a_i e_i \in E$ & $v = \sum_j b_j f_j \in F$

$$\text{then } u \otimes v = \sum_{i,j} a_i b_j e_i \otimes f_j.$$

Facts: (1) If E^* = dual of $E = L(E, \mathbb{R})$

F^* = dual of F

$$\begin{aligned} \text{then } E^* \otimes F^* &\cong L_2(E \times F, \mathbb{R}) \\ &\cong L(E \otimes F, \mathbb{R}) = (E \otimes F)^* \\ \left(\text{by } \alpha \otimes \beta &\longmapsto \alpha \otimes \beta(u \otimes v) \right. \\ &\left. = \alpha(u) \beta(v) \right) \end{aligned}$$

(2) If $\alpha \in L(E, E')$ & $\beta \in L(F, F')$
 (E, E', F, F' = finite dim'd vector spaces)
 then one can define

$$\alpha \otimes \beta \in L(E \otimes F, E' \otimes F')$$

$$\text{by } (\alpha \otimes \beta)(u \otimes v) \stackrel{\text{def}}{=} \alpha(u) \otimes \beta(v)$$

(3) Given a vector bundle E (with fibers $E_x, x \in M$)
 one can define the vector bundle $E^*, \otimes^p E$
 (with fibers E_x^* and $\otimes^p E_x$ respectively)

(4) Given 2 vector bundles E, F (with fibers E_x, F_x)
 with the same base manifold M , we can define
 the vector bundle $E \otimes F$ over M with fiber $E_x \otimes F_x$.

eg: Starting from TM , we can define the cotangent bundle
 T^*M of M (with fibers $(T_p M)^*$), and the

(p,q)-tensor bundle $(\otimes^p TM) \otimes (\otimes^q T^*M)$ of M .

Def: A (p,q)-tensor (field), or more precisely p times contravariant and q times covariant tensor, on M is a (smooth) section of the bundle $(\otimes^p TM) \otimes (\otimes^q T^*M)$.

Note: For $f: M \rightarrow \mathbb{R}$ smooth, we can define

$$df \in \Gamma(T^*M) = df(X) = L_X f = Xf \\ \forall X \in \Gamma(TM).$$

Then $\{dx^j\}_{j=1}^n$ is a dual (local) basis to

$$\left\{ \frac{\partial}{\partial x^i} \right\}_{i=1}^n \quad \text{since} \quad dx^j \left(\frac{\partial}{\partial x^i} \right) = \frac{\partial x^j}{\partial x^i} = \delta_i^j.$$

at each point in a coordinate system with coordinate functions (x^1, \dots, x^n) .

Then $\left\{ \frac{\partial}{\partial x^{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{j_p}} \otimes dx^{i_1} \otimes \dots \otimes dx^{i_q} \right\}$

forms a local basis for $(\otimes^p TM) \otimes (\otimes^q T^*M)$

\Rightarrow in coordinates, a (p,q)-tensor (field) can be

written as

$$T = \sum_{\substack{j_1, \dots, j_p \\ i_1, \dots, i_g}} \frac{\partial}{\partial x^{j_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{j_p}} \otimes dx^{i_1} \otimes \dots \otimes dx^{i_g}$$

1.7 Partitions of Unity

Recall that all manifolds in this course are supposed to have the property that "partitions of unity" is always possible. That is,

$\forall \{U_i\}_{i \in \Lambda}$ = open cover of M ,

\exists locally finite open cover $\{V_k\}_{k \in \Lambda'}$ and a family $\{\varphi_k\}_{k \in \Lambda'}$ of real smooth functions on M such that

- $\{V_k\}_{k \in \Lambda'}$ is subordinate to $\{U_i\}_{i \in \Lambda}$
(i.e. each $V_k \subset U_i$ for some i)
- $\text{supp } \varphi_k \subset V_k$, $\varphi_k \geq 0$, and
$$\sum_{k \in \Lambda'} \varphi_k(x) = 1 \quad \forall x \in M$$

Here $\{V_k\}_{k \in \Lambda'}$ being locally finite means $\forall x \in M$,
 \exists open nbd W of x such that $W \cap V_k = \emptyset$ except for finitely many k 's.