

# MATH5061 - Riemannian Geometry I - 2015/16

Student C

Research

Communi

**Course Name:**  
Riemannian Geometry I

**Teacher:**  
Prof. Tom Yau Heng WAN

**Course Year:**  
2015-16

**Term:**  
2

## General Information

### Lecturer

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### Time and Venue

- Lecture: Monday 9:30-12:15pm; LSB222

## Course Description

This course is intended to provide a solid background in Riemannian Geometry. Topics include: affine connection, tensor calculus, Riemannian metric, geodesics, curvature tensor, completeness and some global theory. Students taking this course are expected to have knowledge in differential geometry of curves and surfaces.

## References

- S. Gallot, D. Hulin, J. Lafontaine, "Riemannian Geometry", 3rd Ed., Springer
- J. Jost, "Riemannian Geometry and Geometric Analysis", 2nd Ed., Springer
- I. Chavel, "Riemannian Geometry - A Modern Introduction", Cambridge
- 伍鴻熙, 沈純理, 虞言林, 《黎曼幾何初步》, 北京大學出版社

## Assessment Scheme

Final exam (Apr 25, 2016)

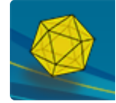
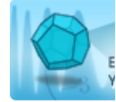
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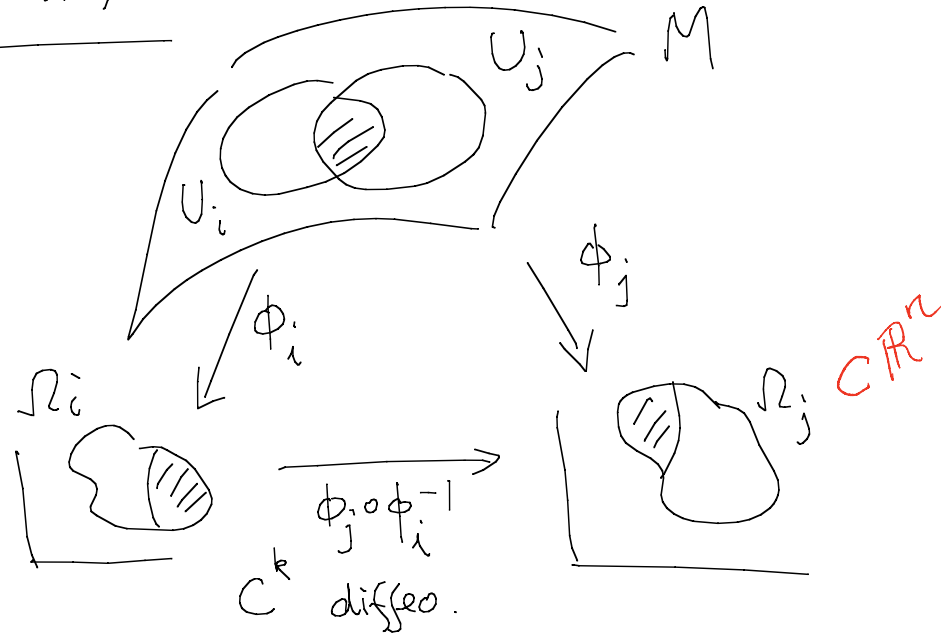
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and thereby help avoid any practice that would not be acceptable.



# Ch 1 Differentiable Manifolds

## 1.1 Abstract Manifolds



Def.: A  $C^k$  atlas on a Hausdorff topological space  $M$  is given by

- (1) an open covering  $\mathcal{U}_i$ ,  $i \in \Lambda$ , of  $M$ ;

(ii') a family of homeomorphisms

$$\phi_i = U_i \rightarrow \Omega_i \subset \mathbb{R}^n \quad (\Omega_i \text{ is open})$$

such that  $\forall i, j \in \Lambda$

$$\phi_j \circ \phi_i^{-1} : \phi_i(U_i \cap U_j) \rightarrow \phi_j(U_i \cap U_j)$$

is a  $C^k$  diffeomorphism.

Remark : •  $\phi_j \circ \phi_i^{-1}$ ,  $i, j \in \Lambda$  (with  $U_i \cap U_j \neq \emptyset$ ) are called transition functions.

•  $(U_i, \phi_i)$  is called a (coordinate) chart,

•  $\phi_i^{-1} : \Omega_i \rightarrow U_i \subset M$  is a local parametrization.

Def: Two  $C^k$  atlas for  $M$ , say  $(U_i, \phi_i)_{i \in \Lambda_1}$  and  $(V_j, \psi_j)_{j \in \Lambda_2}$ , are  $C^k$  equivalent if their union is still a  $C^k$  atlas, that is, if  $\forall i \in \Lambda_1, j \in \Lambda_2$  (st  $U_i \cap V_j \neq \emptyset$ )

$$\phi_i \circ \psi_j^{-1} : \psi_j(U_i \cap V_j) \rightarrow \phi_i(U_i \cap V_j)$$

are  $C^k$  diffeomorphisms.

Def: A differentiable structure of class  $C^k$  on  $M$  is an equivalence class of  $C^k$  atlas.

Remark: If  $M$  is connected, then the integer  $n$  in the definition does not depend on the chart and is defined as the dimension of  $M$ .

Def: A  $C^k$  differentiable manifold of dimension  $n$  is a pair  $(M, \mathcal{A})$ , where  $M$  is a Hausdorff top. space and  $\mathcal{A} = \{(U_i, \phi_i)\}_{i \in \Lambda}$  is a  $C^k$  atlas on  $M$  with  $\phi_i(U_i) \subset \mathbb{R}^n$ .

Remark: • In this course, we consider only  $C^\infty$  differentiable manifold which is connected and a further condition such that "partitions of unity" is always possible.

- All compact manifolds satisfy the further condition.
- We'll refer such a manifold as a smooth manifold (or even simply manifold.)

eg:  $M = T^n$ , the  $n$ -torus ( $T^n = \underbrace{S^1 \times \dots \times S^1}_n$ )

let  $f: \mathbb{R}^n \rightarrow T^n \in \mathbb{C}^n$   
 $\downarrow \quad \downarrow$  ( $f$  is onto)

$$(x_1, \dots, x_n) \mapsto (e^{ix_1}, \dots, e^{ix_n})$$

$\forall p \in T^n, \exists x^p = (x_1^p, \dots, x_n^p) \in \mathbb{R}^n$  s.t.

$$p = f(x^p) \quad (\text{one may choose } x_i^p \in [0, 2\pi), i=1, \dots, n)$$

Consider  $\Omega_p = (x_1^p - \pi, x_1^p + \pi) \times \dots \times (x_n^p - \pi, x_n^p + \pi) \subset \mathbb{R}^n$

and let  $\begin{cases} U_p = f(\Omega_p) \subset T^n & (U_p \text{ open \& contains } p) \\ \phi_p = (f|_{\Omega_p})^{-1}: U_p \rightarrow \Omega_p \subset \mathbb{R}^n & \text{homeo.} \end{cases}$

Then  $\{(\mathcal{U}_p, \phi_p)\}_{p \in T^n}$  is an  $C^\infty$  atlas on  $T^n$ .

In fact, if  $p, q \in T^n$  s.t.  $\mathcal{U}_p \cap \mathcal{U}_q \neq \emptyset$ ,

then  $\phi_q \circ \phi_p^{-1}(x_1, \dots, x_n) \quad ((x_1, \dots, x_n) \in \phi_p(\mathcal{U}_p \cap \mathcal{U}_q) \subset \Omega_p)$

$$= \phi_q(f(x_1, \dots, x_n))$$

$$= \phi_q(e^{ix_1}, \dots, e^{ix_n}) \quad ((e^{ix_1}, \dots, e^{ix_n}) \in \mathcal{U}_p \cap \mathcal{U}_q)$$

$$= (f|_{\Omega_q})^{-1}(e^{ix_1}, \dots, e^{ix_n})$$

$$= (x_1 + 2k_1\pi, \dots, x_n + 2k_n\pi) \quad \text{for some } k_1, \dots, k_n$$

s.t.  $x_i + 2k_i\pi \in (x_i - \pi, x_i + \pi)$

note that  $k_i$  are indep. of  $(x_1, \dots, x_n) \in \phi_p(\mathcal{U}_p \cap \mathcal{U}_q)$

hence  $\phi_q \circ \phi_p^{-1}$  is just a translation in  $\mathbb{R}^n$ .

Therefore  $\phi_g \circ \phi_p^{-1}$  is a  $C^\infty$  diffeo.

$\Rightarrow (T^n, \{(U_p, \phi_p)\}_{p \in T^n})$  is a smooth manifold.

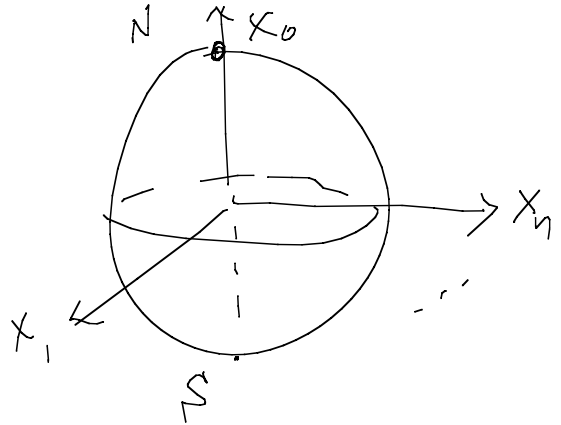
eg  $M = S^n$ , the  $n$ -sphere  $S^n = \{(x_0, x_1, \dots, x_n) \mid \sum_{j=0}^n x_j^2 = 1\} \subset \mathbb{R}^{n+1}$

$$\text{Let } \begin{cases} N = (1, 0, \dots, 0) \in S^n \\ S = (-1, 0, \dots, 0) \in S^n \end{cases}$$

$$\begin{cases} U_1 = S^n \setminus \{N\} \\ U_2 = S^n \setminus \{S\} \end{cases}$$

$$U_1 \cup U_2 = S^n$$

Let





$$\left\{ \begin{array}{l} \phi_1 = U_1 \rightarrow \mathbb{R}^n \quad (\text{Stereographic projections}) \\ \quad \downarrow \\ (x_0, x_1, \dots, x_n) \mapsto \frac{1}{1-x_0} (x_1, \dots, x_n) \\ \\ \phi_2 = U_2 \rightarrow \mathbb{R}^n \\ \quad \downarrow \\ (x_0, x_1, \dots, x_n) \mapsto \frac{1}{1+x_0} (x_1, \dots, x_n) \end{array} \right.$$

are homeomorphisms.

Note that if  $\phi_1(x_0, x_1, \dots, x_n) = (y_1, \dots, y_n)$

$$\text{then } \phi_1^{-1}(y_1, \dots, y_n) = \left( \frac{|y|^2 - 1}{|y|^2 + 1}, \frac{2y_1}{|y|^2 + 1}, \dots, \frac{2y_n}{|y|^2 + 1} \right)$$

If  $y \neq 0$

$$\phi_2 \circ \phi_1^{-1}(y_1, \dots, y_n) = \frac{1}{1 + \frac{|y|^2 - 1}{|y|^2 + 1}} \left( \frac{2y_1}{|y|^2 + 1}, \dots, \frac{2y_n}{|y|^2 + 1} \right)$$

$$= \frac{1}{|y|^2} (y_1, \dots, y_n)$$

In short

$$\left. \phi_2 \circ \phi_1^{-1}(y) = \frac{y}{|y|^2} \quad \forall y \in \mathbb{R}^n \setminus \{0\} \right\}$$

which is a  $C^\infty$  diffeomorphism

$\Rightarrow \mathcal{A} = \{(U_1, \phi_1), (U_2, \phi_2)\}$  is an atlas on  $S^n$ ,  
therefore  $(S^n, \mathcal{A})$  is a smooth manifold.

eg  $\mathbb{R}P^n$  the real projective space (in some book:  $P^n \mathbb{R}$ )

• As topological space

$\mathbb{R}P^n =$  quotient space of  $\mathbb{R}^{n+1} \setminus \{0\}$  by the equivalent relation:

$$x \sim y \iff \exists \lambda \neq 0 \in \mathbb{R} \text{ st. } x = \lambda y$$

$$(x, y \in \mathbb{R}^{n+1} \setminus \{0\})$$

$$= S^n / \{\pm \text{Id}\}$$

(since  $\mathbb{R}P^n$  is Hausdorff,  
compact, connected.)

- Let  $\pi: \mathbb{R}^{n+1} \setminus \{0\} \rightarrow \mathbb{R}P^n$  be the canonical projection map  
i.e.  $\pi(x) = \text{equi. class of } x$ .

Refine  $V_i = \{x = (x_0, x_1, \dots, x_n) \in \mathbb{R}^{n+1} : x_i \neq 0\}$

$$\Phi_i: V_i \rightarrow \mathbb{R}^n$$

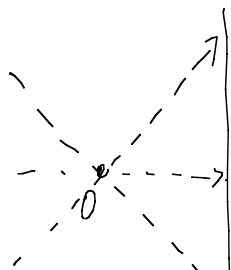
$$\Downarrow$$

$$x \mapsto$$

$$\Downarrow$$

$$\left( \frac{x_0}{x_i}, \dots, \frac{x_{i-1}}{x_i}, \dots, \frac{x_{i+1}}{x_i}, \dots, \frac{x_n}{x_i} \right)$$

this means the  
term deleted.



$$\{x_i = 1\} \cong \mathbb{R}^n$$

Then  $\forall x, y \in V_i$ , we have

$$(*) \quad \underline{\Phi}_i(x) = \underline{\Phi}_i(y) \iff \pi(x) = \pi(y) \text{ (ie. } x \sim y)$$

(check!)

This gives

$$\begin{array}{ccc}
 \mathbb{R}^{n+1} \supset V_i & \xrightarrow{\underline{\Phi}_i} & \mathbb{R}^n \\
 \pi \downarrow & \cong & \nearrow \phi_i \\
 U_i = \pi(V_i) & & 
 \end{array}$$

where  $\phi_i$  is defined by

$$\begin{array}{ccc}
 \phi_i : U_i = \pi(V_i) & \rightarrow & \mathbb{R}^n \\
 \downarrow & & \downarrow \\
 \text{eq. class of } x & \mapsto & \underline{\Phi}_i(x)
 \end{array}$$

( $\phi_i$  is well-defined because of  $(*)$ )

Using  $\pi$  :  $\phi_i(\pi(x)) = \underline{\Phi}_i(x) \quad \sim \quad \phi_i \circ \pi = \underline{\Phi}_i$

Further  $\phi_i = U_i \rightarrow \mathbb{R}^n$  is homeomorphism (Check)

with inverse

$$\phi_i^{-1}(y_0, \dots, y_{n-1}) = \pi(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1})$$

Therefore, if  $y_j \neq 0$ , for  $j < i$ , we have

$$\begin{aligned} (\phi_j \circ \phi_i^{-1})(y_0, \dots, y_{n-1}) &= \phi_j(\pi(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1})) \\ &= \bar{\phi}_j(y_0, \dots, y_j, \dots, 1, y_i, \dots, y_{n-1}) \\ &= \left( \frac{y_0}{y_j}, \dots, \frac{\hat{y}_j}{y_j}, \dots, \frac{1}{y_j}, \frac{y_i}{y_j}, \dots, \frac{y_{n-1}}{y_j} \right) \end{aligned}$$

$\therefore \phi_j \circ \phi_i^{-1} = \phi_i(U_i \cap U_j) \rightarrow \phi_j(U_i \cap U_j)$  is a  $C^\infty$  diffeo,

Hence  $\mathbb{R}P^n$  with the atlas  $\{(U_i, \phi_i)\}_{i=0}^n$  is a smooth manifold.

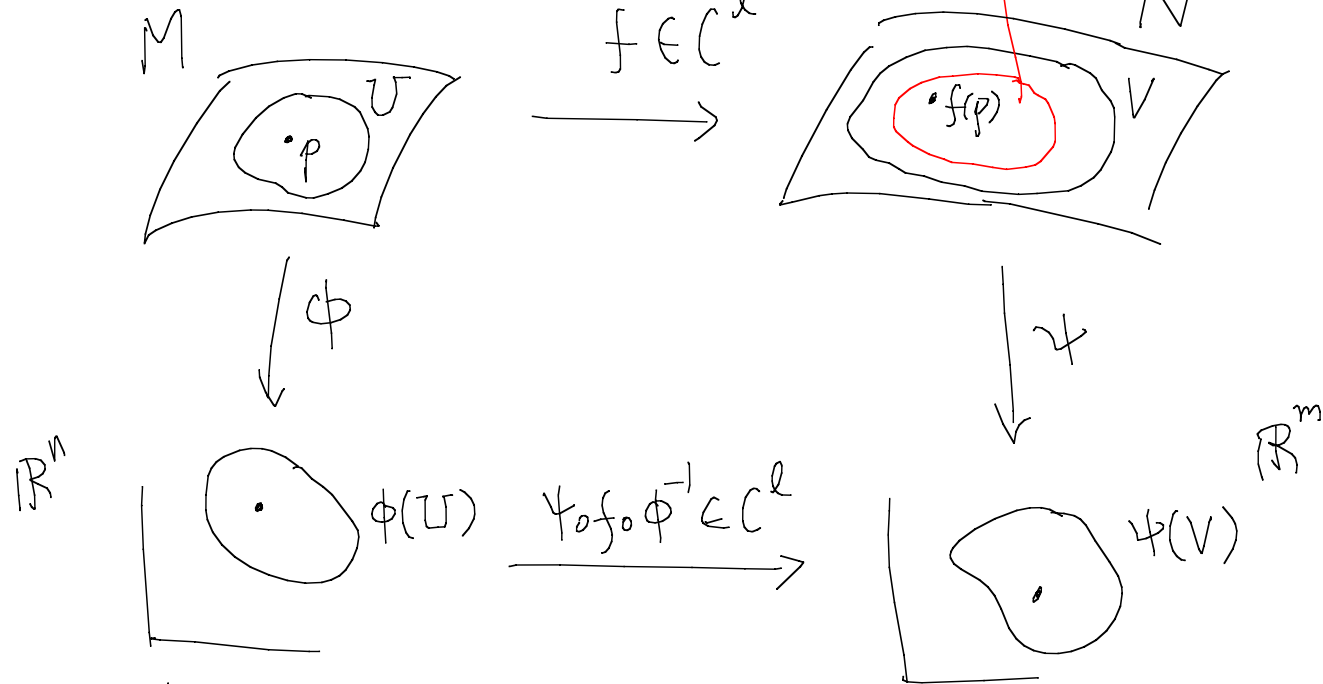
Note:  $\mathbb{R}P^n$  is non-orientable for  $n$  even according to the following definition: (proof omitted)

Def: A smooth manifold  $M$  is said to be orientable if  $\exists$  an atlas on  $M$  s.t.

$$J(\phi_j \circ \phi_i^{-1}) > 0 \quad \forall i, j$$

↑  
Jacobian determinant of  $\phi_j \circ \phi_i^{-1}$ .

## 1.2 Smooth Maps



( $\psi \circ f \circ \phi^{-1}$  is just  $m$  functions of  $n$  variables as in Calculus)

Def: Let  $M$  &  $N$  be  $C^k$  manifolds. A continuous map

$f: M \rightarrow N$  is  $C^l$  map (for  $l \leq k$ ) if

$\forall p \in M$ ,  $\exists$  charts  $(U, \phi)$  &  $(V, \psi)$  for  $M$  &  $N$   
around  $p$  &  $f(p)$  respectively with  $f(U) \subset V$

such that

$$\psi \circ f \circ \phi^{-1}: \phi(U) \rightarrow \psi(V) \text{ is } C^l$$

Note: This definition does not depend on the charts since  
transition functions are  $C^k$  ( $k \geq l$ ) (Ex!)

Def: A  $C^k$  map  $\gamma: (a, b) \rightarrow M$  from an interval to a  
smooth manifold is called a  $C^k$  curve (on  $M$ ).



Def: A  $C^k$  map  $f: M \rightarrow \mathbb{R}$  (or  $\mathbb{C}$ ) is called a  $C^k$  function on  $M$ .

Def: A smooth map  $g: \mathbb{R}^n \rightarrow \mathbb{R}^k$  is a submersion (an immersion, a local diffeomorphism) at  $x \in \mathbb{R}^n$  if  $D_x g: \mathbb{R}^n \rightarrow \mathbb{R}^k$  is surjective (injective, bijective)

Def: Let  $M$  &  $N$  be smooth manifolds. A smooth map  $f: M \rightarrow N$  is a submersion (immersion, local diffeomorphism) at  $p \in M$ , if  $\exists$  charts  $(U, \phi)$  for  $M$  around  $p$ ,  $(V, \psi)$  for  $N$  around  $f(p)$

with  $f(U) \subset V$  s.t.  $\psi \circ f \circ \phi^{-1}$  is a submersion  
(immersion, local diffeomorphism) at  $\phi(p) \in \phi(U) \subset \mathbb{R}^n$ .

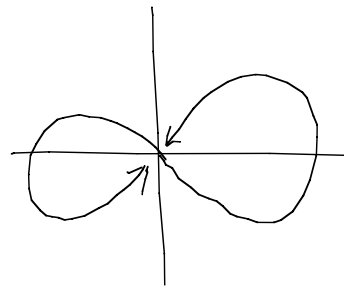
Def: A map  $f: M \rightarrow N$  is a submersion (immersion, local diffeomorphism)  
if it has the property at any point of  $M$ .

Def: A map  $f: M \rightarrow N$  is a diffeomorphism if it is a  
bijection such that both  $f$  and  $f^{-1}$  are smooth.

Def: A map  $f: M \rightarrow N$  is an embedding if it is an  
immersion and  $f: M \rightarrow f(M) \subset N$  (with subspace top)  
is a homeomorphism.

eg:  $\longrightarrow \mathbb{R} \xrightarrow{\gamma} \longrightarrow$

this is an immersion but  
not embedding (Ex)



### 1.3 Tangent vectors

Def 1: Let  $M$  be a smooth manifold and  $p \in M$ .

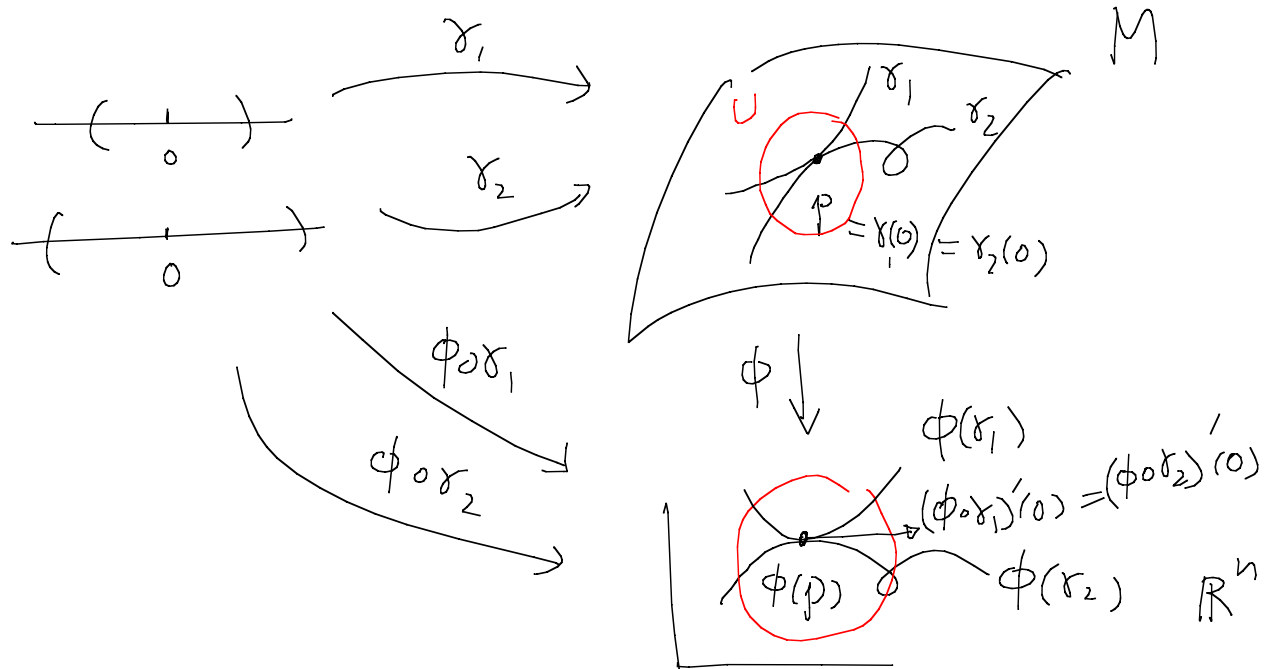
A tangent vector to  $M$  at  $p$  is an equi. class

of  $C^\infty$  curves  $\gamma: I \rightarrow M$ , where  $I =$  interval containing  $0$ ,

such that  $\gamma(0) = p$ , for the equi. relation defined

by  $\gamma_1 \sim \gamma_2 \Leftrightarrow$

$(\phi \circ \gamma_1)'(0) = (\phi \circ \gamma_2)'(0)$   
 for a chart  $(U, \phi)$  around  $p$ .



Ex: Check that the equi. relation is well-defined by showing that for any other chart  $(V, \psi)$  around  $p$ ,

we have

$$(\psi \circ \gamma)'(0) = D_{\phi(p)}(\psi \circ \phi^{-1}) \cdot (\phi \circ \gamma)'(0)$$

where  $D_{\phi(p)}(\psi \circ \phi^{-1})$  is the Jacobi matrix (a differential) of the map  $\psi \circ \phi^{-1}$  at  $\phi(p)$ .

Def 2 (Equivalent definition for tangent vectors)

Let  $M$  be a smooth manifold,  $p \in M$ .  $(U, \phi)$  &  $(V, \psi)$  be 2 coordinate charts for  $M$  around  $p$ . Let  $u, v$  be 2 vectors in  $\mathbb{R}^n$  (considered as tangent vectors to  $\mathbb{R}^n$  at  $\phi(p)$  &  $\psi(p)$  respectively) We say that

$$(U, \phi, u) \cong (V, \psi, v) \iff D_{\phi(p)}(\psi \circ \phi^{-1})u = v$$

Then a tangent vector to  $M$  at  $p$  is a equiv. class of triples  $(U, \phi, u)$ .

Note: • In def 1, a tangent vector is represented by a curve  $\gamma$ .  
We usually write  $\gamma'(0)$  for the tangent vector  $[\gamma]$  for simplicity (Independent of charts)

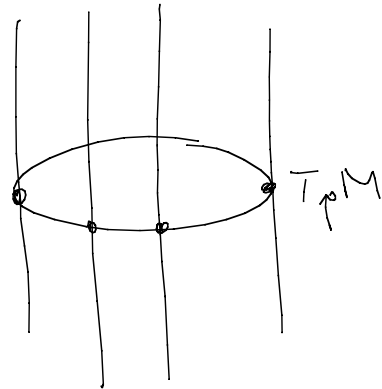
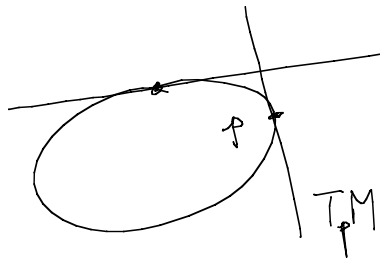
- In def 2, the "same" tangent vector will be represented in a chart  $(U, \phi)$  by a vector  $u \in \mathbb{R}^n$ .
- Def 1  $\Leftrightarrow$  Def 2 by taking  $u = (\phi \circ \gamma)'(0)$ .

Notation: The set of tangent vectors to  $M$  at  $p$  is denoted by  $T_p M$ . (Tangent space to  $M$  at  $p \in M$ ).

Note: If a chart  $(U, \phi)$  is given, then we have an "isomorphism"

$$\begin{array}{ccc} \theta_{U, \phi, p} : \mathbb{R}^n & \longrightarrow & T_p M \\ \downarrow & & \downarrow \\ u & \longmapsto & [(U, \phi, u)] \end{array} \quad (\text{check: 1-1, onto})$$

Def: The disjoint union  $\cup_{p \in M} T_p M$ ,  $\forall p \in M$ , is called the tangent bundle of  $M$ .

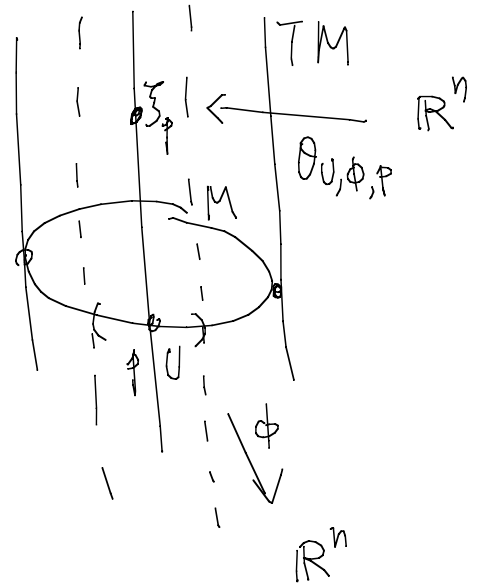


Thm: Let  $M$  be an  $n$ -dim.  $C^p$  manifold ( $p > 1$ ). Then  $TM$  can be equipped with a  $2n$ -dim'l  $C^{p-1}$  abstract manifold structure.

Pf: (Sketch)

For each chart  $(U, \phi)$  of  $M$ , define a "chart"

$$\left( \bigsqcup_{p \in U} T_p M, \underline{\Phi} \right) \text{ for } TM$$





by

$$\Phi(\xi_p) = (\phi(p), \theta_{U, \phi, p}^{-1}(\xi_p))$$
$$\in \mathbb{R}^n \times \mathbb{R}^n \cong \mathbb{R}^{2n}$$

$$\forall \xi_p \in T_p M, p \in U$$

Then one can see all these " $\coprod_{p \in U} T_p M$ " give a

topology on  $TM$  such that  $\Phi$  are homeomorphisms.

And one can check that  $TM$  is Hausdorff and

$\left\{ \left( \coprod_{p \in U} T_p M, \overline{\Phi} \right) \right\}_{(U, \phi)}$  forms an  $C^{\infty}$  atlas of  $TM$ .

(we've differentiated once in the equiv. relation for tangent vectors)

~~XX~~

Def: A (smooth) vector field  $\underline{X}$  on a manifold  $M$  is a smooth section of the tangent bundle  $TM$  of  $M$ ,

i.e.  $\underline{X} : M \rightarrow TM$  is a smooth map

s.t.  $\underline{X}(p) \in T_p M$

- The set of vector fields on  $M$  is denoted by  $\Gamma(TM)$ .

