

§ 4.2 Gauss Lemma, minimizing geodesic

Let (M, g) = Riemannian manifold,

$x \in M$, & $\delta > 0$ sufficiently small such that

$\exp_x: B(\delta) \rightarrow B_\delta$ is a diffeomorphism,

where $B(\delta) = \{v \in T_x M : |v| < \delta\}$, $(|v| = \sqrt{\langle v, v \rangle})$

$B_\delta = \exp_x(B(\delta))$.

Then • $r(t) = \exp_x(tv)$, $t \in (0, 1]$, $v \in B(\delta)$ is called a radial geodesic (segment) joining x to $\exp_x(v)$.

And $\forall t \in (0, \delta)$,

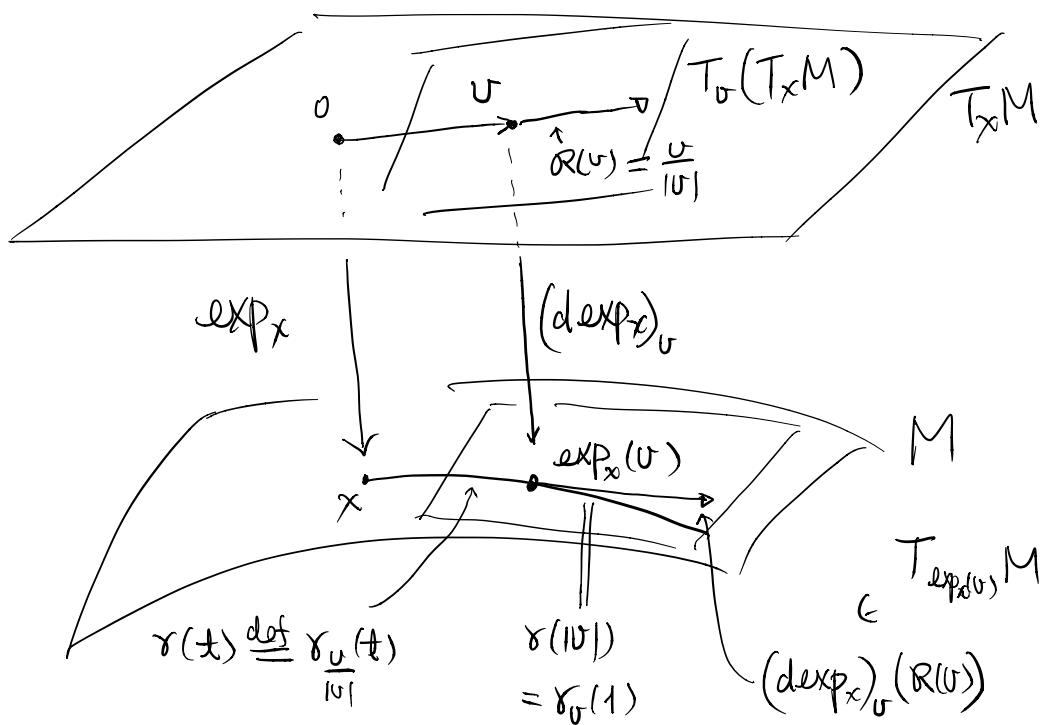
- $S_t = \exp_x(\{v \in T_x M : |v| = t\})$ is called the geodesic sphere of radius t centered at x .
- $B_t = \exp_x(B(t))$ is called the geodesic ball of radius t centered at x .

Lemma : (M, g) , x , δ as above. Define a vector field R on $T_x M \setminus \{0\}$ by

$$R(v) = \frac{v}{|v|} \quad \left(R = T_x M \setminus \{0\} \rightarrow T(T_x M \setminus \{0\}) \right)$$

with $T_v(T_x M \setminus \{0\}) \cong T_x M$

Then $\left| (d\exp_x)_v (R(v)) \right| = 1 \quad (\text{for } v \in B(\delta))$



Pf: For $v \in B(\delta) \setminus \{0\} \subset T_x M \setminus \{0\}$, let

$\gamma(t) = \gamma_{\frac{v}{|v|}}(t)$ the normalized geodesic on M

such that $\begin{cases} \gamma(0) = x & (\text{i.e. } \gamma(t) = \exp_x(t \frac{v}{|v|})) \\ \gamma'(0) = \frac{v}{|v|} \end{cases}$.

By definition of \exp_x ,

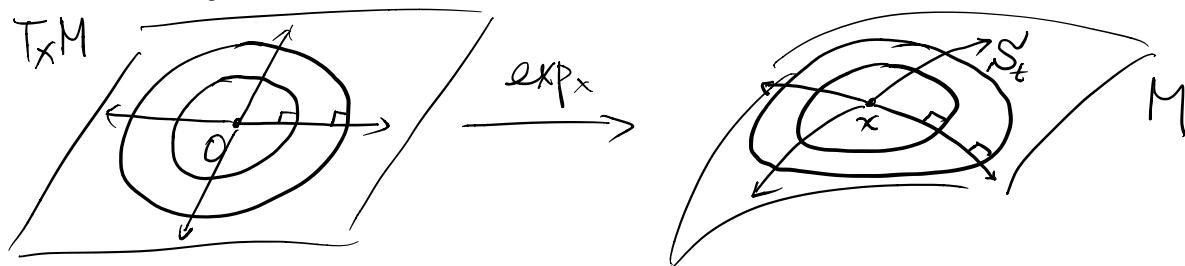
$$\exp_x(v) = \gamma(|v|)$$

Since $R(v) = \text{unit tangent vector of the line}$
 $t \mapsto v + tR(v)$,

$$\begin{aligned} (d\exp_x)_v(R(v)) &= \frac{d}{dt} \Big|_{t=0} (\exp_x)(v + tR(v)) \\ &= \frac{d}{dt} \Big|_{t=0} (\exp_x)((|v|+t)\frac{v}{|v|}) \\ &= \frac{d}{dt} \Big|_{t=0} \gamma(|v|+t) \\ &= \gamma'(|v|) \end{aligned}$$

$$\therefore |(d\exp_x)_v(R(v))| = |\gamma'(|v|)| = |\gamma'(0)| = 1 \quad \times$$

Gauss Lemma: Radial geodesics are orthogonal to
 the geodesic spheres S_t , $\forall t \in (0, \delta)$.



Pf = Define a diffeo

$$F: S^{n-1} \times (0, \delta) \xrightarrow{C^1 T_x M \setminus \{0\}} B_\delta \setminus \{x\}$$
$$(p, t) \xrightarrow{\psi} F(p, t) = \exp_x(t p)$$

Then for fixed $t \in (0, \delta)$,

$$F(\cdot, t): S^{n-1} \times \{t\} \rightarrow S_t$$

is a diffeomorphism.

Let γ = radial geodesic intersecting S_t at the point $\exp_x(tp)$.

We take a local coordinate $\{y^1, \dots, y^{n-1}\}$ around $p \in S^{n-1}$. And let r be the natural parameter of the interval $(0, \delta)$.

Then $\begin{cases} R = dF\left(\frac{\partial}{\partial r}\right) \\ Y_i = dF\left(\frac{\partial}{\partial y^i}\right) \end{cases}$

are vector fields on $B_\delta \setminus \{x\} \subset M$ such that

Y_i are tangential to S_t and form a basis of $T_y S_t$ for $y \in S_t \subset B_\delta \setminus \{x\}$, and

R is tangential to a radial geodesic.

Therefore, we need to show that

$$\langle R, Y_i \rangle = 0, \quad \forall i=1, \dots, n-1, \text{ at } \exp_x(tP).$$

Consider $\langle R, Y_i \rangle$ along the radial geodesic γ .

$$\begin{aligned} \text{Then } \langle R, Y_i \rangle' &= \underbrace{R \langle R, Y_i \rangle}_{\text{derivative wrt parameter } r.} \\ &= \langle D_R R, Y_i \rangle + \langle R, D_R Y_i \rangle \\ &= 0 + \langle R, D_{Y_i} R \rangle + \langle R, [R, Y_i] \rangle \end{aligned}$$

(Since $D_R R = D_{Y_i} \gamma' = 0$)

$$\begin{aligned} \text{However } [R, Y_i] &= [dF(\frac{\partial}{\partial r}), dF(\frac{\partial}{\partial y_i})] \\ &= dF([\frac{\partial}{\partial r}, \frac{\partial}{\partial y_i}]) \\ &= 0 \end{aligned}$$

$$\begin{aligned} \therefore \langle R, Y_i \rangle' &= \langle R, D_{Y_i} R \rangle = \frac{1}{2} Y_i \langle R, R \rangle \\ &= \frac{1}{2} Y_i(1) \quad (\text{by lemma}) \\ &= 0 \end{aligned}$$

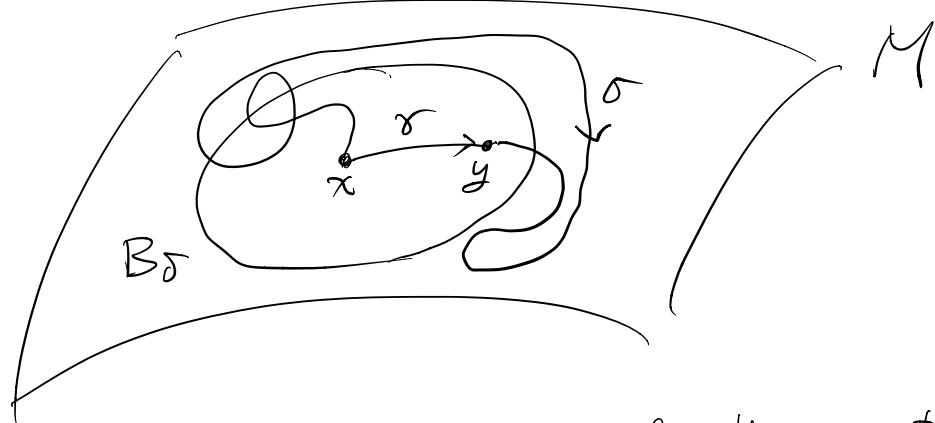
$$\Rightarrow \langle R, Y_i \rangle = \lim_{r \rightarrow 0} \langle R, Y_i \rangle(\gamma(r)) = 0 \quad \text{since } |Y_i| \rightarrow 0 \text{ as } \gamma(r) \rightarrow x \times \cancel{x}$$

Thm: Let $\bullet (M, g)$ = Riemannian manifold

- $x \in M$
- $\delta > 0$ s.t. $\exp_x : B(\delta) \rightarrow B_\delta$ is a diffeo.
- γ = unique radial geodesic joining x and a point $y \in B_\delta \setminus \{x\}$.

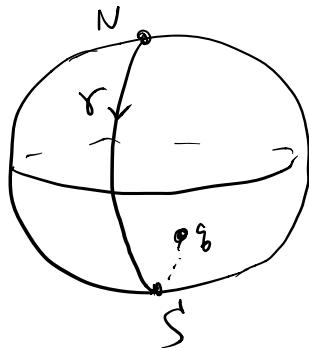
Then $L(\gamma) \leq L(\sigma)$ for all piecewise smooth curve σ on M (not necessary within B_δ) joining x to y .

Equality holds $\Leftrightarrow \sigma$ = monotonic reparametrization of γ .



Cor: Let $\gamma : [0, c] \rightarrow M$ be a arc-length parametrized piecewise smooth curve such that $L(\gamma) \leq L(\sigma)$ for all piecewise smooth curve σ joining $\gamma(0)$ and $\gamma(c)$. Then γ is a geodesic.

Caution: The converse of the Cor. is not true
in general :



r = geodesic, but
not length
minimizing.

Def: A geodesic $\gamma: [0, c] \rightarrow M$ is called a minimizing geodesic if $L(\gamma) \leq L(\tau)$ $\forall \tau$ joining $\gamma(0) = \gamma(c)$.

Pf of Cor (by assuming the Thm.)

Let $x = \gamma(0)$. Choose B_δ as in the Thm.

Let $t_1 = \min \{ t : \gamma(t) \in \partial B_\delta \}$

(If t_1 doesn't exist, then we are done.)

If $\gamma|_{[0, t_1]}$ is not geodesic, then by the theorem

$$L(\gamma|_{[0, t_1]}) > L(\gamma_1)$$

where γ_1 = radial geodesic joining $x = \gamma(0)$ to $\gamma(t_1)$ in B_δ .

$\Rightarrow L(\gamma_1 \cup \gamma|_{[t_1, c]}) < L(\gamma)$ which is a contradiction.

Hence $\gamma|_{[0, t_1]}$ is a geodesic.

Continuing this argument $\Rightarrow \gamma|_{[0, c]}$ is a geodesic.

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Pf of the Thm

As in the proof of the Gauss Lemma, we can find bases $\{R, Y_1, \dots, Y_{n-1}\}$ of $T_z M$ for $z \in B_\delta \setminus \{x\}$, such that $R =$ tangential to the radial geodesic
(and $|R|=1$)

$Y_1, \dots, Y_{n-1} =$ tangential to the geodesic sphere.

WLOG, we may assume $\sigma \subset B_\delta$.

Then for any such $\sigma: [0, 1] \rightarrow B_\delta$ s.t.

$$\sigma(0) = x, \quad \sigma(1) = y,$$

we have $\forall t \in [0, 1]$

$$\sigma'(t) = f(t) R(\sigma(t)) + T(t)$$

for some function $f(t)$,

where $T(t) =$ a linear combination of Y_i 's.

Let $v \in B(\delta)$ be the unique vector st.

$$\exp_x(v) = y.$$

Then $\xi = \exp_x^{-1} \circ \sigma$ is a curve in $B(\delta) \subset T_x M$ joining 0 and v .

Since $(d\exp_x^{-1})(R) = R$ ($=$ radial unit vector field defined above)

$$(d\exp_x^{-1})(Y_i) = \text{tangential to } S_{|\xi(t)|}^{n-1} \subset T_x M,$$

we see that

$$(d\exp_x^{-1})(\langle \sigma', R \rangle R) = f R \quad (\text{by Gauss lemma})$$

is the radial projection of the tangent vector ξ'

$$\Rightarrow |v| = |\xi(1)| - |\xi(0)| = \int_0^1 f(t) dt$$

$$\text{Hence } L(r) = |v| = \int_0^1 f(t) dt$$

where r is the radial geodesic joining x to $y = \exp_x v$.

Gauss lemma again \Rightarrow

$$|\sigma'(t)|^2 = f^2(t) |R(\sigma(t))|^2 + |T(t)|^2 = f(t)^2 + |T(t)|^2$$

$$\Rightarrow L(\sigma) = \int_0^1 |\sigma'| = \int_0^1 \sqrt{f^2 + |T|^2} \geq \int_0^1 f(t) dt = L(r).$$

Finally, if $L(\sigma) = L(\gamma)$, then $T(t) = 0$ & $f > 0$.

$$\Rightarrow \sigma'(t) = f(t) R(\sigma(t)) \text{ with } f > 0$$

$\Rightarrow \sigma$ = monotonic reparametrization of γ . ~~✓~~

§ 4.3 Completeness, metric structure

(M, g) = Riemannian manifold (connected)

Def: $d : M \times M \rightarrow [0, \infty)$ defined by

$$d(x, y) = \inf_{\gamma} L(\gamma),$$

where " \inf " is taken over all piecewise smooth curves γ joining x and y , is called the distance (or metric) of (M, g) .

Thm: (M, d) is a metric space, i.e. d satisfies

$$(1) \quad d(x, y) \geq 0; \quad " = " \text{ iff } x = y,$$

$$(2) \quad d(x, y) = d(y, x),$$

$$(3) \quad d(x, y) \leq d(x, z) + d(z, y).$$

Pf: All are easy (Ex.) and we prove only

" $d(x, y) = 0 \Rightarrow x = y$ ".

Suppose $x \neq y$.

If $y \in B_\delta$, where δ is given as in the "Thm" in §4.2, then

$d(x, y) = L(\gamma)$, where γ = radial geodesic from x to y .

$$\Rightarrow d(x, y) > 0.$$

Continuity argument $\Rightarrow d(x, y) = \delta > 0$ if $y \in \partial B_\delta$

Hence if $y \notin B_\delta$ and σ = curve joining x to y .

Choose the 1st point y_1 of σ on ∂B_δ and conclude that

$$L(\sigma) \geq L(\sigma)_{\text{(from } x \text{ to } y_1)} \geq \delta > 0.$$

Taking "inf" $\Rightarrow d(x, y) \geq \delta > 0$. ~~xx~~

In fact, we have a stronger theorem

Thm: The topology of (M, d) is the same as the original topology of M .

(Pf : Ex, or pg 61-62 of H.Wu, or doCarro.)

Def: A Riemannian manifold (M, g) is said to be complete if the associated metric space (M, d) is complete.

e.g.: $(\mathbb{R}^n, \text{standard metric})$, $(S^n, \text{standard metric})$ are complete.

Hopf-Rinow Theorem: The following statements are equivalent on a Riemannian manifold (M, g) :

- (1) M is complete.
- (2) $\forall x \in M$, \exp_x defined on the whole $T_x M$,
- (3) $\exists x \in M$, \exp_x defined on the whole $T_x M$,
- (4) bounded closed subsets of M are compact.

Cor 1 of Hopf-Rinow Thm

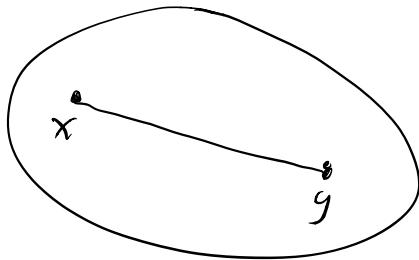
If (M, g) is complete, then $\forall x \neq y \in M$, \exists a minimizing geodesic γ joining x and y .

(Recall: all manifolds are connected in this course!)

Cor 2: If (M, g) is complete, then $\forall x \in M$, $\exp_x: T_x M \rightarrow M$ is surjective.

Notes: • The converse of Cor 1 of Hopf-Rinow Thm is not true in general :

e.g. convex subset in \mathbb{R}^n



- A general complete metric space may not have Heine-Borel property :

e.g.: $S = \{a_1, a_2, \dots\}$ countable infinite set of distinct elements.

Define discrete metric d on S by

$$d(a_i, a_j) = 1 - \delta_{ij}$$

Then (S, d) is a complete metric space which is bounded

$\Rightarrow S$ is a closed and bounded set, but not compact.

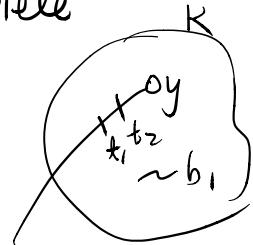
Pf of Hopf-Rinow Thm

(1) \Rightarrow (2) Let $\gamma: [0, \delta) \rightarrow M$ be a geodesic

$$\gamma(t) = \exp_x(tv) \text{ for some } v \in T_x M. (15=1)$$

Suppose that $I = (a_1, b_1)$ is the maximal possible interval containing $[0, \delta)$ such that $\gamma(t)$ is defined. Suppose $b_1 < +\infty$. Then M complete

$$\Rightarrow \exists y \in M \text{ s.t. } \lim_{t \rightarrow b_1} \gamma(t) = y.$$



Let $K = \text{cpt nbd. of } y$

ODE theory $\Rightarrow \exists \varepsilon > 0$ indep. of t_0 s.t.

" If $d(\gamma(t_0), y) < \frac{\varepsilon}{2}$ ($\Leftrightarrow \gamma(t_0) \in K$),

then \exists normalized geodesic $\zeta: [0, \varepsilon] \rightarrow M$
s.t. $\zeta(0) = \gamma(t_0) \wedge \zeta'(0) = \gamma'(t_0)$ "

\Rightarrow joining ζ to γ gives an extension of γ beyond b_1 .

Hence $b_1 = +\infty$.

Similar argument $\Rightarrow a_1 = -\infty$

$\therefore \exp_x(tv)$ defined $\forall t \in (-\infty, \infty)$.

Since v (with $|v|=1$) is arbitrary, \exp_x defined on whole $T_x M$.

(2) \Rightarrow (3) trivial.

(4) \Rightarrow (1) is standard for metric space.

To prove $(3) \Rightarrow (4)$, we claim that

(3) \Rightarrow (5), where

(5) Assume $x \in M$ as in (3), then $\forall y \in M, \exists$ a minimizing geodesic joining x to y .

Pf of claim (5) (i.e. $(3) \Rightarrow (5)$)

Let $\overline{B}(r) = \{y \in M : d(x, y) \leq r\}$

$\Sigma(r) = \{y \in \overline{B}(r) : y \text{ is joined to } x \text{ by a min. geodesic}\}$

Then we need to show that

$\overline{B}(r) = \Sigma(r), \forall r \in [0, \infty)$.

Let $\mathcal{I} = \{r \in [0, \infty) : \overline{B}(r) = \Sigma(r)\}$.

(i) We have shown that

if $r < \delta$ where $\delta > 0$ is given by the "Thm" in
§4.2 \uparrow
(minimizing radial geodesic)

then $r \in J$.

$\Rightarrow J \neq \emptyset$.

(ii) Since \exp_x defined on whole $T_x M \cong \mathbb{R}^n$,
continuous dependence of $\exp_x(tv)$ on v
 $\Rightarrow J$ is closed.

(iii) To show J is open, we need the following fact
(Ex, or see doCarmo)

(*) \forall cpt KCM, $\exists \varepsilon > 0$ such that
 $\forall y, z \in K$ with $d(y, z) \leq \varepsilon$,
then \exists a minimizing geodesic joining $y \approx z$.

Note: This is a stronger result than the Thm in §4.2
in which one of the points has to be the center.

Pf of openness : Let $r \in J$, then $\overline{\mathcal{B}}(r) = \Sigma(r)$

$\therefore \overline{\mathcal{B}}(r) \subset \exp(\overline{\mathcal{B}(r)}) \Rightarrow \overline{\mathcal{B}(r)}$ is compact.
 $\Rightarrow \partial \overline{\mathcal{B}(r)}$ is also compact.

Now $\forall z \in \partial \overline{B}(r)$, $\exists \varepsilon_1(z) > 0$ such that

$\exp_z : B(\varepsilon_1) \rightarrow B_{\varepsilon_1(z)}$ is a diffeomorphism.

By compactness of $\overline{B}(r)$, \exists finitely many z_i such that $\{B_{\frac{1}{2}\varepsilon_1(z_i)}(z_i)\}$ covers $\partial \overline{B}(r)$. This implies

$K = \overline{B}(r) \cup \left(\bigcup_i \overline{B_{\frac{1}{2}\varepsilon_1(z_i)}(z_i)} \right)$ is a compact set that contains $\overline{B}(r + \varepsilon_2)$ for some $0 < \varepsilon_2 < \frac{1}{2}\varepsilon_1$.

Applying (*), $\exists \varepsilon > 0$ with property in (*).

Let $\varepsilon' \in (0, \min\{\varepsilon_2, \varepsilon\})$ and consider

$$y \in \overline{B}(r + \varepsilon')$$

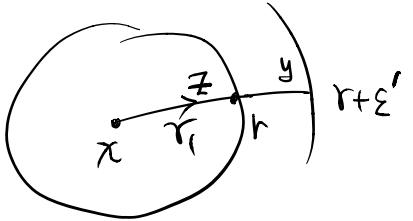
If $y \in \overline{B}(r)$, then $y \in \sum(r) \cap \sum(r + \varepsilon')$ (since $r \in \mathbb{J}$)

If $y \in \overline{B}(r + \varepsilon') \setminus \overline{B}(r)$,

then $\exists z \in \partial \overline{B}(r)$ s.t.

$$d(x, y) = d(x, z) + d(z, y)$$

(by using cptness of $\overline{B}(r)$)
 & definition of $d(x, y)$



Then $r \in \mathcal{I} \Rightarrow$

\exists minimizing geodesic γ_1 joining x & z .

On the other hand,

$$d(z, y) = d(x, y) - d(x, z) \leq r + \varepsilon' - r = \varepsilon' < \varepsilon$$

(*) $\Rightarrow \exists$ minimizing geodesic γ_2 joining z & y .

Then connecting γ_1 & γ_2 , we have a piecewise

smooth curve joining x & y with

$$\text{length} = d(x, z) + d(z, y) = d(x, y)$$

\Rightarrow it must be a minimizing geodesic.

$$\therefore y \in \Sigma(r + \varepsilon')$$

Hence $\overline{B}(r + \varepsilon') \subset \Sigma(r + \varepsilon') \subset \overline{B}(r + \varepsilon')$.

$\therefore \mathcal{I}$ is open.

Hence (i), (ii) & (iii) $\Rightarrow \mathcal{I} = [0, \infty) \therefore$ we've proved
that (3) \Rightarrow (5).

(3) \Rightarrow (4)

\forall bounded & closed set K , $\exists A > 0$ s.t.

$d(x, k) \leq A, \forall k \in K.$

$\Rightarrow K \subset \exp_x(\overline{B}(A))$ (by assumption (3))

$\Rightarrow K \text{ is cpt. (since } \overline{B}(A) \text{ is cpt.)}$

This completes the proof of Hopf-Rinow Thm. \times

Pf of Cor1 : Hopf-Rinow \Rightarrow (2) is true
 $(\Rightarrow (3) \text{ is true})$
 $\Rightarrow (5) \text{ is true } \forall x \in M$
 \Rightarrow Cor 1. is true. \times