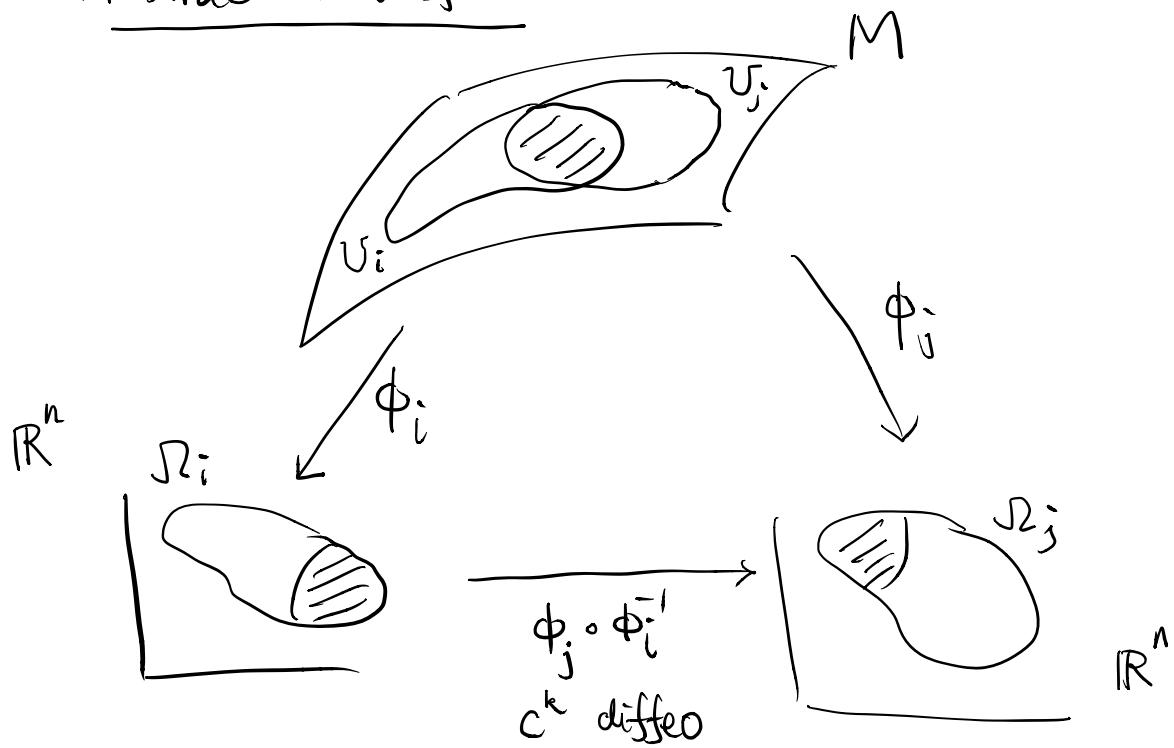


Ch1 Differential Manifolds

1.1 Abstract Manifolds



Def: A C^k atlas on a Hausdorff topological space

M is given by

- (i) an open covering U_i , $i \in \Lambda$, of M ;
- (ii) a family of homeomorphisms

$$\phi_i: U_i \rightarrow \mathcal{U}_i \subset \mathbb{R}^n \quad (\mathcal{U}_i \text{ is open})$$

such that $\forall i, j \in \Lambda$,

$$\phi_j \circ \phi_i^{-1}: \phi_i(U_i \cap U_j) \rightarrow \phi_j(U_i \cap U_j)$$

is a C^k -diffeomorphism.

Remark: • $\phi_j \circ \phi_i^{-1}$, $i, j \in \Lambda$ (with $U_i \cap U_j \neq \emptyset$) are called transition functions.

- (U_i, ϕ_i) is called a (coordinate) chart.
- $\phi_i^{-1}: \mathbb{R}^n \rightarrow U_i \subset M$ is a local parametrization.

Def: Two C^k atlases on M , say $(U_i, \phi_i)_{i \in \Lambda_1}$ and $(V_j, \psi_j)_{j \in \Lambda_2}$ are C^k -equivalent if their union is still a C^k atlas, that is, if $\forall i \in \Lambda_1, j \in \Lambda_2$ (s.t. $U_i \cap V_j \neq \emptyset$)

$$\phi_i \circ \psi_j^{-1} = \psi_j(U_i \cap V_j) \rightarrow \phi_i(U_i \cap V_j)$$

are C^k diffeomorphisms.

Def: A differentiable structure of class C^k on M is an equivalence class of C^k atlases.

Remark: If M is connected, then integer n in the definition doesn't depend on the chart and is defined as the dimension of M .

Def: A C^k differentiable manifold of dimension n is a pair (M, \mathcal{A}) , where M is a Hausdorff top. space and $\mathcal{A} = \{(U_i, \phi_i)\}_{i \in \Lambda}$ is a C^k atlas on M with $\phi_i(U_i) \subset \mathbb{R}^n$.

- Remark:
- In this course, we consider only C^∞ differentiable manifold which is connected and with a further condition such that "partitions of unity" is always possible.
 - All compact manifolds satisfy the further condition.
 - We'll refer such a manifold as a smooth manifold (or even just manifold).

Ex: $M = T^n$, the n-torus ($T^n = \underbrace{S^1 \times \dots \times S^1}_n$)

Pf: Let $f: \mathbb{R}^n \xrightarrow{\psi} T^n \in C^n$ (f is onto)
 $(x_1, \dots, x_n) \mapsto (e^{ix_1}, \dots, e^{ix_n})$

$\forall p \in T^n, \exists x^p = (x_1^p, \dots, x_n^p) \in \mathbb{R}^n$ such that
 $p \in f(x^p)$ (we may choose $x_i^p \in [0, 2\pi]$,
 $i=1, \dots, n$)

Consider $\mathcal{U}_p = (x_1^p - \pi, x_1^p + \pi) \times \dots \times (x_n^p - \pi, x_n^p + \pi)$
open in \mathbb{R}^n containing x^p .

Let $U_p = f(\mathcal{U}_p) \subset T^n$ (U_p open & containing p)

$$\phi_p = (f|_{\mathcal{U}_p})^{-1}: U_p \rightarrow \mathcal{U}_p \subset \mathbb{R}^n \text{ homeo.}$$

Then $\{(U_p, \phi_p)\}_{p \in T^n}$ is an C^∞ atlas on T^n :

In fact, if $p, q \in T^n$ s.t. $U_p \cap U_q \neq \emptyset$,

$$\text{then } \phi_g \circ \phi_p^{-1}(x_1, \dots, x_n) \quad ((x_1, \dots, x_n) \in \phi_p(U_p \cap U_q) \subset \Omega_p)$$

$$= \phi_g(f(x_1, \dots, x_n))$$

$$= \phi_g(e^{ix_1}, \dots, e^{ix_n}) \quad (e^{ix_1}, \dots, e^{ix_n}) \in U_p \cap U_q \subset U_q$$

$$= (f|_{\Omega_q})^{-1}(e^{ix_1}, \dots, e^{ix_n})$$

$$= (x_1 + 2k_1\pi, \dots, x_n + 2k_n\pi) \text{ for some } k_1, \dots, k_n$$

$$\text{such that } x_i + 2k_i\pi \in (x_i^0 - \pi, x_i^0 + \pi)$$

note that k_i are indep of $(x_1, \dots, x_n) \in \phi_p(U_p \cap U_q)$

Hence $\phi_g \circ \phi_p^{-1}$ is just a translation in \mathbb{R}^n .

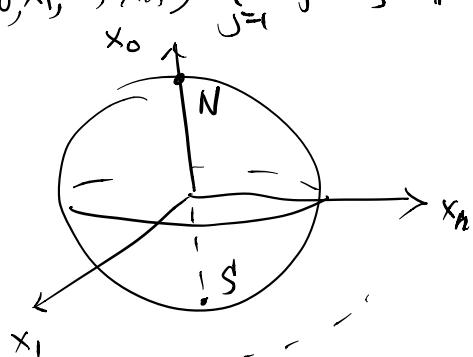
$\Rightarrow \phi_g \circ \phi_p^{-1}$ is a C^∞ diffeo.

$\therefore (T^n, \{(U_p, \phi_p)\}_{p \in T^n})$ is a smooth manifold.

e.g. $M = S^n$, the n -sphere $S^n = \{(x_0, x_1, \dots, x_n) : \sum_{j=1}^n x_j^2 = 1\} \subset \mathbb{R}^{n+1}$

$$\begin{cases} N = (1, 0, \dots, 0) \in S^n \\ S = (-1, 0, \dots, 0) \in S^n \end{cases}$$

$$\begin{cases} U_1 = S^n \setminus \{N\} \\ U_2 = S^n \setminus \{S\} \end{cases}$$



$$U_1 \cup U_2 = S^n$$

Let

$$\left\{ \begin{array}{l} \phi_1: U_1 \rightarrow \mathbb{R}^n \quad (\text{Stereographic projection}) \\ \downarrow \\ (x_0, x_1, \dots, x_n) \mapsto \frac{1}{1-x_0} (x_1, \dots, x_n) \\ \\ \phi_2: U_2 \rightarrow \mathbb{R}^n \\ \downarrow \\ (x_0, x_1, \dots, x_n) \mapsto \frac{1}{1+x_0} (x_1, \dots, x_n) \end{array} \right.$$

are homeomorphism

Note that if $\phi_1(x_0, x_1, \dots, x_n) = (y_1, \dots, y_n) \neq 0$

then $y = (y_1, \dots, y_n) \in \phi_1(U_1 \cap U_2)$

(Ex:) $\boxed{\phi_2 \circ \phi_1^{-1}(y) = \frac{y}{|y|^2}}$ ($\forall y \in \mathbb{R}^n \setminus \{0\}$)

which is a C^∞ diffeomorphism.

$\Rightarrow A = \{(U_1, \phi_1), (U_2, \phi_2)\}$ is an C^∞ atlas

on S^n , therefore (S^n, A) is a smooth manifold.

e.g.: \mathbb{RP}^n the real projective space (in some books = $P^n \mathbb{R}$)

- As topological space

\mathbb{RP}^n = quotient space of $\mathbb{R}^{n+1} \setminus \{0\}$ by the equivalent relation: $(x, y \in \mathbb{R}^{n+1} \setminus \{0\})$

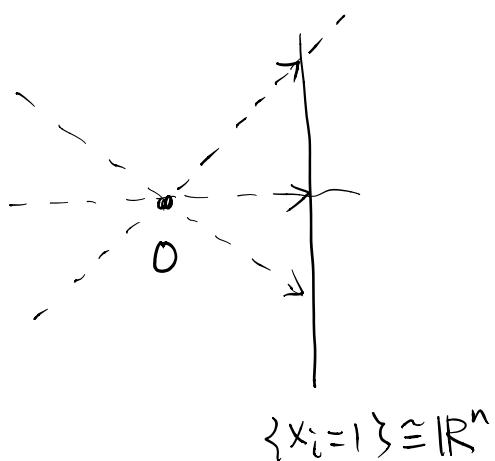
$$x \sim y \Leftrightarrow \exists \lambda \neq 0 \in \mathbb{R} \text{ s.t. } x = \lambda y$$

$$= S^n / \{\pm \text{Id}\} \quad (\text{hence } \mathbb{RP}^n = \text{Hausdorff, compact, connected.})$$

- Let $\pi: \mathbb{R}^{n+1} \setminus \{0\} \rightarrow \mathbb{RP}^n$ be the canonical projection map, i.e. $\pi(x) = \text{equi. class of } x$.

Define $V_i = \{x = (x_0, x_1, \dots, x_n) \in \mathbb{R}^{n+1}, x_i \neq 0\}$

$$\begin{aligned} \Phi_i: V_i &\longrightarrow \mathbb{R}^n \\ x &\longmapsto \left(\frac{x_0}{x_i}, \dots, \overset{i}{\underset{\nwarrow}{\frac{x_i}{x_i}}}, \dots, \frac{x_n}{x_i} \right) \end{aligned} \quad \begin{array}{l} \text{this means the} \\ \text{term is deleted.} \end{array}$$



Then $\forall x, y \in V_i$,

we have

$$\boxed{\begin{aligned} \Phi_i(x) &= \Phi_i(y) \\ \Leftrightarrow \pi(x) &= \pi(y) \end{aligned}} \quad (*)$$

$$\{x_i = 1\} \cong \mathbb{R}^n$$

(i.e. $x \sim y$)

$$\begin{array}{ccccc} \text{This gives } \mathbb{R}^{n+1} \setminus \{0\} & \supset & V_i & \xrightarrow{\Phi_i} & \mathbb{R}^n \\ & & \pi \downarrow & \nearrow \phi_i & \\ & & U_i = \pi(V_i) & & (\phi_i \circ \pi = \Phi_i) \end{array}$$

where ϕ_i is defined by

$$\begin{aligned}\phi_i: U_i = \pi(V_i) &\longrightarrow \mathbb{R}^n \\ \Downarrow & \Downarrow \\ \text{equi. class of } x &\mapsto \Phi_i(x)\end{aligned}$$

(ϕ_i is well-defined because of $(*)$)

Further $\phi_i: U_i \rightarrow \mathbb{R}^n$ is homeomorphism (check!)

with inverse

$$\phi_i^{-1}(y_0, \dots, y_{n-1}) = \pi(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1})$$

Therefore, if $y_j \neq 0$, say for $j < i$, we have

$$\begin{aligned}(\phi_j \circ \phi_i^{-1})(y_0, \dots, y_{n-1}) &= \phi_j(\pi(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1})) \\ &= \Phi_j(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1}) \\ &= \left(\frac{y_0}{y_j}, \dots, \frac{\overset{\wedge}{y_j}}{y_j}, \dots, \frac{1}{y_j}, \frac{y_i}{y_j}, \dots, \frac{y_{n-1}}{y_j} \right)\end{aligned}$$

$$\therefore \phi_j \circ \phi_i^{-1}: \phi_i(U_i \cap U_j) \rightarrow \phi_j(U_i \cap U_j) \text{ is a } C^\infty \text{ diffeo.}$$

(similarly for $i < j$). Hence \mathbb{RP}^n with the atlas

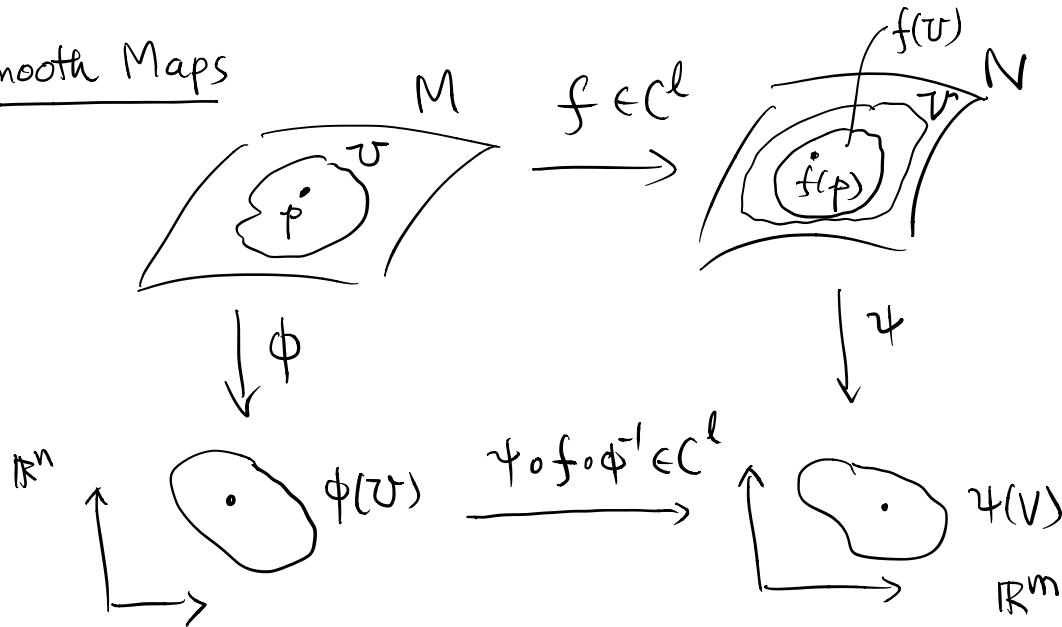
$\{(U_i, \phi_i)\}_{i=0}^n$ is a smooth manifold.

Note: \mathbb{RP}^n is non-orientable for n even according to the following definition: (proof omitted)

Def: A smooth manifold M is said to be orientable if \exists an atlas on M s.t. the Jacobian determinant

$$J(\phi_j \circ \phi_i^{-1}) > 0, \forall i, j.$$

1.2 Smooth Maps



$\psi \circ f \circ \phi^{-1}$ is m functions of n variables as in Calculus

Def: Let M & N be C^k manifolds. A continuous map $f: M \rightarrow N$ is C^l map (for $l \leq k$) if $\forall p \in M$, \exists charts (U, ϕ) & (V, ψ) for M and N around p & $f(p)$ respectively with $f(U) \subset V$ such that $\psi \circ f \circ \phi^{-1}: \phi(U) \rightarrow \psi(V)$ is C^l .

Note: This definition doesn't depend on the charts since transition functions are C^k ($k \geq l$) (Ex!)

Def: A C^k map $\gamma: (a, b) \rightarrow M$ from an open interval to a smooth manifold is called a C^k curve (on M).

Def: A C^k map $f: M \rightarrow \mathbb{R}$ ($\text{or } \mathbb{C}$) is called a C^k function on M .

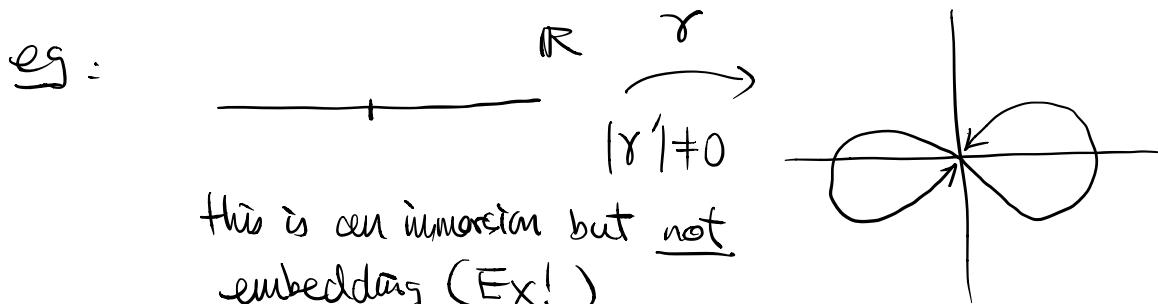
Def: A smooth map $g: \mathbb{R}^n \rightarrow \mathbb{R}^k$ is a submersion (an immersion, a local diffeomorphism) at $x \in \mathbb{R}^n$ if $D_x g: \mathbb{R}^n \rightarrow \mathbb{R}^k$ is surjective (injective, bijective).

Def: Let M & N be smooth manifolds. A smooth map $f: M \rightarrow N$ is a submersion (immersion, local diffeo.) at $p \in M$, if \exists charts (U, ϕ) fa M around p , (V, ψ) fa N around $f(p)$, with $f(U) \subset V$ s.t. $\psi \circ f \circ \phi^{-1}$ is a submersion (immersion, local diffeo.) at $\phi(p) \in \phi(U) \subset \mathbb{R}^n$.

Def: A map $f: M \rightarrow N$ is a submersion (immersion, local diffeo.) if it has the property at any point of M .

Def: A map $f: M \rightarrow N$ is a diffeomorphism if it is a bijection such that both f and f^{-1} are smooth.

Def: A map $f: M \rightarrow N$ is an embedding if it is an immersion and $f: M \rightarrow f(M) \subset N$ (with subspace top.) is a homeomorphism.

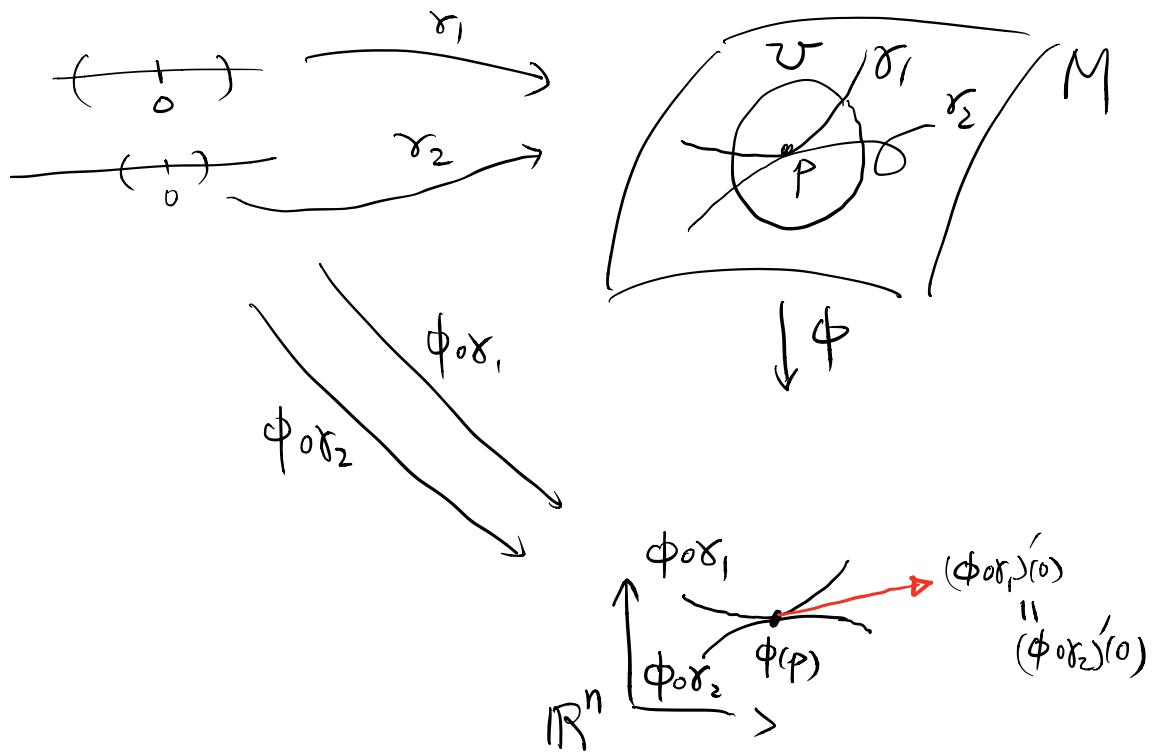


1.3 Tangent vectors

Def 1: Let M be a smooth manifold and $p \in M$. A tangent vector to M at p is an equi. class of C^∞ curves $\gamma: I \rightarrow M$, where $I = \text{interval containing } 0$, such that $\gamma(0) = p$, for the equi. relation defined by $\gamma_1 \sim \gamma_2$

$$\Leftrightarrow (\phi \circ \gamma_1)'(0) = (\phi \circ \gamma_2)'(0)$$

for a chart (U, ϕ) around p .



Ex: Check that the equi. relation is well-defined by showing that for any other chart (V, ψ) around p , we have

$$(\psi \circ \gamma)'(0) = D_{\phi(p)}(\psi \circ \phi^{-1}) \cdot (\phi \circ \gamma)'(0)$$

where $D_{\phi(p)}(\psi \circ \phi^{-1})$ is the Jacobi matrix (n differential) of the map $\psi \circ \phi^{-1}$ at $\phi(p)$.

Def² (Equivalent definition for tangent vectors)

Let M be a smooth manifold, $p \in M$, $(U, \phi) \& (V, \psi)$ be 2 coordinates charts for M around p . Let u, v be 2 vectors in \mathbb{R}^n (considered at tangent vectors to \mathbb{R}^n at $\phi(p)$ and $\psi(p)$ respectively). We say that

$$(U, \phi, u) \sim (V, \psi, v) \Leftrightarrow D_{\phi(p)}(\psi \circ \phi^{-1}) u = v.$$

Then a tangent vector to M at p is a equiv. class of triples (U, ϕ, u) .