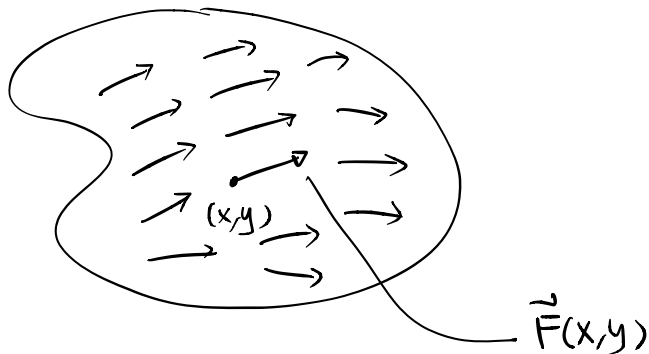


## Vector Fields

Def 10: Let  $D \subset \mathbb{R}^2$  or  $\mathbb{R}^3$  be a region, then a vector field on  $D$  is a mapping  $\vec{F}: D \rightarrow \mathbb{R}^2$  or  $\mathbb{R}^3$  respectively.



In component form:

$$\mathbb{R}^2: \quad \vec{F}(x, y) = M(x, y) \hat{i} + N(x, y) \hat{j}$$

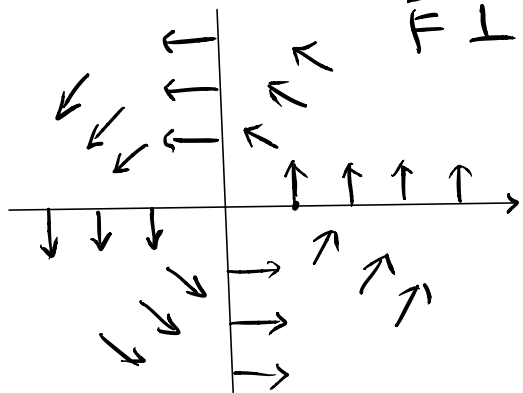
$$\mathbb{R}^3: \quad \vec{F}(x, y, z) = M(x, y, z) \hat{i} + N(x, y, z) \hat{j} + L(x, y, z) \hat{k}$$

where  $M, N, L$  are functions on  $D$  called the components of  $\vec{F}$ .

eg 35:  $\vec{F}(x, y) = \frac{-y \hat{i} + x \hat{j}}{\sqrt{x^2 + y^2}}$  on  $\mathbb{R}^2 \setminus \{(0, 0)\}$   
 $= -\sin\theta \hat{i} + \cos\theta \hat{j}$  (in polar coordinates)

Properties of  $\vec{F}$ :  $|\vec{F}(x, y)| = 1$

$$\vec{F} \perp \vec{r}(x, y) = x \hat{i} + y \hat{j} \\ = r(\cos\theta \hat{i} + \sin\theta \hat{j})$$



(Ex: sketch  $\vec{F}(x, y) = x \hat{i} + y \hat{j}$ )

### eg36 (Gradient vector field of a function)

$$(i) f(x, y) = \frac{1}{2}(x^2 + y^2)$$

$$\vec{\nabla} f(x, y) \stackrel{\text{def}}{=} \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right) = (x, y) = x\hat{i} + y\hat{j} = \vec{r}(x, y) = \vec{r}$$

$$(ii) f(x, y, z) = x$$

$$\vec{\nabla} f(x, y, z) \stackrel{\text{def}}{=} \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right) = (1, 0, 0) = \hat{i}$$

### eg37 (Vector field along a curve)

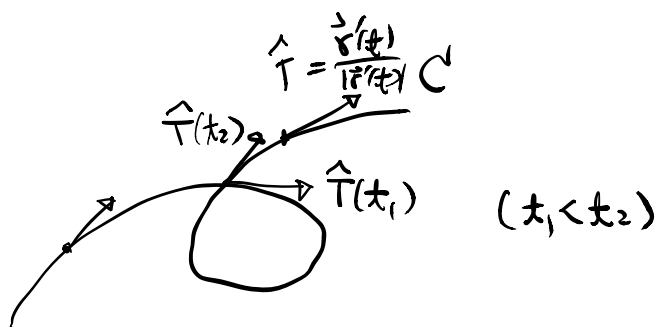
Let  $C$  be a curve in  $\mathbb{R}^2$  parametrized by

$$\begin{array}{ccc} \vec{r} = [a, b] & \longrightarrow & \mathbb{R}^2 \\ \downarrow & & \downarrow \\ t & \longmapsto & (x(t), y(t)) = \vec{r}(t) \end{array}$$

Recall:  $\hat{T} =$  unit tangent vector field along  $C$

$$= \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$$

Note that this vector field  
only defined on  $C$ ,  
but not outside  $C$



Remark for eg37:

If we use  $ds = |\vec{r}'(t)| dt$ , then

$$\hat{T} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{\frac{d\vec{r}}{dt}}{\frac{ds}{dt}} = \frac{d\vec{r}}{ds} \quad (\text{by chain rule})$$

where "arc-length  $s$ " is defined (up to an additive constant)

by 
$$s(t) = \int_{t_0}^t |\vec{r}'(t)| dt$$

A parametrization of a curve  $C$  by arc-length  $s$  is called arc-length parametrization:

$$\vec{r}(s) = \text{arc-length parametrization}$$
$$\Rightarrow \left| \frac{d\vec{r}}{ds}(s) \right| = 1$$

Def 11 A vector field is defined to be continuous/differentiable/ $C^k$  if the component functions are.

eg 3B :

$$\left. \begin{aligned} \vec{F}(x,y) = \vec{r}(x,y) = x\hat{i} + y\hat{j} & \text{ is } C^\infty, \\ \vec{F}(x,y) = \frac{-y\hat{i} + x\hat{j}}{\sqrt{x^2+y^2}} & \text{ is not continuous in } \mathbb{R}^2 \\ & \text{(but continuous in } \mathbb{R}^2 \setminus \{0,0\}) \end{aligned} \right\}$$

### Line integral of vector field

Def 12: Let  $C$  be a curve with orientation given by a parametrization  $\vec{r}(t)$  with  $\vec{r}'(t) \neq \vec{0}$ ,  $\forall t$ . Define the line integral of a vector field  $\vec{F}$  along  $C$  to be

$$\int_C \vec{F} \cdot \hat{T} \, ds$$

where  $\hat{T} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|}$  is the unit tangent vector field along  $C$ .

(i.e.  $C$  is oriented in the direction of  $\vec{r}'(t)$  or  $\hat{T}$  at every point)



Note: If  $\vec{r} = [a, b] \rightarrow \mathbb{R}^n$  ( $n=2, n=3$ ) then

$$\int_C \vec{F} \cdot \hat{T} ds = \int_a^b \vec{F}(\vec{r}(t)) \cdot \frac{\vec{r}'(t)}{|\vec{r}'(t)|} \underbrace{|\vec{r}'(t)| dt}_{ds}$$

$$= \int_a^b \vec{F}(\vec{r}(t)) \cdot \underbrace{\vec{r}'(t) dt}_{d\vec{r}}$$

$\therefore$  naturally, we write

$$\boxed{d\vec{r} = \hat{T} ds} \quad \text{and}$$

$$\boxed{\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r}}$$

eg 38:  $\vec{F}(x, y, z) = z\hat{i} + xy\hat{j} - y^2\hat{k}$

$$C: \vec{r}(t) = t^2\hat{i} + t\hat{j} + \sqrt{t}\hat{k}, \quad 0 \leq t \leq 1$$

Then  $d\vec{r} = (2t\hat{i} + \hat{j} + \frac{1}{2\sqrt{t}}\hat{k}) dt$

and  $\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r}$

$$= \int_0^1 (t\hat{i} + t^2\hat{j} - t^2\hat{k}) \cdot (2t\hat{i} + \hat{j} + \frac{1}{2\sqrt{t}}\hat{k}) dt$$

$$= \int_0^1 (2t\sqrt{t} + t^3 - \frac{t^{3/2}}{2}) dt = \frac{17}{20} \text{ (check!)}$$

Line Integral of  $\vec{F} = M\hat{i} + N\hat{j}$  along

$C: \vec{r}(t) = g(t)\hat{i} + h(t)\hat{j}$  can be expressed as

$$\int_C \vec{F} \cdot \hat{T} ds = \int_C \vec{F} \cdot d\vec{r} = \int_C (\vec{F} \cdot \frac{d\vec{r}}{dt}) dt$$

$$= \int_a^b (Mg' + Nh') dt \quad \left( \begin{array}{l} \text{explicitly:} \\ M(g(t), h(t))g'(t) + N(g(t), h(t))h'(t) \end{array} \right)$$

Similarly for  $\vec{F} = M\hat{i} + N\hat{j} + L\hat{k}$  along

$$C: \vec{r}(t) = g(t)\hat{i} + h(t)\hat{j} + f(t)\hat{k}$$

is

$$\int_C \vec{F} \cdot \hat{T} ds = \int_a^b (Mg' + Nh' + Lf') dt \quad (\text{check!})$$

Note: usually, people write

$$\begin{cases} dx = g'(t)dt \\ dy = h'(t)dt \\ dz = f'(t)dt \end{cases}$$

$$\Rightarrow \int_C \vec{F} \cdot \hat{T} ds = \int_C M dx + N dy + L dz$$

Similarly for  $\mathbb{R}^3$ :

$$\int_C \vec{F} \cdot \hat{T} ds = \int_C M dx + N dy$$

Another way to justify the notation:

$\vec{r} = (x, y, z)$  the position vector

$$\Rightarrow d\vec{r} = (dx, dy, dz) \quad (\text{naturally})$$

Then

$$\begin{aligned} \int_C \vec{F} \cdot \hat{T} ds &= \int_C \vec{F} \cdot d\vec{r} = \int_C (M, N, L) \cdot (dx, dy, dz) \\ &= \int_C M dx + N dy + L dz. \end{aligned}$$

eg 39: Evaluate  $I = \int_C -y dx + z dy + 2x dz$

where  $C: \vec{r}(t) = \cos t \hat{i} + \sin t \hat{j} + t \hat{k} \quad (0 \leq t \leq 2\pi)$   
 $= (\cos t, \sin t, t)$

Solu:  $d\vec{r} = (-\sin t, \cos t, 1) dt$

$$\begin{aligned} \Rightarrow I &= \int_0^{2\pi} [-\sin t (-\sin t) + t(\cos t) + 2\cos t(1)] dt \\ &= \int_0^{2\pi} (\sin^2 t + t \cos t + 2\cos t) dt = \pi \quad \# \end{aligned}$$

# Physics

(1)  $\vec{F}$  = Force field

$C$  = oriented curve,

then 
$$W = \int_C \vec{F} \cdot \hat{T} ds$$

is work done in moving an object along  $C$

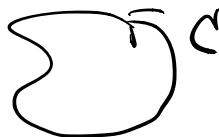
(2)  $\vec{F}$  = velocity vector field of fluid

$C$  = oriented curve

then 
$$\text{Flow} = \int_C \vec{F} \cdot \hat{T} ds$$

Flow along the curve  $C$

If  $C$  is a closed curve, the flow is also called the circulation



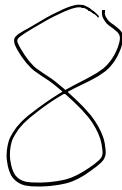

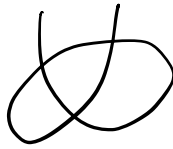
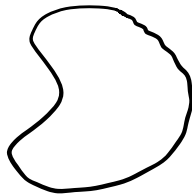
Def 13 = A curve is said to be

(i) simple if it does not intersect with itself except possibly at end points

(ii) closed if starting point = end point.  
(also called a loop)

(iii) simple closed curve if it is both simple and closed.

Note:

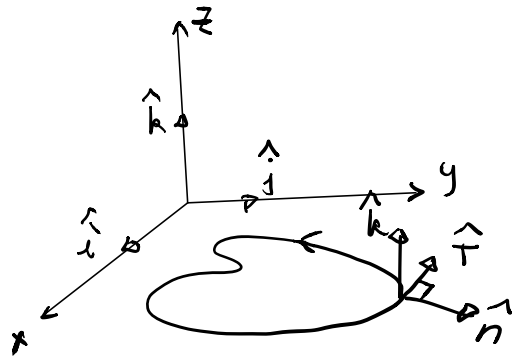
				
simple	No	Yes	No	Yes
closed	Yes	No	No	Yes

(3)  $\vec{F}$  = velocity of fluid

$C$  = oriented plane curve ( $C \subset \mathbb{R}^2$ )  
parametrized by

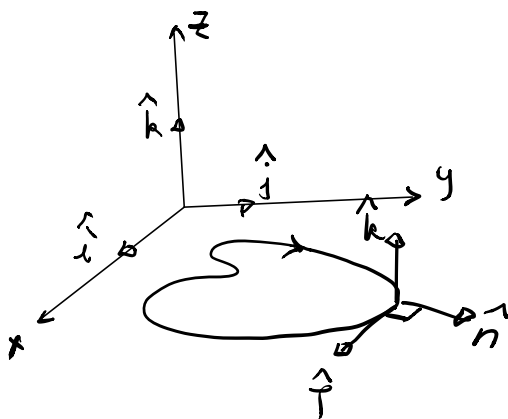
$$\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}.$$

$\hat{n}$  = outward-pointing unit normal vector to the curve  $C$ .



if  $C$  is of anti-clockwise  
orientation

$$\boxed{\hat{n} = \hat{T} \times \hat{k}}$$



if  $C$  is of clockwise  
orientation

$$\boxed{\hat{n} = -\hat{T} \times \hat{k}}$$

Formula for  $\hat{n}$  (wrt the parametrization  $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}$ )

Recall  $\hat{T} = \frac{\vec{r}'(t)}{|\vec{r}'(t)|} = \frac{x'(t)\hat{i} + y'(t)\hat{j}}{|\vec{r}'(t)|}$

(in arc-length parameter:  $\hat{T} = \frac{d\vec{r}}{ds} = \frac{dx}{ds}\hat{i} + \frac{dy}{ds}\hat{j}$ )

Anti-clockwise

$$\hat{n} = \hat{T} \times \hat{k} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{x'}{|\vec{r}'|} & \frac{y'}{|\vec{r}'|} & 0 \\ 0 & 0 & 1 \end{vmatrix} = \frac{y'(t)\hat{i} - x'(t)\hat{j}}{|\vec{r}'(t)|}$$

(or  $\hat{n} = \frac{dy}{ds}\hat{i} - \frac{dx}{ds}\hat{j}$ )

Clockwise

$$\hat{n} = \frac{-y'(t)\hat{i} + x'(t)\hat{j}}{|\vec{r}'(t)|}$$

(or  $\hat{n} = -\frac{dy}{ds}\hat{i} + \frac{dx}{ds}\hat{j}$ )

Flux of  $\vec{F}$  across  $C$   $\stackrel{\text{def}}{=} \int_C \vec{F} \cdot \hat{n} ds$  (amount of fluid getting out of the closed curve  $C$ )

If  $\vec{F} = M(x,y)\hat{i} + N(x,y)\hat{j}$

and  $\vec{r}(t) = x(t)\hat{i} + y(t)\hat{j}$  is anti-clockwise parametrization of  $C$ .

Then

Flux of  $\vec{F}$  across  $C$

$$= \oint_C (M\hat{i} + N\hat{j}) \cdot \left(\frac{dy}{ds}\hat{i} - \frac{dx}{ds}\hat{j}\right) ds$$

$$= \oint_C M dy - N dx$$



" $\oint$ " means the curve is closed and in anti-clockwise orientation.

Similarly " $\oint$ " means the curve is closed and in clockwise orientation.

But in some books, only " $\oint$ " is used, no arrows.

Then one needs to know from context whether the parametrization is anti-clockwise or clockwise.

Convention: We usually refer the anti-clockwise orientation as the positive orientation of a closed curve in  $\mathbb{R}^2$  (wrt the "orientation" of  $\mathbb{R}^2$ ) and " $\oint$ " without orientation explicitly mentioned means positive orientation.

eg 40: Let  $\vec{F} = (x-y)\hat{i} + x\hat{j}$   
 $C: x^2 + y^2 = 1$

Find the flow (anti-clockwise) along  $C$  and flux across  $C$ .

Soln: Let  $\vec{r}(t) = \cos t \hat{i} + \sin t \hat{j}$ ,  $0 \leq t \leq 2\pi$

(note: correct orientation!)

(cont'd next time)