

Row spaces & more bases

Recall: If $A \in M_{mn}$ with columns $\vec{u}_1, \dots, \vec{u}_n$,
then the column space of A , $\mathcal{C}(A) \subset \mathbb{R}^m$
is the span of $\vec{u}_1, \dots, \vec{u}_n$:

$$\mathcal{C}(A) = \langle \{ \vec{u}_1, \dots, \vec{u}_n \} \rangle.$$

If $\vec{v} \in \mathbb{R}^m$, then $\vec{v} \in \mathcal{C}(A)$ if

and only if (1) $A\vec{x} = \vec{v}$ is consistent

(i.e. there exists \vec{x} such that (1) holds).

Column spaces can be understood as nullspaces:

Example: let $A = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 1 & 0 \\ 3 & 0 & 1 \\ 4 & 0 & 0 \end{bmatrix}$

describe the col. space of A , $\mathcal{C}(A) \subseteq \mathbb{R}^4$.

equivalently, characterize all $\vec{v} \in \mathbb{R}^4$ st.

$A\vec{x} = \vec{v}$ is consistent.

augmented matrix $[A | \vec{v}] = \left[\begin{array}{ccc|c} 1 & 1 & 0 & v_1 \\ 2 & 1 & 0 & v_2 \\ 3 & 0 & 1 & v_3 \\ 4 & 0 & 0 & v_4 \end{array} \right]$

\Downarrow $R_2' = R_2 - 2R_1$

$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & V_1 \\ 0 & -1 & 0 & V_2 - 2V_1 \\ 3 & 0 & 1 & V_3 \\ 4 & 0 & 0 & V_4 \end{array} \right]$$



$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & V_1 \\ 0 & -1 & 0 & V_2 - 2V_1 \\ 0 & -3 & 1 & V_3 - 3V_1 \\ 0 & -4 & 0 & V_4 - 4V_1 \end{array} \right]$$



$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & V_1 \\ 0 & 1 & 0 & 2V_1 - V_2 \\ 0 & -3 & 1 & V_3 - 3V_1 \\ 0 & -4 & 0 & V_4 - 4V_1 \end{array} \right]$$

$$R_3' = R_3 + 3R_2$$



$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & V_1 \end{array} \right]$$

$$\left[\begin{array}{ccc|c} 0 & 1 & 0 & 2v_1 - v_2 \\ 0 & 0 & 1 & v_3 - 3v_1 + 3(2v_1 - v_2) \\ 0 & -4 & 0 & v_4 - 4v_1 \end{array} \right]$$

$$\downarrow R_1' = R_1 + 4R_2$$

zero row \rightarrow

$$\left[\begin{array}{ccc|c} 1 & 1 & 0 & v_1 \\ 0 & 1 & 0 & 2v_1 - v_2 \\ 0 & 0 & 1 & 3v_1 - 3v_2 + v_3 \\ 0 & 0 & 0 & v_4 - 4v_1 + 4(2v_1 - v_2) \end{array} \right]$$

$A\vec{x} = \vec{v}$ is consistent if and only if:

$$v_4 - 4v_1 + 4(2v_1 - v_2) = 0$$

$$v_4 + 4v_1 - 4v_2 = 0$$

$$\Rightarrow \vec{v} \in \mathcal{C}(A) \Leftrightarrow v_4 + 4v_1 - 4v_2 = 0$$

$$\Leftrightarrow \vec{v} \in \mathcal{N}(D)$$

where $D = [4 \ -4 \ 0 \ 1]$

Exercise: let $A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \\ 1 & 1 \\ 1 & 0 \end{bmatrix}$. Express $e(A)$ as $N(D)$ for some matrix D .

Answer: $\left[\begin{array}{cc|c} 1 & 2 & v_1 \\ 1 & 3 & v_2 \\ 1 & 1 & v_3 \\ 1 & 0 & v_4 \end{array} \right] \rightsquigarrow \left[\begin{array}{cc|c} 1 & 2 & v_1 \\ 0 & 1 & v_2 - v_1 \\ 0 & -1 & v_3 - v_1 \\ 0 & -2 & v_4 - v_1 \end{array} \right]$

\rightsquigarrow

$$\left[\begin{array}{cc|c} 1 & 2 & v_1 \\ 0 & 1 & v_2 - v_1 \\ 0 & 0 & v_3 - v_1 + v_2 - v_1 \\ 0 & 0 & v_4 - v_1 + 2(v_2 - v_1) \end{array} \right]$$

zero row \rightarrow

zero row \rightarrow

$A\vec{x} = \vec{v}$ is consistent if and only if

$$\Leftrightarrow \begin{cases} v_3 - v_1 + v_2 - v_1 = 0 \\ +2v_1 + v_2 + v_3 = 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} v_4 - v_1 + 2(v_2 - v_1) = 0 \\ -3v_1 + 2v_2 + v_4 = 0 \end{cases}$$

So $A\vec{x} = \vec{v}$ is consistent if and only if

$$\vec{v} \in \mathcal{N}(D) \quad D = \begin{bmatrix} -2 & 1 & 1 & 0 \\ -3 & 2 & 0 & 1 \end{bmatrix}$$

Theorem: Let $A \in M_{mn}$ matrix.

$A \xrightarrow{\text{RREF}} B$. Let B have z zero rows.

Then $\mathcal{C}(A) = \mathcal{N}(D)$ where D is a certain

$n \times m$ matrix.

Let $A \in M_{mn}$. Want a basis of $\mathcal{C}(A)$.

Eg. $A = \begin{bmatrix} 1 & 2 & 1 & 1 & 1 \\ 2 & 0 & 0 & 1 & 3 \\ 3 & 0 & 0 & 1 & 1 \end{bmatrix}$, need to decide which columns to keep & which to throw away.

Theorem: let $A \xrightarrow{\text{RREF}} B$, and let B have

pivot columns with indices d_1, d_2, \dots, d_r .

Eg. $B = \begin{pmatrix} \boxed{1} & * & 0 & * & * & 0 \\ 0 & 0 & \boxed{1} & * & * & 0 \\ 0 & 0 & 0 & 0 & 0 & \boxed{1} \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$. Then a basis for $\mathcal{C}(A)$ is given by:

$\vec{A}_{d_1}, \vec{A}_{d_2}, \dots, \vec{A}_{d_r}$

where

$$A = \left[\begin{array}{c|c|c} \vec{A}_1 & \dots & \vec{A}_n \end{array} \right]$$

Example: $A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \end{bmatrix}$

Find a basis of $\mathcal{C}(A)$.

$$A \rightsquigarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix}$$

$$\rightsquigarrow \begin{array}{c} d_1=1 \quad d_2=2 \\ \left[\begin{array}{ccc} \boxed{1} & 0 & -1 \\ 0 & \boxed{1} & 2 \end{array} \right] = B \\ \text{RREF} \end{array}$$

\Rightarrow basis of $\mathcal{C}(A)$ is $\begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$.

Exercise: let $A = \begin{bmatrix} 1 & 0 & 2 \\ 1 & 1 & 3 \\ 0 & 1 & 1 \end{bmatrix}$

find a basis of $\mathcal{C}(A)$.

Answer: $A \xrightarrow{\text{RRZF}}$

$$\begin{bmatrix} \boxed{1} & 0 & \boxed{2} \\ 0 & \boxed{1} & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

$d_1=1 \quad d_2=2$

basis = $\{ \vec{A}_1, \vec{A}_2 \} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$.

Note: $\begin{bmatrix} 2 \\ 3 \\ 1 \end{bmatrix} = 2 \cdot \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

Recall, if $A \in M_{n \times n}$, then A is non-singular if and only if $\vec{A}_1, \dots, \vec{A}_n$ are a basis of \mathbb{R}^n .

Can deduce this from our theorem above:

\cap , \cap RRZF \cap \rightarrow

$$A \text{ non-singular} \Leftrightarrow A \begin{pmatrix} \vec{v}_1 \\ \vdots \\ \vec{v}_n \end{pmatrix} = I_n.$$

\Leftrightarrow all columns of RREF of A are pivots.

This shows that $\vec{A}_1, \dots, \vec{A}_n$ are a basis of $\mathcal{C}(A)$. Need to also show

$$\mathcal{C}(A) = \mathbb{R}^n \quad (\text{i.e. } A\vec{x} = \vec{v} \text{ is always consistent, for any } \vec{v} \in \mathbb{R}^n)$$



Row space of a matrix.

$$D. \text{ for } A, M \quad A = \begin{bmatrix} \vec{u}_1 \\ \vdots \\ \vec{u}_m \end{bmatrix}$$

Definition. Let $A \in \mathbb{R}^{m \times n}$. Then $A = \begin{bmatrix} \vec{u}_1 \\ \vdots \\ \vec{u}_m \end{bmatrix}$

then $R(A)$ (row space of A) is the span of $\vec{u}_1, \vec{u}_2, \dots, \vec{u}_m \in \mathbb{R}^n$.

i.e. $R(A) = \langle \{ \vec{u}_1, \dots, \vec{u}_m \} \rangle$.

Can reformulate in terms of the column space of a different matrix: Alternative definition: Let $A \in M_{mn}$.

The row space $R(A) = C(A^t)$.

Example: $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \\ 0 & 1 \end{bmatrix}$. $R(A) = C(A^t) \subset \mathbb{R}^2$
 $A^t = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix}$

$$A^t \xrightarrow{\text{RREF}} \begin{bmatrix} \boxed{1} & 1 & 0 \\ 0 & 0 & \boxed{1} \end{bmatrix} \quad d_1=1 \quad d_2=3.$$

$$\text{basis of } \mathcal{C}(A^t) = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} = \text{basis of } \mathcal{R}(A).$$

Theorem: Suppose A & B are row-equivalent.

$$\text{Then } \mathcal{R}(A) = \mathcal{R}(B).$$

Proof: Strategy of proof is to show that if B is obtained from A by a single row operation, then $\mathcal{R}(A) = \mathcal{R}(B)$. Then we can

deduce that if B is obtained from A by multiple row operations, $R(A) = R(B)$.

Recall: row operations are: 1) $R_i \rightarrow \alpha R_i$ $\alpha \neq 0$

$$2) R_i \rightarrow R_i + \alpha R_j$$

$$3) R_i \leftrightarrow R_j.$$

$$\text{Let } A = \begin{bmatrix} \hline \vec{u}_1^t \\ \vdots \\ \hline \vec{u}_m^t \end{bmatrix} \quad A^t = \left[\begin{array}{c|c} \vec{u}_1 \\ \dots \\ \vec{u}_n \end{array} \right]$$

Apply row operation of type 1) to A :

$$A \xrightarrow{1) } B = \begin{bmatrix} \hline \vec{u}_1^t \\ \vdots \end{bmatrix} \quad B^t = \left[\begin{array}{c|c} | \\ | \\ | \\ | \\ | \end{array} \right]$$

$$U = \begin{bmatrix} \vdots \\ \hline \alpha \vec{u}_i \\ \hline \vdots \\ \hline \vec{u}_m \end{bmatrix} \quad U = \begin{bmatrix} \vec{u}_1 & \dots & \alpha \vec{u}_i & \dots & \vec{u}_m \end{bmatrix}$$

Need to show $R(A) = R(B) \Leftrightarrow \mathcal{C}(A^t) = \mathcal{C}(B^t)$.

Let $\vec{v} \in \mathcal{C}(A^t)$, i.e. $\vec{v} = a_1 \vec{u}_1 + \dots + \alpha_i \vec{u}_i + \dots + \vec{u}_m$
(use $\alpha \neq 0$)

$$= a_1 \vec{u}_1 + \dots + \left(\frac{a_i}{\alpha} \right) (\alpha \vec{u}_i) + \dots + \vec{u}_m.$$

\swarrow col of A^t
 \searrow col of B^t

$\in \mathcal{C}(B^t)$.

Hence $R(A) \subset R(B)$.

Let $\vec{v} \in \mathcal{C}(B^t)$, i.e. $\vec{v} = a_1 \vec{u}_1 + \dots + a_i (\alpha \vec{u}_i) + \dots + \vec{u}_m$
 $= a_1 \vec{u}_1 + \dots + (a_i \alpha) \vec{u}_i + \dots + \vec{u}_m$

$$\in \mathcal{E}(A^t).$$

Hence $R(B) \subset R(A)$

$$\Rightarrow R(B) = R(A)$$

We now check that operations of type 2 preserve row spaces.

$$\text{let } A = \begin{bmatrix} \vec{u}_1^t \\ \vdots \\ \vec{u}_m^t \end{bmatrix} \quad A^t = \left[\begin{array}{c|c|c} \vec{u}_1 & \dots & \vec{u}_m \end{array} \right]$$

$$A \xrightarrow{R_i' = R_i + \alpha R_j} B = \begin{bmatrix} \vec{u}_1^t \\ \vdots \\ \vec{u}_i^t + \alpha \vec{u}_j^t \\ \vdots \end{bmatrix} \quad B^t = \left[\begin{array}{c|c|c} \vec{u}_1 & \dots & \vec{u}_i + \alpha \vec{u}_j & \dots \end{array} \right]$$

$$||L|| \quad ||R|| \quad \dots \quad ||R^t|| \quad ||R^t||$$

Want to show: $\mathcal{N}(A) = \mathcal{N}(B) \Leftrightarrow \mathcal{C}(A) = \mathcal{C}(B)$.

Suppose $\vec{v} \in \mathcal{C}(A^t)$; i.e. $\vec{v} = a_1 \vec{u}_1 + \dots + a_m \vec{u}_m$.

$$\vec{v} = a_1 \vec{u}_1 + \dots + a_j \vec{u}_j + \dots + \underline{a_i \vec{u}_i} + \dots + a_m \vec{u}_m$$

$$= a_1 \vec{u}_1 + \dots + a_j \vec{u}_j + \dots + a_i (\vec{u}_i + \underline{\alpha \vec{u}_j} - \underline{\alpha \vec{u}_j}) + \dots + a_m \vec{u}_m$$

$$= a_1 \vec{u}_1 + \dots + [a_j \vec{u}_j - \underline{a_i \alpha \vec{u}_j}] + \dots + a_i (\vec{u}_i + \alpha \vec{u}_j) + \dots + a_m \vec{u}_m$$

$$= a_1 \underline{\vec{u}_1} + \dots + (a_j - a_i \alpha) \underline{\vec{u}_j} + \dots + a_i (\underline{\vec{u}_i + \alpha \vec{u}_j}) + \dots + a_m \underline{\vec{u}_m}$$
$$\in \mathcal{C}(B^t)$$

Hence $\mathcal{C}(A^t) \subset \mathcal{C}(B^t)$.

$$\begin{aligned}
 \text{Let } \vec{v} \in \mathcal{C}(B^t), \quad \vec{v} &= a_1 \vec{u}_1 + \dots + a_j (\vec{u}_j + \alpha \vec{u}_j) + \dots + a_m \vec{u}_m \\
 &= a_1 \vec{u}_1 + \dots + a_j \vec{u}_j + a_j \alpha \vec{u}_j + \dots + a_m \vec{u}_m \\
 &= a_1 \vec{u}_1 + \dots + (a_j + a_j \alpha) \vec{u}_j + \dots + a_m \vec{u}_m \\
 &\in \mathcal{C}(A^t).
 \end{aligned}$$

$$\text{Hence } \mathcal{C}(B^t) \subset \mathcal{C}(A^t)$$

$$\text{Hence } \mathcal{C}(B^t) = \mathcal{C}(A^t).$$

Question: If A & B are row equivalent,

do we have $\mathcal{C}(A) = \mathcal{C}(B)$?

Answer: No. Example: Let $A = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \in M_{2,1}$

$$B = \begin{bmatrix} 1 \end{bmatrix} \in M_{2,1}.$$

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Then $A \xrightarrow{\text{RREF}} B$.

But $\mathcal{C}(A) = \langle \begin{bmatrix} 1 \\ 2 \end{bmatrix} \rangle \neq \mathcal{C}(B) = \langle \begin{bmatrix} 1 \\ 0 \end{bmatrix} \rangle$.

Basis of row space:

Theorem: Let $A \in M_{mn}$, $A \xrightarrow{\text{RREF}} B$.

Let S be the nonzero columns of B^t .

Then 1) $\mathcal{R}(A) = \langle S \rangle$.
2) S is linearly independent.

(so S forms a basis of $\mathcal{R}(A)$).

Ex. 1. 1. $A = \begin{bmatrix} 1 & 1 \\ 2 & 1 \end{bmatrix}$

Example: let $A = \begin{bmatrix} 1 & 2 \\ 1 & 0 \end{bmatrix}$

$$A \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & -1 \end{bmatrix} = B$$

$$B^t = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$S = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ is a basis of $R(A)$.

This produces a very nice basis of $R(A)$.

(basis vectors in S tend to have a lot of zeros).

We can use this theorem to give a new basis

of $\mathcal{C}(A)$ for any matrix $A \in M_{mn}$.

Theorem: $\mathcal{C}(A) = \mathcal{R}(A^t)$. (Recall: $\mathcal{R}(A) = \mathcal{C}(A)$).

Proof: Let $B = A^t$.

$$\mathcal{R}(B) = \mathcal{C}(B^t) \quad (\text{by definition}).$$

$$\text{But } B^t = (A^t)^t = A.$$

$$\text{So } \mathcal{R}(A^t) = \mathcal{C}(A) \quad \text{as desired.}$$

So, having expressed $\mathcal{C}(A)$ as $\mathcal{R}(A^t)$, can use our basis of $\mathcal{R}(A^t)$ to get a basis of $\mathcal{C}(A)$.

$\{ \dots \}$

Example: $H = \begin{bmatrix} 1 & 2 & 0 \end{bmatrix}$

Find basis of $C(A)$.

(equivalently, basis of $R(A^t)$).

$$A^t = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 0 & -1 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$$

So $\left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$ is a basis of $R(A^t)$
 $= C(A)$.