

Basis of a subspace

Definition: let $W \subset \mathbb{R}^n$ be a subspace.

let $\vec{u}_1, \dots, \vec{u}_n \in W$.

We say $\vec{u}_1, \dots, \vec{u}_n$ are a basis of W

if 1) $W = \langle \vec{u}_1, \dots, \vec{u}_n \rangle$

2) $\vec{u}_1, \dots, \vec{u}_n$ are linearly indep.

Example: let $W = \mathbb{R}^2$ let $\vec{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\vec{u}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

Claim: \vec{u}_1, \vec{u}_2 is a basis of W .

Proof: 1) let $\vec{v} \in \mathbb{R}^2 = W$.

if $1 + 1 = 2$ \rightarrow $1 - 1 = 0$

Want to show $v \in \langle \vec{u}_1, \vec{u}_2 \rangle$

\Leftrightarrow there exists $\vec{\alpha} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix}$ s.t.

$$\begin{bmatrix} \vec{u}_1 & | & \vec{u}_2 \end{bmatrix} \vec{\alpha} = \vec{v}.$$

i.e. $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}.$

nonsingular \rightarrow

Can pick $\alpha_1 = v_1$ $\alpha_2 = v_2$.

2) Want to show \vec{u}_1, \vec{u}_2
are linearly independent.

$$\Leftrightarrow \mathcal{N}(A) = \{0_2\}$$

where $A = \begin{bmatrix} \vec{u}_1 & | & \vec{u}_2 \end{bmatrix}.$

$A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ has nullspace

$$\{0\}$$

Hence \vec{u}_1, \vec{u}_2 is a basis of $W = \mathbb{R}^2$.

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Example 2: let $W = \mathbb{R}^2$, $\vec{u}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\vec{u}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

Claim: \vec{u}_1, \vec{u}_2 is a basis of W .

Proof: 1) Want to show that

$$\mathbb{R}^2 = \langle \vec{u}_1, \vec{u}_2 \rangle.$$

\Leftrightarrow for any $\vec{v} \in \mathbb{R}^2$,
there exists $\vec{\alpha} \in \mathbb{R}^2$ s.t.

$$\begin{bmatrix} \vec{u}_1 & | & \vec{u}_2 \end{bmatrix} \vec{\alpha} = \vec{v}$$

i.e. $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \vec{\alpha} = \vec{v}$.

Perform row reduction:

$$\begin{bmatrix} 1 & 0 & | & \vec{\alpha} \\ 1 & 1 & | & \vec{\alpha} \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & | & \vec{\alpha}' \\ 0 & 1 & | & \vec{\alpha}' \end{bmatrix}$$

Since there are no zero rows,

equation is consistent, i.e. there exists
a solution.

2) Want to show \vec{w}_1, \vec{w}_2 are linearly independent.

$$\Leftrightarrow \text{SDU}(A) = \{0_2\}$$

where $A = [\vec{w}_1 \mid \vec{w}_2] = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$.

Can check as before that this holds. (RREF has no zero rows).

Theorem: Let $W \subset \mathbb{R}^m$ be a subspace,

and let $\vec{u}_1, \dots, \vec{u}_n$ be a basis.

Then given $\vec{v} \in W$, there exist unique

$\alpha_1, \dots, \alpha_n \in \mathbb{R}$ s.t.

$$\vec{v} = \alpha_1 \vec{u}_1 + \dots + \alpha_n \vec{u}_n.$$

Proof: To show existence of $\alpha_1, \dots, \alpha_n$, use
that $W = \langle \vec{u}_1, \dots, \vec{u}_n \rangle$.

To show uniqueness:

$$\begin{aligned} \text{Suppose } \vec{v} &= \alpha_1 \vec{u}_1 + \dots + \alpha_n \vec{u}_n \\ &= \beta_1 \vec{u}_1 + \dots + \beta_n \vec{u}_n \end{aligned}$$

where $\alpha_i, \beta_i \in \mathbb{R}$.

$$\begin{aligned} \text{Then } \underline{\alpha_m} \vec{v} - \vec{v} &= (\alpha_1 \vec{u}_1 + \dots + \alpha_n \vec{u}_n) \\ &\quad - (\beta_1 \vec{u}_1 + \dots + \beta_n \vec{u}_n) \\ &= \underline{(\alpha_1 - \beta_1) \vec{u}_1 + \dots + (\alpha_n - \beta_n) \vec{u}_n} \end{aligned}$$

By linear independence of $\vec{u}_1, \dots, \vec{u}_n$,
this implies $\alpha_1 - \beta_1 = 0$, $\alpha_2 - \beta_2 = 0$, \dots , $\alpha_n - \beta_n = 0$.

$$\Leftrightarrow \alpha_1 = \beta_1, \quad \alpha_2 = \beta_2, \quad \dots, \quad \alpha_n = \beta_n$$

This proves uniqueness.

The theorem allows us to label vectors
 $\vec{v} \in W$ by $\alpha_1, \dots, \alpha_n \in \mathbb{R}$, the scalars appearing
in $\vec{v} = \alpha_1 \vec{u}_1 + \dots + \alpha_n \vec{u}_n$.

Let $A \in M_{mn}$. We can find a basis of the
nullspace of A $N(A) \subset \mathbb{R}^n$ as follows:

Step 1) : If $A \xrightarrow{\text{RREF}} B$

$$N(A) = N(B).$$

So we will calculate ↗

2) let $B = \begin{bmatrix} \textcircled{1} & \textcircled{2} & \textcircled{3} \\ 0 & 1 & * & 0 & 0 & * \\ 0 & 0 & 0 & 1 & 0 & * \\ 0 & 0 & 0 & 0 & 1 & * \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

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Let $r = \#$ of pivots (= rank of B).

We will find a basis $\vec{u}_1, \dots, \vec{u}_{n-r}$ of

$N(B)$.

To calculate \vec{u}_i , consider i^{th} pivotless

column. look for \vec{u}_i of the form

$$\vec{u}_i = \begin{bmatrix} 0 \\ * \\ 0 \\ * \\ * \\ 0 \end{bmatrix} - \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \leftarrow i^{\text{th}} \text{ row.}$$

nonzero only in places corresponding
to pivot columns

There is a unique such vector in $N(A)$.

Theorem: $\vec{u}_1, \dots, \vec{u}_{n-r}$ form a basis of nullspace.

Earlier, we described $N(A)$ by sets like

$$\left\{ \begin{bmatrix} a \\ a+b \\ b \\ a \end{bmatrix}, a, b \in \mathbb{R} \right\}.$$

Now we think of this as

$$\left\{ a \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + b \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, a, b \in \mathbb{R} \right\}.$$

$\nearrow \vec{u}_1 \quad \nearrow \vec{u}_2$ basis

Definition: Let $A \in M_{mn}$.

The column space of A
(sometimes called the span of A)
is the set of all vectors $\vec{x} \in \mathbb{R}^m$
of the form $A\vec{v}$ for some $\vec{v} \in \mathbb{R}^n$.

Equivalently, if $A = [\vec{u}_1 | \dots | \vec{u}_n]$,

column space = $\langle \vec{u}_1, \dots, \vec{u}_n \rangle$.

Question: let $A = \begin{bmatrix} 1 & 0 & 1 \\ 3 & 0 & 3 \\ 2 & 1 & 3 \end{bmatrix}$.

Find a basis of the column space of A .