

4. Numerical Methods.

$$(P) \quad \min_{x \in K} f(x) \quad K \subseteq \mathbb{R}^n. \rightarrow K := \left\{ x \in \mathbb{R}^n : \begin{array}{l} g_i(x) \leq 0 \\ h_j(x) = 0 \end{array} \right\}$$

K is a closed set.

4.1. Gradient projection.


Definition: Let $K \subseteq \mathbb{R}^n$ be a closed set, we say x^* is a projection of point $y \in \mathbb{R}^n$ to the set K if $x^* \in K$ is a solution to

$$\min_{x \in K} \|x - y\|^2$$

Proposition: If K is a convex closed subset in \mathbb{R}^n , then there exists a unique projection of y to K , denoted by $\Pi_K(y)$.

Moreover, $\Pi_K(y)$ is the unique point in K satisfying.

$$\langle y - \Pi_K(y), z - \Pi_K(y) \rangle \leq 0, \quad \forall z \in K.$$

And, $\|\Pi_K(y_1) - \Pi_K(y_2)\| \leq \|y_1 - y_2\| \quad \forall y_1, y_2 \in \mathbb{R}^n.$ 

Proof: ① $x \mapsto \|x-y\|^2$ is strictly convex.

If x_1, x_2 be two different solutions to $\min_{x \in K} \|x-y\|^2$.

then $x_3 := \frac{x_1+x_2}{2} \in K$ will satisfy $\|x_3-y\|^2 < \frac{\|x_1-y\|^2 + \|x_2-y\|^2}{2}$.

which is a contradiction!

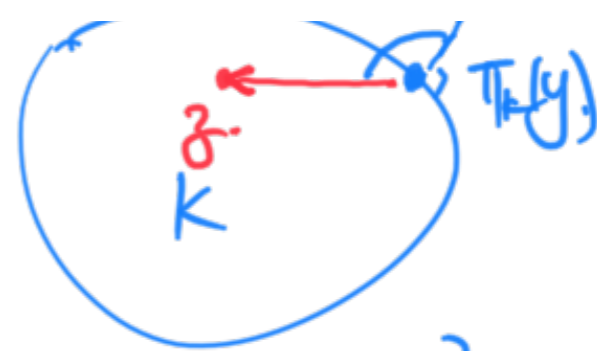
So $\min_{x \in K} \|x-y\|^2$ has a unique solution.

② $\forall z \in K$, then $tz + (1-t)\pi_K(y) \in K$, $t \in [0,1]$.

$$\Rightarrow \|\cancel{y - \pi_K(y)}\|^2 \leq \|y - \underbrace{(tz + (1-t)\pi_K(y))}_{\in K}\|^2.$$

$$\Rightarrow \|\cancel{y - \pi_K(y)}\|^2 - 2t \langle y - \pi_K(y), z - \pi_K(y) \rangle + t^2 \|z - \pi_K(y)\|^2.$$

$$\Rightarrow 2t \langle y - \pi_K(y), z - \pi_K(y) \rangle \leq t^2 \|z - \pi_K(y)\|^2 \quad \forall t \in (0,1]$$



$$\Rightarrow \langle y - \pi_K(y), z - \pi_K(y) \rangle \leq \frac{t}{2} \|z - \pi_K(y)\|^2, \quad \forall t \in (0, 1]$$

$$\Rightarrow \langle y - \pi_K(y), z - \pi_K(y) \rangle \leq 0.$$

2.2. If $x^* \in K$ satisfies $\langle y - x^*, z - x^* \rangle \leq 0 \quad \forall z \in K.$

Then: $\forall z \in K, \|y - z\|^2 - \|y - x^*\|^2 = \|y - x^* + x^* - z\|^2 - \|y - x^*\|^2$

$$\Rightarrow \boxed{x^* = \pi_K(y)} \quad = 2 \langle y - x^*, x^* - z \rangle + \|x^* - z\|$$

$$= -2 \langle y - x^*, z - x^* \rangle + \|x^* - z\|$$

$$\geq 0. \quad \forall z \in K.$$

3. $\| \pi_K(y_1) - \pi_K(y_2) \|^2$

$$= \langle \pi_K(y_1) - \pi_K(y_2), \pi_K(y_1) - \pi_K(y_2) \rangle$$

$$\leq \langle y_1 - y_2, \pi_K(y_1) - \pi_K(y_2) \rangle$$

$\rightarrow z \in K.$

$$\langle y_1 - \pi_K(y_1), \pi_K(y_2) - \pi_K(y_1) \rangle \leq 0$$

$$\langle y_2 - \pi_K(y_2), \pi_K(y_1) - \pi_K(y_2) \rangle \leq 0$$

$\rightarrow z \in K$

Cauchy-Schwarz.

$$\leq \|y_1 - y_2\| \| \pi_K(y_1) - \pi_K(y_2) \|$$

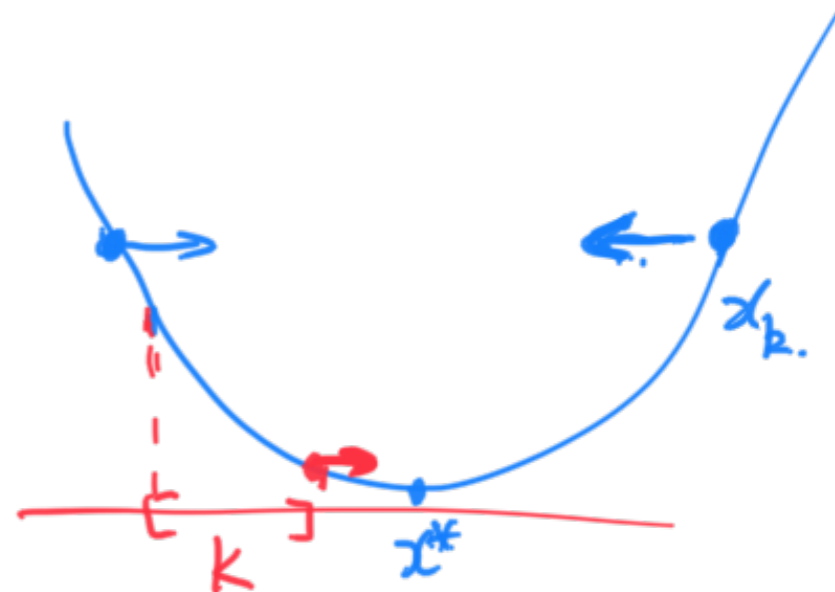
$$\leq \|y_1 - y_2\| \| \pi_K(y_1) - \pi_K(y_2) \|$$

$$\|y_1 - y_2\| \cdot \|\pi_K(y_1) - \pi_K(y_2)\|$$

$$\|y_2 - \pi_K(y_2)\|, \|\pi_K(y_2) - \pi_K(y_1)\| \leq 0$$

$$\Rightarrow \|\pi_K(y_1) - \pi_K(y_2)\| \leq \|y_1 - y_2\| \quad \#$$

Algorithm: $x_{k+1} = \pi_K(x_k - \rho \nabla f(x_k))$



Theorem, Assume that K is closed convex subset of \mathbb{R}^n .

$f: \mathbb{R}^n \rightarrow \mathbb{R} \in C^2$ and $\text{Hess}(f) \geq \alpha I_n$ for some $\alpha > 0$.

And ∇f is Lipschitz.

with Lipschitz constant $M > 0$.

Moreover, $\rho \in (0, \frac{2\alpha}{M^2})$.

$$\begin{pmatrix} \partial_{x_1 x_1}^2 f & & \\ & \dots & \\ & & \partial_{x_n x_n}^2 f \end{pmatrix}$$

f is strictly convex.
Coercive.

Then: $x_k \rightarrow x^*$, where x^* is the unique solution to $\min_{x \in K} f(x)$

Lemma: In the context of the theorem, one has

$$\underline{\langle \nabla f(y) - \nabla f(x^*), y - x^* \rangle \geq \alpha \|y - x^*\|}$$

$$\text{and: } \underline{\Pi_K(x^* - \rho \nabla f(x^*)) = x^*}$$

$$\text{Proof: } \textcircled{1} \text{ Let } \phi(t) \stackrel{\Delta}{=} \langle \nabla f(ty + (1-t)x^*), y - x^* \rangle = \begin{cases} \langle \nabla f(y), y - x^* \rangle & t=1 \\ \langle \nabla f(x^*), y - x^* \rangle & t=0 \end{cases}$$

$t \in [0, 1]$

$$\Rightarrow \langle \nabla f(y) - \nabla f(x^*), y - x^* \rangle = \phi(1) - \phi(0) = \int_0^1 \phi'(t) dt \geq \alpha \|y - x^*\|^2$$

Since

$$\begin{aligned} \phi'(t) &= \langle \text{Hess}(f) \cdot (ty + (1-t)x^*) (y - x^*)^T, y - x^* \rangle \\ &\geq \alpha \langle I_n (y - x^*)^T, y - x^* \rangle = \alpha \|y - x^*\|^2 \end{aligned}$$

$\textcircled{2}$ Notice that x^* is the solution of $\min_{x \in K} f(x)$.

Then, for any $z \in K$, $(1-t)x^* + tz \in K \quad \forall t \in [0, 1]$

$$\Rightarrow f((1-t)x^* + tz) - f(x^*) \geq 0$$



taking the limit $t \downarrow 0$.

$$\Rightarrow \rho \langle \nabla f(x^*), \cancel{y} - x^* \rangle \geq 0$$

$$\Rightarrow \forall \cancel{y} \in K, \quad \left\langle \underbrace{(x^* - \rho \nabla f(x^*))}_y - x^*, \cancel{y} - x^* \right\rangle \leq 0, \quad \forall \cancel{y} \in K.$$

$$\Rightarrow x^* = \Pi_K(y) = \Pi_K(x^* - \rho \nabla f(x^*)). \quad \#$$

Proof of Theorem: $\|x_{k+1} - x^*\|^2 = \|\Pi_K(x_k - \rho \nabla f(x_k)) - x^*\|^2.$

$$= \|\Pi_K(x_k - \rho \nabla f(x_k)) - \Pi_K(x^* - \rho \nabla f(x^*))\|^2.$$

$$\leq \| \underbrace{(x_k - \rho \nabla f(x_k))} - \underbrace{(x^* - \rho \nabla f(x^*))} \|^2$$

$$\|\Pi_K(y_1) - \Pi_K(y_2)\| \leq \|y_1 - y_2\|$$

$$= \| \underbrace{(x_k - x^*) - \rho(\nabla f(x_k) - \nabla f(x^*))} \|^2$$

$$\|y_1 - y_2\|^2 = \|y_1\|^2 - 2\langle y_1, y_2 \rangle + \|y_2\|^2$$

$$= \|x_k - x^*\|^2 - 2\rho \langle x_k - x^*, \nabla f(x_k) - \nabla f(x^*) \rangle + \rho^2 \|\nabla f(x_k) - \nabla f(x^*)\|^2$$

$$\leq \underbrace{(1 - 2\rho\alpha + \rho^2 M^2)}_{\geq \alpha \|x_k - x^*\|^2} \|x_k - x^*\|^2 \leq M^2 \|x_k - x^*\|^2.$$

$$\Rightarrow \|x_{k+1} - x^*\|^2 \leq \beta^{k+1} \|x_0 - x^*\|^2.$$

$\rightarrow 0$ as $k \rightarrow +\infty$ #

$$\beta := 1 - 2\rho\alpha + \rho^2 M^2 < 1$$

since $\rho < \frac{2\alpha}{M^2} \Leftrightarrow \rho^2 M^2 < 2\rho\alpha$.

Remark: The convergence rate is $C \cdot \beta^k$, where k is the number of iteration.

4.2. Uzawa Algorithm. (Affine equality constraints.)

$$(P) \quad \min_{\{x: Ax=b\}} f(x).$$

$$K = \{x \in \mathbb{R}^n: Ax=b\}.$$

A is matrix $m \times n$. $m \leq n$.

$b \in \mathbb{R}^m$.

$$\text{Rank}(A) = m.$$

$f: \mathbb{R}^n \rightarrow \mathbb{R}$ convex. $\in C^1$.

$$(D) \quad \max_{\lambda \in \mathbb{R}^m} d(\lambda)$$

$$\text{where } d(\lambda) = \min_{x \in \mathbb{R}^n} (f(x) + \langle \lambda, Ax - b \rangle)$$

Algorithm of Uzawa:

$$\lambda_{k+1} = \lambda_k + \rho \nabla d(\lambda_k)$$

$$= \lambda_k + \rho (Ax_k - b)$$

$$x_k \text{ is solution to } \underline{d(\lambda_k)} = \min_{x \in \mathbb{R}^n} (f(x) + \langle \lambda_k, Ax - b \rangle)$$

Remark: $\lambda \mapsto f(x) + \langle \lambda, Ax - b \rangle$ is affine.

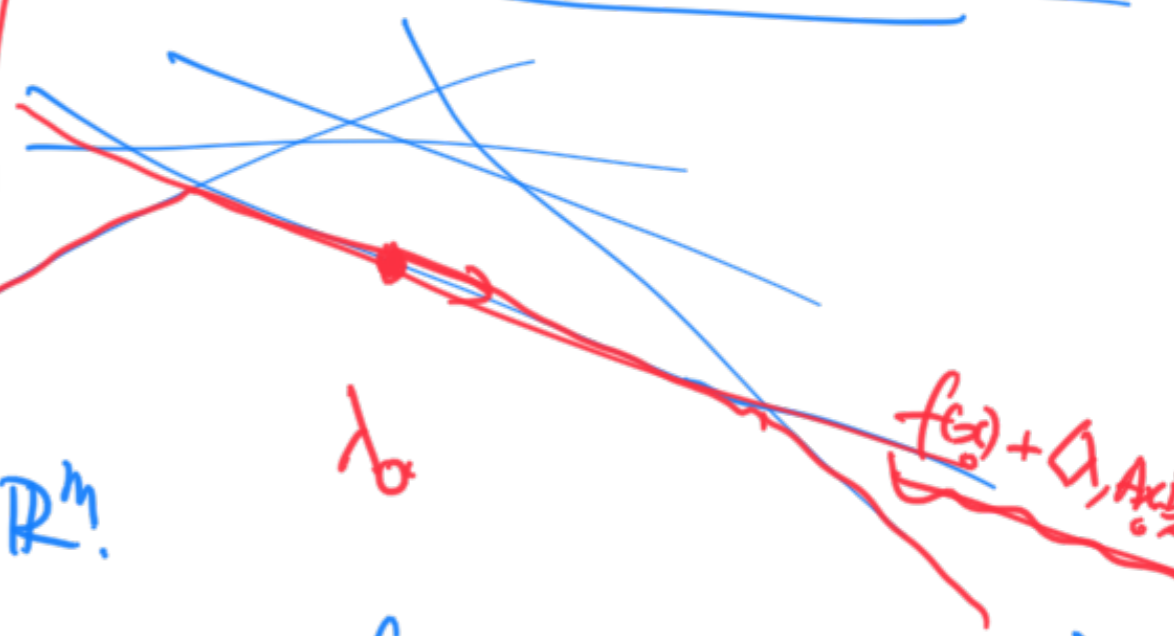
so $\lambda \mapsto d(\lambda)$ is concave.

Lemma: Assume that d is differentiable at $\lambda_0 \in \mathbb{R}^m$.

and $x_0 \in \mathbb{R}^n$ be a solution to $d(\lambda_0) = \min_{x \in \mathbb{R}^n} (f(x) + \langle \lambda_0, Ax - b \rangle)$

Then: $\nabla d(\lambda_0) = Ax_0 - b$

Proof: Take $v \in \mathbb{R}^m$, $h > 0$.



$$\begin{aligned}
 \underline{d(\lambda_0 + h v)} &\leq \underline{f(x_0) + \langle \lambda_0 + h v, A x_0 - b \rangle} \\
 &= \underline{f(x_0) + \langle \lambda_0, A x_0 - b \rangle} + h \langle v, A x_0 - b \rangle \\
 &= d(\lambda_0) + h \langle v, A x_0 - b \rangle
 \end{aligned}$$

$$\Rightarrow \frac{d(\lambda_0 + h v) - d(\lambda_0)}{h} \geq \langle v, A x_0 - b \rangle$$

$$h \downarrow 0 \Rightarrow \left. \begin{aligned}
 \langle \nabla d(\lambda_0), v \rangle &\geq \langle v, A x_0 - b \rangle \\
 \langle \nabla d(\lambda_0), -v \rangle &\geq \langle -v, A x_0 - b \rangle
 \end{aligned} \right\} \Rightarrow \nabla d(\lambda_0) = A x_0 - b. \quad \#$$

Theorem: Assume that f is convex and $\text{Hess}(f) \geq \alpha I_d$ for some $\alpha > 0$.
 and let $\rho \in (0, \frac{2\alpha}{\|A\|^2})$. with $\|A\|^2 := \max_{\|x\|=1} x^T A^T A x$.

then: ① $x_k \rightarrow x^*$.

② $\lambda_k \rightarrow \lambda^*$ (λ^* is solution to $\max_{\lambda \in \mathbb{R}^m} d(\lambda)$)

Proof: ① Let x^* be the solution of (P). and λ^* be such that.

$$\nabla f(x^*) + A^T \lambda^* = 0.$$

$$Ax^* = b.$$

$$\Leftrightarrow A \nabla f(x^*) + \underbrace{AA^T}_{\text{Hessian}} \lambda^* = 0$$

$$\Leftrightarrow \lambda^* = -\underbrace{(AA^T)^{-1}}_{\text{Hessian}^{-1}} A \nabla f(x^*)$$

Given λ_k , x_k is solution to $\min_{x \in \mathbb{R}^n} f(x) + \langle \lambda_k, Ax - b \rangle$

$$\Rightarrow \nabla f(x_k) + A^T \lambda_k = 0 \quad (\text{first order necessary condition})$$

$$\Rightarrow \nabla f(x_k) - \nabla f(x^*) + A^T (\lambda_k - \lambda^*) = 0$$

$$\textcircled{2} \quad \lambda_{k+1} - \lambda^* = \lambda_k + \rho(Ax_k - b) - \lambda^*.$$

$$= \lambda_k - \lambda^* + \rho A(x_k - x^*)$$

$$\leftarrow (b = Ax^*)$$

$$\Rightarrow \|\lambda_{k+1} - \lambda^*\|^2 = \|\lambda_k - \lambda^* + \rho A(x_k - x^*)\|^2$$

$$\| \lambda_k - \lambda^* \|^2 + 2\rho \langle \lambda_k - \lambda^*, A(x_k - x^*) \rangle + \rho^2 \|A(x_k - x^*)\|^2$$

$$\approx \| \lambda_k - \lambda^* \|^2 + \underbrace{2\rho \langle A^T(\lambda_k - \lambda^*), x_k - x^* \rangle}_{\geq \alpha \|x_k - x^*\|^2} + \underbrace{\rho^2 \|A\|^2 \|x_k - x^*\|^2}_{> 0}$$

$$= \| \lambda_k - \lambda^* \|^2 - \underbrace{2\rho \langle \nabla f(x_k) - \nabla f(x^*), x_k - x^* \rangle}_{\geq \alpha \|x_k - x^*\|^2} + \rho^2 \|A\|^2 \|x_k - x^*\|^2$$

$$\leq \underbrace{\| \lambda_k - \lambda^* \|^2}_{> 0} - \underbrace{(2\rho\alpha - \rho^2 \|A\|^2)}_{> 0} \|x_k - x^*\|^2$$

$$\Rightarrow \left(\| \lambda_{k+1} - \lambda^* \|^2 \right)_{k \geq 1} \text{ is decreasing.} \Rightarrow \| \lambda_{k+1} - \lambda^* \|^2 \xrightarrow{k \rightarrow +\infty} C$$

$$\Rightarrow \underbrace{\| \lambda_k - \lambda^* \|^2 - \| \lambda_{k+1} - \lambda^* \|^2}_{> 0} \rightarrow 0 \text{ as } k \rightarrow +\infty$$

$$\Rightarrow \underbrace{(2\rho\alpha - \rho^2 \|A\|^2)}_{> 0} \|x_k - x^*\|^2 \leq \| \lambda_k - \lambda^* \|^2 - \| \lambda_{k+1} - \lambda^* \|^2 \rightarrow 0$$

$$\Rightarrow \|x_k - x^*\|^2 \rightarrow 0 \text{ as } k \rightarrow +\infty$$

③ Remember: $\lambda_k = -(AA^T)^{-1} A \nabla f(x_k) \rightarrow -(AA^T)^{-1} A \nabla f(x^*)$
 \parallel
 λ^*

$\Rightarrow \nabla d(\lambda^*) = Ax^* - b = 0.$

$\Rightarrow \lambda^*$ is a solution to $\max_{\lambda \in \mathbb{R}^m} d(\lambda)$ #

4.3. Gradient Algorithm for optimization without constraint.

$\min_{x \in \mathbb{R}^n} f(x).$

f is convex.

$\Rightarrow \nabla f(x)$ is a subgradient.

Algo: - $x_{k+1} = \left(x_k - \rho_k \nabla f(x_k) \right)$

~~$\text{Hess}(f) \succeq \alpha I_n$~~

Assumption: ①. $\sum_{k=1}^{+\infty} \rho_k = +\infty$, $\left(\sum_{k=1}^{+\infty} \rho_k^2 < +\infty \right)$, $\rho_k > 0 \cdot \forall k$

$$(2) \quad \underline{\| \nabla f \|_{\infty} < +\infty.}$$

$$\underline{\langle x - x^*, \nabla f(x) \rangle > 0 \quad \forall x \neq x^*}$$

∇f is continuous.

$$k \rightarrow +\infty$$

Theorem: $x_k \rightarrow x^*$ as

$$\begin{aligned} \text{Proof: } (1) \quad \|x_{k+1} - x^*\|^2 &= \|x_k - x^* - f_k \nabla f(x_k)\|^2 \\ &= \|x_k - x^*\|^2 - \underbrace{2 f_k \langle x_k - x^*, \nabla f(x_k) \rangle}_{> 0} + f_k^2 \|\nabla f(x_k)\|^2 \\ &\leq \|x_k - x^*\|^2 + \underbrace{f_k^2 \|\nabla f\|_{\infty}} \end{aligned}$$

$$\Rightarrow y_k := \|x_k - x^*\| - \sum_{i=1}^k f_i^2 \|\nabla f\|_{\infty} \downarrow \text{ in } k.$$

$$\text{and } y_k \geq 0 - \underbrace{\left(\sum_{i=1}^{\infty} f_i^2 \right) \|\nabla f\|_{\infty}} > -\infty \quad \forall k.$$

$$\Rightarrow y_k \rightarrow y_{\infty} \in \mathbb{R}.$$

Besides:
$$d_k = \|x_k - x^*\| - \frac{\sum_{i=1}^k p_i^2 \| \nabla f \|_\infty}{\sum_{i=1}^k p_i^2 \| \nabla f \|_\infty} \Rightarrow \|x_k - x^*\|^2 \rightarrow l \in \mathbb{R}.$$

And
$$\sum_{i=1}^k p_i^2 \| \nabla f \|_\infty \rightarrow \sum_{i=1}^{\infty} p_i^2 \| \nabla f \|_\infty$$

② It is enough to prove that $l = 0$.

If $l > 0$ \emptyset

Then
$$\eta := \min_{\frac{l}{2} \leq \|x - x^*\|^2 \leq 2l} \langle x - x^*, \nabla f(x) \rangle > 0$$

Since $\|x_k - x^*\|^2 \rightarrow l$, then for k large enough, one has

$$\frac{l}{2} \leq \|x_k - x^*\|^2 \leq 2l$$

$$\Rightarrow \sum_{k=1}^{\infty} p_k \underbrace{\langle x_k - x^*, \nabla f(x_k) \rangle}_{\geq \eta} \geq \eta \cdot \underbrace{\left(\sum_{k=1}^{\infty} p_k \right)}_{= +\infty} = +\infty$$

However,
$$\sum_{k=1}^{\infty} p_k \langle x_k - x^*, \nabla f(x_k) \rangle = -\sum_{k=1}^{\infty} p_k \dots$$

$k \geq 1$

$\sum_{k \geq 1} (\rho_k - \rho, \alpha_{k+1} - \alpha_k)$

(since $\alpha_{k+1} - \alpha_k = -\rho \nabla f(\alpha_k)$)

$$= -\frac{1}{2} \sum_{k \geq 1} \left(\underbrace{\|\alpha_{k+1} - \alpha^*\|^2}_{\text{circled}} - \|\alpha_k - \alpha^*\|^2 - \underbrace{\|\alpha_{k+1} - \alpha_k\|^2}_{\text{underlined}} \right)$$

$$= \frac{1}{2} \sum_{k \geq 1} \left(\rho_k^2 \|\nabla f(\alpha_k)\|^2 - \rho + \|\alpha_0 - \alpha^*\|^2 \right) \quad \leftarrow \text{A 60}$$

Contradiction!

$$\Rightarrow \rho = 0.$$

$$\Rightarrow \|\alpha_k - \alpha^*\|^2 \rightarrow 0.$$

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