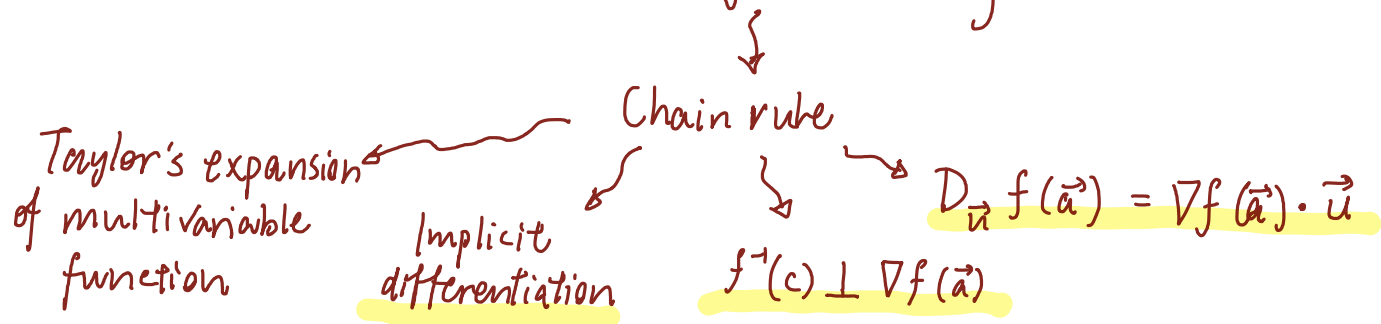


Tutorial 9

(Total) differentiability



(try to think about the "meaning" of each \rightsquigarrow)

① Let $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ be a function (totally) differentiable at the point $(1, 2)$. The (directional) derivative of f at $(1, 2)$ in the direction of $\hat{i} + \hat{j}$ is $2\sqrt{2}$ and that in the direction of $-2\hat{j}$ is -3 . What is the (directional) derivative of f in the direction of $-\hat{i} - 2\hat{j}$?

Ans: Since f is (totally) differentiable at $(1, 2)$,

$$\nabla f(1, 2) = \left(\frac{\partial f}{\partial x}(1, 2), \frac{\partial f}{\partial y}(1, 2) \right) \text{ exists.}$$

$$\text{Let } x_0 := \frac{\partial f}{\partial x}(1, 2) \text{ and } y_0 := \frac{\partial f}{\partial y}(1, 2).$$

Again, by (total) differentiability of f , we have

$$D_{\frac{(1,1)}{\|(1,1)\|}} f(1,2) = \nabla f(1,2) \cdot \left(\frac{(1,1)}{\|(1,1)\|} \right)$$

$$\text{and } D_{\frac{(0,-2)}{\|(0,-2)\|}} f(1,2) = \nabla f(1,2) \cdot \left(\frac{(0,-2)}{\|(0,-2)\|} \right), \text{ which gives}$$

$$\begin{cases} 2\sqrt{2} = (x_0, y_0) \cdot \frac{(1,1)}{\sqrt{2}} \\ -3 = (x_0, y_0) \cdot \frac{(0,-2)}{2} \end{cases} \iff \begin{cases} 4 = x_0 + y_0 \\ -3 = -y_0 \end{cases} \therefore \nabla f(1,2) = (1, 3)$$

$$\therefore D_{\frac{(-1,-2)}{\|(-1,-2)\|}} f(1,2) = (1, 3) \cdot \frac{(-1,-2)}{\|(-1,-2)\|} = \frac{-1-6}{\sqrt{5}} = \frac{-7}{\sqrt{5}} //$$

Remark for Q.1:



Imagine you're walking on a hill whose surface can be modeled by a (totally) differentiable surface.

If you know the slopes in any two non-parallel directions, then you'll probably know the slope along all other directions.

② Consider the following equation:

$$xe^y + \sin(xy) + y - \ln 2 = 0$$

(a) Why can we talk about $\frac{dy}{dx}$ at a point $(0, \ln 2)$?

(b) Find $\frac{dy}{dx}$ at the point $(0, \ln 2)$.

Before discussing the answer, let me state two important results in advanced calculus.

Inverse Function Theorem: Suppose $f: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is C^1 in an open set containing a , and $\det(Df(a)) \neq 0$.

Then there exist open $V \ni a$ and open $W \ni f(a)$ such that $f: V \rightarrow W$ has a continuous inverse $f^{-1}: W \rightarrow V$ which is differentiable and $\forall y \in W, D(f^{-1})(y) = Df(f^{-1}(y))^{-1}$.

Implicit Function Theorem: Suppose $f: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}^m$ is C^1 in an open set containing (a, b) and $f(a, b) = 0$. Let M be the $m \times m$ matrix $\left(\frac{\partial f_i}{\partial x_{n+j}}(a, b) \right)$. If $\det M \neq 0$, then there exist open $A \ni a$ and open $B \ni b$ such that $\forall x \in A, \exists! g(x) \in B$ such that $f(x, g(x)) = 0$ and g is differentiable.

Ans: 2(a) Let $f: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$ be defined as

$$f(x, y) := x e^y + \sin(xy) + y - \ln(2).$$

Since f is continuously differentiable on $\mathbb{R} \times \mathbb{R}$ and $f(0, \ln 2) = 0$, and

$$\frac{\partial f}{\partial y} = x e^y + x \cos(xy) + 1$$

is not zero at $(0, \ln 2)$, it follows from Implicit Function Theorem that there exist open sets A and B in \mathbb{R} with $0 \in A$ and $\ln 2 \in B$ such that $y: A \rightarrow B$ is a differentiable function.

Therefore, $\frac{dy}{dx}$ exists on A .

2(b) From (a), we may define a function $h: A \rightarrow \mathbb{R}$ by

$$h(x) = x e^{y(x)} + \sin(x \cdot y(x)) + y(x) - \ln(2),$$

such that $h(x) \equiv 0$.

Applying Chain Rule,

$$0 = \frac{dh}{dx}$$

$$= \left[e^y + x e^y \frac{dy}{dx} \right] + \cos(x \cdot y) \cdot \left[x \frac{dy}{dx} + y \right] + \frac{dy}{dx}$$

$$= (x e^y + x \cos(xy) + 1) \frac{dy}{dx} + y \cos(xy) + e^y$$

$$\therefore \left. \frac{dy}{dx} \right|_{(x,y)=(0, \ln 2)} = \frac{-\ln 2 - 2}{1} = -(2 + \ln 2) \equiv$$

③ Recall the following thm in Week 9 lecture notes:

Let Ω be an open subset of \mathbb{R}^n . Let $f: \Omega \rightarrow \mathbb{R}$ be a function. Let $c \in \mathbb{R}$. Let $S := f^{-1}(c)$ and $a \in S$. Suppose f is differentiable at a , and $\nabla f(a) \neq 0$. Then $\nabla f(a) \perp S$ at a .

(a) Is $S := f^{-1}(c)$ a surface?

(Actually how is a "surface" defined?)

(b) Let $f: \mathbb{R}^3 \rightarrow \mathbb{R}$ be defined as $f(x, y, z) = 2z - x^2$.

Let $P_0 := (2, 0, 2)$.

(i) Show that $f^{-1}(0)$ is a "surface".

(ii) Find equation of tangent plane to the surface at P_0 .

Ideas: 3(a) Let me try to rephrase a lemma on P.11 of Milnor's Topology from the Differentiable Viewpoint:

If $f: \mathbb{R}^m \rightarrow \mathbb{R}$ is smooth and if $y \in \mathbb{R}$ is a regular value,

(i.e. $\forall x \in f^{-1}(y), Df(x) \neq \vec{0}$)

then the set $f^{-1}(y) \subseteq \mathbb{R}^m$ is a smooth manifold of ("surface")

dimension $(m-1)$. (Pf: use Inverse Function Theorem)

3(b)(i) f is a polynomial function, which is smooth

Let $(x, y, z) \in f^{-1}(0)$. $Df(x, y, z) = (-2x, 0, 2) \neq \vec{0}$.

By the above lemma, $f^{-1}(0)$ is indeed a "surface".

(ii) $\nabla f(2, 0, 2) = Df(2, 0, 2) = (-4, 0, 2)$

Since f is differentiable at $(2, 0, 2)$ and $\nabla f(2, 0, 2) \neq 0$, we have $\nabla f(2, 0, 2) \perp f^{-1}(0)$. $\therefore -4(x-2) + 2(z-2) = 0$,