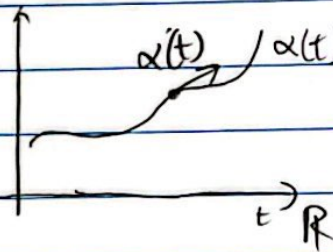
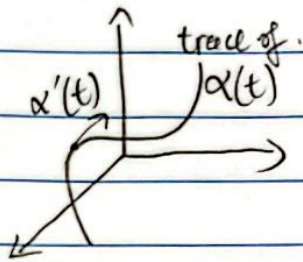
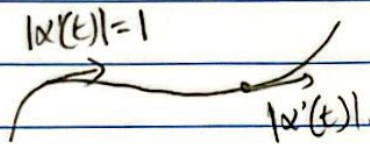


Curves in  $\mathbb{R}^3$ :  $\alpha: I \subset \mathbb{R} \rightarrow \mathbb{R}^3$  smooth.

"sets in  $\mathbb{R}^3$  that are one-dimensional" (later, we'll want to study sets in  $\mathbb{R}^3$  that are "two-dim" i.e. surfaces)



Parametrization by arc-length: curve is going at constant speed.

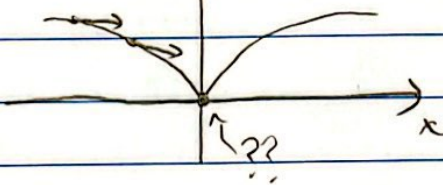


Can think of it as a normalization.

Often, our results won't depend on choice of parametrization, so when calculating, this is always a convenient choice.

Regularity: Essentially want a tangent vector at every point. (i.e. a 1-dim tangent space at each pt.)

$$\Leftrightarrow \alpha'(t) \neq 0 \quad \forall t \in \mathbb{R}.$$



$$\alpha: \mathbb{R} \rightarrow \mathbb{R}^2 \text{ by } \alpha(t) = (t^3, t^2), \quad t \in \mathbb{R}.$$

↑  
component f<sub>i</sub>'s are smooth,  
but still admits a singular point.

do (anno 1-2.5):  $\alpha: I \rightarrow \mathbb{R}^3$  regular curve. Show that  $|\alpha(t)|$  is a nonzero constant iff  $\alpha(t)$  orthogonal to  $\alpha'(t)$ .  $\forall t \in I$ .

Pf:  $\Rightarrow$  Suppose  $|\alpha(t)| \equiv C$  const. Then  $C = |\alpha(t)| = \sqrt{\alpha(t) \cdot \alpha(t)} \Leftrightarrow C^2 = \alpha(t) \cdot \alpha(t)$ .

$\Leftrightarrow \frac{d}{dt} \alpha(t) \cdot \alpha(t) = \frac{d}{dt} C^2 = 0$ . But LHS =  $2\alpha'(t) \cdot \alpha(t) \Rightarrow \alpha \perp \alpha' \forall t$ .

$\Leftarrow$  Now suppose  $\alpha \perp \alpha' \forall t$ , then  $2\alpha'(t) \cdot \alpha(t) = 0 \Leftrightarrow \frac{d}{dt} |\alpha(t)| = 0 \Rightarrow |\alpha(t)|$  is constant  $\checkmark$ .

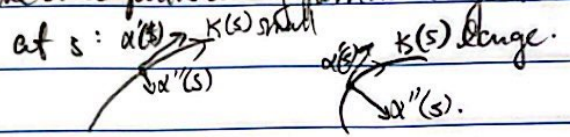


## Frenet Frame:

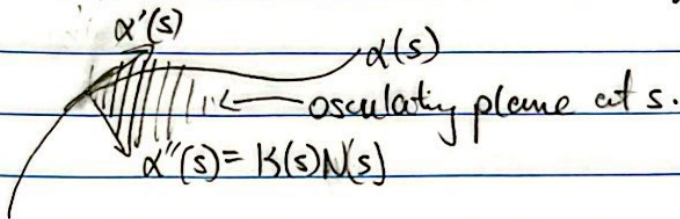
Curvature  $K(s) = |\alpha''(s)|$  - measures how rapidly the curve pulls away from the tangent line

Normal  $N(s) = \frac{1}{K(s)} \alpha''(s)$ . ( $K(s) > 0$ )

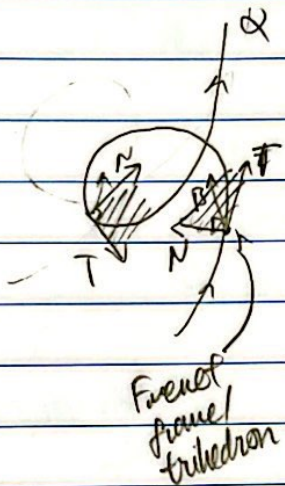
Binormal  $B(s) = \alpha'(s) \times N(s)$ .



$$\alpha'(s) \perp \alpha''(s) \text{ since } |\alpha'(s)| = 1 \Leftrightarrow \frac{d}{dt} |\alpha'(s)|^2 = 0 \Leftrightarrow 2\alpha'(s) \cdot \alpha''(s) = 0.$$



$B(s)$  is a unit vector normal to the osculating plane.



Torsion:  $B'(s) = -\tau(s)N(s)$  (note, do Camo lies sign convention)

measures the degrees to which the curve pulls away from the osculating plane at  $s$ .

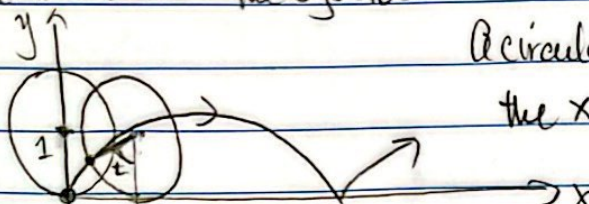
Frenet frame:  $T(s) = \alpha'(s)$ ,  $N(s) = \frac{1}{K(s)} \alpha''(s)$ ,  $B(s) = T(s) \times N(s)$   
all unit vectors

and the derivatives:  $K(s) = |T'(s)|$ ,  $B'(s) = -\tau(s)N(s)$  when expressed in the basis  $\{T, N, B\}$  yields geometric information about the curve (curvature and torsion)

And the point is that the curvature and torsion completely determines the curve.



# do-Praxis 1-3.2 The Cycloid

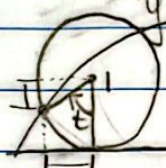


A circular disk of radius 1 rolls without slipping along the x-axis.

a) Obtain a parametrized curve  $\alpha: \mathbb{R} \rightarrow \mathbb{R}^2$  the trace of which is the cycloid and determine its singular pts.

Determine  $x(t) = t - \cos t$ .

$y(t) = 1 - \sin t$ .



From adding the motions of  $(x, y) = (t, 1)$  with  $-(\sin t, \cos t)$ .



Singular Pts:  $0 = \alpha'(t) = (1 - \cos t, \sin t)$

$\sin t = 0 \Leftrightarrow t = k\pi, k \in \mathbb{Z}$ .

$1 - \cos t = 0 \Leftrightarrow \cos t = 1 \Leftrightarrow t = 2k\pi, k \in \mathbb{Z}$ .

So singular pts at  $2k\pi, k \in \mathbb{Z}$ .

b) Compute the arc-length of the cycloid corresponding to a complete rotation of the disk:

Complete rotation:  $t = 0$  to  $t = 2\pi$ .

$\alpha'(t) = (1 - \cos t, \sin t)$

$$|\alpha'(t)|^2 = (1 - \cos t)(1 - \cos t) + \sin^2 t = 1 - 2\cos t + \cos^2 t + \sin^2 t = 2 - 2\cos t$$

$\Rightarrow |\alpha'(t)| = \sqrt{2 - 2\cos t}$

$s = \int_0^{2\pi} \sqrt{2 - 2\cos t} dt$

$1 - \cos t = 2\sin^2(\frac{t}{2}) \Leftrightarrow 2 - 2\cos t = 4\sin^2(\frac{t}{2})$

$= 2 \int_0^{2\pi} \sqrt{\sin^2(\frac{t}{2})} dt = 2 [-2\cos(\frac{t}{2})]_0^{2\pi} = 4(1+1) = \boxed{8}$

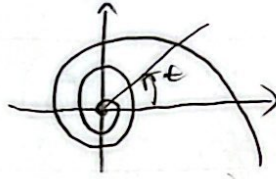


Arc length:

Compute curvature and torsion of the logarithmic spiral.

$$\alpha(t) = (ae^{bt} \cos t, ae^{bt} \sin t, 0)$$

$a > 0, b < 0$  constants.



Torsion = 0 since this is a plane curve.

Arc length:  $K(s) = \dots$

$$\alpha'(t) = (abe^{bt} \cos t - ae^{bt} \sin t, abe^{bt} \sin t + ae^{bt} \cos t)$$

$$\begin{aligned} \alpha''(t) &= (ab^2e^{bt} \cos t - abe^{bt} \sin t - abe^{bt} \sin t - ae^{bt} \cos t, \\ &\quad ab^2e^{bt} \sin t + abe^{bt} \cos t + abe^{bt} \cos t - ae^{bt} \sin t) \\ &= (ab^2e^{bt} \cos t - 2abe^{bt} \sin t - ae^{bt} \cos t, ab^2e^{bt} \sin t + 2abe^{bt} \cos t - ae^{bt} \sin t) \end{aligned}$$

$$\begin{aligned} |\alpha'(t)|^2 &= (abe^{bt} \cos t - ae^{bt} \sin t)^2 + (abe^{bt} \sin t + ae^{bt} \cos t)^2 \\ &= a^2b^2e^{2bt} \cos^2 t - 2ab^2e^{2bt} \cos t \sin t + a^2e^{2bt} \sin^2 t \\ &\quad + a^2b^2e^{2bt} \sin^2 t + 2ab^2e^{2bt} \sin t \cos t + a^2e^{2bt} \cos^2 t \\ &= a^2b^2e^{2bt} + a^2e^{2bt} = a^2e^{2bt}(1+b^2). \end{aligned}$$

$$\text{So } |\alpha'(t)| = ae^{bt} \sqrt{1+b^2}$$

$$\begin{aligned} L(t_1, t_2) &= \int_{t_1}^{t_2} |\alpha'(t)| dt = \int_{t_1}^{t_2} ae^{bt} \sqrt{1+b^2} dt = a\sqrt{1+b^2} \int_{t_1}^{t_2} e^{bt} dt \\ &= a\sqrt{1+b^2} \frac{1}{b} e^{bt} \Big|_{t_1}^{t_2} \\ &= \frac{a}{b} \sqrt{1+b^2} (e^{bt_2} - e^{bt_1}) \end{aligned}$$

Curvature:

Curvature:  $K(s) = \frac{|\alpha'(t) \times \alpha''(t)|}{|\alpha'(t)|^3}$  (use this because it is more convenient than reparametrizing by arc-length)

$$\alpha'(t) \times \alpha''(t) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ abe^{bt} \cos t - ae^{bt} \sin t & abe^{bt} \sin t + ae^{bt} \cos t & 0 \\ ab^2e^{bt} \cos t - 2abe^{bt} \sin t - ae^{bt} \cos t & ab^2e^{bt} \sin t + 2abe^{bt} \cos t - ae^{bt} \sin t & 0 \end{vmatrix}$$

$$\begin{aligned} &= [(abe^{bt} \cos t - ae^{bt} \sin t)(ab^2e^{bt} \sin t + 2abe^{bt} \cos t - ae^{bt} \sin t) - (abe^{bt} \sin t + ae^{bt} \cos t)(ab^2e^{bt} \cos t - 2abe^{bt} \sin t - ae^{bt} \cos t)] \hat{k} \\ &= a^2(1+b^2)e^{2bt} \hat{k}. \end{aligned}$$

$$\text{So } |\alpha'(t) \times \alpha''(t)| = a^2(1+b^2)e^{2bt}, \quad |\alpha'(t)|^3 = a^3e^{3bt}(1+b^2)^{3/2}$$

$$\Rightarrow K(s) = \frac{1}{ae^{bt} \sqrt{1+b^2}}. \quad \text{Since } b < 0, \text{ this says the curvature grows exponentially in time } t.$$