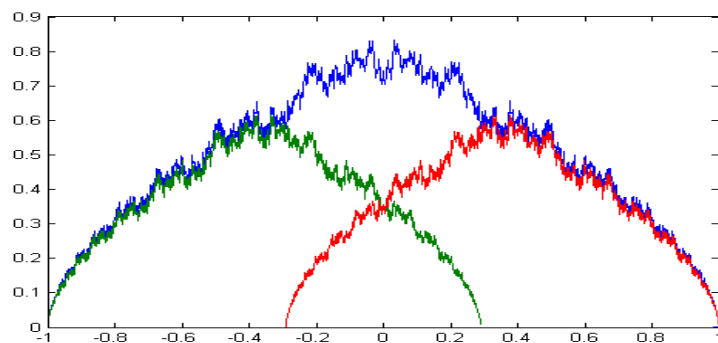


# Bernoulli Convolutions and Branching Dynamical Systems

AFRT, Hong Kong, 10 Dec 2012

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1. Pisot and non-Pisot case
  2. Branching Dynamical Systems
  3. Computer experiments
  4. Smooth cases
- many questions - few answers



I apologize for not mentioning many beautiful results of the organizers and of the audience.

- ① Pisot and non-Pisot case
  - the measure  $\nu$
  - the Erdős problem
  - growth rate of inverse functions
  - distribution of values for inverse iteration

Def (Bernoulli convolution  $\nu$ )

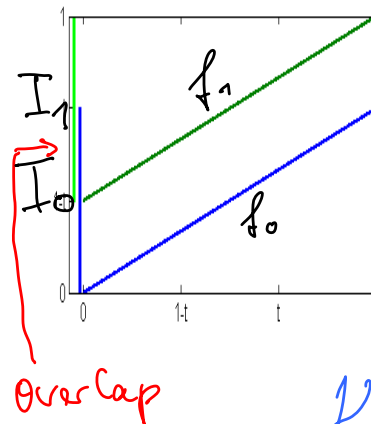
Take  $t \in (\frac{1}{2}, 1)$  and similarity maps

$$f_0(x) = tx \quad \text{on } I = [0, 1]$$

$$f_1(x) = tx + 1 - t$$

The self-similar set for  $\{f_0, f_1\}$  is

$$I = f_0(I) \cup f_1(I) = I_0 \cup I_1$$



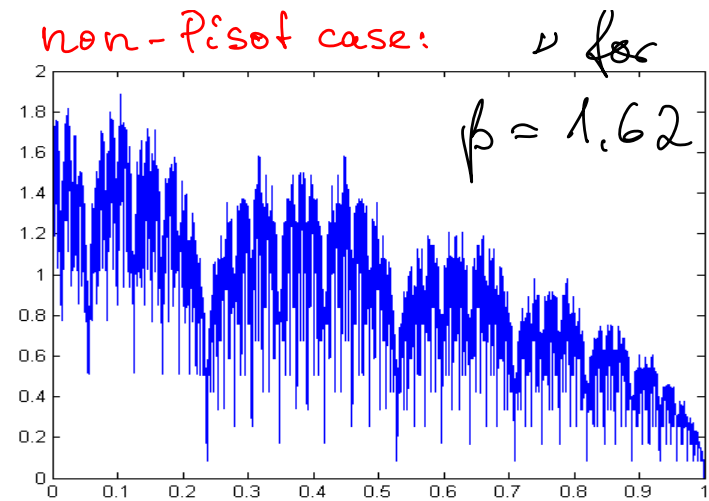
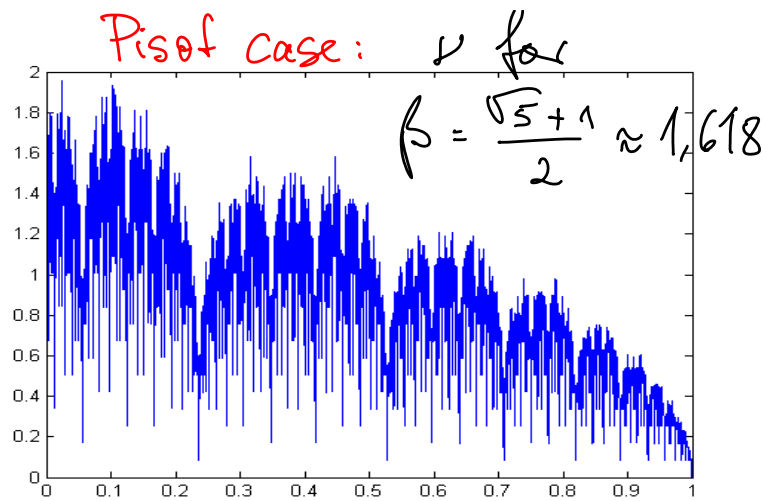
$\nu$  is the self-similar measure on  $I$  given by  $f_0, f_1$  and weights  $p_0 = p_1 = \frac{1}{2}$ .

$$\nu = \frac{1}{2} \nu \circ f_0^{-1} + \frac{1}{2} \nu \circ f_1^{-1}$$

Old Problem: for which  $t \geq \frac{1}{2}$  does  $\nu$  have a density function?

Erdős 1939: if  $\beta = \frac{1}{t}$  is a Pisot number (algebraic integer, all conjugate roots  $\beta_i$  fulfil  $|\beta_i| < 1$ ) there is no density function.

Wintner 1935: for  $\beta = \sqrt[k]{2}$ ,  $k = 0, 1, 2, \dots$  there is a density.  
 Garsia 1962: also for some algebraic integers  $\beta$   
 Solomyak 1995: for Lebesgue almost all  $\beta \in (1, 2)$  there is a density.

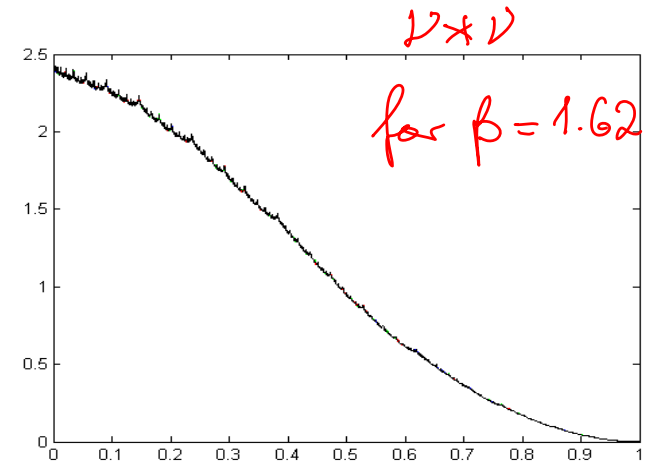
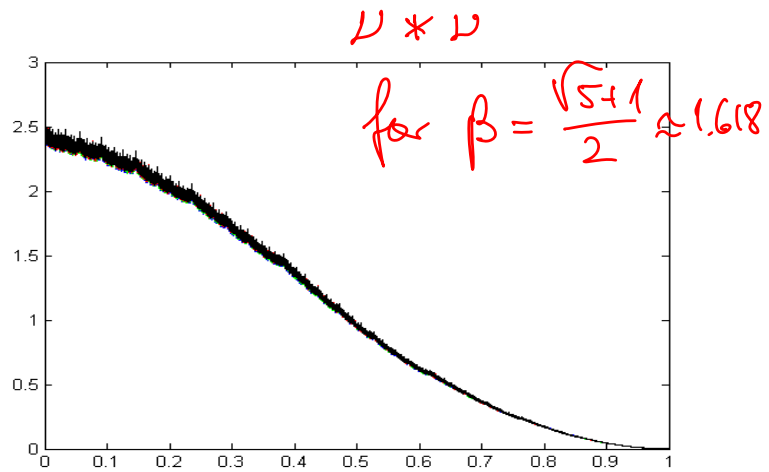


Convention: since measures are symmetric, we show only their right half, and we normalize so that the support is again  $[0,1]$ .

Construction: histogram of orbit of random iteration of  $f_0, f_1$  (IFS).

We used a more accurate method described below.

For the correlation measure  $\nu * \nu$ , the difference is easier to recognize.

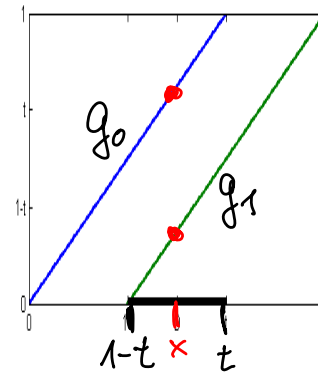


To see a real difference, we consider the *inverse functions* of  $f_i$

$$g_0(x) = \beta x, \quad x \in I_0 = [0, t]$$

$$g_1(x) = \beta x + 1 - \beta, \quad x \in I_1 = [1-t, 1]$$

where  $\beta = \frac{1}{t} \in (1, 2)$ .



$G = \{g_0, g_1\}$  is a multivalued map. For  $x \in D = I_0 \cap I_1$ ,  $G(x)$  consists of two points.

How many values do we obtain if we  $n$  times apply  $G$ ?

How does  $|G^n(x)|$  depend on  $x$ ?

Actually,  $|G^n(x)|$  for large  $n$  is a proxy for a density  $d(x)$  of  $\nu$ .

Theorem (Feng + Sidorov, Kempton)

$$\lim_{n \rightarrow \infty} \sqrt[n]{|G^n(x)|} = \gamma$$

for Lebesgue almost all  $x$ .

De-Jun Feng + Sidorov 2009

Pisot case:  $\gamma < \frac{2}{\beta}$

T. Kempton 2012

when density exists:  $\gamma = \frac{2}{\beta}$

Remark. For Lebesgue measure  $\lambda$  on  $I$ ,

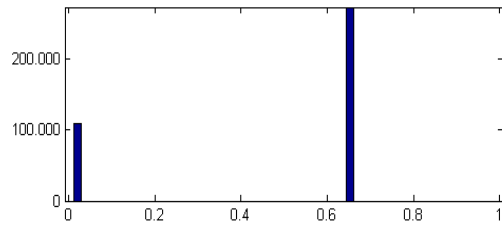
$$\lambda \circ G^{-1} = \lambda g_0^{-1} + \lambda g_1^{-1} = \frac{2}{\beta} \cdot \lambda$$

Remark. Even for  $\beta = \frac{\sqrt{5}+1}{2}$ , the difference of  $\gamma$  and  $\frac{2}{\beta}$  is small:

$$\gamma \approx 0.996 \cdot \frac{2}{\beta}$$

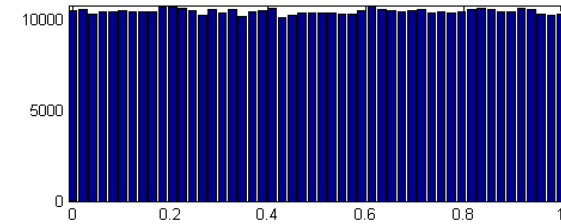
In the theorem, each  $y \in G^n(x)$  is counted with its multiplicity.

Remark. A much more obvious difference between Pisot and non-Pisot case is the distribution of the values in  $G^n(x)$  for fixed  $n$ .



Histogram of the values  $G^n(x)$ ,  $n=60$   
for the Pisot case  $\beta = \frac{\sqrt{5}+1}{2}$ .

Two values with large multiplicity.



Histogram of the values  $G^n(x)$ ,  $n=60$   
for the non-Pisot case  $\beta = 1.62$ .  
Values seem to be equidistributed.

Prop. For Pisot  $\beta$  there is a  $C$   
such that for all  $n$  and  $x$ ,  
 $G^n(x)$  has at most  $C$   
different points.

Prop.  $\nu$  has a density if and only if  
for Lebesgue almost all  $x$ ,  
the distribution of the  
points of  $G^n(x)$  tends to the  
equidistribution on  $[0, 1]$   
for  $n \rightarrow \infty$ .

## ② Branching Dynamical Systems

Let  $J_1, \dots, J_m$  be subsets of a set  $J$ ,  
and  $g_i: J_i \rightarrow J$  mappings.

Then  $G = \{g_1, \dots, g_m\}$  is called  
BDS.

We put  $G(x) = \{g_i(x) \mid x \in J_i\}$

and  $G(A) = \bigcup_{a \in A} G(x)$  for sets  $A$ .

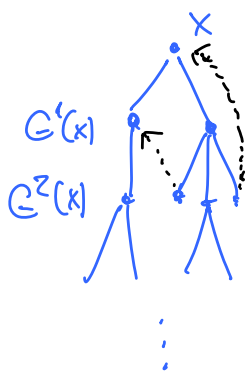
Points in  $G^n(x) = \underbrace{G \dots G(x)}_n$   
are called successors of  $x$   
in generation  $n$ .

The forward orbit of  $x$ ,

$$G^\infty(x) = \bigcup_{n=0}^{\infty} G^n(x)$$

has a tree-like  
structure.

Cycles can appear.



*Question:* Determine the periodic  
orbits of  $G$  — the  $x$  for which  
 $G^\infty(x)$  consists of a finite  
number of points.

*Pisot case: many / else: very few*

*Jordan, Sturmfels, Solomyak 2011, Th. 15*

*Talk of R. Zeller*

Let  $N^n(x) = |G^n(x)|$  be the number of  $n$ -th generation successors of  $x$ , counted with multiplicity.

$$\text{If } \gamma(x) = \lim_{n \rightarrow \infty} \sqrt[n]{N^n(x)}$$

exists, it is called growth factor of successors of  $x$ .

A finite measure  $\mu$  on  $J$  is invariant for  $G$ , with growth factor  $\gamma$ , if

$$\gamma \cdot \mu(B) = \sum_{i=1}^m \mu(g_i^{-1}(B))$$

for measurable sets  $B \subseteq J$ .

$\gamma$  is a kind of average of all  $\gamma(x)$ .

**Questions.** For which  $G$  does an invariant measure  $\mu$  exist?

Under which conditions will

$\gamma(x)$  exist

and  $\gamma(x) = \gamma$  for  $\mu$ -almost all  $x$ ?

Study the ergodic and mixing properties of tree-like orbits.

When  $G^n(x)$  is considered as a probability measure  $\mu_n(x)$ , will there be some limit for  $n \rightarrow \infty$ ?

Does the limit depend on  $x$ ?

How is it related with  $\mu$ ?

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The BDS  $G$  acts as an operator on the piecewise constant functions  $S^n(x) = N^n(x) \cdot \gamma^{-n}$  (standardized number of successors).

$$S^{n+1}(x) = \tilde{G}(S^n(x)) = \frac{1}{\gamma} \sum_{x \in J_i} S^n(g_i(x))$$

This action can be extended to functions  $h: J \rightarrow \mathbb{R}$ .

$$\tilde{G}h(x) = \frac{1}{\gamma} \sum_{x \in J_i} h(g_i(x))$$

What properties does this operator have on function spaces  $L_1, \mathcal{L}, \mathcal{L}^k$ ?

Prop. If  $\mu$  is invariant, then  $\tilde{G}$  is a positive continuous operator on  $L_1(\mu)$ , and  $\|\tilde{G}h\|_1 = \|h\|_1$  for  $h \geq 0$ .

(straightforward, cf. Keupton)

Bernoulli convolutions are a nice testbed for all these questions.

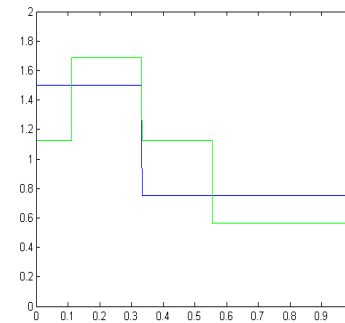
### ③ Computer experiments

For  $\beta = 3/2$ , we determine the standardized number of successors for  $10^5$  equally spaced  $x$ .

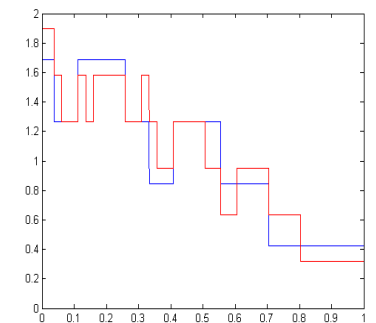
Starting with  $h_0 = 1$ , we iterate  $\tilde{G}$ :

$$h_n = \tilde{G} h_{n-1} \quad n=1, 2, \dots, 30$$

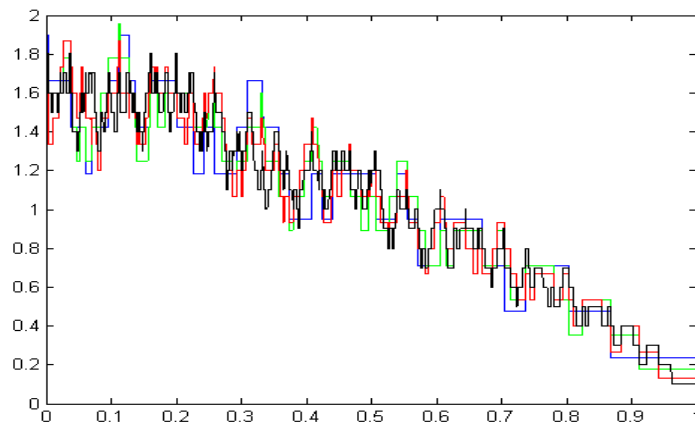
$h_n = S^n(x)$  offspring in generation  $n$



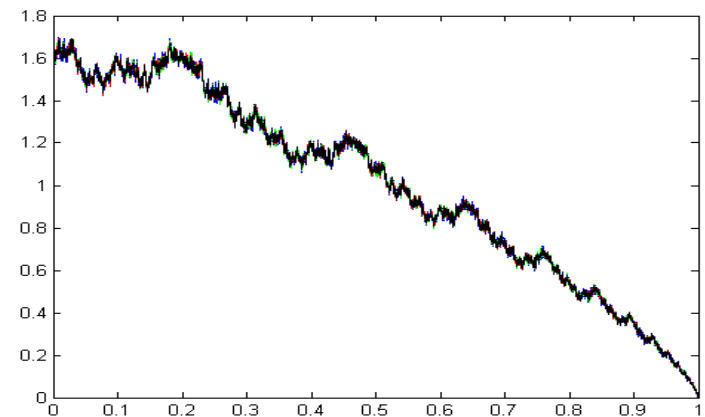
$h_1, h_2$



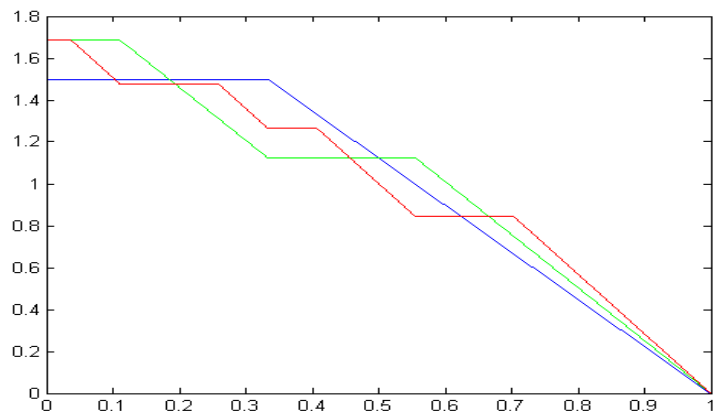
$h_3, h_4$



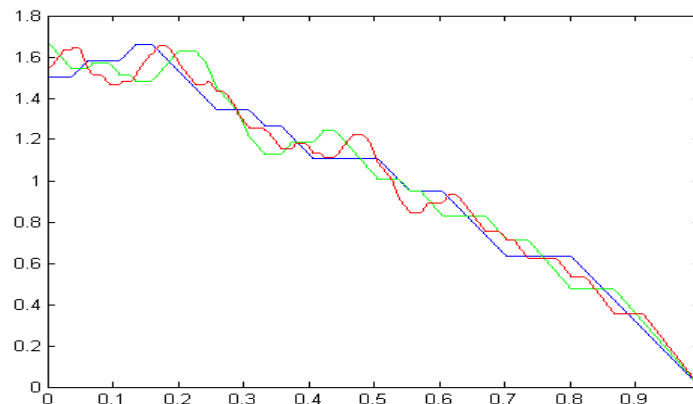
$h_7$  up to  $h_{10}$



after 30 iterations: 1)



Starting with a linear function  $h_0$



Iteration remains within  $\mathcal{L}([0,1])$ .

Prop. The following subspaces of  $\mathcal{L}_1(\mathbb{R})$  are invariant under  $\tilde{G}$ .

$$\mathcal{L}_0 = \{ h \mid \text{continuous, } h(1) = 0 \}$$

$$\mathcal{L}_0^k = \{ h \mid k \text{ times differentiable, } h^{(j)}(1) = 0 \text{ for } j = 0, \dots, k \}$$

Prop. IFS on  $[0,1]$ ,  $f_i(x) = tx + v_i$  with inverse functions

$$g_i(x) = \beta(x - v_i), \quad \beta = \frac{1}{t}.$$

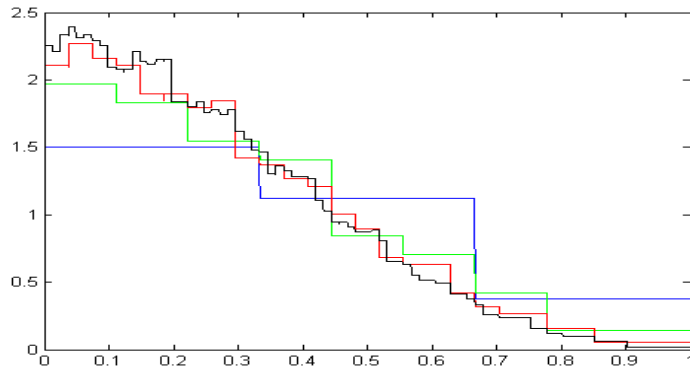
Then the operator  $\tilde{G}$  is just the restriction of Hutchinson's operator to  $\mathcal{L}_1(\mathbb{R})$ .

Remember: Hutchinson's operator acts on the space of finite measures  $\kappa$  by

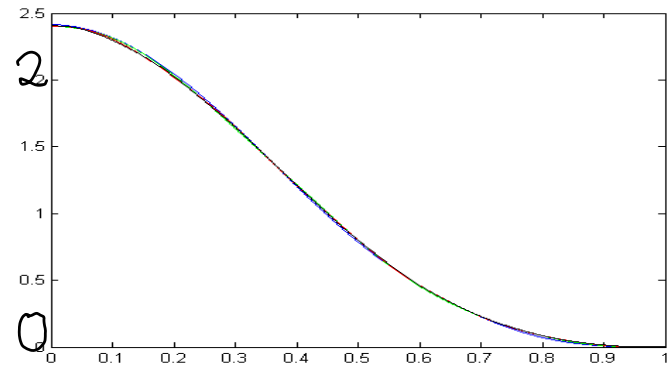
$$H\kappa = \frac{1}{m} \sum_{i=1}^m \kappa \circ f_i^{-1} = \frac{1}{m} \sum_{i=1}^m \kappa \circ g_i$$

It is contractive with respect to transport distance.

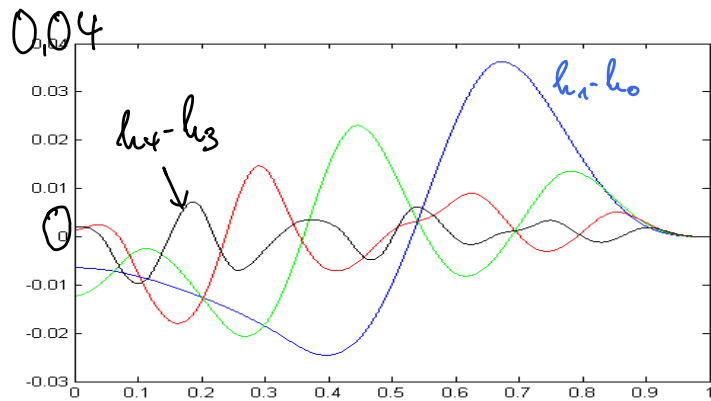
For any probability measure  $\kappa_0$ , the sequence  $\kappa_n = H^n \kappa_0$  converges to the invariant measure  $\nu$  of the IFS. This also holds for every  $h_0$  and  $h_n = \tilde{G}^n h_0$ , but the limit need not be in  $L_1$ .



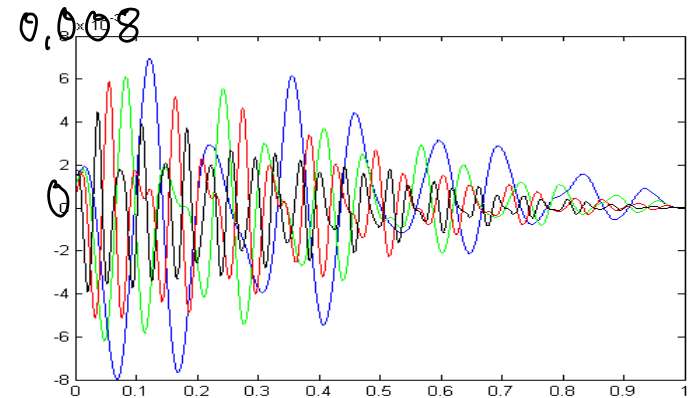
Approximation of  $\nu = \nu * \nu$  for  $\beta = 3/2$ .



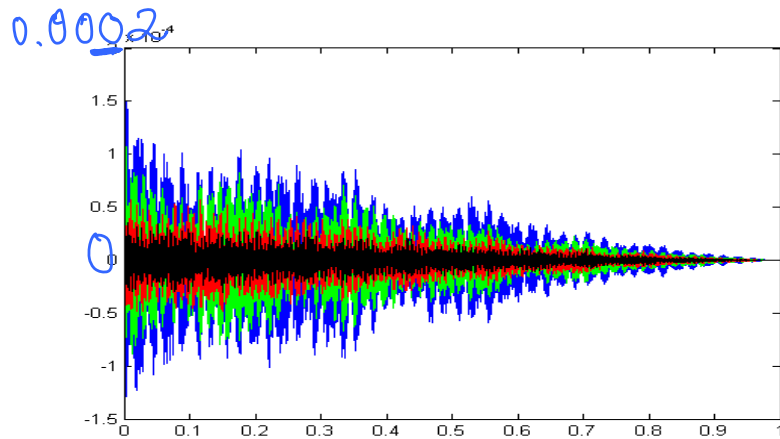
$h_n$  up to  $h_4$  for a smooth starting function



Differences between first iterations

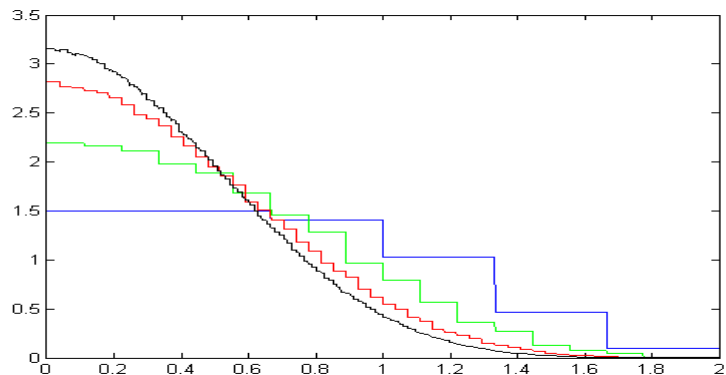


Differences between iterations  $h_5$  to  $h_8$

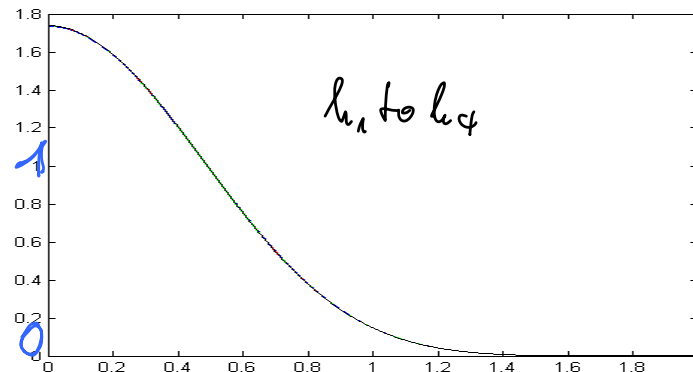


subsequent differences

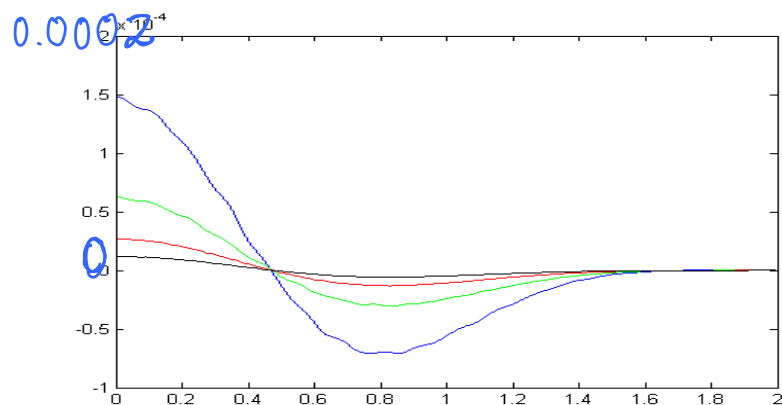
Differences become small,  
 but perhaps they accumulate.  
 Let us consider the still more  
 smooth measure  $\mathcal{G} \times \mathcal{G}$   
 for  $\beta = \frac{3}{2}$ .



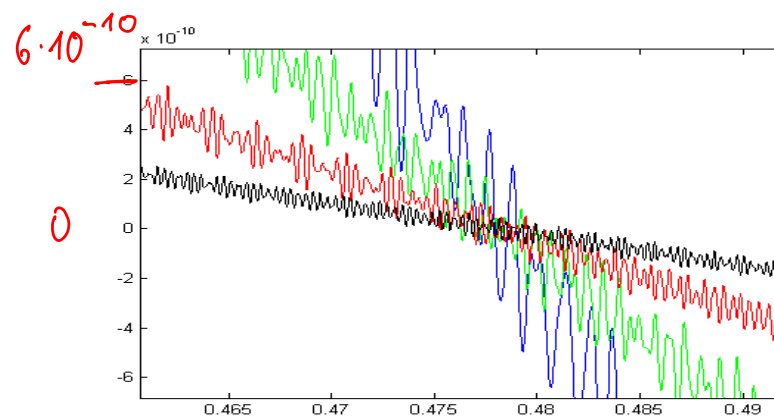
Successor functions  $S^1$  to  $S^4$  for  $g * g$



$g * g$ :  $h_0 = (1 + \cos \pi x)^4$  is almost perfect



Differences of iterations



High-frequency corrections exist, but they decrease very fast.

## ④ Smooth cases

Prop. (cf. Wintner (1935))

If  $\nu_\beta$  admits a density,  
then  $\nu_{\sqrt{\beta}}$  also has a density

since  $\nu_{\sqrt{\beta}} = \nu_\beta * \nu_\beta \circ \beta$

where  $\nu_\beta \circ \beta(A) = \nu_\beta(\beta A)$

Thus  $\nu_\beta$  becomes more smooth  
(more continuous, more derivatives)  
when  $\beta$  comes nearer to 1.

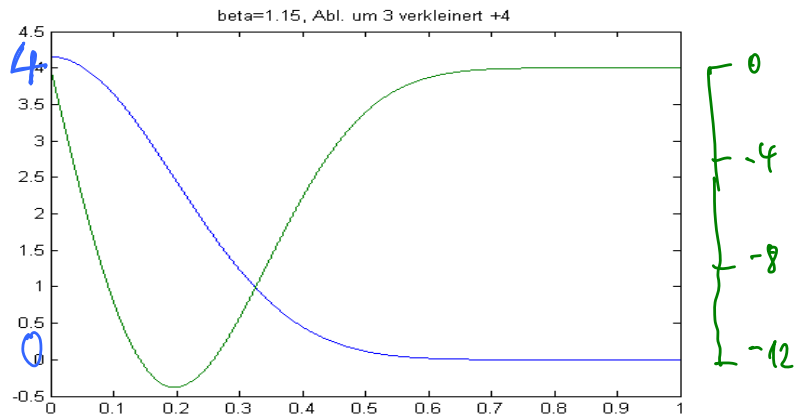
However, there is a small result  
into the other direction:

Smoothing Lemma. Let  $\nu_\beta$  have  
no density, and let  $\beta$  not belong  
to a certain countable set  $B$ .

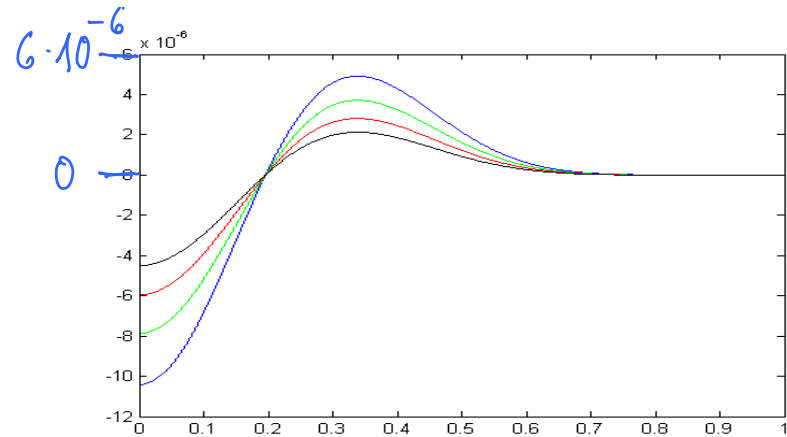
Then  $\nu * \nu$  does not have a  
bounded density.

This motivates the study of  
smooth cases. In the following,  
we take  $\beta = 1, 15$  and the  
correlation measure

$$\varrho = \nu * \nu.$$



density  $h$  of  $\nu$  and its derivative  $h'$



Differences  $h_{n+1} - h_n$  of approximations

Observation: up to a constant, the differences  $h_{n+1} - h_n$  approach the second derivative  $h''$  of  $h$ .  $\tilde{G}$  becomes a  $\|\cdot\|_\infty$ -contraction on certain subspaces of  $C[0,1]$  and even  $C^k[0,1]$ .

**Problem.** Prove the geometrical convergence of the corrections  $h_{n+1} - h_n$  to zero, by means of a recursive estimate, and computer support to find the proper starting function.

Why is  $h_{n+1} - h_n$  near to  $h''$ ?

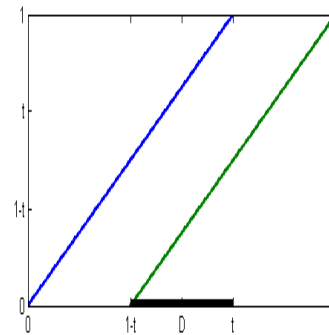


Prop. IFS  $f_i(x) = tx + v_i$ , arbitrary  $p_i$ ,  
 $i = 1 \dots m$   
 $\beta = 1/t$ ,  $G = \{g_1 \dots g_m\}$  inverse maps.

If the self-sim. measure  $\nu$  has a density  $h$  with  $k$  derivatives,  
 then  $h^{(j)}$  is an eigenvector of  $\tilde{G}$   
 with eigenvalue  $\beta^{-j}$   $j = 0, \dots, k$ .

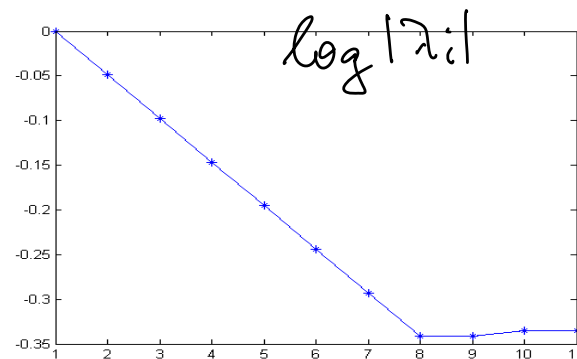
Question: What is the spectrum of  $\tilde{G}$ ?

Without factor  $1/8$ ,  
 $\tilde{G}$  is just a centrally  
 symmetric 0-1-matrix.

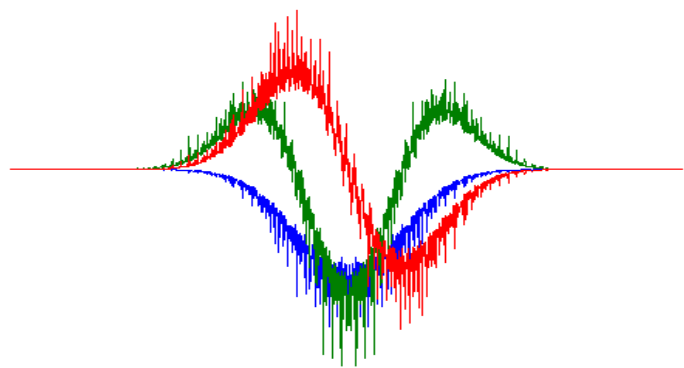


Experiment: Model  $\tilde{G}$  by  $n \times n$ -matrix  
 of zeros and ones. (Matlab,  $n = 1500$ )  
 Determine the leading eigenvalues  
 and corresponding eigenvectors.

Take  $\nu$  for  $\beta = 1.05$ .

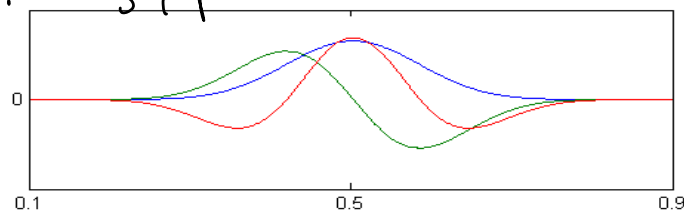


For  $i = 1, \dots, 7$ ,  $\lambda_i$  is real and  $\lambda_i = \beta^{1-i}$   
 (error  $\leq 10^{-4}$ )

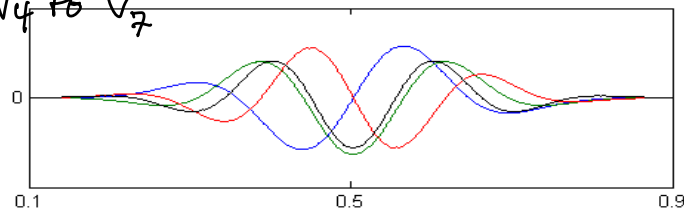


The first 3 eigenvectors in row form

$v_1$  to  $v_3$ , polished



$v_4$  to  $v_7$



Conjecture. Let  $\beta_1 = 1.32$ . There are numbers  $\beta_1 > \beta_2 > \beta_3 > \dots > 1$  so that  $\tilde{G}$  for  $\beta \in (\beta_{n+1}, \beta_n)$  has the leading eigenvalues  $1, \beta^{-1}, \dots, \beta^{1-n}$ , with eigenfunctions similar to those of Sturm-Liouville operators.

Difficulties of the Erdős problem

- Definition of  $\nu$  recursive, not explicit
- Action of  $\tilde{G}$  on  $L_1$ , not on  $L_2$
- densities  $h$  are  $e^k$ , not  $e^\infty$

still, seems solvable.