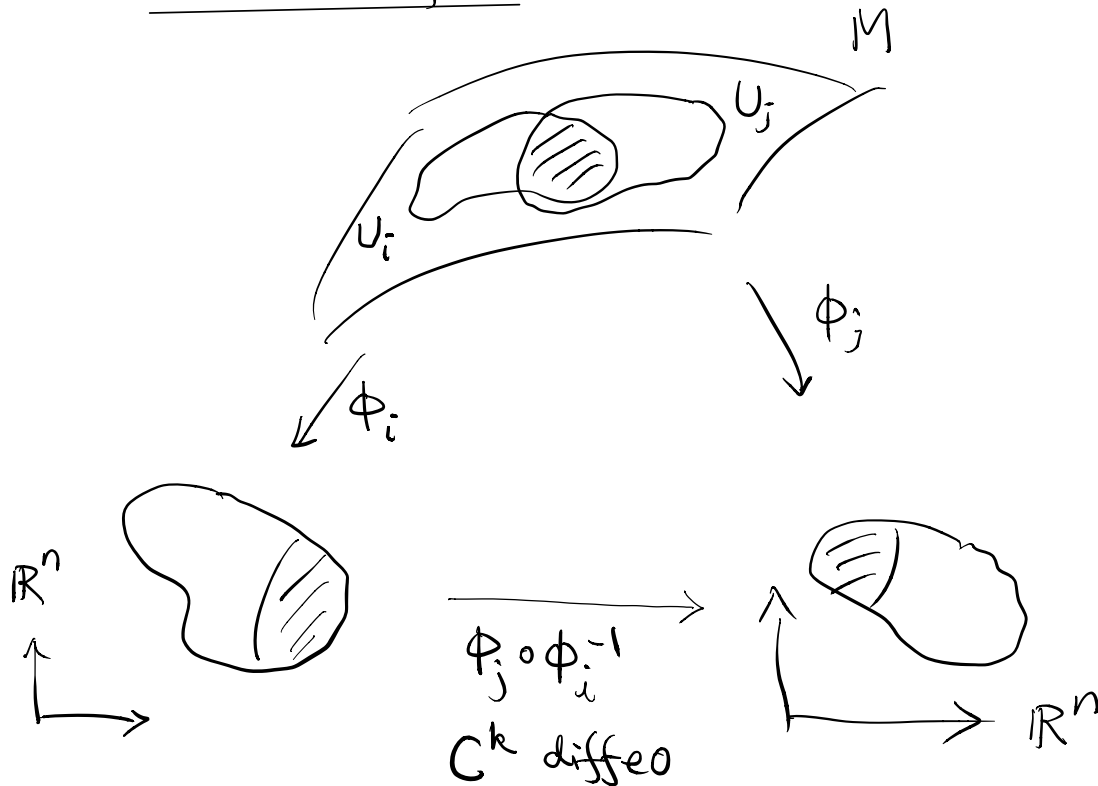


Ch1 Differential Manifolds

1.1 Abstract Manifolds



Def: A C^k atlas on a Hausdorff topological space

M is defined by

(i) an open covering $\mathcal{U}_i, i \in \Lambda$, of M

(ii) a family of homeomorphisms

$$\phi_i = \mathcal{U}_i \rightarrow \Omega_i \subset \mathbb{R}^n \quad (\Omega_i \text{ open})$$

such that $\forall i, j \in \Lambda$,

$$\phi_j \circ \phi_i^{-1} = \phi_j(\mathcal{U}_i \cap \mathcal{U}_j) \rightarrow \phi_j(\mathcal{U}_i \cap \mathcal{U}_j)$$

is a C^k -diffeomorphism.

Remark: • $\phi_j \circ \phi_i^{-1}$, $i, j \in \Lambda$ (with $U_i \cap U_j \neq \emptyset$) are called transition functions.

• (U_i, ϕ_i) is called a (coordinate) chart.

• $\phi_i^{-1}: \Omega_i \rightarrow U_i \subset M$ is a local parametrization.

Def: "Two" C^k atlases on M , say $(U_i, \phi_i)_{i \in \Lambda_1}$ and $(V_j, \psi_j)_{j \in \Lambda_2}$ are C^k -equivalent if their union is still a C^k -atlas, that is, if $\forall i \in \Lambda_1$, $j \in \Lambda_2$ (st. $U_i \cap V_j \neq \emptyset$), then

$$\phi_i \circ \psi_j^{-1} = \psi_j(U_i \cap V_j) \rightarrow \phi_i(U_i \cap V_j)$$
are C^k -diffeomorphism.

Def: A differentiable structure of class C^k on M is an equivalence class of C^k atlases.

Remark: If M is connected, then the integer n in the definition doesn't depend on the chart and is defined as the dimension of M .

Def: A C^k differentiable manifold of dimension n is a pair (M, \mathcal{A}) , where M is a Hausdorff top. space and $\mathcal{A} = [(U_i, \phi_i)_{i \in \Lambda}]$ is a differentiable structure given by a C^k atlas on M with $\phi_i(U_i) \subset \mathbb{R}^n$.

Remark: In this course, we consider only C^∞ diff. manifold which is connected and with a further condition such that "partitions of unity" is always possible.

- All compact manifolds satisfy the further condition.
- We'll refer such a manifold as a smooth manifold (or even just manifold)

eg: $M = T^n$, the n -torus ($T^n = \underbrace{S^1 \times \dots \times S^1}_n$) is a manifold.

If: let $f: \mathbb{R}^n \rightarrow T^n \in \mathbb{C}^n$
 $(x_1, \dots, x_n) \mapsto (e^{ix_1}, \dots, e^{ix_n})$ (f is onto)

$\forall p \in T^n, \exists x^p = (x_1^p, \dots, x_n^p) \in \mathbb{R}^n$ s.t.

$p = f(x^p)$ (we may choose $x_i^p \in [0, 2\pi)$, $i=1, \dots, n$)

Consider $\Omega_p = (x_1^p - \pi, x_1^p + \pi) \times \dots \times (x_n^p - \pi, x_n^p + \pi)$
 open in \mathbb{R}^n containing x^p .

let $U_p = f(\Omega_p) \subset T^n$ ($\Rightarrow U_p$ open & containing p)

$$\phi_p = (f|_{\Omega_p})^{-1}: U_p \rightarrow \Omega_p \subset \mathbb{R}^n \text{ homeo.}$$

Then $(U_p, \phi_p)_{p \in T^n}$ is a C^∞ atlas on T^n :

In fact, if $p, q \in T^n$ s.t. $U_p \cap U_q \neq \emptyset$, $\Omega_p \cup \Omega_q$

then $\phi_q \circ \phi_p^{-1}(x_1, \dots, x_n) \quad (x_1, \dots, x_n) \in \phi_p(U_p \cap U_q)$

$$= \phi_q(f(x_1, \dots, x_n)) = \phi_q(e^{ix_1}, \dots, e^{ix_n})$$

$$= (f|_{\Omega_q})^{-1}(e^{ix_1}, \dots, e^{ix_n})$$

$$= (x_1 + 2k_1\pi, \dots, x_n + 2k_n\pi) \text{ for some } k_1, \dots, k_n$$

$$\text{such that } x_i + 2k_i\pi \in (x_i^q - \pi, x_i^q + \pi)$$

note that k_i are indep. of $(x_1, \dots, x_n) \in \phi_p(U_p \cap U_q)$

hence $\phi_q \circ \phi_p^{-1}$ is just a translation in \mathbb{R}^n (Ex!)

$\Rightarrow \phi_q \circ \phi_p^{-1}$ is a C^∞ diffeo.

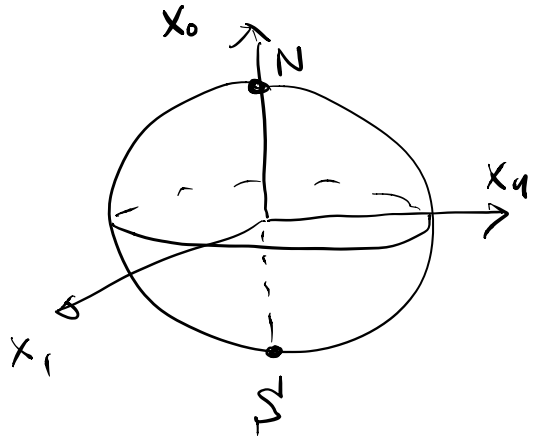
$\therefore (T^n, (U_p, \phi_p)_{p \in T^n})$ is a smooth manifold. ~~xx~~

eg $M = S^n$, the n -sphere $S^n = \{(x_0, x_1, \dots, x_n) \mid \sum_{j=0}^n x_j^2 = 1\} \subset \mathbb{R}^{n+1}$

is a manifold.

(Sketch)

$$\begin{cases} N = (1, 0, \dots, 0) \in S^n \\ S = (-1, 0, \dots, 0) \in S^n \end{cases}$$



$$\begin{cases} U_1 = S^n \setminus \{N\} \\ U_2 = S^n \setminus \{S\} \end{cases} \quad (\Rightarrow U_1 \cup U_2 = S^n)$$

Let $\phi_1: U_1 \xrightarrow{\psi} \mathbb{R}^n$ (Stereographic projection)

$$\left\{ \begin{aligned} (x_0, x_1, \dots, x_n) &\mapsto \frac{1}{1-x_0} (x_1, \dots, x_n) \\ \phi_2: U_2 &\xrightarrow{\psi} \mathbb{R}^n \end{aligned} \right.$$

$$(x_0, x_1, \dots, x_n) \mapsto \frac{1}{1+x_0} (x_1, \dots, x_n)$$

are homeomorphisms.

Note that if $\phi_1(x_0, x_1, \dots, x_n) = (y_1, \dots, y_n) \neq 0$

$$\text{then } y = (y_1, \dots, y_n) \in \phi_1(U_1 \cap U_2) \\ (= \phi_2(U_1 \cap U_2))$$

and $\phi_2 \circ \phi_1^{-1}(y) = \frac{y}{|y|^2} \quad (\forall y \in \mathbb{R}^n, y \neq 0)$

which is a C^∞ -diffeomorphism,

$\Rightarrow \{(U_1, \phi_1), (U_2, \phi_2)\}$ is an C^∞ atlas

and hence $(S^n, \mathcal{A} = [\{(U_1, \phi_1), (U_2, \phi_2)\}])$ is a smooth manifold. $\#$

eg $\mathbb{R}P^n$ the real projective space (in some book: $P^n(\mathbb{R})$)

• As topological space

$\mathbb{R}P^n =$ quotient space of $\mathbb{R}^{n+1} \setminus \{0\}$ by the equivalent relation: $x \sim y \Leftrightarrow \exists \lambda \neq 0 \in \mathbb{R}$ s.t. $x = \lambda y$

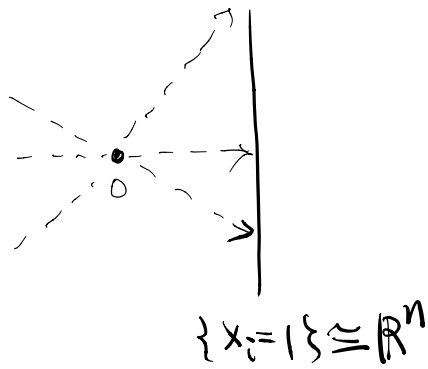
$= S^n / \{\pm \text{Id}\}$ (hence $\mathbb{R}P^n =$ Hausdorff, compact, connected.)

• Let $\pi: \mathbb{R}^{n+1} \setminus \{0\} \rightarrow \mathbb{R}P^n$ be the canonical projection map, i.e. $\pi(x) =$ equiv. class of x .

Define $V_i = \{x = (x_0, x_1, \dots, x_n) \in \mathbb{R}^{n+1}, x_i \neq 0\}$

$$\begin{array}{ccc} \bar{\Phi}_i = V_i & \longrightarrow & \mathbb{R}^n \\ \downarrow \subset & & \downarrow \subset \\ x & \longmapsto & \left(\frac{x_0}{x_i}, \dots, \frac{x_i}{x_i}, \dots, \frac{x_n}{x_i} \right) \end{array}$$

this means the term is deleted.



Then $\forall x, y \in V_i$, we have

$$\boxed{\begin{aligned} \Phi_i(x) &= \Phi_i(y) \\ \Leftrightarrow \pi(x) &= \pi(y) \end{aligned}} \quad (*)$$

(i.e. $x \sim y$)

This gives $\mathbb{R}^{n+1} \setminus \{0\} \supset V_i \xrightarrow{\Phi_i} \mathbb{R}^n$

$$\begin{array}{ccc} & \mathbb{R} & \\ \pi \downarrow & \cong & \nearrow \Phi_i \\ \mathbb{R}P^n \supset U_i = \pi(V_i) & & \end{array} \quad (\Phi_i \circ \pi = \Phi_i)$$

where Φ_i is defined by

$$\begin{array}{ccc} \Phi_i = U_i = \pi(V_i) & \longrightarrow & \mathbb{R}^n \\ \downarrow & & \downarrow \\ \text{equiv. class of } x & \longmapsto & \Phi_i(x) \end{array}$$

(Φ_i is well-defined because of $(*)$)

Further $\Phi_i: U_i \rightarrow \mathbb{R}^n$ is a homeomorphism (check!)

with inverse

$$\Phi_i^{-1}(y_0, \dots, y_{n-1}) = \pi(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1})$$

Therefore, if $y_j \neq 0$, say for $j < i$, we have

$$\begin{aligned}
(\phi_j \circ \phi_i^{-1})(y_0, \dots, y_{n-1}) &= \phi_j(\pi(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1})) \\
&= \Phi_j(y_0, \dots, y_{i-1}, 1, y_i, \dots, y_{n-1}) \\
&= \left(\frac{y_0}{y_j}, \dots, \frac{y_i}{y_j}, \dots, \frac{y_{i-1}}{y_j}, \frac{1}{y_j}, \frac{y_i}{y_j}, \dots, \frac{y_{n-1}}{y_j} \right)
\end{aligned}$$

$\therefore \phi_j \circ \phi_i^{-1} = \Phi_j(U_i \cap U_j) \rightarrow \phi_j(U_i \cap U_j)$ is a C^∞ diffeo.

(Similarly for $i < j$). Hence $\mathbb{R}P^n$ with the atlas

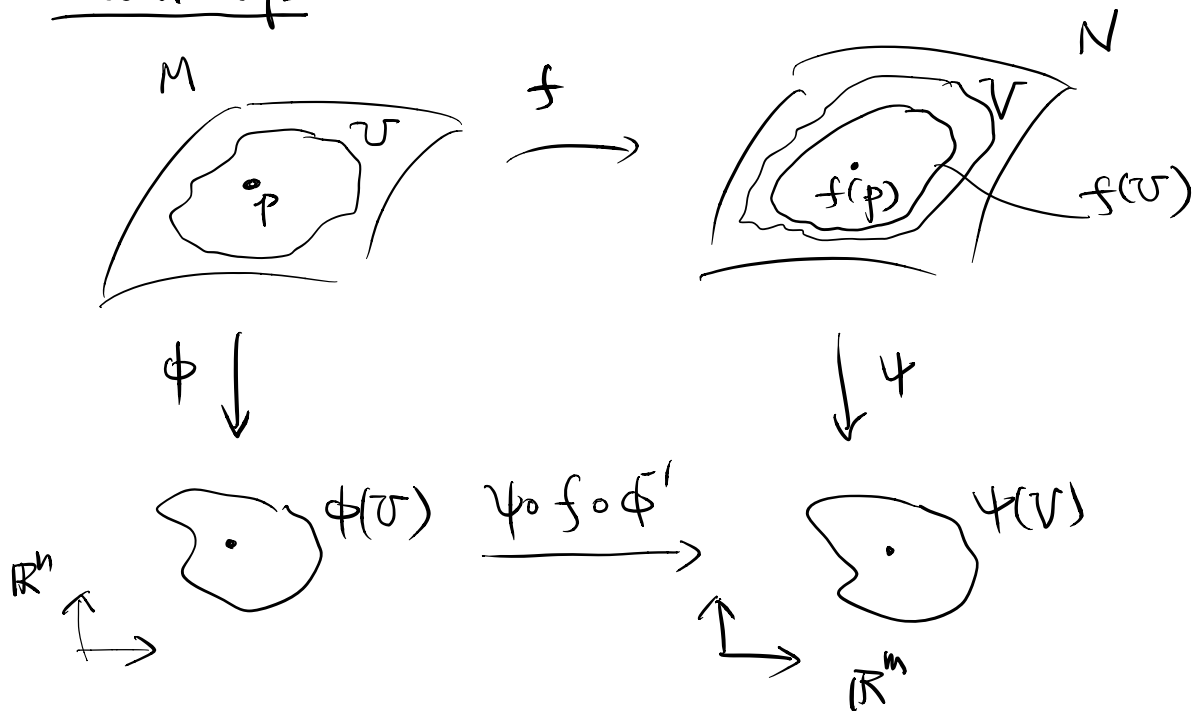
$(U_{\bar{i}}, \phi_{\bar{i}})_{\bar{i}=0, \dots, n}$ is a smooth manifold.

Note: $\mathbb{R}P^n$ is non-orientable for n even according to the following definition:

Def: A smooth manifold M is said to be orientable if \exists an atlas on M s.t. the Jacobian determinant

$$\det(J(\phi_j \circ \phi_i^{-1})) > 0, \quad \forall i, j.$$

1.2 Smooth Maps



Def: Let M & N be C^k manifolds. A continuous map $f: M \rightarrow N$ is C^l map (for $l \leq k$) if $\forall p \in M$ \exists charts (U, ϕ) , (V, ψ) for M and N around p and $f(p)$ respectively with $f(U) \subset V$ s.t.

$\psi \circ f \circ \phi^{-1}: \phi(U) \rightarrow \psi(V)$ is C^l
 (coordinate representation of f) (as a map: $\mathbb{R}^n \rightarrow \mathbb{R}^m$)

Note: This definition doesn't depend on the charts since transition functions are C^k ($k \geq l$). (Ex!)

Def: A C^k map $\gamma: (a, b) \rightarrow M$ from an open interval to a smooth manifold is called a C^k curve in M

Def: A C^k map $f: M \rightarrow \mathbb{R}$ ($\text{or } \mathbb{C}$) is called a C^k function on M

Def: A smooth map $g: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a submersion (an immersion, a local diffeomorphism) at $x \in \mathbb{R}^n$ if $D_x g: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is surjective (injective, bijective).

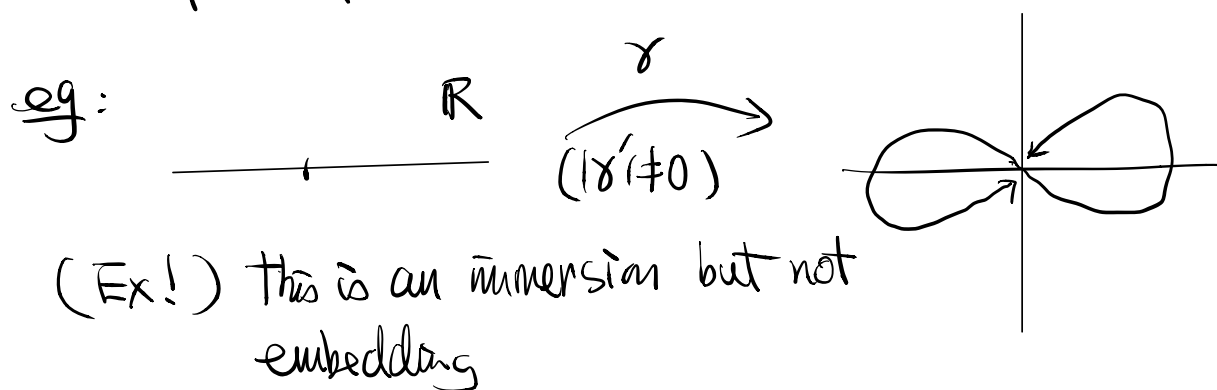
Def: Let M & N be smooth manifolds. A smooth map $f: M \rightarrow N$ is a submersion (immersion, local diffeo) at $p \in M$, if \exists charts (U, ϕ) for M around p , (V, ψ) for N around $f(p)$, with $f(U) \subset V$ s.t. $\psi \circ f \circ \phi^{-1}$ is a submersion (immersion, local diffeo) at $\phi(p) \in \phi(U) \subset \mathbb{R}^n$.

(check: this is well-defined)

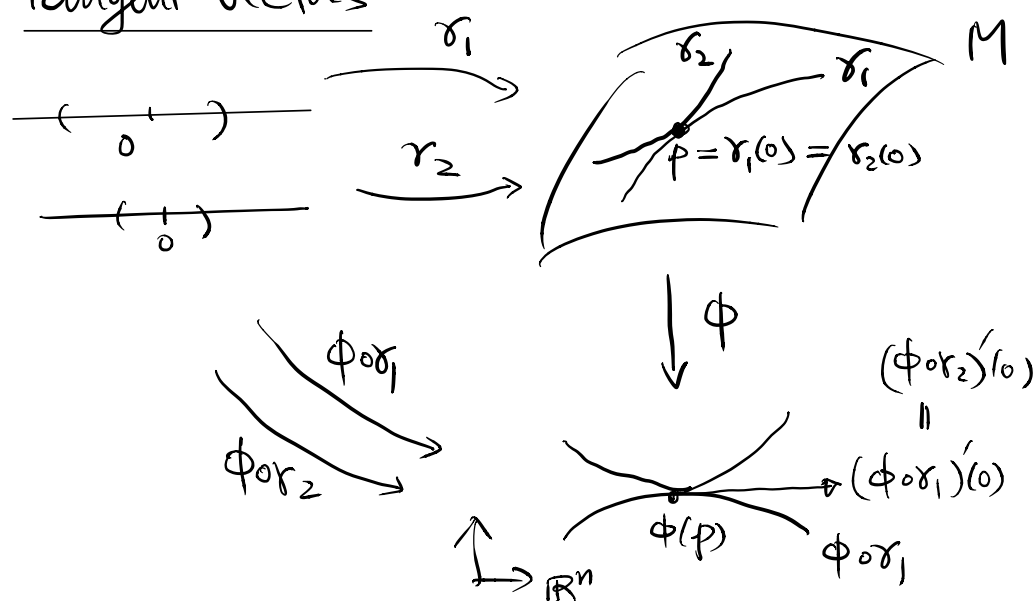
Def: A map $f: M \rightarrow N$ is a submersion (immersion, local diffeo) if it has the property at any point of M .

Def: A map $f: M \rightarrow N$ is a diffeomorphism if it is a bijection such that both f and f^{-1} are smooth.

Def: A map $f: M \rightarrow N$ is an embedding if it is an immersion and $f: M \rightarrow f(M) \subset N$ (with subspace top.) is a homeomorphism.



1.3 Tangent vectors



Def 1: Let M be a smooth manifold and $p \in M$. A tangent vector to M at p is an equi. class of C^∞ curves $\gamma: I \rightarrow M$, where $I = \text{interval containing } 0$, such that $\gamma(0) = p$, for the equi. relation defined by

$$\Leftrightarrow (\phi \circ \gamma_1)'(0) = (\phi \circ \gamma_2)'(0) \text{ for a chart } (U, \phi) \text{ around } p.$$

Ex: check that the equi. relation is well-defined by showing that for any other chart (V, ψ) around p , we have

$$(\psi \circ \gamma)'(0) = D_{\phi(p)}(\psi \circ \phi^{-1})(\phi \circ \gamma)'(0)$$

where $D_{\phi(p)}(\psi \circ \phi^{-1})$ is the Jacobi matrix (or differential) of the map $\psi \circ \phi^{-1}$ at $\phi(p)$.

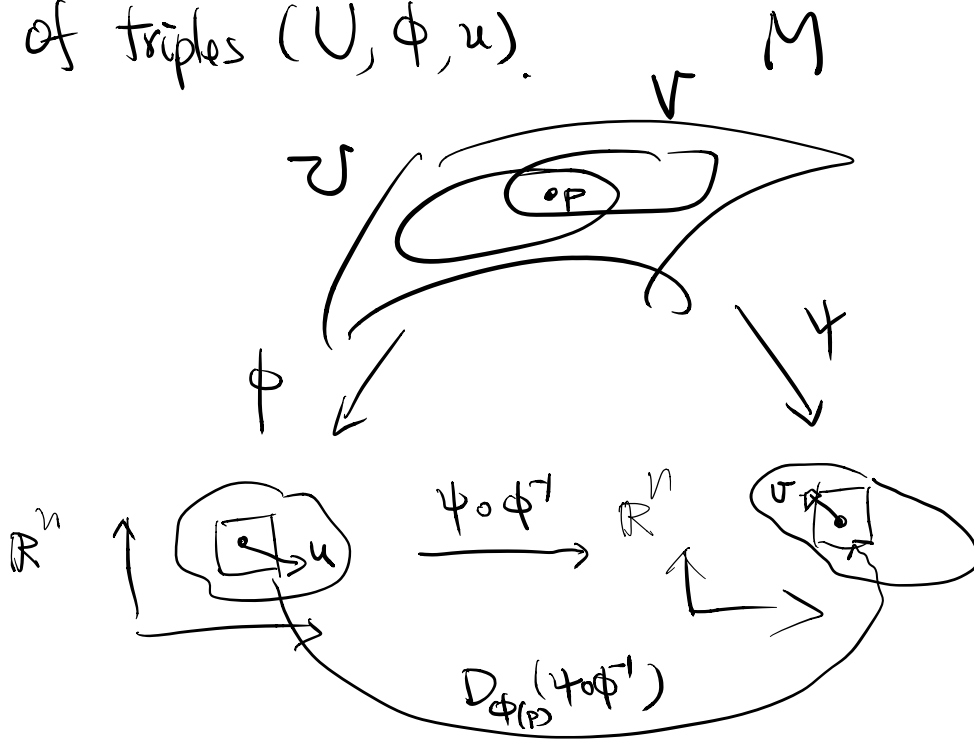
Def 2 (Equivalent definition for tangent vectors)

Let M be a smooth manifold, $p \in M$, $(U, \phi) \in (V, \psi)$ be 2 charts for M around p . Let u, v be

2 vectors in \mathbb{R}^n (considered as tangent vectors to \mathbb{R}^n at $\phi(p)$ and $\psi(p)$ respectively). We say that

$$(U, \phi, u) \sim (V, \psi, v) \iff D_{\phi(p)}(\psi \circ \phi^{-1})u = v.$$

Then a tangent vector to M at p is an equi. class of triples (U, ϕ, u) .



Notes =. In def 1, a tangent vector is represented by a curve γ . We usually write $\gamma'(0)$ for the tangent vector $[\gamma]$ for simplicity (indep. of chart).

- In def 2, the "same" tangent vector will be represented in a chart (U, ϕ) by a vector $u \in \mathbb{R}^n$

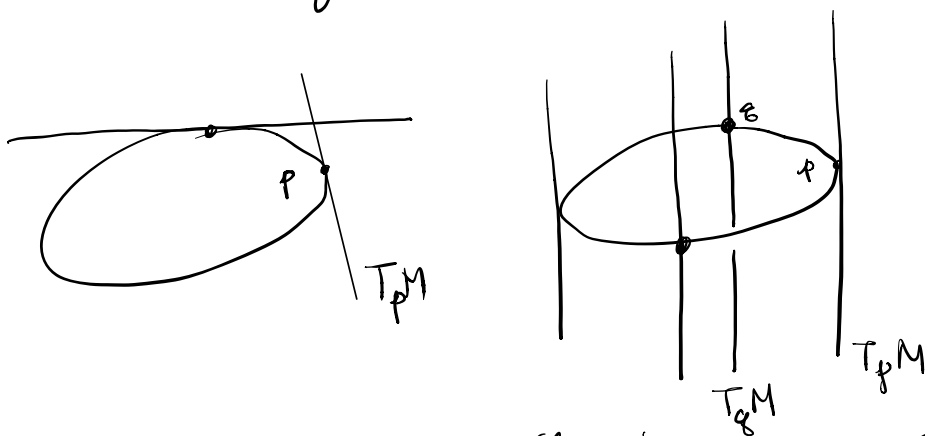
- Def 1 \Leftrightarrow Def 2 by taking $\boxed{u = (\phi \circ \gamma)'(0)}$.

Notation: The set of tangent vectors to M at p is denoted by $T_p M$ (Tangent space to M at $p \in M$)

Note: If a chart (U, ϕ) is given, then we have an "isomorphism"

$$\begin{array}{ccc} \theta_{U, \phi, p} : \mathbb{R}^n & \longrightarrow & T_p M \\ \downarrow & & \downarrow \\ u & \longmapsto & [(U, \phi, u)] \end{array}$$

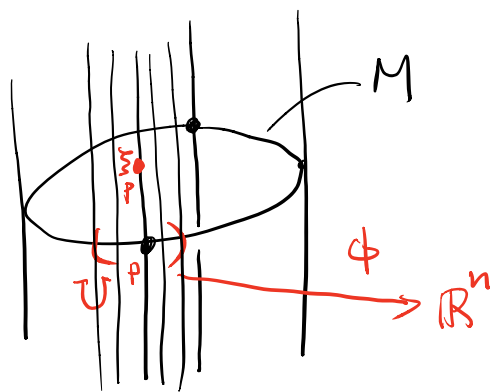
Def: The disjoint union $\bigsqcup T_p M$, $\forall p \in M$, is called the tangent bundle of M .



Thm: Let M be an n -dim'l C^k manifold ($k > 1$)
Then TM can be equipped with a $2n$ -dim'l C^{k-1} abstract manifold structure.

(Sketch of Pf)

For each chart (U, ϕ) of M
define a "chart"



$(\coprod_{p \in U} T_p M, \bar{\Phi})$ for TM by

$$\bar{\Phi}(\xi_p) = (\phi(p), \theta_{U, \phi, p}^{-1}(\xi_p)) \in \mathbb{R}^n \times \mathbb{R}^n$$

$$\forall \xi_p \in T_p M \text{ \& } p \in U.$$

the one can see all these " $\coprod_{p \in U} T_p M$ " give a topology

on TM s.t. $\bar{\Phi}$ are homeomorphisms. And one can

check that TM is Hausdorff and $\left\{ \left(\coprod_{p \in U} T_p M, \bar{\Phi} \right) \right\}_{(U, \phi)}$

forms an C^{k-1} atlas of TM .

(We've differentiated once in the equiv. relation for tangent vectors.)

✘