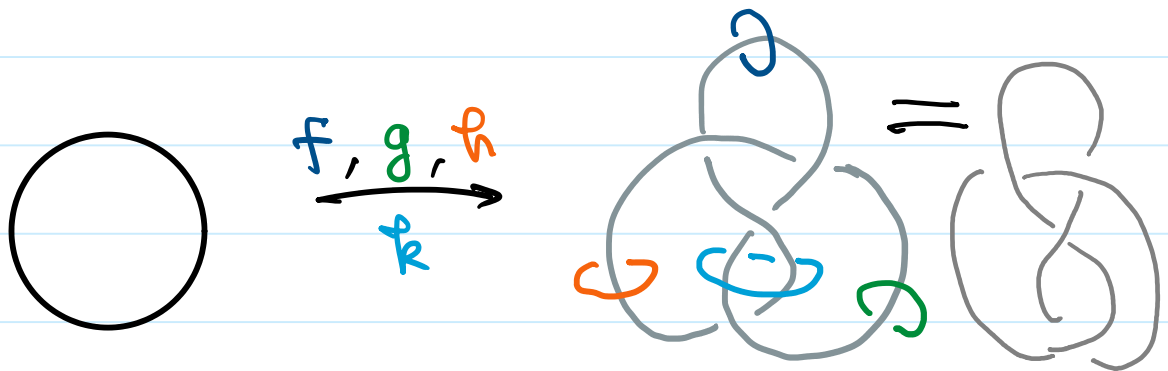


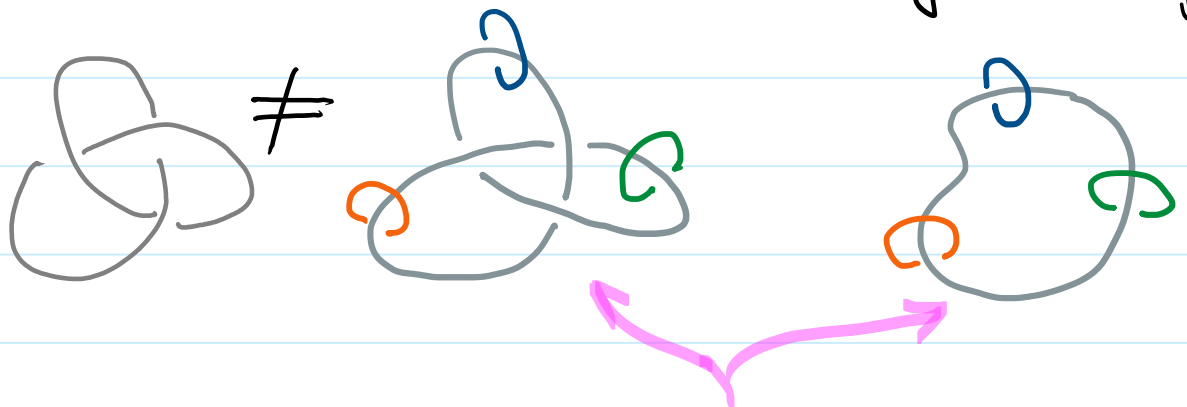
**Recall.** Two continuous mappings  $f, g: X \rightarrow Y$  are **homotopic** (under  $H: X \times [0, 1] \rightarrow Y$ ), denoted  $f \stackrel{H}{\simeq} g$ , if  $H$  is continuous and  $\forall x \in X \quad H(x, 0) = f(x), H(x, 1) = g(x)$ .

**Example.** Take  $X = S^1$ ,  $Y = \mathbb{R}^3 \setminus (\text{knot})$



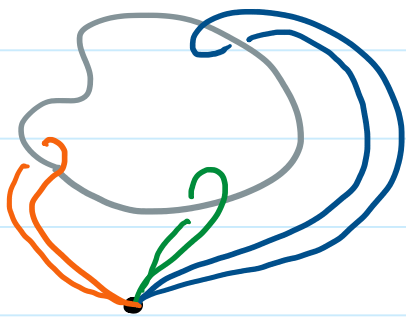
Easy to expect  $f \simeq g \simeq h \not\simeq k$

This is not good enough

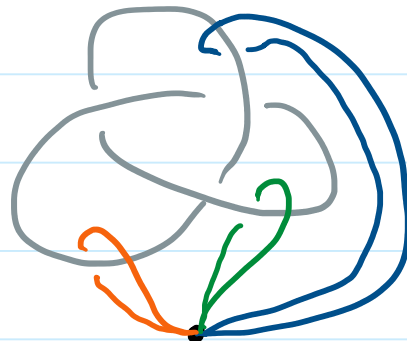


Similar situation occurs in every  $\mathbb{R}^3 \setminus \text{knot}$  no matter how simple or complicated the knot is!

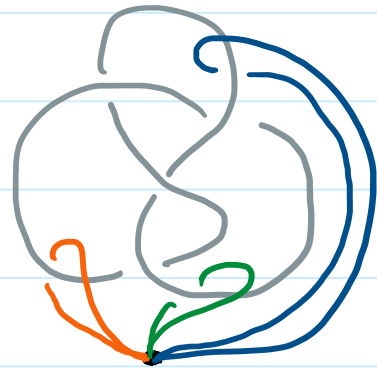
On the other hand,



$$f \cong g \cong h$$



$$f \not\cong g \not\cong h$$



$$f \not\cong g \not\cong h$$

In fact, the algebraic relations among them are different

**Definition.** Let  $A \subset X$  and  $Y$  be spaces.

Two continuous mappings  $f, g: X \rightarrow Y$  are **homotopic rel  $A$**  under  $H: X \times [0,1] \rightarrow Y$

if  $H$  is continuous such that

$$(1) \forall x \in X, H(x, 0) = f(x), H(x, 1) = g(x)$$

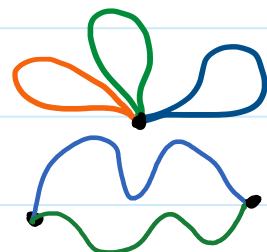
$$(2) \forall t \in [0,1], \forall a \in A, H(a, t) = f(a) = g(a)$$

i.e.,  $f|_A \equiv g|_A$  at first

In above, we study  $f, g, h$  in terms of

$$\bullet X = S^1, A = \{pt\} \quad \text{OR}$$

$$\bullet X = [0,1], A = \{0,1\}$$



**Definition.** Let  $X$  be a topological space.

Two paths  $\gamma_0, \gamma_1: [0, 1] \rightarrow X$  are **path homotopic** if they are homotopic rel  $\{0, 1\}$

$\gamma_0, \gamma_1$  have same end-points at first

i.e.,  $\gamma_0(0) = \gamma_1(0)$ ;  $\gamma_0(1) = \gamma_1(1)$ .

If, in addition, both  $\gamma_0, \gamma_1$  are loops, then they are **loop homotopic rel  $\{0, 1\}$**

Must start with

$$\begin{array}{ccc} \gamma_0(0) & = & H(0, t) = \gamma_1(0) \\ \parallel & & \\ \gamma_0(1) & = & H(1, t) = \gamma_1(1) \end{array}$$

$\gamma_t(0)$  above  $H(0, t)$  and  $\gamma_t(1)$  below  $H(1, t)$

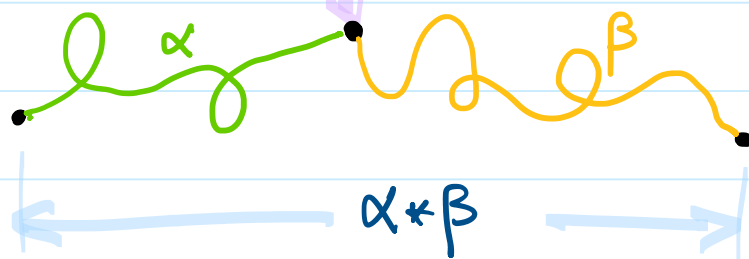
**Theorem.** Every theorem about homotopy has analogous versions for path / loop homotopy.

Here is a useful fact particularly for path or loop homotopy

**Proposition.** If  $\varphi: [0, 1] \rightarrow [0, 1]$  is a change of parameter, i.e., homeomorphism with  $\varphi(0) = 0, \varphi(1) = 1$ , then for any path  $\gamma: [0, 1] \rightarrow X$ ,  $\gamma \circ \varphi \simeq \gamma$  rel  $\{0, 1\}$ .

Definition. Let  $\alpha, \beta: [0, 1] \rightarrow X$  be paths in  $X$  with  $\alpha(1) = \beta(0)$ . Their concatenation

$\alpha * \beta: [0, 1] \rightarrow X$  is a path defined by

$$\alpha * \beta(s) = \begin{cases} \alpha(2s) & , s \in [0, \frac{1}{2}] \\ \beta(2s-1) & , s \in [\frac{1}{2}, 1] \end{cases}$$


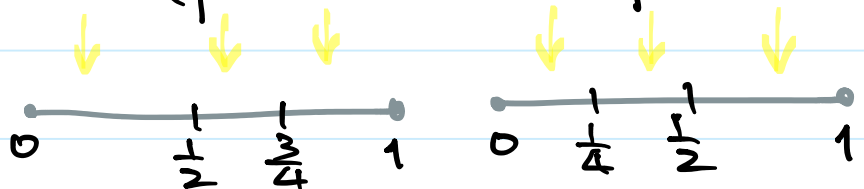
Geometrically,  $\alpha * \beta$  is simply first travel  $\alpha$  then travel  $\beta$ .

What about this

$$\sigma(s) = \begin{cases} \alpha(3s) & , s \in [0, \frac{1}{3}] \\ \beta(\frac{3}{2}s - \frac{1}{2}) & , s \in [\frac{1}{3}, 1] \end{cases}$$

As mappings,  $\sigma \neq \alpha * \beta$

Moreover,  $\alpha * (\beta * \gamma) \neq (\alpha * \beta) * \gamma$



By above proposition,  $\sigma \simeq \alpha * \beta$  rel  $\{0, 1\}$

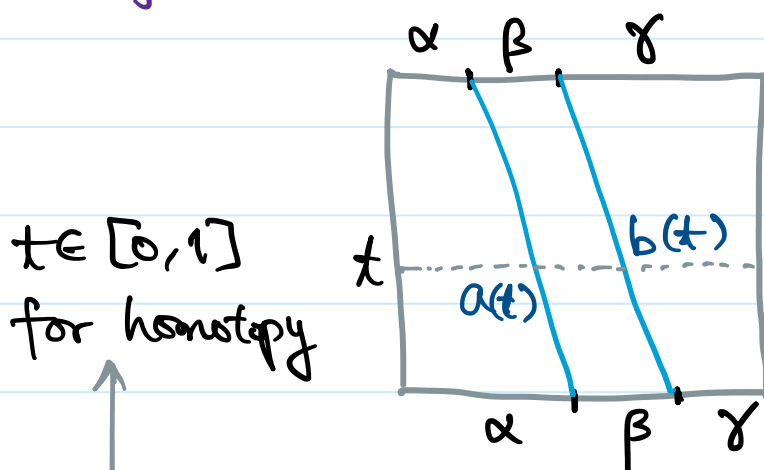
In fact, we have more useful results.

**Proposition.** Under well-defined conditions,  
if  $\alpha_0 \simeq \alpha_1 \text{ rel } \{0,1\}$  and  $\beta_0 \simeq \beta_1 \text{ rel } \{0,1\}$   
then  $\alpha_0 * \beta_0 \simeq \alpha_1 * \beta_1 \text{ rel } \{0,1\}$ .

**Proof.** Easy. Exercise.

**Proposition.**  $\alpha * (\beta * \gamma) \simeq (\alpha * \beta) * \gamma \text{ rel } \{0,1\}$

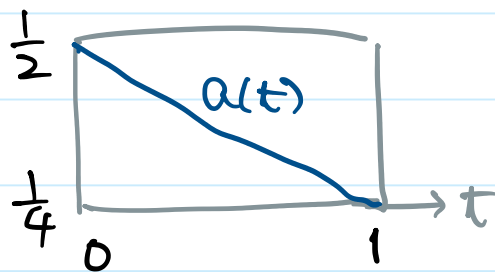
**Proof.** Observe the schematic diagram



$s \in [0,1]$ , parameter for path

The homotopy  $H: [0,1] \times [0,1] \rightarrow X$

$$\text{is } H(s,t) = \begin{cases} \alpha(\text{Exercise}), & s \in [0, a(t)] \\ \beta(\text{Exercise}), & s \in [a(t), b(t)] \\ \gamma(\text{Exercise}), & s \in [b(t), 1] \end{cases}$$

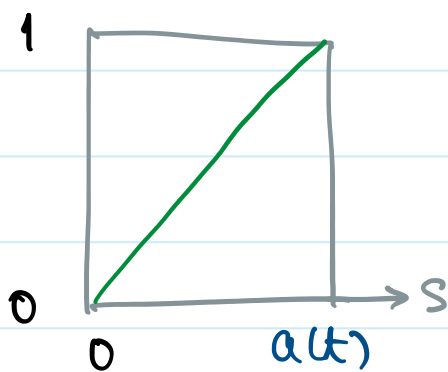


$$\therefore \frac{a(t) - \frac{1}{2}}{t - 0} = \frac{-1}{4}$$

$$a(t) = \frac{-t}{4} + \frac{1}{2}$$

Similarly,  $b(t)$  can be found.

Answer to Exercise for  $\alpha$ :



Thus, it should be

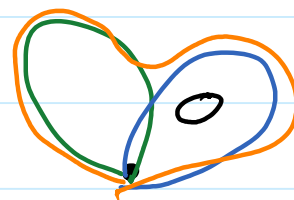
$$\alpha\left(\frac{s}{a(t)}\right).$$

Now, consider all loops  $\gamma: [0, 1] \rightarrow X$   
based at  $x_0 \in X$ , i.e.,  $\gamma(0) = x_0 = \gamma(1)$   
 under loop homotopy.

Definition. The fundamental group of  $X$  at  $x_0$

$$\text{is } \pi_1(X, x_0) = \left\{ \begin{array}{l} \text{loops in } X \\ \text{based at } x_0 \end{array} \right\} / \approx \text{rel } \{0, 1\}$$

$$\text{with } [\alpha] \cdot [\beta] \stackrel{\text{def}}{=} [\alpha * \beta]$$



$\pi_1(X, x_0)$  has an associative (but may not be commutative) "multiplication".

We have established that

$$\pi_1(X, x_0) = \left\{ \text{loops in } X \text{ based at } x_0 \in X \right\} / \cong \text{rel } \{0, 1\}$$

has a "multiplication".

The following facts guarantee that  $\pi_1(X, x_0)$  is truly a group.

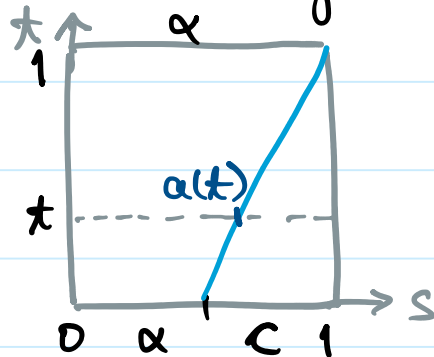
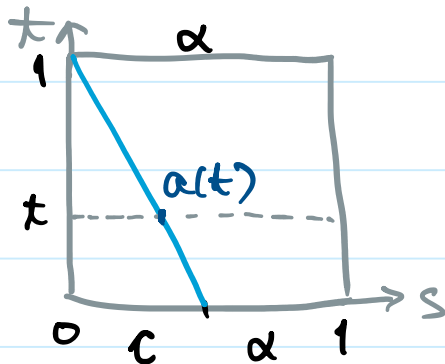
**Proposition.** Let  $c: [0, 1] \rightarrow \{x_0\} \subset X$  be the constant loop. Then for each loop  $\alpha: [0, 1] \rightarrow X$  based at  $x_0$ ,

$$c * \alpha \cong \alpha * c \cong \alpha \text{ rel } \{0, 1\}$$

That is,  $[c]$  is the identity of  $\pi_1(X, x_0)$

**Main idea of proof.**

Observe the two schematic diagrams



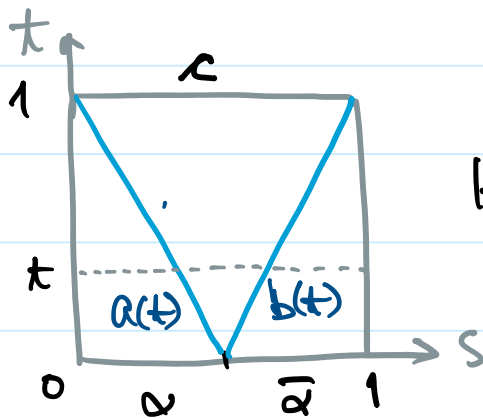
**Proposition.** For each loop  $\alpha: [0,1] \rightarrow X$  based at  $x_0 \in X$ , define  $\bar{\alpha}: [0,1] \rightarrow X$  by  $\bar{\alpha}(s) = \alpha(1-s)$ ,  $s \in [0,1]$ .

Then  $\bar{\alpha}$  is a loop based at  $x_0$  and  $\alpha * \bar{\alpha} \simeq c \simeq \bar{\alpha} * \alpha \text{ rel } \{0,1\}$

Equivalently,  $[\bar{\alpha}] = [\alpha]^{-1}$  in  $\pi_1(X, x_0)$

**Proof.** The rationale is a bit different.

First, observe the schematic diagram



$$H(s,t) = \begin{cases} \alpha(s), & s \in [0, a(t)] \\ x_0, & s \in [a(t), b(t)] \\ \bar{\alpha}(s), & s \in [b(t), 1] \end{cases}$$

If they run through  $[0,1]$  as before, what is the geometric meaning?

fast  $\alpha$  at  $x_0$  fast  $\bar{\alpha}$

stay long at  $x_0$

almost infinite speed NOT continuous

Should travel as  $\alpha$  part of  $\alpha$   $x_0$  part of  $\bar{\alpha}$   $\bar{\alpha}$   $\bar{\alpha}(s)$

i.e.,  $a(t)$   $b(t) = 1 - a(t)$