

1. **Definition. (Systems of linear equations.)**

Let a_{ij} be (fixed) real numbers for each $i = 1, \dots, m$ and for each $j = 1, \dots, n$.

Let b_k be (fixed) real numbers for each $k = 1, \dots, m$.

(a) The system of m simultaneous equations with unknowns x_1, x_2, \dots, x_n

$$\left\{ \begin{array}{l} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m \end{array} \right.$$

is called a system of m linear equations with n unknowns.

The numbers a_{ij} 's, b_k 's are referred to as givens in this system of linear equations.

(b) Denote such a system of linear equations by (S) .

Let t_1, t_2, \dots, t_n be (fixed) real numbers.

We say $(x_1, x_2, \dots, x_n) = (t_1, t_2, \dots, t_n)$ is a solution of the system (S) if and only if the m equalities

$$\begin{aligned} a_{11}t_1 + a_{12}t_2 + \dots + a_{1n}t_n &= b_1, \\ a_{21}t_1 + a_{22}t_2 + \dots + a_{2n}t_n &= b_2, \\ &\vdots \\ a_{m1}t_1 + a_{m2}t_2 + \dots + a_{mn}t_n &= b_m \end{aligned}$$

hold simultaneously.

(c) (Again denote such a system of linear equations by (S) .)

- i. We say (S) is consistent if and only if there is some solution for (S) .
- ii. We say (S) is inconsistent if and only if there is no solution for (S) .

2. Definition. (Equation operation ‘adding a scalar multiple of one equation to another’.)

Consider the system of linear equations

$$(S) : \begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{cases}$$

in which x_1, x_2, \dots, x_n are the unknowns.

Suppose α is a real number.

When we replace the k -th equation

$$a_{k1}x_1 + a_{k2}x_2 + \cdots + a_{kn}x_n = b_k$$

of (S) by the equation

$$(\alpha a_{i1} + a_{k1})x_1 + (\alpha a_{i2} + a_{k2})x_2 + \cdots + (\alpha a_{in} + a_{kn})x_n = \alpha b_i + b_k,$$

in which $i \neq k$, to obtain some (other) system, we say we are applying the equation operation ‘ $\alpha \times \odot_i + \odot_k$ ’ to (S) .

Such an equation operation is called ‘adding a scalar multiple of one equation of (S) to another equation of (S) ’.

3. Definition. (Equation operation ‘multiplying a non-zero scalar to one equation’.)

Consider the system of linear equations

$$(S) : \begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{cases}$$

in which x_1, x_2, \dots, x_n are the unknowns.

Suppose β is a non-zero real number.

When we replace the k -th equation

$$a_{k1}x_1 + a_{k2}x_2 + \cdots + a_{kn}x_n = b_k$$

of (S) by the equation

$$\beta a_{k1}x_1 + \beta a_{k2}x_2 + \cdots + \beta a_{kn}x_n = \beta b_k,$$

to obtain some (other) system, we say we are applying the equation operation ‘ $\beta \times \bigcirc_k$ ’ to (S) .

Such an equation operation is called ‘multiplying a non-zero scalar to one equation of (S) ’.

4. **Definition.** (Equation operation ‘interchanging two equations’.)

Consider the system of linear equations

$$(S) : \begin{cases} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2 \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m \end{cases}$$

in which x_1, x_2, \dots, x_n are the unknowns.

When we interchange the i -th equation

$$a_{i1}x_1 + a_{i2}x_2 + \cdots + a_{in}x_n = b_i$$

of (S) and the k -th equation

$$a_{k1}x_1 + a_{k2}x_2 + \cdots + a_{kn}x_n = b_k$$

of (S) , in which $i \neq k$, to obtain some (other) system, we say we are applying the equation operation ‘ $\odot_i \leftrightarrow \odot_k$ ’ to (S) .

Such an equation operation is called ‘interchanging two equations of (S) ’.

5. Definition. (Equation operations.)

Let $(S), (T)$ be systems of m linear equations with n unknowns.

We say we are applying one equation operation on (S) to obtain the system (T) if and only if (T) is the resultant of the application of

- one equation operation ‘adding a scalar multiple of one equation of (S) to another’,
or
- one equation operation ‘multiplying a non-zero scalar to one equation (S) ’, or
- one equation operation ‘interchanging two equations of (S) ’.

6. Definition. (Equivalent systems of linear equations.)

Let $(S), (T)$ be systems of m linear equations with n unknowns.

We say (S) is equivalent to (T) as systems if and only if both statements below hold:

- (a) Every solution of (S) is a solution of (T) .
- (b) Every solution of (T) is a solution of (S) .

7. Theorem (1).

Let $(S), (T)$ be systems of m linear equations with n unknowns.

- (a) Suppose (T) is resultant from the application of one equation operation on (S) . Then (S) is equivalent to (T) as systems.*
- (b) Suppose (T) is resultant from the application of finitely many equation operations, starting from (S) . Then (S) is equivalent to (T) as systems.*

8. Theorem (2).

The statements below hold:

- (a) Suppose (S) is a system of m linear equations with n unknowns. Then (S) is equivalent to (S) as systems.*
- (b) Let $(S), (T)$ be systems of m linear equations with n unknowns. Suppose (S) is equivalent to (T) as systems. Then (T) is equivalent to (S) as systems.*
- (c) Let $(S), (T), (U)$ be systems of m linear equations with n unknowns. Suppose (S) is equivalent to (T) as systems, and (T) is equivalent to (U) as systems. Then (S) is equivalent to (U) as systems.*