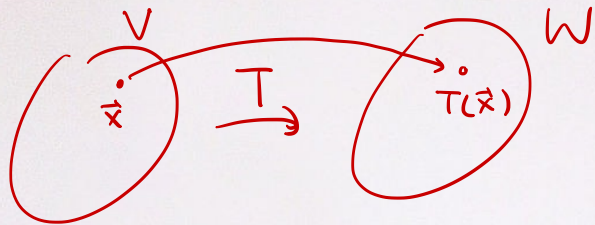


## Lecture 7:

Recall: • Linear Transformation  $T: V \rightarrow W$  :



$$\textcircled{1} T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$$

$$\textcircled{2} T(a\vec{x}) = aT(\vec{x})$$

$$\bullet N(T) \stackrel{\text{def}}{=} \{ \vec{x} \in V \mid T(\vec{x}) = \mathbf{0} \} \subset V$$

$$R(T) \stackrel{\text{def}}{=} \{ T(\vec{x}) \mid \vec{x} \in V \} \subset W$$

Proved that:  $N(T)$  and  $R(T)$  are subspaces,

Remark:  $T: V \rightarrow W$  is onto iff  $R(T) = W$   
(follows from the def)

Proposition: A linear transformation  $T: V \rightarrow W$  is one-to-one  
iff  $N(T) = \{\vec{0}\}$ .

Pf: (Recap: One-to-one  $\Leftrightarrow$  " $T(\vec{x}) = T(\vec{y}) \Rightarrow \vec{x} = \vec{y}$ ")

$(\Rightarrow)$  If  $T$  is one-to-one, then: for any  $\vec{x} \in N(T)$ ,

$$\text{we have } T(\vec{x}) = \vec{0}_W = T(\vec{0}_V)$$

$$\Rightarrow \vec{x} = \vec{0}_V$$

This implies  $N(T) = \{\vec{0}_V\}$ .

( $\Leftarrow$ ) Suppose  $N(T) = \{\vec{0}_V\}$

Let  $\vec{x}, \vec{y} \in V$  such that  $T(\vec{x}) = T(\vec{y})$ .

Then:  $T(\vec{x}) - T(\vec{y}) = T(\vec{x} - \vec{y}) = \vec{0}$

This implies  $\vec{x} - \vec{y} \in N(T) = \{\vec{0}_V\}$

$\therefore \vec{x} - \vec{y} = \vec{0}_V$  or  $\vec{x} = \vec{y}$ .

$\therefore T$  is 1-1.

Definition: Let  $T: V \rightarrow W$  be a linear transformation.

If  $N(T)$  and  $R(T)$  are finite-dimensional, we define:

- Nullity is denoted as Nullity  $(T)$  is the dimension of  $N(T)$ .
- Rank is denoted as Rank  $(T)$  is the dimension of  $R(T)$ .

Lemma: Let  $T: V \rightarrow W$  be a linear transformation. If

$\beta = \{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n\}$  is a basis for  $V$ , then:

$$R(T) = \text{Span}(T(\beta)) \stackrel{\text{def}}{=} \text{Span}\{T(\vec{v}_1), T(\vec{v}_2), \dots, T(\vec{v}_n)\}$$

Proof:  $\because T(\vec{v}_j) \in R(T)$  for  $j=1, 2, \dots, n$

and  $R(T)$  is subspace.

$$\therefore \text{Span} \left\{ \underset{\substack{\uparrow \\ R(T)}}{T(\vec{v}_1)}, \underset{\substack{\uparrow \\ R(T)}}{T(\vec{v}_2)}, \dots, \underset{\substack{\uparrow \\ R(T)}}{T(\vec{v}_n)} \right\} \subset R(T)$$

Conversely, let  $\vec{w} \in R(T)$  where  $\vec{x} \in V$ .

$$\text{Then: } \exists a_1, a_2, \dots, a_n \in F \text{ s.t. } \vec{x} = \sum_{j=1}^n a_j \vec{v}_j.$$

$$\text{So, } \vec{w} = T(\vec{x}) = T\left(\sum_{j=1}^n a_j \vec{v}_j\right) = \sum_{j=1}^n a_j T(\vec{v}_j) \in \text{Span}\{T(\vec{v}_1), \dots, T(\vec{v}_n)\}$$

$$\therefore R(T) \subset \text{Span}(T(\beta)) \quad \therefore R(T) = \text{Span}(T(\beta))$$

Example:  $T: P_2(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$  defined by:

$$T(f) = \begin{pmatrix} f(0) & f(1) \\ 0 & f'(0) \end{pmatrix}$$

We have:  $R(T) = \text{span} \{ T(1), T(x), T(x^2) \}$

$$= \text{span} \left\{ \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right\}$$

Lin. indep.

$$\Rightarrow \text{Rank}(T) = 3$$

## Theorem: (Rank - Nullity Theorem)

Let  $V$  and  $W$  be vector spaces s.t.  $V$  is finite-dimensional.

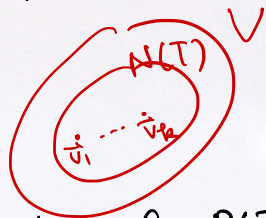
Then for any linear transformation  $T: V \rightarrow W$ , we have:

$$\text{nullity}(T) + \text{Rank}(T) = \text{dim}(V)$$

Proof: Let  $n = \text{dim}(V)$  and  $k = \text{dim}(N(T)) \leq n$

Choose a basis  $\{\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k\}$  for  $N(T)$  and extend it to a basis  $\{\vec{v}_1, \dots, \vec{v}_k, \vec{v}_{k+1}, \dots, \vec{v}_n\}$  for  $V$ .

Claim:  $S = \{T(\vec{v}_{k+1}), T(\vec{v}_{k+2}), \dots, T(\vec{v}_n)\}$  is a basis for  $R(T)$ .



$$\begin{aligned}
 \textcircled{1} \quad R(T) &= \text{span} \{ T(\vec{v}_1), T(\vec{v}_2), \dots, T(\vec{v}_n) \} \\
 &= \text{span} \{ \underbrace{T(\vec{v}_{k+1}), \dots, T(\vec{v}_n)}_S \} = \text{span}(S)
 \end{aligned}$$

$\textcircled{2}$  Now suppose  $\exists b_{k+1}, b_{k+2}, \dots, b_n \in F$  s.t.

$$\sum_{i=k+1}^n b_i T(\vec{v}_i) = \vec{0}.$$

Then, by linearity, we have:  $T\left(\sum_{i=k+1}^n b_i \vec{v}_i\right) = \vec{0}$

$$\Rightarrow \sum_{i=k+1}^n b_i \vec{v}_i \in N(T)$$



$$\therefore \sum_{i=k+1}^n b_i \vec{v}_i = \sum_{i=1}^k c_i \vec{v}_i \quad \text{for some } c_1, \dots, c_k \in F.$$

But then: 
$$\sum_{i=1}^k (-c_i) \vec{v}_i + \sum_{i=k+1}^n b_i \vec{v}_i = \vec{0}$$

$\therefore \{\vec{v}_1, \dots, \vec{v}_n\}$  is a basis for  $V$  and so it is lin. ind.

$$\therefore (-c_i) = 0 \quad \text{for } i=1, 2, \dots, k$$

$$b_i = 0 \quad \text{for } i=k+1, k+2, \dots, n$$

$\therefore S$  is lin. ind.

$\therefore S$  is basis for  $R(T)$ .

$$\begin{aligned} \therefore & \text{Nullity}(T) + \text{Rank}(T) \\ &= \overset{\parallel}{k} + (n-k) \parallel \\ &= n = \text{dim}(V) \parallel \end{aligned}$$