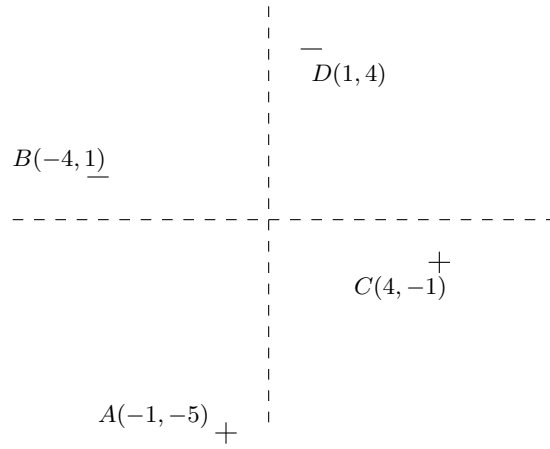


## CMSC5724: Exercise List 4

Answer all the problems below based on the following set  $P$  of points  $A, B, C$  and  $D$ :



where “+” represents label 1 and “-” represents label  $-1$ .

**Problem 1.** What is the margin of the separation line  $\ell : -x - 5y = 0$ ?

**Answer:** The distance between  $\ell$  and the points in  $P$  are as follows:

- $A: \frac{|-1 \times (-1) - 5 \times (-5)|}{\sqrt{(-1)^2 + (-5)^2}} = \sqrt{26}.$
- $B: \frac{|-4 \times (-1) + 1 \times (-5)|}{\sqrt{(-1)^2 + (-5)^2}} = 1/\sqrt{26}.$
- $C: \frac{|4 \times (-1) - 1 \times (-5)|}{\sqrt{(-1)^2 + (-5)^2}} = 1/\sqrt{26}.$
- $D: \frac{|1 \times (-1) + 4 \times (-5)|}{\sqrt{(-1)^2 + (-5)^2}} = 21/\sqrt{26}.$

Therefore, the margin of  $\ell$  is  $1/\sqrt{26}$ .

**Problem 2.** Run Margin Perceptron on  $P$  with  $\gamma_{guess} = 0.1$ , and give the equation of the line that is maintained by the algorithm at the end of each iteration.

**Answer:** Let us represent the line maintained by Margin Perceptron as  $c_1x + c_2y = 0$ . Define  $\vec{c} = [c_1, c_2]$ . At the beginning of Margin Perceptron,  $\vec{c} = [0, 0]$ . We use  $\vec{A}$  to denote the vector  $[-1, -5]$ , obtained by listing the coordinates of  $A$ . Define  $\vec{B}, \vec{C}, \vec{D}$  similarly.

*Iteration 1.*  $A$  does not satisfy  $\vec{A} \cdot \vec{c} > 0$ . So we update  $\vec{c}$  to  $\vec{c} + \vec{A} = [0, 0] + [-1, -5] = [-1, -5]$ .

*Iteration 2.* No more violation. So we have found a separation line  $-x - 5y = 0$ .

**Problem 3.** Same as the previous problem but with  $\gamma_{guess} = 4/\sqrt{26}$ .

**Answer:** Starting with  $\vec{c} = [0, 0]$ , Margin Perceptron runs as follows:

*Iteration 1.*  $A$  does not satisfy  $\vec{A} \cdot \vec{c} > 0$ . So we update  $\vec{c}$  to  $\vec{c} + \vec{A} = [0, 0] + [-1, -5] = [-1, -5]$ .

*Iteration 2.* The distance between  $B$  and the line determined by  $\vec{c}$  is  $1/\sqrt{26}$ , which is smaller than  $\gamma_1/2$ . So we update  $\vec{c}$  to  $\vec{c} - \vec{B} = [-1, -5] - [-4, 1] = [3, -6]$ .

*Iteration 3.* No more violation. So we have found a separation line  $3x - 6y = 0$ .

**Problem 4.** Give an instance of quadratic programming to find an origin-passing separation plane with the maximum margin.

**Answer:** Minimize  $w_1^2 + w_2^2$  subject to the following constraints:

- $(-1)w_1 + (-5)w_2 \geq 1$
- $4w_1 + (-1)w_2 \geq 1$
- $(-4)w_1 + w_2 \leq -1$
- $w_1 + 4w_2 \leq -1$

**Problem 5.** Consider the following instance of quadratic programming in  $\mathbb{R}^d$ :

$$\begin{aligned} & \text{minimize } |\mathbf{w}| \text{ subject to} \\ & \mathbf{w} \cdot \mathbf{p}_i \geq 1 \text{ for each } i \in [1, n] \end{aligned}$$

where  $\mathbf{p}_1, \dots, \mathbf{p}_n$  are  $n$  given points in  $\mathbb{R}^d$ . Prove: if an optimal  $\mathbf{w}$  exists, there must exist at least one  $i \in [1, n]$  such that  $\mathbf{w} \cdot \mathbf{p}_i = 1$ .

**Answer:** We will give a proof by contradiction. Suppose that  $\mathbf{w}$  is an optimal solution and  $\mathbf{w} \cdot \mathbf{p}_i > 1$  for every  $i \in [1, n]$ . Define  $\tau = \min_i \mathbf{w} \cdot \mathbf{p}_i$  and  $\mathbf{w}' = \mathbf{w}/\tau$ . We know  $\tau > 1$  (otherwise, there exists an  $i$  such that  $\mathbf{w} \cdot \mathbf{p}_i = 1$ ):

- $\mathbf{w} \cdot \mathbf{p}_i \geq \tau$  for each  $i \in [1, n]$

which implies

- $\mathbf{w}' \cdot \mathbf{p}_i \geq 1$  for each  $i \in [1, n]$ .

Hence,  $\mathbf{w}'$  is a feasible solution of the quadratic programming. However, the fact  $|\mathbf{w}'| < |\mathbf{w}|$  contradicts the optimality of  $\mathbf{w}$ .

**Problem 6.** Let  $\gamma_{opt}$  be the maximum margin of an origin-passing separation plane on a set  $P$  of points. Denote by  $R$  the largest distance from a point in  $P$  to the origin.

Suppose that, given a value  $\gamma$ , margin Perceptron ensures the following:

- if it terminates, it definitely returns a separation plane with margin at least  $\alpha \cdot \gamma$ , where  $\alpha$  is an arbitrary constant less than 1;
- if  $\gamma \leq \gamma_{opt}$ , it definitely terminates after at most  $c \cdot R^2/\gamma^2$  corrections, for some constant (which depends on  $\alpha$ ).

Design an algorithm to find a separation plane with margin at least  $\alpha \cdot \beta \cdot \gamma_{opt}$  after  $O(R^2/\gamma_{opt}^2)$  corrections in total, where  $\beta$  can be any constant less than 1.

**Answer:** Use exactly the same algorithm taught in the class that repeatedly runs margin Perceptron with an increasingly smaller  $\gamma$ , except that we set  $\gamma$  to  $\beta^{i-1} \cdot R$  in the  $i$ -th run.

Suppose that the value of  $\gamma$  in the final run is  $\gamma_{final} = \beta^x \cdot R$ . Since we did not stop at the previous run, we know that  $\gamma_{final}/\beta > \gamma_{opt}$ , namely,  $\gamma_{final} > \beta \cdot \gamma_{opt}$ .

In the final run, the separation plane returned must have a margin at least  $\alpha \cdot \gamma \geq \alpha \cdot \beta \cdot \gamma_{opt}$ .

The total number of corrections is no more than

$$cR^2 \left( \frac{1}{\gamma_{final}^2} + \frac{\beta^2}{\gamma_{final}^2} + \frac{\beta^4}{\gamma_{final}^2} \dots \right) = O(R^2/\gamma_{final}^2) = O(R^2/\gamma_{opt}^2).$$